# Power amplifier





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The amplifier is ready for use as supplied, but it must be properly installed by a qualified person using the machine designer's wiring diagram

#### 1. Safety notes

- The amplifiers described in these installation and start-up guidelines are designed exclusively for electrical control of the corresponding Eaton proportional valves specified.
- Start-up, maintenance and repair operations may only be performed by qualified personnel with knowledge of electrics/electronics.
- 3. The 24V DC supply voltage must meet the guidelines for safe low voltages according to VDE 0551/EN 607242/IEC 742.

#### 2. Pre-installation checks

- 1. Check for any damage received in transit.
- 2. Ensure that the model code on this amplifier is the correct one for the application.
- 3. Check that the 24V DC power supply is within the specification.
- 4. Ensure that no adjustments are made before the amplifier is installed and powered up.
- Ensure that the power is switched OFF before installing it into its edge connector. (Never insert or remove the amplifier while the electronic system is live.)

# 3. Installation requirements according to European EMC regulations

- Use screened cables for the wires between amplifier and solenoid. The screen must be connected to protective ground at the amplifier end.
- 2. The amplifier board must be mounted in a metal housing which is connected to an efficient ground point.
- The wiring for the LVDT(if fitted) must be screened and grounded at both ends to efficient ground points.
   Alternatively, double screened cable can be used for the LVDT with the two screens grounded at opposite ends.

#### Table 1.

#### ЕМС

LINC		
Radiated Emission	CISPR 11:2015	Class A: 30MHz to 1 GHz
Radiated Immunity	IEC 61000-4-3:2010	Class A: 80MHz to 2.7 GHz: 10V/m
Conducted Emissions	CISPR 11:2015	Class A: 150KHz to 30MHz
Conducted immunity	IEC 61000-4-6:2008 DC Port: 3Vrms Signal Port: 3Vrms	Class A: 150kHz to 80 MHz
Electric fast Transient immunity	IEC61000-4-4:2012 DC Port: ±2kV Signal Port: ±1kV	Class B
Surge Immunity Test	IEC 61000-4-5:2014 DC Port: ±1kV Signal Port: ±0.5kV	Class B
Electrostatic discharge (ESD)	IEC 61000-4-2:2008 Air: ±8kV Contact: ±4kV	Class B

### 🛕 WARNING

#### Electromagnetic Compatibility (EMC)

It is necessary to ensure that the unit is wired up in accordance with the connection arrangements shown in this catalog. For effective protection, the user's electrical cabinet, the valve subplate or manifold and the cable screens should be connected to efficient earth (ground) points. In all cases, both valve and cable should be kept as far away as possible from any source of electromagnetic radiation such as cables carrying heavy current, relays and certain kinds of portable radio transmitters, etc. Difficult environments could mean that extra screening may be necessary to avoid the interference.

### **General description**

The power amplifier has five voltage inputs (one inverting) and a current input 0-20 mA. Adjustments for set zero point or deadband compensation and for gain allow the amplifier to be easily tuned to the proportional control valve. The ramp function generator can be switched on and off using the "ramp enable" control.

Monitor points on the front panel allow measurement of the conditioned command signal, and either of spool position LVDT signal or (for valves without LVDT) of solenoid current. ("Conditioned command signal" is the input signal modified according to settings of set zero point or deadband compensation, gain and ramp functions.)

#### **Features**

- User-friendly front panel with all the necessary adjustments, LEDs and monitor points
- · Electronic overload protection with automatic reset
- Pulse width modulation for high efficiency
- Can be equipped with plug-in modules for special functions
- Switchable ramp function generator for controlling rates of increase and decrease of output
- 24V DC power supply
- Either current or voltage input signals
- Standard input and output signals
- CE Electromagnetic compatibility.- 2014/30/EU
- RoHS Compatibility-DIRECTIVE 2011/65/EU

# CE

This product has been designed and tested to meet specific standards outlined in the European Electromagnetic Compatibility Directive (EMC) 2014/30/EU which repealed Directive 89/336/EEC, amended by Directives 91/263/EEC, 92/31/EEC, 93/68/EEC and 93/97/EEC. For instructions on installation requirements to achieve effective protection levels, see the Installation Wiring Practices for Vickers Electronic Products leaflet 2468. Wiring practices relevant to this Directive are indicated by A Electromagnetic Compatibility (EMC).

# The following power amplifier models are covered in this catalog

#### Table 2.

Power amplifier	For proportional valve
EEA-PAM-513-A-33	KCG-3, 1* series KCG-6/8, 1* series KX(C)G-6/8, 1* series
EEA-PAM-523-A-33	KTG4V-3H*, 6* series KDG4V-3H*, 6* series KDG5V-5/7/8, 1* series
EEA-PAM-525-A-33	KTG4V-5H*, 3* series KDG4V-5H*, 3* series
EEA-PAM-533-A-33	KFTG4V-3, 2* series KFDG4V-3, 2* series
EEA-PAM-535-A-33	KFTG4V-5, 2* series KFDG4V-5, 2* series
EEA-PAM-541-A-33	KHDG5V-5/7/8, 3* series With zero-lapped main spool
EEA-PAM-553-A-33	KSDG4V-3, 1* series
EEA-PAM-561-A-33	KFDG5V-5, 3* series KFDG5V-7, 1* series
EEA-PAM-568-A-33	KFDG5V-8, 1* series
EEA-PAM-571-A-33	CVU-**-EFP1-3*
EEA-PAM-581-A-33	KHDG5V-5/7/8, 3* series

### **Front panel**

#### Model

#### 523, 525, 533, 535, 561, 568 and 581





541, 553 OO24V 15V 00  $\bigcirc$ \_\_\_\_ μ Potentiometer Ø [20] Adjust valve zero  $\bigcirc \bigcirc$ 

▲ Ø 2 mm (0.0787 ″ dia.) sockets

### **Electrical block diagram**





Note: This is a typical diagram and all the features depicted may not be applicable to all amplifiers, (e.g. LVDTs and dither)

#### Table 3.

Command signals an	d outputs		All models except 553 and 571	553	571	
Non-inverting voltage b6/8/10 or z8	Non-inverting current z6	Inverting voltage z10	Secondary pins	Output		
-			bz4			
	-		bz4	D to A	P to B	Value algood
		+	bz4	— P 10 A		valve closed
-		+	N/A			
+			bz4			
	+		bz4	D to D	D to A	A to D and D to A
		-	bz4	— P to B P to A		A LO D ANU D LO A
+		-	N/A			

# **Operating data**

#### Table 3. continued

Power supply:			
Nominal	24V DC x 50W		
Vmin Vmax.	20 - 40V (incl. pkto-pk. ripple 10% max.)		
Amplifier shut-down	<18V DC		
Protection	Reverse-polarity		
Signal sources:			
	± 15V x 50 mA max. (pkto-pk. ripple 50 mV)		
	± 10V (1%) x 5 mA max. (pkto-pk. ripple 20 mV)		
Temperature drift	< 1 mV/°C (<0,5 mV/ °F) 0-50°C (32 - 122°F)		
	All outputs short-circuit protected		
Command inputs			
Voltage:			
Direct-V	o b8, b6, z8 & b10		
Inverting-V	o z10		
Umin Umax.	0 ± 10V		
	47 kΩ		
Current z6:			
Range I	0 + 20 mΔ		
	1000		
Power drive	= PWM short-circuit protected		
Max. solenoid current	See table on next page		
Current at zero (OV command signal on MP1)	See table on next page		
Dither	Factory-set		
Deadband compensation	See table on next page		
Gain	See table on next page		
Ramp-time adjustment:			
Factory setting	Min. ≈ 50 ms		
min - max	50 ms - 5s		
	50 ms - 5s		
	Automatic reset		
Enabled 721	>9.8 - 0\/</p		
	Open circuit or $< 1.5$ V		
Kamps:	> 0.0 - 401/		
Pirabled – 624			
	Upen circuit or $\leq$ 4.5V		
	22 kΩ		
Command signal monitor point:			
Front nonal MP1 & h19	Monitor signal after deadband compensation (minimum setting), gain and ramps:		
	10  kO short-circuit protected		
Output Monitor Point (Main) 🖄 :			
Front-panel ) <sup>MP2</sup> &o z18	513/523/525 (without LVDT): 1 V/A		
	Other types (with LVDT): $\pm$ 10V at full stroke		
	10 k $\Omega$ short-circuit protected		

