

# Installation Manual For

# 8300-013 Rev J Automatic Pitch Trim



TRUTRAK FLIGHT SYSTEMS

1488 S. Old Missouri Road Springdale, AR 72764

POSTAL SERVICE ADDRESS

P.O. Box 189 Springdale AR 72765-0189

Ph: 479-751-0250 Fax: 479-751-3397

www.trutrakap.com

# IT IS THE INSTALLERS RESPONSIBILITY TO ENSURE THAT THE TRIM SYSTEM DOES NOT EXCEED THE ABILITY OF THE PILOT TO CONTROL THE AIRCRAFT AT ANY SPEED WITH THE TRIM TAB AT FULL DEFLECTION IN EITHER POSITION.

IF UNABLE TO MAINTAIN FLIGHT CONTROL WITH THE TRIM TABS AT FULL DEFLECTION THEN STOPS WILL BE NEEDED IN THE AIRCRAFT TRIM SYSTEM.

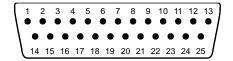
# **Table of Contents**

Electrical Pin-Out	3
Pitch Auto Trim Block Diagram	5
28 Volt Aircraft with 12 Volt Trim System	6
Trouble Shooting	7
Autotrim Ground Setup	8
Autotrim Ground Checkout (Do this before first flight with the autotrim)	8
Autotrim Status Lamp Indications	8
Autotrim Checkout Flowchart (All tests performed at the elevator surface, not at the stick/yoke)	
RETURN MERCHANDISE POLICY	.11
Autotrim Dimensions	.12

Revision	Date	Discription	Pages
С	12/22/2009	New auto trim module All	
D	06/03/2011	Updated trouble guide 1, 5 & 6	
E	2/23/2015	Updated for new autotrim All	
		design	
F	3/2/2015	Corrected diagrams for LED	4-6
G	3/30/2015	Corrected setup procedure	9
Н	7/13/2017	Added note to diagrams	4-6
		for LED polarity	
I	10/23/2017	Corrected Pin 16	4
		Connection	
J	10/30/2017	Corrected Flowchart	9

#### **Electrical Pin-Out**

The table below provides a brief explanation of each pin function on the 25-pin connector P101.



