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Technical Data

| Power Supply | 24 VAC, $\pm 20 \%, 50 / 60 \mathrm{~Hz}, 24 \mathrm{VDC}, \pm 10 \%$ |
| :---: | :---: |
| Power consumption in operation | 3.5 W |
| Power consumption in rest position | 1.3 W |
| Transformer sizing | 6 VA (class 2 power source) |
| Shaft Diameter | $1 / 2 \ldots 1.05$ " round, centers on $1 / 2^{\prime \prime}$ and $3 / 4$ " with insert, 1.05 " without insert |
| Electrical Connection | 18 GA plenum cable with $1 / 2^{\prime \prime}$ conduit connector, degree of protection NEMA 2 / IP54, $3 \mathrm{ft}[1 \mathrm{~m}] 10 \mathrm{ft}[3 \mathrm{~m}]$ and $16 \mathrm{ft}[5 \mathrm{~m}$ ] |
| Overload Protection | electronic throughout 0...95 ${ }^{\circ}$ rotation |
| Operating Range | $0 . . .135 \Omega$, Honeywell Electronic Series 90, input $0 . . .135 \Omega$ |
| Position Feedback | 2... 10 V , Max. 0.5 mA |
| Angle of rotation | Max. $95^{\circ}$, adjustable with mechanical stop |
| Torque motor | 180 in-lb [20 Nm] |
| Direction of motion motor | selectable with switch 0/1 |
| Position indication | Mechanically, 30... 65 mm stroke |
| Manual override | external push button |
| Running Time (Motor) | default 150 s , variable 90... 350 s |
| Ambient humidity | max. 95\% r.H., non-condensing |
| Ambient temperature | $-22 . . .122^{\circ} \mathrm{F}$ [-30...50$\left.{ }^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40 \ldots 176^{\circ} \mathrm{F}$ [-40...80${ }^{\circ} \mathrm{C}$ ] |
| Degree of Protection | IP54, NEMA 2, UL Enclosure Type 2 |
| Housing material | UL94-5VA |
| Agency Listing | cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2014/30/EU and 2014/35/EU |
| Noise level, motor | $45 \mathrm{~dB}(\mathrm{~A})$ |
| Servicing | maintenance-free |
| Quality Standard | ISO 9001 |
| Weight | 1.5 lb [0.68 kg] |

$\dagger$ Rated Impulse Voltage 800V, Type action 1, Control Pollution Degree 3.

Torque min. 180 in-lb, for control of damper surfaces up to 45 sq . ft.

## Application

For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.

The actuator is mounted directly to a damper shaft up to 1.05 " in diameter by means of its universal clamp. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft.

The default parameters for 0 to $135 \Omega$ input applications of the ...MFT95 actuator are assigned during manufacturing. If necessary, custom versions of the actuators can be ordered. The parameters can be changed by two means: pre-set and custom configurations from Belimo or on-site configurations using the Belimo PC-Tool software.

## Operation

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The actuator provides $95^{\circ}$ of rotation and a visual indicator indicates position of the actuator. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.

The actuators use a brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.

Add-on auxiliary switches or feedback potentiometers are easily fastened directly onto the actuator body for signaling and switching functions.

For low ambient temperatures, the optional supplemental $(-H)$ Heater add-on is available.