#### Table 3. continued

4.	
Output monitor point (Pilot) 💢 :	
o z20	541/581 (with LVDT): ± 10V at full stroke
Output – Z	10 k $\Omega$ short-circuit protected
Ramp-active indicator ————————————————————————————————————	
	Output > + 10V
	Output < - 10V
	Output = 0V (± 2V ripple)
Output – Z –	10 kΩ
Drive signal zero indicator ————————————————————————————————————	
Drive signal at null (within deadband limits)	Output = Supply minus 1.5V; I = 50 mA max.
Drive active	$Output = 0 \pm 2V$
Output resistance – Z	50 Ω
Alarm outputo z20	
Set alarm Signal	Enable amplifier (on pin z24) when switching power on HIGH when alarm is activated: Output = Supply volts minus 2 volts; I = 50 mA max.
	LOW when solenoid overload has occurred (maintained until reset): Output = 0 to +/-2 volts; Output impedance = 50
Reset after failure	Disable and re-enable on pin z24
Ambient temperature range	0 - 50 °C (32 - 122 °F) full specification
Edge connectors DIN 41612	On board F48 Male Mating connector F32 Female (rows b and z only) for Type-A only Mating connector F48 Female compatible with all card Types A through F
$\Delta \square \Delta$	330g (0.15 lb)
Cardholder F32	02-104807 compatible with card Type-A only
F48	02-104808 compatible with all card Types A through F

#### Table 4.

Model	513	523 525	533	535	541	553	561 568	571	581
Max. solenoid current	1.6A	1.6A	2.7A	2.7A	3.2A	3.2A	1.8A	2.9A	3.2A
Amplifier input current at OV command signal (MP1)	0.3A	0.3A	0.3A	0.3A	1.7A	1.7A	1.4A	1.1A	1.7A
Deadband compensation									
Factory setting (% of max. spool stroke)	-	25%	15%	10%	_	_	10%	10%	10%
Adjustment per direction (% of max. spool stroke from centered position)	-	0 - 50%	0 - 50%	0 - 50%	-	-	0 - 50%	0 - 50%	0 - 50%
Gain									
Factory setting	10%/V	10%/V	10%/V	10%/V	10%/V	10%/V	10%/V	10%/V	10%/V
Adjustment per direction	2.5 - 10%/V	2.5 - 10%/V	2.5 - 10%/V	2.5 - 10%/V	-	-	2.5 - 10%/V	2.5 - 10%/V	2.5 - 10%/V
Zero adjustment (% of max. spool stroke)	0 - 50%	-	-	-	+/- 25%	+/-25%	-	-	-

## Wiring connections

### Amplifier models to Typical Valve Type





Amplifier model: 553



#### Amplifier models: 541, 581



 $\perp$  Customer s protective ground connection.

Amplifier models: 533, 535



Amplifier models: 561, 568



#### Amplifier model: 571



Note: If valves are fitted with the "B" type LVDT, the screen will be grounded at the valve end by the shell of the connector.

### Typical input connection circuitry 72 b2 z6 b6 b8 -<u>\_\_\_\_\_</u>b10\_\_ EEA-PAM- 513-A-33 z8 523/525 533/535 z10 561/568 571 b4 581 <u>z4</u> Customer 's protective ground connection.

Valve solenoid connections

#### LVDT connections



# A WARNING

#### **Electromagnetic Compatibility (EMC)**

- 1. Screened cables should be used for the command signals, the solenoid connections and the LVDT connections.
- 2. Particular attention should be paid to the grounding of the screens as shown in the diagrams.
- 3. The screen on the LVDT cable needs to be grounded at both ends. An alternative method to prevent creating earth loops is to use double screened cable with each screen grounded at opposite ends.
- 4. The amplifiers should be mounted in a metal enclosure which is connected to an efficient ground point.

### Installation dimensions in mm (inches)

Plug-in Unit of 3U Height (IEC 297)





### Dedicated installation requirement for Type A card

### Wiring sizes

Use 3-core screened cable  $\geq$  0.5 mm² (20 AWG) per wire for signal and LVDT wiring.

For wiring runs between amplifier and solenoid up to 50 meters (164 ft): EEA-PAM-523 and EEA-PAM-525 must have a wire cross-section of 1.5 mm<sup>2</sup> (15 AWG); for all other models use wire of  $\geq$  1 mm<sup>2</sup> (18 AWG) cross-section.

### **Front panel controls**

Any of the following controls may be on the front panel (depending on the amplifier type) and can be adjusted as described.

#### 1. Set zero:

On amplifier types 513, 541 and 553, this sets the electrical null of the valve.

#### 2. Deadband compensation:

The two potentiometers are factory set at 10% (20% for 523 models) of valve maximum spool stroke. The setting may be optimized for your application as follows:

Apply a small command signal (e.g. 250 mV) and check for hydraulic response from the valve. (For 2-stage valves the correct pilot pressure must be available to obtain response from the main-stage spool.) If this does not occur then adjust the applicable potentiometer clockwise until it does. Alternatively, to reduce valve hydraulic response turn the potentiometer counter-clockwise.

#### 3. Gain

The gain potentiometers are factory set for 100% output at 10V command signal. Turning the gain potentiometers clockwise increases the gain; turning counter-clockwise reduces gain.

#### 4. Ramps

Factory setting of ramp potentiometers: all amplifiers are set to minimum ramp time.

Turning the controls clockwise increases ramp time; turning counter-clockwise decreases ramp time. There are separate controls for accelerating and for decelerating ramps.

#### 5. Front panel indicator lights (LEDs)

Amplifiers may have some, or all, of the following LEDs, depending on amplifier type:

#### Table 5.

Panel symbol	Function indicated	Color	Normal working state
24V	Power supply ON	Green	ON
15V	Internal supply ON	Green	ON
Б	Output enabled	Yellow	ON
¢	Overload detection	Red	OFF
	LVDT failure	Red	OFF
цЊъ	Ramps enabled	Yellow	ON
¢	Current to solenoid (Light intensity varies with solenoid current)	Yellow	ON

#### 6. Fault diagnosis

# If the amplifier fails to work the following checks should be made:

- 1. Check that all wiring is correct to the machine designer's instructions.
- 2. Check that there is a 24V supply and that the 24V LED is ON.
- Check that the 15V internal voltage LED is ON (if 24V LED is ON and this 15V LED is OFF then the amplifier should be replaced.)
- 4. Check that the amplifier is enabled and the LED is ON.
- 5. Check that the LVDT failure LED is OFF. (If ON check the LVDT wiring and connections.)

To check correct function of the amplifier, disconnect all valve connections and link z22 ( +15V) with a 1.2 kQ resistor to b14. (To check the double feedback amplifiers EEA-PAM-581/541, make an additional link between z22 (+15V) and z14 with a 1.2 kQ resistor.)

After installation of resistor link(s), the LVDT failure LED should be OFF. If not, replace the amplifier (caution: a link without resistor damages the amplifier).

- 6. Check that the overload LED is OFF. (If ON, check the wiring to the solenoids and the solenoid resistance by an ohmmeter. Compare the measured value with the catalog data.)
- Check that an appropriate valve driving signal is available (monitor point at the front panel).
   ± 10V at monitor point represents ± 100% output
- 8. The solenoid current (non-feedback valves) or the LVDT signal (feedback valves) can be measured at the front panel monitor point.
  - Solenoid current can be measured as a voltage signal (1 volt per amp)
  - ± 10V LVDT signal at monitor point represents
     ± 100% spool stroke

## Valve connection table

This table shows how the different valves have to be connected to the associated amplifier.