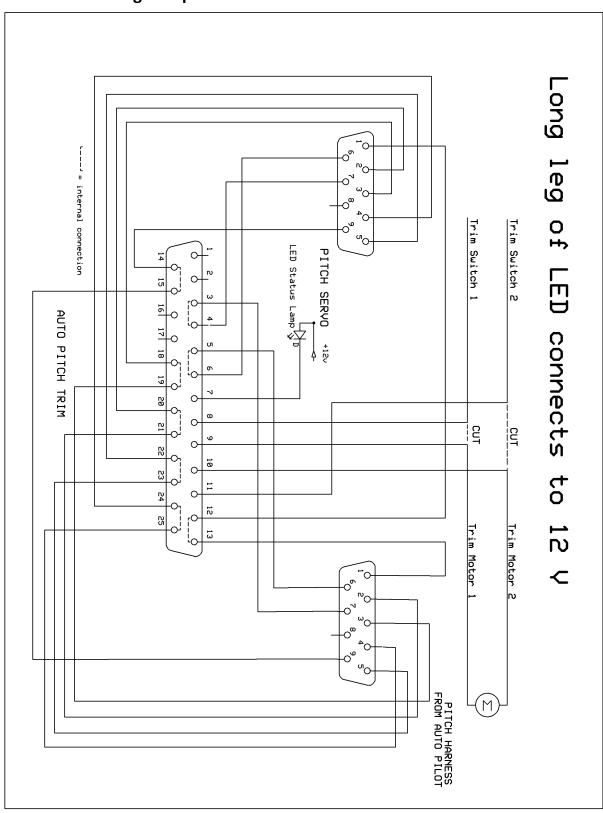
25-Pin Connector P101

1 No Connection. Reserved for future expansion. 2 No Connection. Reserved for future expansion. 3 Pitch Servo Trim Sensor. Pitch servo trim sensor output to autopilot programmer. @2.5 v AP engaged no load			
2 No Connection. Reserved for future expansion. 3 Pitch Servo Trim Sensor. Pitch servo trim sensor output to autopilot programmer. 4 Pitch Servo Trim Sensor. Pitch servo trim sensor input from pitch servo pin 7. 5 Torque Control. Pitch servo torque control input from autopilot programmer. 6 Torque Control. Pitch servo torque control output from autopilot programmer. 7 LED Lamp Output. LED status lamp output 8 Trim motor control 1. Line 1 to existing Trim motor control system. 9 Motor 1. Line 1 to existing trim servo motor. Will not control relays 10 Motor 2. Line 2 to existing trim servo motor. Will not control relays 11 Trim motor control 2. Line 2 to existing Trim motor control system. 12 Power. Connects to autopilot master or pitch servo power line from programmer. 13 Power. Connects to pitch servo pin 1. 14 Ground. Ground connection 15 Ground. Connect to aircraft ground. 16 No Connection. Reserved for future expansion. 17 No Connection. Reserved for future expansion. 18 PH1P. Servo drive line output to pitch servo pin 3. 19 PH1P. Servo drive line input from programmer 20 PH1N. Servo drive line input from programmer 21 PH2P. Servo drive line input from programmer 22 PH2P. Servo drive line output to pitch servo pin 5. 23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line output to pitch servo pin 4.	P101 Pin		Notes
Pitch Servo Trim Sensor. Pitch servo trim sensor output to autopilot programmer. @2.5 v AP engaged no load Pitch Servo Trim Sensor. Pitch servo trim sensor input from pitch servo pin 7. @2.5 v AP engaged no load Torque Control. Pitch servo torque control input from autopilot programmer. @5 volt, AP engaged Torque Control. Pitch servo torque control output to pitch servo. @5 volt, AP engaged  Torque Control. Pitch servo torque control output to pitch servo. @5 volt, AP engaged  Torque Control. Pitch servo torque control output to pitch servo. @5 volt, AP engaged  Trim motor control 1. Line 1 to existing Trim motor control system.  Motor 1. Line 1 to existing trim servo motor. Will not control relays  Motor 2. Line 2 to existing trim servo motor. Will not control relays  Trim motor control 2. Line 2 to existing Trim motor control system.  Power. Connects to autopilot master or pitch servo power line from programmer.  Power. Connects to pitch servo pin 1.  Ground. Ground connection  Ground. Ground connection  No Connection. Reserved for future expansion.  PHIP. Servo drive line output to pitch servo pin 3.  PHIP. Servo drive line output to pitch servo pin 2.  PHIN. Servo drive line input from programmer  PHIN. Servo drive line input from programmer  PHIP. Servo drive line input from programmer	1	No Connection. Reserved for future expansion.	
4 Pitch Servo Trim Sensor. Pitch servo trim sensor input from pitch servo pin 7. @2.5 v AP engaged no load 5 Torque Control. Pitch servo torque control input from autopilot programmer. @5 volt, AP engaged 6 Torque Control. Pitch servo torque control output to pitch servo. @5 volt, AP engaged 7 LED Lamp Output. LED status lamp output 8 Trim motor control 1. Line 1 to existing Trim motor control system. 9 Motor 1. Line 1 to existing trim servo motor. Will not control relays Voltage in @max 5 amps 10 Motor 2. Line 2 to existing trim servo motor. Will not control relays Voltage in @max 5 amps 11 Trim motor control 2. Line 2 to existing Trim motor control system. 12 Power. Connects to autopilot master or pitch servo power line from programmer. 13 Power. Connects to pitch servo pin 1. 14 Ground. Ground connection 15 Ground. Connect to aircraft ground. Aircraft ground 16 No Connection. Reserved for future expansion. 17 No Connection. Reserved for future expansion. 18 PH1P. Servo drive line output to pitch servo pin 3. 19 PH1P. Servo drive line input from programmer 20 PH1N. Servo drive line output to pitch servo pin 2. 21 PH1N. Servo drive line output to pitch servo pin 5. 22 PH2P. Servo drive line output to pitch servo pin 5. 23 PH2P. Servo drive line output to pitch servo pin 4.	2	No Connection. Reserved for future expansion.	
5 Torque Control. Pitch servo torque control input from autopilot programmer. 6 Torque Control. Pitch servo torque control output to pitch servo. 7 LED Lamp Output. LED status lamp output 8 Trim motor control 1. Line 1 to existing Trim motor control system. 9 Motor 1. Line 1 to existing trim servo motor. Will not control relays 10 Motor 2. Line 2 to existing trim servo motor. Will not control relays 11 Trim motor control 2. Line 2 to existing Trim motor control system. 12 Power. Connects to autopilot master or pitch servo power line from programmer. 13 Power. Connects to pitch servo pin 1. 14 Ground. Ground connection 15 Ground. Connect to aircraft ground. 16 No Connection. Reserved for future expansion. 17 No Connection. Reserved for future expansion. 18 PH1P. Servo drive line output to pitch servo pin 3. 19 PH3P. Servo drive line input from programmer 20 PH3N. Servo drive line output to pitch servo pin 2. 21 PH3N. Servo drive line output to pitch servo pin 5. 23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line input from programmer 27 PH2N. Servo drive line input from programmer 28 PH3P. Servo drive line input from programmer 29 PH3P. Servo drive line output to pitch servo pin 5. 20 PH3P. Servo drive line input from programmer	3	<b>Pitch Servo Trim Sensor</b> . Pitch servo trim sensor output to autopilot programmer.	@2.5 v AP engaged no load