| KH8 | Damper crank arm |
| :---: | :---: |
| 4e6essories |  |
| KG8 | Ball joint |
| KG10A | Ball joint |
| SH8 | Push rod for KG6 \& KG8 ball joints ( 36 " L, 5/16" diameter). |
| SH10 | Push rod for KG10A ball joint (36" L, 3/8" diameter). |
| ZG-DC1 | Damper clip for damper blade, 3.5 " width. |
| ZG-DC2 | Damper clip for damper blade, 6 " width. |
| ZS-100 | Weather shield - galvaneal $13 \times 8 \times 6$ " ( $\mathrm{xWW} \times \mathrm{D}$ ) . |
| ZS-101 | Base plate for ZS-100. |
| ZS-150 | Weather shield - PC w/ foam seal 16x8-3/8x4" (LxWxD). |
| AV8-25 | Shaft extension |
| TF-P | Anti-rotation bracket TF/NKQ/AM/NM/LM. |
| ZG-100 | Univ. right angle bracket 17"x11-1/8"x6" (HxWxbase). |
| ZG-101 | Univ. right angle bracket 13x11x7-7/16" (HxWxbase). |
| TOOL-06 | 8 mm and 10 mm wrench. |
| Z-SPA | Adapter |
| PS-100 | Low voltage and control signal simulator. |
| AH-25 | Actuator arm |
| K-AM25 | Standard NKQ/AM/NM clamp (1/2" to 1.05"). |
| K-SA | Shaft clamp reversible |
| ZG-109 | Right angle bracket for ZS-260. |
| ZG-110 | Stand-off bracket for ZS-260. |
| ZG-112 | LF right angle bracket 4-1/2x5-1/2x2-1/2" (HxWxD). |
| ZG-JSA-1 | 1" diameter jackshaft adaptor (11" L). |
| ZG-JSA-2 | 1-5/16" diameter jackshaft adaptor ( $12^{\prime \prime} \mathrm{L}$ ). |
| ZG-JSA-3 | 1.05 " diameter jackshaft adaptor ( $12^{\prime \prime} \mathrm{L}$ ). |
| ZG-NMA | Mounting kit for linkage operation |
| ZS-260 | Explosion proof housing. |
| ZS-300 | NEMA 4X, 304 stainless steel enclosure. |
| ZS-300-5 | NEMA 4X, 316L stainless steel enclosure. |
| ZS-300-C1 | 1/2" shaft adaptor, standard wtih ZS-300(-5). |
| ZS-300-C2 | 3/4" shaft adaptor for ZS-300(-5). |
| ZS-300-C3 | 1" shaft adaptor for ZS-300(-5). |
| Z-SMA | Base plate extension |
| UK24LON | Gateway MP to LonWorks |
| UK24BAC | Gateway MP to BACnet MS/TP |
| UK24MOD | Gateway MP to Modbus RTU |
| ZTH US | Handheld programming tool w/ ZK1-GEN, ZK2-GEN, ZK6-GEN. |
| S1A | Auxiliary switch for damper actuators and rotary actuators |
| S2A | Auxiliary switch for damper actuators and rotary actuators |
| P475 | Shaft mount, non-Mercury aux. switch for $1 / 2^{\prime \prime}$ dia. shafts. |
| P475-1 | Shaft mount, non-Mercury aux. switch for 1" dia. shafts. |
| P140A GR | Feedback potentiometer for damper actuators and rotary actuators |
| P500A GR | Feedback potentiometer for damper actuators and rotary actuators |
| P1000A GR | Feedback potentiometer for damper actuators and rotary actuators |
| P2800A GR | Feedback potentiometer for damper actuators and rotary actuators |
| P5000A GR | Feedback potentiometer for damper actuators and rotary actuators |
| P10000A GR | Feedback potentiometer for damper actuators and rotary actuators |
| NSV24 US | Battery back-up module for non-spring return actuators. |
| NSV-BAT | 12V 1.2AH battery (two required for NSV24 US). |
| ZG-X40 | 120 to 24 VAC, 40 VA transformer. |
| TF-CC US | Cable conduit connector, 1/2". |
| 43442-00001 | Cable gland (for NEMA 4 models). |
| ZK1-GEN | Connection cable |
| ZK2-GEN | Connection cable |



Low Limit Control


## High Limit Control



Multiple Actuators

## Typical Specification

Proportional control damper actuators shall be electronic direct-coupled type, which require no crank arm and linkage and be capable of direct mounting to a shaft up to $3 / 4^{\text {" diameter. Actuators must provide proportional damper control }}$ in response to a 2 to 10 VDC or, with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. If required, actuator will be provided with screw terminal strip for electrical connections (AMX24-SR-T and NMX24-SR-T). Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication. Actuators shall be cULus listed, have a 5 -year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Wiring Diagrams

Provide overload protection and disconnect as required.
Actuators may also be powered by 24 VIC.
Actuators and controller must have separate transformers.
Consult controller instruction data for more detailed information.
Resistor value depends on the type of controller and the number of actuators. No resistor is used for one actuator. Honeywell $®$ resistor kits may also be used.

To reverse control rotation, use the reversing switch.
Actuators may be controlled in parallel. Current draw and input impedance must be observed.

