### **EFB24-SR Damper Actuator Technical Data Sheet**

Modulating, Spring Return, AC 24 V/DC, for DC 2...10 V or 4...20 mA Control Signal









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†Rated Impulse Voltage 800V, Type of action 1.AA, Control Pollution Degree 3

#### Torque min. 270 in-lb, for control of air dampers

### Application

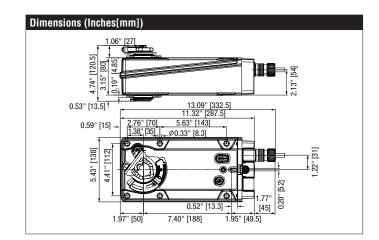
For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft up to 1.05" in diameter by means of its universal clamp. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft. The actuator operates in response to a DC 2…10 Vor, with the addition of a  $500\Omega$  resistor, a 4...20 mA control input from an electronic controller or positioner. A DC 2…10 V feedback signal is provided for position indication.

A common installation technique for control of multi-section dampers is to use the U5 position feedback of one actuator (Master) to control multiple actuators (Slaves). Belimo refers to this as Master/Slave control. The only requirement is that the actuators are installed on MECHANICALLY SEPARATE damper shafts.

#### Operation

The EF.24-SR series actuators provide true spring return operation for reliable failsafe application and positive close off on air tight dampers. The spring return system provides constant torque to the damper with, and without, power applied to the actuator. The EF.24-SR series provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The EF.24-SR uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact fail-safe position. The ASIC monitors and controls the brushless DC motor's rotation and provides a digital rotation sensing function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The EF.24-SR actuator is shipped at 5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.

Installation Note: Use flexible metal conduit. Push the UL listed conduit fitting device over the actuator's cable to butt against the enclosure. Screw in conduit connector. Jacket the actuator's input wiring with UL listed flexible conduit. Properly terminate the conduit in a suitable junction box.





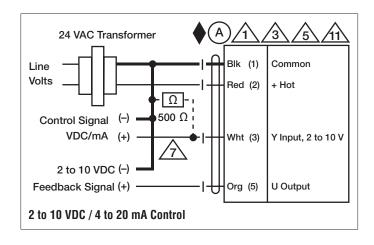
### **EFB24-SR Damper Actuator Technical Data Sheet**

Modulating, Spring Return, AC 24 V/DC, for DC 2...10 V or 4...20 mA Control Signal