6 Torque Control. Pitch servo torque control output to pitch servo. @5 volt, AP engaged 7 LED Lamp Output. LED status lamp output 8 Trim motor control 1. Line 1 to existing Trim motor control system. 9 Motor 1. Line 1 to existing trim servo motor. Will not control relays Voltage in @max 5 amps 10 Motor 2. Line 2 to existing trim servo motor. Will not control relays Voltage in @max 5 amps 11 Trim motor control 2. Line 2 to existing Trim motor control system. 12 Power. Connects to autopilot master or pitch servo power line from programmer. 11 – 35V input 13 Power. Connects to pitch servo pin 1. 14 Ground. Ground connection 15 Ground. Connect to aircraft ground. 16 No Connection. Reserved for future expansion. 17 No Connection. Reserved for future expansion. 18 PH1P. Servo drive line output to pitch servo pin 3. 19 PH1P. Servo drive line input from programmer 20 PH1N. Servo drive line input from programmer 21 PH2P. Servo drive line input from programmer 22 PH2P. Servo drive line input from programmer 23 PH2P. Servo drive line input from programmer 24 PH2P. Servo drive line input from programmer 25 PH2P. Servo drive line input from programmer	4	<b>Pitch Servo Trim Sensor</b> . Pitch servo trim sensor input from pitch servo pin 7.	@2.5 v AP engaged no load
7 LED Lamp Output. LED status lamp output 8 Trim motor control 1. Line 1 to existing Trim motor control system. 9 Motor 1. Line 1 to existing trim servo motor. Will not control relays Voltage in @max 5 amps 10 Motor 2. Line 2 to existing trim servo motor. Will not control relays Voltage in @max 5 amps 11 Trim motor control 2. Line 2 to existing Trim motor control system. 12 Power. Connects to autopilot master or pitch servo power line from programmer. 11 – 35V input 13 Power. Connects to pitch servo pin 1. 14 Ground. Ground connection 15 Ground. Connect to aircraft ground. Aircraft ground 16 No Connection. Reserved for future expansion. 17 No Connection. Reserved for future expansion. 18 PH1P. Servo drive line output to pitch servo pin 3. 19 PH1P. Servo drive line input from programmer 20 PH1N. Servo drive line input from programmer 21 PH2P. Servo drive line input from programmer 22 PH2P. Servo drive line input from programmer 23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line input from programmer 25 PH2P. Servo drive line input from programmer	5	<b>Torque Control</b> . Pitch servo torque control input from autopilot programmer.	@5 volt, AP engaged
8 Trim motor control 1. Line 1 to existing Trim motor control system. 9 Motor 1. Line 1 to existing trim servo motor. Will not control relays Voltage in @max 5 amps 10 Motor 2. Line 2 to existing trim servo motor. Will not control relays Voltage in @max 5 amps 11 Trim motor control 2. Line 2 to existing Trim motor control system. 12 Power. Connects to autopilot master or pitch servo power line from programmer. 13 Power. Connects to pitch servo pin 1. 14 Ground. Ground connection 15 Ground. Connect to aircraft ground. 16 No Connection. Reserved for future expansion. 17 No Connection. Reserved for future expansion. 18 PH1P. Servo drive line output to pitch servo pin 3. 19 PH1P. Servo drive line input from programmer 20 PH1N. Servo drive line output to pitch servo pin 2. 21 PH1N. Servo drive line input from programmer 22 PH2P. Servo drive line output to pitch servo pin 5. 23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line output to pitch servo pin 4.	6	<b>Torque Control</b> . Pitch servo torque control output to pitch servo.	@5 volt, AP engaged
9 Motor 1. Line 1 to existing trim servo motor. Will not control relays 10 Motor 2. Line 2 to existing trim servo motor. Will not control relays 11 Trim motor control 2. Line 2 to existing Trim motor control system. 12 Power. Connects to autopilot master or pitch servo power line from programmer. 13 Power. Connects to pitch servo pin 1. 14 Ground. Ground connection 15 Ground. Connect to aircraft ground. 16 No Connection. Reserved for future expansion. 17 No Connection. Reserved for future expansion. 18 PH1P. Servo drive line output to pitch servo pin 3. 19 PH1P. Servo drive line input from programmer 20 PH1N. Servo drive line output to pitch servo pin 2. 21 PH1N. Servo drive line input from programmer 22 PH2P. Servo drive line output to pitch servo pin 5. 23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line output to pitch servo pin 4.	7	LED Lamp Output. LED status lamp output	
10 Motor 2. Line 2 to existing trim servo motor. Will not control relays  11 Trim motor control 2. Line 2 to existing Trim motor control system.  12 Power. Connects to autopilot master or pitch servo power line from programmer.  13 Power. Connects to pitch servo pin 1.  14 Ground. Ground connection  15 Ground. Connect to aircraft ground.  16 No Connection. Reserved for future expansion.  17 No Connection. Reserved for future expansion.  18 PH1P. Servo drive line output to pitch servo pin 3.  19 PH1P. Servo drive line input from programmer  20 PH1N. Servo drive line output to pitch servo pin 2.  21 PH1N. Servo drive line input from programmer  22 PH2P. Servo drive line output to pitch servo pin 5.  23 PH2P. Servo drive line input from programmer  24 PH2N. Servo drive line input from programmer	8	Trim motor control 1. Line 1 to existing Trim motor control system.	
11 Trim motor control 2. Line 2 to existing Trim motor control system.  12 Power. Connects to autopilot master or pitch servo power line from programmer.  13 Power. Connects to pitch servo pin 1.  14 Ground. Ground connection  15 Ground. Connect to aircraft ground.  16 No Connection. Reserved for future expansion.  17 No Connection. Reserved for future expansion.  18 PH1P. Servo drive line output to pitch servo pin 3.  19 PH1P. Servo drive line input from programmer  20 PH1N. Servo drive line output to pitch servo pin 2.  21 PH1N. Servo drive line input from programmer  22 PH2P. Servo drive line output to pitch servo pin 5.  23 PH2P. Servo drive line input from programmer  24 PH2N. Servo drive line output to pitch servo pin 4.	9	Motor 1. Line 1 to existing trim servo motor. Will not control relays	Voltage in @max 5 amps