#### Table 6.

Value type	Amplifier type	Solenoid with LVDT or hydraulic A	Solenoid without LVDT or hydraulic B
KCG-3/6/8 and KX(C)G-6/8	EEA-PAM-513-A-33	b26/b28	-
K*G4V-3 and KDG5V-5/7/8	EEA-PAM-523-A-33	b26/b28	z26/z28
K*G4V-5	EEA-PAM-525-A-33	b26/b28	z26/z28
KF*G4V-3	EEA-PAM-533-A-33	b26/b28	z26/z28
KF*G4V-5	EEA-PAM-535-A-33	b26/b28	z26/z28
KHDG5V-5/7/8 zero lapped	EEA-PAM-541-A-33	-	z26/z28
KSDG4V-3	EEA-PAM-553-A-33	-	z26/z28
KFDG5V-5/7	EEA-PAM-561-A-33	-	z26/z28
KFDG5V-8	EEA-PAM-568-A-33	-	z26/z28
CVU-**-EFP1	EEA-PAM-571-A-33	-	z26/z28
KHDG5V-5/7/8	EEA-PAM-581-A-33	-	z26/z28

#### Table 7.

	Pilot sta	ge LVDT			Main sta	ige LVDT		
Valve type	Pin 1	2	3	4	Pin 1	2	3	4
KCG-3/6/8 and KX(C)G-6/8	-	-	-		-	-	-	
K*G4V-3 and KDG5V-5/7/8	-	-	-		-	-	-	-
K*G4V-5	-	-	-		_	-	-	
KF*G4V-3	-	-	-		b14	z22	b16	
KF*G4V-5	-	-	-	b14	b14	z22	b16	
KHDG5V-5/7/8 zero lapped	z14	z22	z16	Not connected	b14	z22	b16	Not connected
KSDG4V-3	-	-	-		b14	z22	b16	
KFDG5V-5/7	-	-	-		b14	z22	b16	]
KFDG5V-8	-	-	-		b14	z22	b16	
CVU-**-EFP1	-	-	-		b14	z22	b16	
KHDG5V-5/7/8	z14	z22	z16		b14	z22	b16	

### **General description**

The EEA-PAM-5\*\*-B-33 Eurocards are power amplifiers with a four-input (demand signal) module and ramp function generator with guadrant detection for separate adjustment of acceleration and deceleration.

The type of EEA-PAM-5\*\*-B-33 amplifier used depends on the type of proportional valve, see "Model Codes".

### Features and benefits

- Includes all features of "A" amplifiers
- 2 ramp times set by front-panel potentiometers; can be varied by external voltage signals
- 4 adjustable command pre-sets selectable by 24V logic signal
- Polarity of 10V reference voltage selectable by 24V logic signal
- CE electromagnetic compatibility.- 2014/30/EU
- RoHS Compatibility-DIRECTIVE 2011/65/EU

# **Front panel**



- In the case of EEA-PAM-523/525 amplifiers, one of these relationships
- may not apply if two single solenoid valves are connected.

### Model codes

#### Table 8.

Amplifier model	For valves	
EEA-PAM-513-B-33	KCG-3; KCG-6/8	)
	KX(C)G-6/8	With type "H"
EEA-PAM-523-B-33	K*G4V-3; KDG5V-5/7/8	coils only
EEA-PAM-525-B-33	K*G4V-5	- J
EEA-PAM-533-B-33	KF*G4V-3	_
EEA-PAM-535-B-33	KF*G4V-5	_
EEA-PAM-561-B-33	KFDG5V-5/7	_
EEA-PAM-568-B-33	KFDG5V-8	_
EEA-PAM-571-B-33	CVU-**-EFP1	_
EEA-PAM-581-B-33	KHDG5V-5/7/8	_

# **Operating data**

### Table 9.

Power requirements:	See appropriate base amplifier, e.g. for EEA-PAM-535-B-33 see EEA-PAM-535-A-33
Control (output) supplies: Z22	+15V for LVDTs only
Output voltages for control:	
At pin z2	+ 10V ( ± 1 %) x 5 mA
At pin b2	- 10V ( ± 1 % ) x 5 mA
At pins z2 and b2	Ripple <20 mV pkto-pk.
	Temperature drift <1 mV/° C (<0.5 mV/° F) thru' 0-50° C (32-122° F) range
	All outputs short-circuit protected
Command signal inputs:	
Direct-voltage pins b8, b6,z8, b10	
Inverting-voltage pin z10	
Voltage range	±10V
Input impedance (voltage)	47kΩ
Current pin z6	
Current range	±20mA
Input impedance (current)	100Ω
Command voltage source: d20	± 10V x 10mA
Command voltage polarity selection:	
For flow from (main) port P to A 🔺	Pin d2 at 0 to +5V
For flow from (main) port P to B 🔺	Pin d2 at +10 to +40V
Input impedance	47kΩ
Warning: Loss of signal at pin d2 causes polarity reversal ar	d possible erratic motion.
▲ In the case of EEA-PAM-523/525 amplifiers, one of these	relationships may not apply if two single-solenoid valves are connected.
Logic inputs:	
Switch-on voltage	+10 to +40V
Switch-off voltage	<+5V
Input current d10, d12, d14 or d18	≤10 mA
Command voltage inputs: d22, d24, d26 and d28	
Voltage and source	+ 10V gives valve flow from port P to B, or -10V gives flow from P to A $\blacklozenge$
Input impedance	Four 50kΩ pots
External command potentiometer	5kΩ; 0.25W minimum
	Part no. 714127; see catalog 2460
	◆ Not applicable when using EEA-PAM-523/525 amplifiers to drive two single-solenoid valves.
Voltage-controlled ramp generator:	
Acceleration pin d6	± 10V
Deceleration pin d8	± 10V
	Note: At any ramp pot. setting, positive voltages increase ramp times and negative voltages decrease them. With pot. set at zero, 0 to $\pm$ 10V equates to a ramp time range of 50ms to 5s. With pot. set at max 0 to $\pm$ 10V equates to a ramp time of 5s to 50 ms
Input impedance d6 or dR	10k0
Drive enabled (nower available to solenoid) 724	$\Delta nn  v > 9.8 \rangle to < 40 \rangle (22 k 0)$
Drive disabled (no nower to solenoid) 724	Apply open circuit or up to 4.5V
Alarm output: 712	Fnable amplifier (on nin z24) when switching nower on
Set alarm	HIGH when alarm is activated
Signal	Output = Supply minus 2V
orginar	$I = 50 \text{ m}\Delta$ may
	I NW when selenoid overlead has occurred. (Maintained until reset.)
	Dutout – 0 to + 2 volte
	Output $-$ 0 to $\pm 2$ volto
Rosot after failure	Disable and re-enable on nin 224

#### Table 9. continued

Ramps enabled (valve switching rate limited by b24 ramp potentiometers)	Apply >9.8V to <40V (22 kΩ)
Ramps disabled (fastest valve switching; b24 ramp circuit bypassed)	Apply open circuit or up to 4.5V
Ramp active indicator: b12	
Drive ramping up	Output >10V
Drive ramping down	Output <-10V
Drive not ramping	Output OV ( ± 2V ripple)
Output resistance	10κΩ
Drive signal zero indicator: b20	
Drive signal at null (within deadband limits)	Output = Supply minus 1.5V
	I = 50 mA max.
Drive active	Output = 0 ± 2V
Output resistance	50Ω
Ambient temperature range	0 to 50° C (32 to 122° F)
Storage temperature range	-25 to +85° C (-12 to +185° F)
Edge connectors	DIN 41612 F48 male type on board. Mating connector must be an F48 female type
Installation dimensions and panel display	Dimensions are the same as for the corresponding base amplifier but the panel display is different; see first page
Mass	0.40 kg (0.88 lb) approx.
Other characteristics	See the relevant base amplifier EEA-PAM-5**-A-33.
Cardholder F48	02-104808

## **WARNING**

#### Electromagnetic Compatibility (EMC)

This product has been designed and tested to meet specific standards outlined in the European Electromagnetic Compatibility Directive (EMC) 2014/30/EU which repealed Directive 89/336/EEC, amended by Directives 91/263/EEC, 92/31/EEC, 93/68/EEC and 93/97/EEC. For instructions on installation requirements to achieve effective protection levels, see this leaflet and the Installation Wiring Practices for Vickers Electronic Products leaflet 2468. Wiring practices relevant to this Directive are indicated by Electromagnetic Compatibility (EMC).

### **Circuit and Connections**

### EEA-PAM-5\*\*-B-33

Shown with command logic module. Individual ramp adjustments of spool acceleration and deceleration, independent of direction of movement, are on the base amplifier. Additionally, acceleration and deceleration can

Note: Read circuit in conjunction with that for relevant base amplifier EEA-PAM-5\*\*-A

be controlled by variable voltage inputs to pins d6 and d8 respectively. The circuit here includes the essential characteristics of all amplifiers listed in the "Model Codes" section, two pages back; actual amplifiers omit certain sub-circuits to those connection pins not needed for the valves concerned.

![](_page_18_Figure_6.jpeg)

⊥ Customer's protective earth connection.