AV8-25 Shaft extension  EF-P Anti-rotation bracket EFB(X)/GKB(X)/GMB(X).  IND-EFB End stop indicator  K9-2 Shaft clamp reversible  KG10A Ball joint  KH10 Damper crank arm  KH-EFB Actuator arm  SH10 Push rod for KG10A ball joint (36" L, 3/8" diameter).  TOOL-07 13 mm wrench.  ZG-100 Univ. right angle bracket 17"x11-1/8"x6" (HxWxbase).  ZG-120 Jackshaft mounting bracket.  ZG-DC1 Damper clip for damper blade, 3.5" width.  ZG-DC2 Damper clip for damper blade, 6" width.  ZG-FFB Mounting kit for linkage operation  ZG-JSA-3 1.05" diameter jackshaft adaptor (12" L).  IRM-100 Input rescaling module for modulating actuators.  P475 Shaft mount, non-Mercury aux. switch for 1" dia. shafts.  PS-100 Low voltage and control signal simulator.  PTA-250 Pulse width modulation interface for modulating actuators.  SGA24 Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR  SGF24 Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR  TF-CC US Cable conduit connector, 1/2".  ZG-R01 4 to 20 mA adaptor, 500Ω, 1/4 W resistor w 6" pigtail wires.  ZG-SGF Mounting plate for SGF.  ZG-X40 120 to 24 VAC, 40 VA transformer.	Accessories		
IND-EFB End stop indicator K9-2 Shaft clamp reversible KG10A Ball joint KH10 Damper crank arm KH-EFB Actuator arm SH10 Push rod for KG10A ball joint (36" L, 3/8" diameter). TOOL-07 13 mm wrench. ZG-100 Univ. right angle bracket 17"x11-1/8"x6" (HxWxbase). ZG-120 Jackshaft mounting bracket. ZG-DC1 Damper clip for damper blade, 3.5" width. ZG-DC2 Damper clip for damper blade, 6" width. ZG-BFB Mounting kit for linkage operation ZG-JSA-3 1.05" diameter jackshaft adaptor (12" L). IRM-100 Input rescaling module for modulating actuators. P475 Shaft mount, non-Mercury aux. switch for 1/2" dia. shafts. PS-100 Low voltage and control signal simulator. PTA-250 Pulse width modulation interface for modulating actuators. SGA24 Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR SGF24 Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR TF-CC US Cable conduit connector, 1/2". ZG-R01 4 to 20 mA adaptor, 500Ω, 1/4 W resistor w 6" pigtail wires. ZG-R02 50% voltage divider kit (resistors with wires).			
<ul> <li>K9-2 Shaft clamp reversible</li> <li>KG10A Ball joint</li> <li>KH10 Damper crank arm</li> <li>KH-EFB Actuator arm</li> <li>SH10 Push rod for KG10A ball joint (36" L, 3/8" diameter).</li> <li>TOOL-07 13 mm wrench.</li> <li>ZG-100 Univ. right angle bracket 17"x11-1/8"x6" (HxWxbase).</li> <li>ZG-120 Jackshaft mounting bracket.</li> <li>ZG-DC1 Damper clip for damper blade, 3.5" width.</li> <li>ZG-DC2 Damper clip for damper blade, 6" width.</li> <li>ZG-FFB Mounting kit for linkage operation</li> <li>ZG-JSA-3 1.05" diameter jackshaft adaptor (12" L).</li> <li>IRM-100 Input rescaling module for modulating actuators.</li> <li>P475 Shaft mount, non-Mercury aux. switch for 1/2" dia. shafts.</li> <li>P475-1 Shaft mount, non-Mercury aux. switch for 1" dia. shafts.</li> <li>PS-100 Low voltage and control signal simulator.</li> <li>PTA-250 Pulse width modulation interface for modulating actuators.</li> <li>SGA24 Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR</li> <li>SGF24 Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR</li> <li>TF-CC US Cable conduit connector, 1/2".</li> <li>ZG-R01 4 to 20 mA adaptor, 500Ω, 1/4 W resistor w 6" pigtail wires.</li> <li>ZG-R02 50% voltage divider kit (resistors with wires).</li> <li>ZG-SGF Mounting plate for SGF.</li> </ul>	EF-P	Anti-rotation bracket EFB(X)/GKB(X)/GMB(X).	
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<ul> <li>KH10 Damper crank arm</li> <li>KH-EFB Actuator arm</li> <li>SH10 Push rod for KG10A ball joint (36" L, 3/8" diameter).</li> <li>TOOL-07 13 mm wrench.</li> <li>ZG-100 Univ. right angle bracket 17"x11-1/8"x6" (HxWxbase).</li> <li>ZG-120 Jackshaft mounting bracket.</li> <li>ZG-DC1 Damper clip for damper blade, 3.5" width.</li> <li>ZG-DC2 Damper clip for damper blade, 6" width.</li> <li>ZG-EFB Mounting kit for linkage operation</li> <li>ZG-JSA-3 1.05" diameter jackshaft adaptor (12" L).</li> <li>IRM-100 Input rescaling module for modulating actuators.</li> <li>P475 Shaft mount, non-Mercury aux. switch for 1/2" dia. shafts.</li> <li>PS-100 Low voltage and control signal simulator.</li> <li>PTA-250 Pulse width modulation interface for modulating actuators.</li> <li>SGA24 Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR</li> <li>SGF24 Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR</li> <li>TF-CC US Cable conduit connector, 1/2".</li> <li>ZG-R01 4 to 20 mA adaptor, 500Ω, 1/4 W resistor w 6" pigtail wires.</li> <li>ZG-R02 50% voltage divider kit (resistors with wires).</li> <li>ZG-SGF Mounting plate for SGF.</li> </ul>	K9-2	Shaft clamp reversible	