12 Power. Connects to autopilot master or pitch servo power line from programmer. 13 Power. Connects to pitch servo pin 1. 14 Ground. Ground connection 15 Ground. Connect to aircraft ground. 16 No Connection. Reserved for future expansion. 17 No Connection. Reserved for future expansion. 18 PH1P. Servo drive line output to pitch servo pin 3. 19 PH1P. Servo drive line input from programmer 20 PH1N. Servo drive line output to pitch servo pin 2. 21 PH1N. Servo drive line input from programmer 22 PH2P. Servo drive line output to pitch servo pin 5. 23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line output to pitch servo pin 4.	10	Motor 2. Line 2 to existing trim servo motor. Will not control relays	Voltage in @max 5 amps
Power. Connects to pitch servo pin 1.  Ground. Ground connection  Ground. Connect to aircraft ground.  No Connection. Reserved for future expansion.  No Connection. Reserved for future expansion.  PH1P. Servo drive line output to pitch servo pin 3.  PH1P. Servo drive line input from programmer  PH1N. Servo drive line output to pitch servo pin 2.  PH1N. Servo drive line input from programmer  PH2P. Servo drive line input from programmer  PH2P. Servo drive line output to pitch servo pin 5.  PH2P. Servo drive line input from programmer  PH2N. Servo drive line input from programmer	11	<b>Trim motor control 2</b> . Line 2 to existing Trim motor control system.	
14 Ground. Ground connection 15 Ground. Connect to aircraft ground. 16 No Connection. Reserved for future expansion. 17 No Connection. Reserved for future expansion. 18 PH1P. Servo drive line output to pitch servo pin 3. 19 PH1P. Servo drive line input from programmer 20 PH1N. Servo drive line output to pitch servo pin 2. 21 PH1N. Servo drive line input from programmer 22 PH2P. Servo drive line output to pitch servo pin 5. 23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line output to pitch servo pin 4.	12	<b>Power</b> . Connects to autopilot master or pitch servo power line from programmer.	11 – 35V input
15 Ground. Connect to aircraft ground. 16 No Connection. Reserved for future expansion. 17 No Connection. Reserved for future expansion. 18 PH1P. Servo drive line output to pitch servo pin 3. 19 PH1P. Servo drive line input from programmer 20 PH1N. Servo drive line output to pitch servo pin 2. 21 PH1N. Servo drive line input from programmer 22 PH2P. Servo drive line output to pitch servo pin 5. 23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line output to pitch servo pin 4.	13	<b>Power</b> . Connects to pitch servo pin 1.	
16 No Connection. Reserved for future expansion.  17 No Connection. Reserved for future expansion.  18 PH1P. Servo drive line output to pitch servo pin 3.  19 PH1P. Servo drive line input from programmer  20 PH1N. Servo drive line output to pitch servo pin 2.  21 PH1N. Servo drive line input from programmer  22 PH2P. Servo drive line output to pitch servo pin 5.  23 PH2P. Servo drive line input from programmer  24 PH2N. Servo drive line output to pitch servo pin 4.	14	Ground. Ground connection	
17 No Connection. Reserved for future expansion.  18 PH1P. Servo drive line output to pitch servo pin 3.  19 PH1P. Servo drive line input from programmer  20 PH1N. Servo drive line output to pitch servo pin 2.  21 PH1N. Servo drive line input from programmer  22 PH2P. Servo drive line output to pitch servo pin 5.  23 PH2P. Servo drive line input from programmer  24 PH2N. Servo drive line output to pitch servo pin 4.	15	Ground. Connect to aircraft ground.	Aircraft ground
PH1P. Servo drive line output to pitch servo pin 3.  PH1P. Servo drive line input from programmer  PH1N. Servo drive line output to pitch servo pin 2.  PH1N. Servo drive line input from programmer  PH2P. Servo drive line output to pitch servo pin 5.  PH2P. Servo drive line input from programmer  PH2P. Servo drive line output to pitch servo pin 4.	16	No Connection. Reserved for future expansion.	
19 PH1P. Servo drive line input from programmer 20 PH1N. Servo drive line output to pitch servo pin 2. 21 PH1N. Servo drive line input from programmer 22 PH2P. Servo drive line output to pitch servo pin 5. 23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line output to pitch servo pin 4.	17	No Connection. Reserved for future expansion.	
20 PH1N. Servo drive line output to pitch servo pin 2. 21 PH1N. Servo drive line input from programmer 22 PH2P. Servo drive line output to pitch servo pin 5. 23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line output to pitch servo pin 4.	18	PH1P. Servo drive line output to pitch servo pin 3.	
21 PH1N. Servo drive line input from programmer 22 PH2P. Servo drive line output to pitch servo pin 5. 23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line output to pitch servo pin 4.	19	PH1P. Servo drive line input from programmer	
22 PH2P. Servo drive line output to pitch servo pin 5. 23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line output to pitch servo pin 4.	20	PH1N. Servo drive line output to pitch servo pin 2.	_
23 PH2P. Servo drive line input from programmer 24 PH2N. Servo drive line output to pitch servo pin 4.	21	PH1N. Servo drive line input from programmer	
24 PH2N. Servo drive line output to pitch servo pin 4.	22	PH2P. Servo drive line output to pitch servo pin 5.	
	23	PH2P. Servo drive line input from programmer	
25 PH2N. Servo drive line input from programmer	24	PH2N. Servo drive line output to pitch servo pin 4.	
	25	PH2N. Servo drive line input from programmer	