▼ Solenoid current for 523/525-B models; LVDT position for all others.

▲ On front panel.

See under this heading in "Operating Data" table.

#### Table 10. Logic selection inputs

Logic input pin	Command pot.	Secondary pin	Voltage to pin d2	Valve flow	
d10	1	bdz30	0 +24V	P-A P-B	}■
d12	2	bdz30	0 +24V	P-A P-B	}■
d14	3	bdz30	0 +24V	P-A P-B	}■
d18	4	bdz30	0 +24V	P-A P-B	}■

In the case of EEA-PAM-523/525-B models, one of these relationships may not apply if two single-solenoid valves are connected.

# Solenoid and LVDT connections for proportional valves

#### Table 11.

	Solenoid with		Pilot-	stage L'	VDT, (b	lack plug):	Main-stage LVDT, (gray plug):			
Amplifier type	flow P to B	or on pilot valve	Pin 1	Pin 2	Pin 3	Pin 4	Pin 1	Pin 2	Pin 3	Pin 4
EEA-PAM-513-B-33	b26/b28	-	-	-	-	Not connected	-	-	-	Not connected
EEA-PAM-523-B-33	b26/b28	z26/z28	-	-	-	Not connected	-	-	-	Not connected
EEA-PAM-525-B-33	b26/b28	z26/z28	-	-	-	Not connected	-	-	-	Not connected
EEA-PAM-533-B-33	b26/b28	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-535-B-33	b26/b28	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-561-B-33	-	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-568-B-33	-	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-571-B-33	-	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-581-B-33	-	z26/z28	z14	z22	z16	Not connected	b14	z22	b16	Not connected

# Installation dimentions in mm (inches)

![](_page_20_Figure_2.jpeg)

### **General description**

The EEA-PAM-5\*\*-C-33 Eurocards are power amplifiers with a 4-input (demand signal) module and 4-ramp function generator with quadrant detection. The ramp generator allows acceleration and deceleration to be set separately for both directions of movement.

The type of EEA-PAM-5\*\*-C-33 amplifier used depends on the type of proportional valve, see "Model Codes" on next page.

### **Features and benefits**

- All features of "A" amplifiers
- 4 adjustable ramp times, 4-quadrant acceleration/ deceleration
- 4 adjustable command pre-sets selectable by 24V logic signal
- Polarity of the 10V reference voltage selectable by 24V logic signal
- CE electromagnetic compatibility.- 2014/30/EU
- RoHS Compatibility-DIRECTIVE 2011/65/EU

### **Front panel**

![](_page_21_Figure_12.jpeg)

#### Electromagnetic Compatibility (EMC)

It is necessary to ensure that the valve is wired up in accordance with the connection arrangements shown in this leaflet. For effective protection, the user's electrical cabinet, the valve subplate or manifold and the cable screens should be connected to efficient earth (ground) points. In all cases, both valve and cable should be kept as far away as possible from any source of electromagnetic radiation such as cables carrying heavy current, relays and certain kinds of portable radio transmitters, etc. Difficult environments could mean that extra screening may be necessary to avoid the interference.

A WARNING

# Model codes

#### Table 12.

Amplifier model	For valves	
EEA-PAM-523-C-33	K*G4V-3; KDG5V-5/7/8	With type "H"
EEA-PAM-525-C-33	K*G4V-5	<b>f</b> coils only
EEA-PAM-533-C-33	KF*G4V-3	
EEA-PAM-535-C-33	KF*G4V-5	
EEA-PAM-561-C-33	KFDG5V-5/7	
EEA-PAM-568-C-33	KFDG5V-8	

### **Operating data**

#### Table 13.

Power requirements:		See appropriate base amplifier, e.g. for EEA-PAM-535-C-33 see EEA-PAM-535-A-33
Control (output) supplies:	z22	+15V for LVDTs only
Output voltages for control:		
At pin z2		+ 10V ( ± 1 %) x 5 mA
At pin b2		-10V ( ± 1 % ) x 5 mA
At pins z2 and b2		Ripple <20 mV pkto-pk. Temperature drift <1 mV/° C (<0.5 mV/° F) thru' 0-50° C (32-122° F) range All outputs short-circuit protected
Command signal inputs:		
Direct-voltage pins b	8, b6,z8, b10	
Inverting-voltage pin	z10	
Voltage range		±10V
Input impedance (voltage)		47κΩ
Current pin	z6	
Current range		±20mA
Input impedance (current)		100Ω
Command voltage source:	d20	± 10V x 10mA
Command voltage polarity selection:		
For flow from (main) port P to A 🔺		Pin d2 at 0 to +5V
For flow from (main) port P to B 🔺		Pin d2 at +10 to +40V
Input impedance		47κΩ
Warning: Loss of signal at pin d2 causes polar ▲ In the case of EEA-PAM-523/525 amplifiers	ity reversal ar , one of these	Id possible erratic motion. . relationships may not apply if two single-solenoid valves are connected.

Logic inputs:	
Switch-on voltage	+10 to +40V

Switch-off voltage		<+5V
Input current	d10, d12, d14 or d18	<10 mA
Command voltage inputs:	d22, d24, d26 and d28	
Voltage and source		+ 10V gives valve flow from port P to B, or -10V gives flow from P to A $\blacklozenge$
Input impedance		Four 50kΩ pots
External command potentiometer		5kΩ; 0.25W minimum
		Part no. 714127; see catalog 2460
		◆ Not applicable when using EEA-PAM-523/525 amplifiers to drive two single-solenoid valves.

#### Table 13. continued

Drive enabled (power available to solenoid)	z24	Apply >9.8V to <40V (22 kΩ)
Drive disabled (no power to solenoid)	z24	Apply open circuit or up to 4.5V
Alarm output:	z12	Enable amplifier (on pin z24) when switching power on
Set alarm		HIGH when alarm is activated
Signal		Output = Supply minus 2V
		I=50 mA max.
		LOW when solenoid overload has occurred. (Maintained until reset.)
		Output = 0 to $\pm 2$ volts
		Output resistance = 50 ohms
Reset after failure		Disable and re-enable on pin z24
Ramps enabled (valve switching rate limited by ramp potentiometers)	b24	Apply >9.8V to <40V (22 kΩ)
Ramps disabled (fastest valve switching; ramp circuit bypassed)	b24	Apply open circuit or up to 4.5V
Ramp active indicator:	b12	
Drive ramping up		Output >10V
Drive ramping down		Output <-10V
Drive not ramping		Output OV ( ± 2V ripple)
Output resistance		10kΩ
Drive signal zero indicator:	b20	
Drive signal at null (within deadband limits)		Output = Supply minus 1.5V
		1 = 50 mA max.
Drive active		$Output = 0 \pm 2V$
Output resistance		50Ω
Ambient temperature range		0 to 50° C (32 to 122° F)
Storage temperature range		-25 to +85° C (-12 to +185° F)
Edge connectors		DIN 41612 F48 male type on board. Mating connector must be an F48 female type
Installation dimensions and panel display		Dimensions are the same as for the corresponding base amplifier but the panel display is different
Mass		0.40 kg (0.88 lb) approx.
Other characteristics		See the relevant base amplifier EEA-PAM-5**-A-33.
Cardholder	F48	02-104808

### **Circuit and connections**

### EEA-PAM-5\*\*-C-33

Shown with command logic module. Individual ramp adjustments of spool acceleration and deceleration, independent of direction of movement, are on the base

Note: Read circuit in conjunction with that for relevant base amplifier EEA-PAM-5\*\*-A

amplifier. The circuit here includes the essential characteristics of all amplifiers listed in the "Model Codes" section, actual amplifiers omit certain sub-circuits to those connection pins not needed for the valves concerned.

![](_page_24_Figure_6.jpeg)

- Customer's protective earth connection.

▼ Solenoid current for 523/525-C models; LVDT position for all others.

On front panel.

See under this heading in "Operating Data" table

#### Table 14. Logic Selection Inputs

Logic input pin	Command pot.	Secondary pin	Voltage to pin d2	Valve flow	
d10	1	bdz30	0 +24V	P-A P-B	}■
d12	2	bdz30	0 +24V	P-A P-B	}=
d14	3	bdz30	0 +24V	P-A P-B	}■
d18	4	bdz30	0 +24V	P-A P-B	}■

In the case of EEA-PAM-523/525-C models, one of these relationships may not apply if two single-solenoid valves are connected.