<ul> <li>KH-EFB Actuator arm</li> <li>SH10 Push rod for KG10A ball joint (36" L, 3/8" diameter).</li> <li>TOOL-07 13 mm wrench.</li> <li>ZG-100 Univ. right angle bracket 17"x11-1/8"x6" (HxWxbase).</li> <li>ZG-120 Jackshaft mounting bracket.</li> <li>ZG-DC1 Damper clip for damper blade, 3.5" width.</li> <li>ZG-DC2 Damper clip for damper blade, 6" width.</li> <li>ZG-EFB Mounting kit for linkage operation</li> <li>ZG-JSA-3 1.05" diameter jackshaft adaptor (12" L).</li> <li>IRM-100 Input rescaling module for modulating actuators.</li> <li>P475 Shaft mount, non-Mercury aux. switch for 1/2" dia. shafts.</li> <li>P475-1 Shaft mount, non-Mercury aux. switch for 1" dia. shafts.</li> <li>PS-100 Low voltage and control signal simulator.</li> <li>PTA-250 Pulse width modulation interface for modulating actuators.</li> <li>SGA24 Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR</li> <li>SGF24 Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR</li> <li>TF-CC US Cable conduit connector, 1/2".</li> <li>ZG-R01 4 to 20 mA adaptor, 500Ω, 1/4 W resistor w 6" pigtail wires.</li> <li>ZG-R02 50% voltage divider kit (resistors with wires).</li> <li>ZG-SGF Mounting plate for SGF.</li> </ul>	KG10A	Ball joint	
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ZG-DC2       Damper clip for damper blade, 6" width.         ZG-EFB       Mounting kit for linkage operation         ZG-JSA-3       1.05" diameter jackshaft adaptor (12" L).         IRM-100       Input rescaling module for modulating actuators.         P475       Shaft mount, non-Mercury aux. switch for 1/2" dia. shafts.         P475-1       Shaft mount, non-Mercury aux. switch for 1" dia. shafts.         PS-100       Low voltage and control signal simulator.         PTA-250       Pulse width modulation interface for modulating actuators.         SGA24       Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR         SGF24       Positioners suitable for use with the modulating damper actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR         TF-CC US       Cable conduit connector, 1/2".         ZG-R01       4 to 20 mA adaptor, 500Ω, 1/4 W resistor w 6" pigtail wires.         ZG-R02       50% voltage divider kit (resistors with wires).         ZG-SGF       Mounting plate for SGF.	ZG-120	Jackshaft mounting bracket.	
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$\begin{array}{c} \text{SGA24} & \text{Positioners suitable for use with the modulating damper actuators} \\ \text{LMA-SR, NMA-SR, SMA-SR and GMA-SR} \\ \text{SGF24} & \text{Positioners suitable for use with the modulating damper actuators} \\ \text{LMA-SR, NMA-SR, SMA-SR and GMA-SR} \\ \text{TF-CC US} & \text{Cable conduit connector, 1/2".} \\ \text{ZG-R01} & \text{4 to 20 mA adaptor, } 500\Omega, \text{1/4 W resistor w 6" pigtail wires.} \\ \text{ZG-R02} & \text{50\% voltage divider kit (resistors with wires).} \\ \text{ZG-SGF} & \text{Mounting plate for SGF.} \\ \end{array}$	PS-100	Low voltage and control signal simulator.	
$ \begin{array}{c} LMA\text{-}SR, NMA\text{-}SR, SMA\text{-}SR \ and \ GMA\text{-}SR \\ \hline SGF24 & Positioners suitable for use with the modulating damper actuators \\ LMA\text{-}SR, NMA\text{-}SR, SMA\text{-}SR \ and \ GMA\text{-}SR \\ \hline TF\text{-}CC \ US & Cable \ conduit \ connector, \ 1/2". \\ \hline ZG\text{-}R01 & 4 \ to \ 20 \ mA \ adaptor, \ 500\Omega, \ 1/4 \ W \ resistor \ w \ 6" \ pigtail \ wires. \\ \hline ZG\text{-}R02 & 50\% \ voltage \ divider \ kit \ (resistors \ with \ wires). \\ \hline ZG\text{-}SGF & Mounting \ plate \ for \ SGF. \\ \hline \end{array} $	PTA-250	Pulse width modulation interface for modulating actuators.	
	SGA24		
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ZG-R02 50% voltage divider kit (resistors with wires). ZG-SGF Mounting plate for SGF.	TF-CC US	Cable conduit connector, 1/2".	
ZG-SGF Mounting plate for SGF.	ZG-R01	4 to 20 mA adaptor, 500Ω, 1/4 W resistor w 6" pigtail wires.	
	ZG-R02	50% voltage divider kit (resistors with wires).	
ZG-X40 120 to 24 VAC, 40 VA transformer.	ZG-SGF	Mounting plate for SGF.	
	ZG-X40	120 to 24 VAC, 40 VA transformer.	

# Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a  $500\Omega$  resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.



## **EFB24-SR Damper Actuator Technical Data Sheet**



Modulating, Spring Return, AC 24 V/DC, for DC 2...10 V or 4...20 mA Control Signal

#### Wiring Diagrams



### WARNING! LIVE ELECTRICAL COMPONENTS!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.



Meets cULus requirements without the need of an electrical ground connection.



Actuators with appliance cables are numbered.



Provide overload protection and disconnect as required.



Actuators may also be powered by 24 VDC.



Only connect common to negative (-) leg of control circuits.



A 500  $\Omega$  resistor (ZG-R01) converts the 4 to 20 mA control signal to 2



Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.