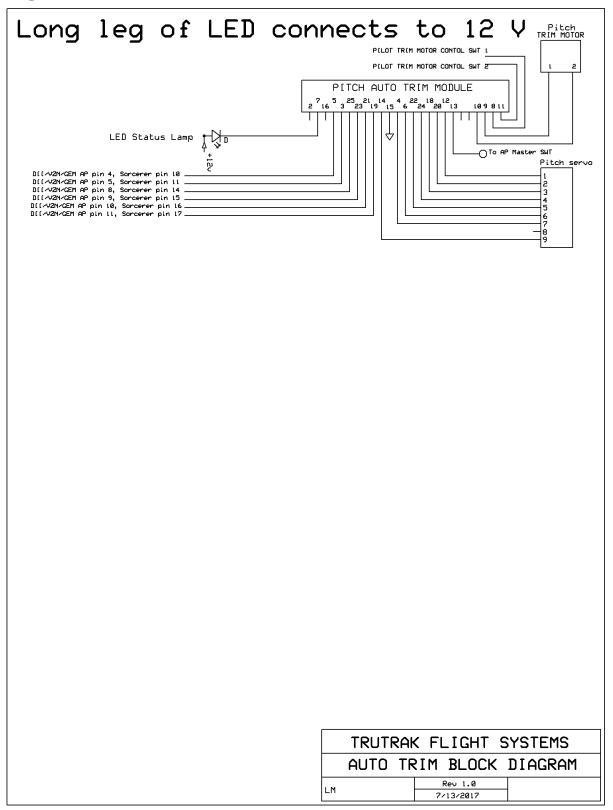
The Trim motor control from the pilot trim switch system will pass through the Auto Trim module when the Auto Pilot is **NOT** ENGAGED through a normally closed relay internally. Once the Auto Pilot is engaged the Auto Trim will open the relay and pulse the voltage that is applied to pin 12 / 13 and ground on pins 9 and 10 according to which direction the sense voltage from the Pitch Servo indicates to drive the trim motor. This control voltage and ground MUST be connected to the trim motor ONLY, it will not drive the trim relay system.