## Solenoid and LVDT connections for proportional valves

#### Table 15.

	Solenoid with		Pilot-stage LVDT, (black plug):				Main-stage LVDT, (gray plug):			
Amplifier type	flow P to B	or on pilot valve	Pin 1	Pin 2	Pin 3	Pin 4	Pin 1	Pin 2	Pin 3 Pin 4	
EEA-PAM-523-C-33	b26/b28	z26/z28	-	-	-	Not connected	-	-	-	Not connected
EEA-PAM-525-C-33	b26/b28	z26/z28	-	-	-	Not connected	-			Not connected
EEA-PAM-533-C-33	b26/b28	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-535-C-33	b26/b28	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-561-C-33		z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-568-C-33		z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected

#### Installation dimentions in mm (inches)

![](_page_26_Figure_2.jpeg)

122.4 (4.82)

3(0.12)

![](_page_26_Figure_3.jpeg)

# Dedicated installation recommendation for Type B & C card

The operation of this amplifier has been factory-checked before dispatch as meeting the specification shown in this catalog.

The amplifier is ready for use as supplied, but it must be properly installed by a qualified person using the machine designer's wiring diagram.

#### 1. Wiring sizes

- 1. Use 3-core screened cable  $\ge 0.5 \text{ mm}^2$  (20 AWG) per wire for signal and LVDT wiring.
- For wiring runs between amplifier and solenoid up to 50 metres (164 ft): EEA-PAM-523 and EEA-PAM-525 must have a screened cable with a cross-section of 1.5 mm<sup>2</sup> (15 AWG)
- 3. For all other models use screened cable of  $\geq$  1  $mm^2$  (18 AWG) cross-section.

#### 2. Front panel controls

Any of the following controls may be on the front panel (depending on the amplifier type) and can be adjusted as described.

#### 1. Set zero:

On amplifier types 513-B this sets the electrical null of the valve

#### 2. Deadband compensation:

The two potentiometers are factory set at 10% (20% for type 523) of valve maximum spool stroke. The setting may be optimized for your application as follows:

Apply a small command signal (e.g. 250 mV) and check for hydraulic response from the valve. (For 2-stage valves the correct pilot pressure must be available to obtain response from the main-stage spool.) If this does not occur then adjust the applicable potentiometer clockwise until it does. Alternatively, to reduce valve hydraulic response turn the potentiometer counter-clockwise.

A 250 mV command signal can be achieved by turning a selected command signal potentiometer counter-clockwise to the endstop.

#### 3. Command Signals 1 to 4

Turning the input 1,2,3,4 adjustment potentiometers clockwise increases output, turning counter-clockwise reduces output. Use the four input adjustment potentiometers to set four independent command signals.

#### 4. Gain (only available with type C)

The gain potentiometers are factory set for 100% output at 10V command signal. Turning the gain potentiometers clockwise increases the gain, turning counter-clockwise reduces gain.

#### 5. Ramps

The factory settings of ramp potentiometers are minimum ramp time. Turning the controls clockwise increases ramp time, turning counter-clockwise decreases ramp time. On type B there are two separate controls for accelerating and for decelerating ramps, valid for both directions of movement.

On type C there are four separate controls for both accelerating and for decelerating ramps, independently adjustable for both directions.

#### 3. Front panel indicator lights (LEDs)

Amplifiers may have some, or all, of the following LEDs, depending on amplifier type:

#### Table 16.

Panel symbol	Function indicated	Color	Normal working state
24V	Power supply ON	Green	ON
15V	Internal supply ON	Green	ON
д	Output enabled	Yellow	ON
¢	Overload detection	Red	OFF
-11	LVDT failure	Red	OFF
л₩	Ramps enabled	Yellow	ON
\$	Current to solenoid (Light intensity varies with solenoid current)	Yellow	ON

#### 4. Valves connection table

#### Table 17.

			Solenoid	Pilot-stage LVDT				Main-stage LVDT			
Value type	Amplifier type	or hydraulic A	hydraulic B	Pin 1	Pin 2	Pin 3	Pin 4	Pin 1	Pin 2	Pin 3	Pin 4
KCG-3/6/8 and KX(C)G-6/8	EEA-PAM-513-B-33	b26/b28	-	-	-	-		-	-	-	
K*G4V-3 and KDG5V-5/7/8	EEA-PAM-523-B/C-33	b26/b28	z26/z28	-	-	-	-	-	-	-	-
K*G4V-5	EEA-PAM-525-B/C-33	b26/b28	z26/z28	-	-	-	-	-	-	-	-
KF*G4V-3	EEA-PAM-533-B/C-33	b26/b28	z26/z28	-	-	-	Not	b14	z22	b16	Not
KF*G4V-5	EEA-PAM-535-B/C-33	b26/b28	z26/z28	-	-	-	<sup>-</sup> connected	b14	z22	b16	<sup>-</sup> connected
KFDG5V-5/7	EEA-PAM-561-B/C-33	-	z26/z28	-	-	-	-	b14	z22	b16	-
KFDG5V-8	EEA-PAM-568-B/C-33	-	z26/z28	-	-	-	-	b14	z22	b16	-
CVU-**-EFP1	EEA-PAM-571-B-33	-	z26/z28	-	-	-	-	b14	z22	b16	-
KHDG5V-5/7/8	EEA-PAM-581-B-33	-	z26/z28	z14	z22	z16	-	b14	z22	b16	-

Note: If valves are fitted with the "E" type LVDT, the screen will be grounded at the valve end by the shell of the connector.

#### 5. Fault diagnosis

If the amplifier fails to work the following checks should be made:

- 1. Check that all wiring is correct to the machine designer's instructions.
- 2. Check that there is a 24V supply and that the 24V LED is ON.
- Check that the 15V internal voltage LED is ON (if 24V LED is ON and this 15V LED is OFF then the amplifier should be replaced.)
- 4. Check that the amplifier is enabled and the LED is ON.
- 5. Check that the LVDT failure LED is OFF. (If ON check the LVDT wiring and connections.)

To check correct function of the amplifier, disconnect all valve connections and link z22 (+15V) with a 1.2 k $\Omega$  resistor to b14. (To check the double feedback amplifiers EEA-PAM-581, make an additional link between z22 (+15V) and z14 with a 1.2 k $\Omega$  resistor.) After installation of resistor link(s), the LVDT failure LED should be OFF. If not, replace the amplifier (caution: a link without resistor damages the amplifier).

- Check that the overload LED is OFF. (If ON, check the wiring to the solenoids and the solenoid resistance by an ohmmeter. Compare the measured value with the catalog data.)
- 7. Check that an appropriate command signal is applied (monitor point at the front panel)
  - ±10V at monitor point represents ±100% output
- 8. The solenoid current (non-feedback valves) or the LVDT signal (feedback valves) can be measured at the front panel monitor point.
  - Solenoid current can be measured as a voltage signal (1 volt per amp)
  - ±10V LVDT signal at monitor point represents ±100% stroke.

# Type D Power amplifiers with PID modules

### **General description**

The EEA-PAM-5\*\*-D-33 Eurocards are power amplifiers with integrated PID modules. Each of these cards replaces two conventional electronic cards.

### **Features and benefits**

- Includes all features of "A" amplifiers (except gain)
- User configurable PID feed-forward, closed-loop operation
- Command input ramps
- Analog feedback sensor interface
- Automatic switch-over p/Q function
- Built-in test feature

- The design reduces the amount of external wiring, saves space in the rack enclosure and requires only one 24V supply
- The general purpose, integrated module can be configured using DIL switches (D1-D9) and potentiometers for the following applications:
  - Closed-loop pressure control using either proportional pressure valves or servo-performance proportional valves
  - Closed-loop velocity control
  - Closed-loop position control
  - \* p/Q control with internal or external switch-over from Q to p
- The DIL-switch and potentiometer settings can easily be reconfigured on different cards
- CE electromagnetic compatibility.- 2014/30/EU
- RoHS Compatibility-DIRECTIVE 2011/65/EU

# Front panel

LEDs		[15] Mode switch
[1] 24V power supply input, green		- TEST VALVE setting
[2] 15V control supply output, green		– AUTO function setting
[3] Drive (solenoid) enabled, yellow		[16] Test netention ster
[4] Overload, red	VALVE LOOP	
[5] LVDT failure, red		LEDs
[6] Drive level to solenoid, yellow		[17] PID-controller enabled, yellow
Potentiometers		[18] Integrator enabled, yellow
[7] Deadband compensation, flow P to B 🔺 🔶 🦳		[19] Feedback = command signal, green
[8] Deadband compensation, flow P to A 🔺 🔶		[20] Sensor failure, red
LED		Potentiometers
[9] Bamps enabled, vellow		[21] Feed-forward signal scaling
		[22] P-gain
Potentiometers		[23] I-gain
[10] Command ramp up		[24] D-gain
[11] Command ramp down		Monitor points
Monitor points		[25] MP3: Command signal
[12] MP1: Conditioned command signal		[26] MP5: PID-controller output
[13] Common ground (0V)		[27] MP6: Integrator output
[14] MP2: LVDT (spool) position 🛡 🛛		[28] MP4: Feedback signal
▲ Number and function of potentiometers [7], [8], [7.2] vary according to model type as follows: For models -513/541/553-	[7.2] Offset	ED and symbol not on EEA-PAM-513/523/525 amplifiers. olenoid current for EEA-PAM-523/525-D models. 2,0 mm (0.0787 "dia.) sockets. the case of EEA-PAM-523/525-D models one of these lationships may not apply if two single solenoid valves are nnected.