Total Weight	Voltage	Current	Trim Motor Output
.5 LB	11 V – 35 V	.25 A – 5 A	Input voltage / 5 Amps

# Retrofit to existing autopilot harness

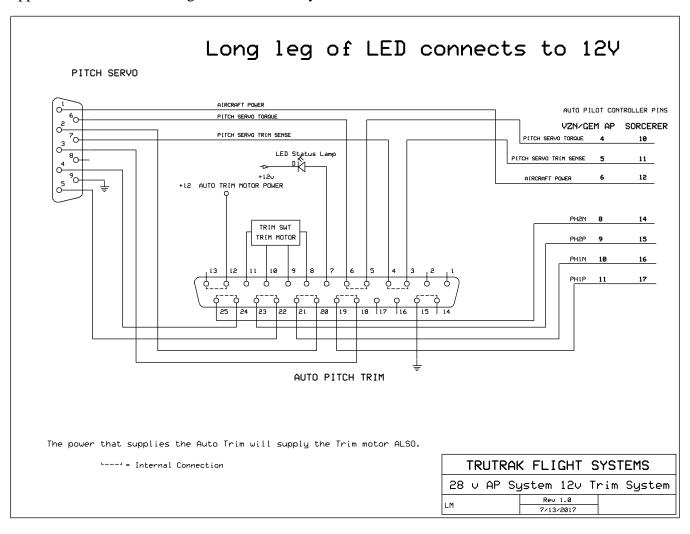


# Pitch Auto Trim Block Diagram



# 28 Volt Aircraft with 12 Volt Trim System

The Voltage that is supplied to the Auto Trim system will drive the trim motor with the same voltage when the Auto Trim system is in operation. The pitch servo and the auto trim system do NOT need to be supplied with the same voltage to work correctly.



# **Trouble Shooting**

Problem	Cause	Corrective Action
Trim motor will not move with	No aircraft voltage and/or	Correct power, ground, & torque
control pressure and manual	torque voltage to auto trim	wiring
trim control is functional	system	Engage auto pilot before testing
Trim motor will not move &	Trim sense voltage incorrect	Check 2.5 voltage at pin 3 or 4
manual trim control	with auto pilot engaged from	Voltage will increase or decrease
nonfunctional	pitch servo pin 7	with elevator pressure
Trim motor only runs in one	Auto trim motor control wires	Auto trim motor control wires
direction	not connected to trim motor	must be connected to the trim
	(relays).	motor only.
Trim bar briefly shows on	Auto trim controller speed too	Adjust trim speed via setup mode
autopilot display	slow	
Aircraft hunts up & down in	Auto trim controller speed too	Adjust trim speed via setup mode
pitch	high	

#### **Autotrim Installation**

- -The autotrim module can be mounted in any location, in any orientation. Generally it is installed near the pitch servo to minimize the wire length required for installation.
- -The LED status lamp can also be installed in any location desired. However, it must be visible for the setup procedure. The lamp will also indicate a failure so having it visible even during normal operation is beneficial. NOTE: The status lamp is NOT the LED on the side of the autotrim module itself.

## **Autotrim Ground Setup**

- -The autotrim ground setup is a simple process outlined below. The autotrim module pulses the trim motor instead of running it continuously. This prevents a rapid trim runaway in case the ground check was not completed properly. This ground setup process describes
  - 1) Power up the autopilot system. The LED status lamp should illuminate and stay lit for no more than five seconds. Once the lamp goes out, move to step 2.
  - 2) Engage the autopilot then press and hold one direction on the aircraft trim switch for 10 seconds. After 10 seconds, the status lamp will illuminate again and stay lit until the trim switch is released. Release the trim switch.
  - 3) The status lamp will now flash at the currently selected autotrim speed. Tapping one of the trim switches will adjust the speed slower, tapping the other switch will adjust it faster. Which is which depends on how it was wired, so it is not a constant. The speed of the lamp flash will adjust with each switch tap.
  - 4) Once the desired speed is set, simply do not press any trim switch for 10 seconds. The status lamp will stop flashing. This indicates the autotrim is no longer in setup mode and the desired trim speed has been saved.
  - 5) Setup is complete, disengage the autopilot and proceed to Autotrim Ground Checkout.

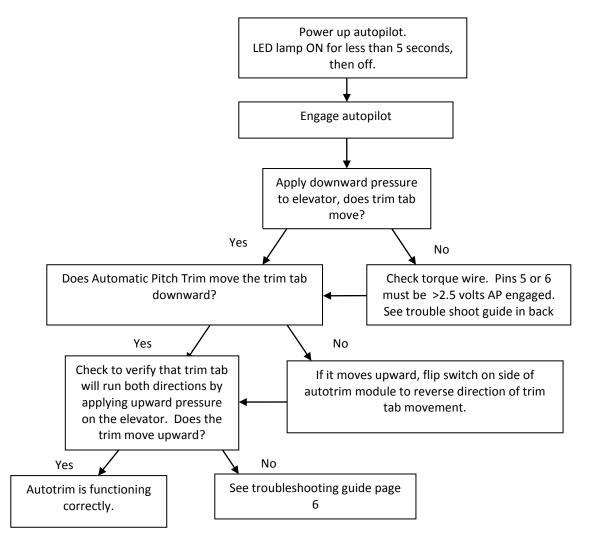
# Autotrim Ground Checkout (Do this before first flight with the autotrim)

- -Once installation and setup is complete, follow the below checkout procedure before flying with the autotrim for the first time. Following this procedure will prevent runaway trim conditions in flight.
  - 1) Verify that the manual trim control moves the trim tab in the appropriate direction.
  - 2) Center the elevator control then engage the autopilot.
  - 3) Gently apply pressure downward on the elevator, not from the stick but from the actual elevator.
  - 4) The trim tab should move downward as well. If the trim tab moves up, the autotrim direction is reversed so the switch on the side of the autotrim will need to be flipped. Once it is flipped, repeat steps 2-4.

# **Autotrim Status Lamp Indications**

- -The LED status lamp four different indications:
  - 1) <u>Steady On at Power Up</u>: This is the self-test of the autotrim module. This lasts no more than five seconds right as power is applied to the autopilot system.
  - 2) <u>Steady On during Ground Setup</u>: This indicates that the autotrim is entering setup mode so the autotrim speed can be adjusted.
  - 3) Flashing during Ground Setup: This flashing indicates the speed the autotrim will pulse the trim motor.
  - 4) <u>Steady On during Normal Flight Operation</u>: This indicates that the autotrim has detected an internal failure and will no longer function. Manual trim control will be restored if this occurs.

# Autotrim Checkout Flowchart (All tests performed at the elevator surface, not at the stick/yoke)



Note: If the above technique has been completed and the automatic trim module still does not run the trim, then first try applying more force to the system when holding the up elevator. If the pitch servo slips easily when holding the force, ensure that the pitch servo torque is set at the maximum value and hold as much force as possible without slipping the servo. If the torque is set at the maximum and the system still does not function, check automatic trim wiring. See trouble shoot guide in back

The switch in the first slot of the controller is to switch trim motor direction, see above diagram.

Two small slots are control indication LEDs, see above.

#### AUTO TRIM TROUBLE SHOOTING.

Does the Trim bar always show on the display with the Auto pilot programmer engaged? Does the Auto trim drive the trim motor with no pressure on the elevator?

#### **AUTO PILOT PROGRAMMER TEST**

Disconnect Auto trim harness 25 pin connector.

Insert test contact pin into pin location 3 (Trim Sense 2.5v no control surface load)

Insert test pin contact into pin location 15 (Ground)

Apply power to Autopilot system

**Engage Autopilot** 

Check for trim sense voltage at (pin 3) to ground (pin 15) should be 2.5 volts. This should be checking the voltage on the trim sense wire from the autopilot programmer.

If yes, continue Programmer test good.

Reconnect Auto trim harness

#### **AUTO TRIM MODULE TEST**

Disconnect Pitch servo harness 9 pin connector

Insert test contact pin into pin location 9 of servo connector (Ground)

Insert test contact pin into pin location 7 of servo connector (Trim Sense 2.5v)

Apply power to Auto pilot system

Engage Auto pilot

Check for trim sense voltage at (pin 7) to ground (pin 9) should be 2.5 volts. This should be checking the voltage on the trim sense wire from the Auto trim module.

If yes, continue Module test good.

Reconnect Pitch servo harness

#### SERVO TRIM SENSE TEST

Remove cover from Pitch servo 9 pin connector to access pin contacts.

Connect volt meter to aircraft ground. (confirm good ground by check for resistance to pin 9 of servo connector). Must be 0 ohms.

Connect volt meter to pin 7 of servo connector.

Apply power to autopilot system

Engage autopilot

Test voltage at pin 7 of servo, Must be @ 2.5 with **no load** on elevator. Apply pressure to elevator in both directions. Should be able to vary voltage up or down according to amount of force applied. Voltage range 0-5 volts.

If yes, continue Servo test good.

Reassemble connector shell.