### A WARNING

#### **Electromagnetic Compatibility (EMC)**

It is necessary to ensure that the valve is wired up in accordance with the connection arrangements shown in this leaflet. For effective protection, the user's electrical cabinet, the valve subplate or manifold and the cable screens should be connected to efficient earth (ground) points. In all cases, both valve and cable should be kept as far away as possible from any source of electromagnetic radiation such as cables carrying heavy current, relays and certain kinds of portable radio transmitters, etc. Difficult environments could mean that extra screening may be necessary to avoid the interference.

# Type D Power amplifiers with PID modules

# Model codes

#### Table 18.

Amplifier model	For valves	
EEA-PAM-513-D-33	KCG-3, KCG-6/8	With type "H"
	KX(C)G-6/8	coils only
EEA-PAM-523-D-33	K*G4V-3, KDG5V-5/7/8	
EEA-PAM-525-D-33	K*G4V-5	
EEA-PAM-533-D-33	KF*G4V-3	
EEA-PAM-535-D-33	KF*G4V-5	
EEA-PAM-541-D-33	KHDG5V-5/7/8 with zerolapped mainspool	
EEA-PAM-553-D-33	KSDG4V-3	
EEA-PAM-561-D-33	KFDG5V-5/7	
EEA-PAM-568-D-33	KFDG5V-8	
EEA-PAM-571-D-33	CVU-**-EFP1	
EEA-PAM-581-D-33	KHDG5V-5/7/8	

# **Operating data**

#### Table 19.

Power (input) supply		See appropriate base amplifier, e.g. for EEA-PAM-535-D-33 see EEA-PAM-535-A-33
Control (output) supplies:	z22	+15V for LVDTs only
Reference voltages	z2	+10V x 5 mA
	b2	-10V x 5 mA
Analog inputs: Command signal inputs		
Direct-voltage pins b6, b	8, b10, z8	
Inverting-voltage input	z10	
Voltage range		± 10V
Input impedance (voltage)		47 kΩ
Current input	z6	
Current range		± 20 mA
Input impedance (current)		100Ω
Feed-forward input	d8	
Input impedance		6 kΩ
Voltage range		± 10V
Input to ramp generator	d28	
Input impedance		10 kΩ
Voltage range		± 10V
Inputs from sensors		
Voltage input	d2	
Input impedance		1 ΜΩ
Voltage range		0 to 10V, or ± 10V
Current input	d2	
Input impedance		100Ω
Current range (See "DIL Switches" five pages on) Monitoring of sensor failure for sensors with a current outout o	nly	4-20 mA or 0-20 mA
$\blacksquare$ The demand signal should have the same voltage range as the	ne sensor f	feedback,i.e. 0 to 10V, or ± 10V.
Digital inputs:		
Drive enable (power available to solenoid)	z24	
Ramps enable	b24	
Integrator enable	d14	⚠ Warning: In a power-up sequence, the integrator should not be enabled until all hydraulic, electric and control power and signals are applied and stable. Abrupt or unpredictable motion may occur if integrator is enabled during this transition time.

# **Operating data**

### Table 19. continued

	_	
PID-controller enable	d12	
Enabled		17 to 40V
Disabled		0 to 3.5V
Load current		< 10 mA
Digital outputs:		
Sensor failure	d18	
Sensor failure		Vcc –2V
Sensor o.k.		<3V
Load current (withstands a continuous short-circuit condition)		≤ 100 mA
This output may be used only in conjunction with sensors		
providing a current output (4-20 mA)		
Feedback = command signal	d10	
Feedback matches demand		Vcc –2V
Feedback does not match demand		<3V
Load current (withstands a continuous short-circuit condition)		< 100 mA
The load at pin d18 and pin d10 has to be connected to ground		
Analog outputs:		
PID-controller output	d4	
Error signal	d22	
Feedback signal	d24	
Load impedance		$\geq$ 10 k $\Omega$ ; short-circuit proof
Voltage range		± 10V
Output from ramp generator	d26	
Load resistance		$\ge$ 5 k $\Omega$ ; short-circuit proof
Voltage range		± 10V
Alarm output (drive output status):	z12	
Set alarm		Enable amplifier (on pin z24) >500 ms after switching power on.
Signal		HIGH when alarm is activated.
-		Output = Supply volts minus 2 volts.
		I = 50 mA max.
		LUW when solenoid overload has occurred.
		$\frac{1}{1000} = 0 \text{ to } \pm 1/-2 \text{ volts}$
		Output resistance = 50 ohms.
Reset after failure		Disable and re-enable on pin z24.
Ramp active indicator:	b12	
Drive ramping up		Output > 10V
Drive ramping down		Output < - 10V
Drive not ramping		Output 0 ± 10V
Output resistance		10 kΩ
Drive signal zero indicator:	b20	
Drive signal at null (within deadband limits)		Output = Supply minus 1.5V; I = 50 mA max.
Drive active		$Output = 0 \pm 2V$
Output resistance		50 Ω
Potentiometers:		
Feed-forward		V = 20% to 100%
P-gain (depends on DIL switch D2):		P = 0.1  to  50 V/V
I-gain range		K = 0.5 to 100 V/s/V
D-gain range		K. = 0 to 0.05 V/V/s
Sensor signal gain range		90% to 120%
Sensor signal offset range		+ 10%

Located on PID module.

# **Operating data**

#### Table 19. continued

Monitor points:		
Conditioned command signal	MP1	
LVDT (spool) position 🔺	MP2	
Command signal	MP3	
Feedback signal	MP4	
PID-controller output	MP5	
Integrator output (100%, independent of D3, D4, D5)	MP6	
Voltage range		± 10V
Monitor point impedance		10 kΩ
Ambient conditions:		
Storage temperature range		-25 to +85 °C (-13 to +185°F)
Operating temperature range		0 to 50 °C (32 to 122 °F)
Mass		0.4 kg (0.88 lb) approx.
Installation wiring requirements for Vickers electronic products		2468
Cardholder	F48	02-104808

▲ All amplifiers except EEA-PAM-523/525 models, in which solenoid current is monitored.

### **Circuit and Connections**

### EEA-PAM-5\*\*-D-33

Note: Read circuit in conjunction with that for relevant base amplifier EEA-PAM-5\*\*-A

![](_page_34_Figure_4.jpeg)

≟ Customer's protective ground connection.

# Type D Power amplifiers with PID modules

## **Solenoid and LVDT connections for proportional valves**

#### Table 20.

	Solenoid with	with Pilot-stage LVDT, (black plug):		Main-stage LVDT, (gray plug):						
Amplifier type	flow P to B	or on pilot valve	Pin 1	Pin 2	Pin 3	Pin 4	Pin 1	Pin 2	Pin 3	Pin 4
EEA-PAM-513-D-33	b26/b28	-	-	-	-	Not connected	-	-	-	Not connected
EEA-PAM-523-D-33	b26/b28	z26/z28	-	-	-	Not connected	-	-	-	Not connected
EEA-PAM-525-D-33	b26/b28	z26/z28	-	-	-	Not connected	-	-	-	Not connected
EEA-PAM-533-D-33	b26/b28	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-535-D-33	b26/b28	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-541-D-33	-	z26/z28	z14	z22	z16	Not connected	b14	z22	b16	Not connected
EEA-PAM-553-D-33	-	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-561-D-33	-	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-568-D-33	-	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-571-D-33	-	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-581-D-33	-	z26/z28	z14	z22	z16	Not connected	b14	z22	b16	Not connected

3rd angle projection

### Installation dimentions in mm (inches)

Plug-in Unit of 3U height, to IEC 297

![](_page_35_Figure_6.jpeg)

# Type D Power amplifiers with PID modules

### Application notes

#### **DIL Switches**

![](_page_36_Figure_3.jpeg)

Factory setting

The controller is configured for the application using DIL switches, located on the board.