#### TRIM MOTOR CONTROL TEST

Disconnect Auto Trim Module harness connector

Insert test contact pin into pins 8 & 11

Connect volt meter across pins, there should be aircraft voltage when trim system is actuated with pilot trim control. This voltage must be positive one direction and negative in the other. If a Relay Deck is installed in the Trim System it MUST be wire BEFORE the Auto Trim Module and Trim motor.

**Reconnect Auto Trim Module harness** 

Connect volt meter across Trim motor output pins 9 & 10

Engage auto pilot, there should be pulsing voltage when trim system is actuated with pressure on the elevator. This voltage must be positive one direction and negative in the other.

#### This concludes the trim system testing



### **RETURN MERCHANDISE POLICY AND PROCEDURE**

Under no circumstances should products be returned to TruTrak without first obtaining a Return of Merchandise Authorization number (RMA #) from TruTrak. An RMA # may be obtained by contacting us at 866-878-8725.

Products that do not have an RMA # will not be processed.

Please include some form of documentation stating the reason for the return and describing any symptoms, failure modes, suspected causes of damage, diagnostics performed, data collected, etc.

Product(s) should be packaged in their original shipping containers. In lieu of this, they should be very carefully packaged in containers suitable to protect them during transit. Note that damage caused during shipping will not be repaired under warranty.

The outside of the box must be clearly marked with the RMA # issued by TruTrak and the RMA # must also be noted on the return documents.

Products will be returned to the customer at no charge via FedEx Ground or UPS Ground. If customer requests expedited shipping (2<sup>nd</sup> Day or Overnight) they will be charged the shipping cost and must supply a credit card number.

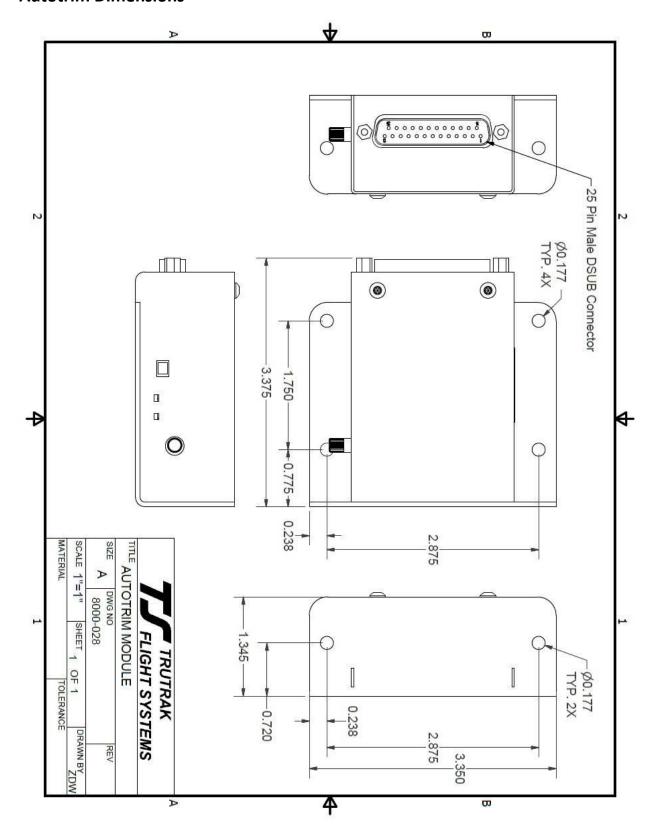
Send ALL return shipments to:

Trutrak Flight Systems, Inc. 1500 South Old Missouri Road Springdale, AR 72764 USA Attention: Returns Dept. RMA# \_\_\_\_\_

#### **Warranty On TruTrak Flight Systems Products**

We here at TruTrak Flight Systems know how important it is to feel as though the customer is purchasing a product that the manufacturer is going to stand behind. For this reason we want offer more than the basic one year warranty that is standard to this industry. The warranty on all TruTrak products will be three years from the date of purchase. Abuse and misuse of a product are not covered under this warranty. Modification to a product may void the warranty, as well as carry a penalty when upgrading to another product. This three year warranty will be for all products except the Pictorial Turn & Bank, which will continue to have a warranty of one year from the date of purchase.

## **Autotrim Dimensions**



This page intentionally left blank

This page intentionally left blank

This page intentionally left blank

TRUTRAK FLIGHT SYSTEMS

1500 S. Old Missouri Road Springdale, AR 72764

POSTAL SERVICE ADDRESS

P.O. Box 189 Springdale AR 72765-0189

Ph: 479-751-0250 Fax: 479-751-3397 Toll free: 866-TRUTRAK

866-(878-8725)

www.trutrakap.com