The DIL switch operates as follows:

#### Table 21.

Switch	On	Off
D1:	For sensors with 4 to 20 mA output	For sensors with ± 10V or 20 mA outputs
D2:	P-gain 2 to 50	P-gain 0,1 to 2
D6:	One-sided limitation of the integrator output. (Only useful for proportional pressure and proportional throttle valves.)	No limitations of integrator output
D7:	Inverts the controller output signal	Non-inverted signal
D8:	For sensors with 4 to 20 mA output	For sensors with ± 10V or 20 mA outputs
D9:	Ramp signal not inverted	Ramp signal inverted
D10:	Not used	-

For p/Q control with automatic switch-over, connect d16 to z2 (+10V). The flow command signal (Q) is applied to the feed-forward input, d8, and the desired pressure setpoint voltage applied to a command signal input (b6/8/10 or z6/8/10). The pressure feedback sensor is connected to the sensor input d2, or d6 as required. The pressure control loop will override the flow command to limit the pressure to the level determined by the pressure setpoint voltage. Adjust P, I and D gains for best performance.

The switches D3, D4 and D5 belong together. They limit the l-gain between 5% and 100% as follows:

D3	D4	D5	l-limit
ON	ON	ON	100%
ON	ON	OFF	50%
ON	OFF	ON	35%
ON	OFF	OFF	25%
OFF	ON	ON	5.9%
OFF	ON	OFF	5.8%
OFF	OFF	ON	5.3%
OFF	OFF	OFF	5.0%

#### Operation of the integrated test mode

The basic operation of the hydraulic actuator can be tested by using the 3-position mode switch mounted on the front panel. To select different modes the toggle switch must be lifted slightly before turning it to a new position.

## A CAUTION

Before setting the mode switch to either "Test valve" or "Test loop" make sure the test potentiometer is set to "0". Otherwise sudden movements of the actuator may occur. The mode switch has three positions:

#### Auto

The controller operates in closed-loop mode, using the external command signal. The test potentiometer is disconnected.

#### **Test valve**

An open-loop command signal for the valve comes directly from the potentiometer. The external input signal is disconnected. The hydraulic part of the system may be tested in this configuration.

#### Test loop

The closed-loop command signal for the PID-controller comes directly from the potentiometer. The external signal input is disconnected. This configuration allows for verification of the valve polarity and the control parameters.

![](_page_36_Figure_22.jpeg)

# Dedicated installation recommendation for Card Type D

#### 1. Pre-installation checks:

 The controller has to be configured for the application by the DIL switches. When replacing an existing amplifier, set the DIL switches in the same position as the old amplifier

![](_page_37_Figure_4.jpeg)

#### 2. Wiring sizes

- 1. Use 3-core screened cable  $\geq 0.5 \mbox{ mm}^2$  (20 AWG) per wire for signal and LVDT wiring.
- For wiring runs between amplifier and solenoid up to 25 metres (82 ft), use wire of ≥ 1 mm<sup>2</sup> (18 AWG) cross-section.

#### 3. Installation requirements according to European EMC regulations

 The screen for LVDT wiring has to be connected to protective earth at both ends. PIN 4 on the LVDT plug is connected to LVDT housing. Alternatively, double screened cable can be used with two screens grounded at opposite ends.

#### 4. Front panel controls

Any of the following controls may be on the front panel (depending on the amplifier type) and can be adjusted as described.

#### 1. Set zero:

On amplifier types 513, 541 and 553 this sets the electrical null of the valve

#### 2. Deadband compensation:

(not available on types 513, 541 and 553)

The two potentiometers are factory set at 10% (20% for types 523 and 533) of valve maximum spool stroke. The setting may be optimized for your application as follows:

Apply a small command signal (e.g. 250 mV) and check for hydraulic response from the valve. (For 2-stage valves the correct pilot pressure must be available to obtain response from the main-stage spool.) If this does not occur then adjust the applicable potentiometer clockwise until it does. Alternatively, to reduce valve hydraulic response turn the potentiometer counter-clockwise.

#### 3. Ramps

The ramp generator is available as a separate unit and

can be used to ramp the command signal. The factory settings of ramp potentiometers are minimum ramp time. Turning the controls clockwise increases ramp time, turning counter-clockwise decreases ramp time.

#### 4. PID controller

The adjustment of the PID controller must be done

by a qualified person with knowledge of closed loop systems. Adjust the controls V, P, I, D to achieve optimum performance of the closed loop system.

#### 5. Integrated Test Unit

The basic operation of the valve, the hydraulic actuator and the whole closed loop system can be tested by using the integrated test facilities on the front panel.

Caution: Before setting the mode switch to either "Test valve" or "Test loop", make sure the test potentiometer is set to "0". Otherwise sudden movements of the actuator may occur.

#### 5. Reconfiguration of controller parameters

Once the controller parameters have been optimized and set, they can be measured by means of an ohmmeter. This allows an easy reconfiguration of the controller on different cards for use as spare parts or on standard machine series. Four test points are located on the PID module for this purpose, see diagram for locations. The resistance between the appropriate test point and ground (at the front panel monitor point) determines the controller parameters:

- P = P-gain
- = I-gain
- D = D-gain
- / = Feed-forward gain

#### Location of User Features on PID Module

![](_page_37_Figure_34.jpeg)

# Type D Power amplifiers with PID modules

#### 6. Front panel indicator lights (LEDs)

Amplifiers may have some, or all, of the following LEDs, depending on amplifier type:

#### Table 22.

Panel symbol	Function indicated	Color	Normal working state
24V	Power supply ON	Green	ON
15V	Internal supply ON	Green	ON
Б	Output enabled	Yellow	ON
ø	Overload detection	Red	OFF
	LVDT failure	Red	OFF
л₩	Ramps enabled	Yellow	ON
¢	Current to solenoid (Light intensity varies with solenoid current)	Yellow	ON

#### 7. Fault diagnosis:

If the amplifier fails to work the following checks should be made

- Check that all wiring is correct to the machine designer's instructions
- 2. Check that there is a 24V supply and that the 24V LED is ON
- Check that the 15V internal voltage LED is ON (if 24V LED is ON and this 15V LED is OFF then the amplifier should be replaced.)
- 4. Check that the amplifier is enabled and the LED is ON

#### 8. Valve connection table

This table shows how the different valves have to be connected to the associated amplifier.

#### Table 23.

				Pilot-stage LVDT				Main-stage LVDT			
Value type Amplifier type	Solenoid with LVDT or hydraulic A	Solenoid without LVDT or hydraulic B	Pin 1	2	3	4	Pin 1	2	3	4	
KCG-3/6/8 and KX(C)G-6/8	EEA-PAM-513-D-33	b26/b28	-	-	-	-		_	-	_	
K*G4V-3 and KDG5V-5/7/8	EEA-PAM-523-D-33	b26/b28	z26/z28	_	_	-		-	-	-	
K*G4V-5	EEA-PAM-525-D-33	b26/b28	z26/z28	-	-	-		-	-	-	
KF*G4V-3	EEA-PAM-533-D-33	b26/b28	z26/z28	_	-	-		b14	z22	b16	
KF*G4V-5	EEA-PAM-535-D-33	b26/b28	z26/z28	-	_	_		b14	z22	b16	
KHDG5V-5/7/8 zero lapped	EEA-PAM-541-D-33	-	z26/z28	z14	z22	z16		b14	z22	b16	Screen
KSDG4V-3	EEA-PAM-553-D-33	-	z26/z28	_	_	_		b14	z22	b16	
KFDG5V-5/7	EEA-PAM-561-D-33	-	z26/z28	-	-	-		b14	z22	b16	
KFDG5V-8	EEA-PAM-568-D-33	-	z26/z28	-	-	-		b14	z22	b16	
CVU-**-EFP1	EEA-PAM-571-D-33	-	z26/z28	_	_	-		b14	z22	b16	
KHDG5V-5/7/8	EEA-PAM-581-D-33	-	z26/z28	z14	z22	z16		b14	z22	b16	

 Check that the LVDT failure LED is OFF. (If ON check the LVDT wiring and connections.) To check correct function of the amplifier, disconnect

all valve connections and link z22 (+15V) with a 1.2 k $\Omega$  resistor to b14. (To check the double feedback amplifiers EEA-PAM-581/541, make an additional link between z22 (+15V) and z14 with a 1.2 k $\Omega$  resistor.)

After installation of resistor link(s), the LVDT failure LED should be OFF. If not, replace the amplifier (caution: a link without resistor damages the amplifier).

- Check that the overload LED is OFF. (If ON, check the wiring to the solenoids and the solenoid resistance by an ohmmeter. Compare the measured value with the catalog data.)
- 7. Check that an appropriate valve driving signal is available (monitor point MP1 at the front panel).
  - ±10V at monitor point represents ±100% output of the valve
- The solenoid current (non-feedback valves) or the LVDT signal (feedback valves) can be measured at the front panel monitor point MP2.
  - Solenoid current can be measured as a voltage signal (1 volt per amp)
  - ±10V LVDT signal at monitor point represents ±100% stroke
- 9. Check that the DIL switches are set correctly, corresponding to the application.
- 10. Check the PID controller operation by using the monitor points MP3, 4,5,6 at the front panel. The integrated test facility is a support to check the operation.

### EEA-PAM-5\*\*-E-33 Series

### **General description**

A strip guidance controller serves to control the position of an electrohydraulic actuator, using optical sensors.

The controller can be used for strip-edge or strip-center guidance or stack height control.

It consists of a power amplifier for roportional valves, and an integrated module for strip guidance control.

### **Features and benefits**

- Includes all features of "A" amplifiers (except gain)
- Input offset compensation
- Strip guidance control
- · Voltage or current input sensor interface
- Built-in test feature
- CE electromagnetic compatibility.- 2014/30/EU
- RoHS Compatibility-DIRECTIVE 2011/65/EU

### **Front panel**

LEDs [1] 24V power supply input, green [2] 15V control supply output, green [3] Drive (solenoid) enabled, yellow [4] Overload, red [5] LVDT failure, red	P	<ul> <li>[15] Mode switch <ul> <li>TEST VALVE setting</li> <li>AUTO function setting</li> <li>TEST LOOP setting</li> </ul> </li> <li>[16] Test potentiometer </li> <li>LEDs </li> <li>[17] Controller active, vellow</li> </ul>
[6] Drive level to solenoid, yellow	.+-+-	[18] Sensor out of range, red
[7] Deadband compensation, flow P to B         [8] Deadband compensation, flow P to A         LED         [9] Ramps enabled, yellow		<ul> <li>[19] Maximum closed-loop velocity +</li> <li>[20] Maximum closed-loop velocity -</li> <li>LEDs</li> <li>[21] Open-loop command (+) active</li> </ul>
Potentiometers         [10] Acceleration ramp         [11] Deceleration ramp		<ul><li>[22] Open-loop command (-) active</li><li>Potentiometers</li><li>[23] Open-loop command +</li></ul>
Monitor points  [12] MP1: Conditioned input signal [13] Common ground (0V) [14] MP2: LVDT (spool) position		<ul> <li>[24] Open-loop command –</li> <li>Monitor points ■</li> <li>[25] MP3: Output signal of sensor with current output, non-inverting</li> <li>[26] MP5: Conditioned sensor signal, ± 10V full scale</li> </ul>
<ul> <li>▲ Solenoid current for EEA-PAM-523/525-E models.</li> <li>■ Ø2,0 mm (0.0787 "dia.) sockets.</li> </ul>		<ul><li>[27] MP6: Controller output</li><li>[28] MP4: Output signal of sensor with current output, inverting</li></ul>

### 🛕 WARNING

#### **Electromagnetic Compatibility (EMC)**

It is necessary to ensure that the valve is wired up in accordance with the connection arrangements shown in this leaflet. For effective protection, the user's electrical cabinet, the valve subplate or manifold and the cable screens should be connected to efficient earth (ground) points. In all cases, both valve and cable should be kept as far away as possible from any source of electromagnetic radiation such as cables carrying heavy current, relays and certain kinds of portable radio transmitters, etc. Difficult environments could mean that extra screening may be necessary to avoid the interference.

### Operation

Non-contact optical sensors measure the position of the strip edge. The output from a sensor is an electrical signal, which is fed to the strip guidance controller (signal ranges 0 to 20 mA, 4 to 20 mA, 0 to +10V, or 0 to +24V). When activated, the strip guidance controller maintains the strip edge exactly in the center of the measuring range.

If the position of the strip edge deviates from the center of the measuring range, the controller causes the actuator to move the strip edge back into position.

When closed-loop control is activated by the digital input signal "Automatic", the strip edge is moved from its current position into the measuring range of the sensor. The maximum actuator velocity (forwards and reverse) can be set on the front panel. Whenever the strip edge leaves the measuring range of the sensor, the controller generates a digital output signal which can be processed by the machine controller.

If closed-loop control is not activated, the controller can be operated open-loop. In this case the actuator travels at the velocity set by potentiometer "V+" when digital input "set +" is activated. "V -" and digital input "set -" are used for movements in the reverse direction.

### **Operating data**

#### Table 25.

A built-in test function together with front panel monitor points, considerably simplify start-up and fault diagnosis.

#### **Model codes**

#### Table 24.

Amplifier model	For valves	
EEA-PAM-523-E-33	KDG4V-3 and KDG5V-5/7/8	With type
EEA-PAM-525-E-33	KDG4V-5	"H"coils only
EEA-PAM-533-E-33	KFDG4V-3	
EEA-PAM-535-E-33	KFDG4V-5	
EEA-PAM-541-E-33	KHDG5V-5/7/8 zero-lap	
EEA-PAM-553-E-33	KSDG4V-3	
EEA-PAM-561-E-33	KFDG5V-5/7	
EEA-PAM-568-E-33	KFDG5V-8	
EEA-PAM-581-E-33	KHDG5V-5/7/8	

Power supply	zbd32	See appropriate base amplifier, e.g. for EEA-PAM-535-E-33 see EEA-PAM-535-A-33
Control (output) supplies:	z22	+15V for LVDTs only
Differential inputs for sensor:		
Voltage input, non-inverting	d2	+24V max., $R_{i} = 100 \text{ k}\Omega$
Voltage input, inverting	d6	24V max., R <sub>i</sub> = 100 kΩ
Current input, non-inverting	d8	20 mA max., R <sub>i</sub> = 100Ω
Current input, inverting	d12	20 mA max., R <sub>i</sub> = 100Ω
Digital inputs (opto-isolated):		
Set +	d22	24V DC nom., 20 to 40V DC max., $R_i = 2.7 \text{ k}\Omega$
Set –	d20	24V DC nom., 20 to 40V DC max., $R_i = 2.7 \text{ k}\Omega$
Automatic	d18	24V DC nom., 20 to 40V DC max., R = 2.7 kΩ
Drive enable	z24	Enable = 9.8 to 40V Disable = 0 to 4.8V or open, $R_i$ = 47 k $\Omega$
Ramp enable	b24	Enable = 9.8 to 40V Disable = 0 to 4.8V or open, $R_i = 47 \text{ k}\Omega$
Digital output (opto-isolated):		
Out of range	d24	24V DC nom. Short-circuit proof. I <sub>max</sub> = 100 mA
Potentiometers:		
Deadband compensation		Separate controls for each direction from spool-centered position 0 to 50% of max. current
Ramp time adjustment		Separate controls for acceleration and deceleration 50 ms to 5 sec
Closed-loop velocities		Separate controls for forward and reverse 5 to 100%
Open-loop command		Separate controls for forward and reverse 0 to 100%
Monitor points		
(Numbers corresponding to the numbering on the front panel and in the circuit diagram)		MP1: Conditioned input signal, $\pm$ 10V MP2: LVDT (spool) position, $\pm$ 10V MP3: Output signal of sensor with current output, non-inverting 0 to 2V = 0 to 20 mA MP4: Output signal of sensor with current output, inverting 0 to 2V = 0 to 20 mA MP5: Conditioned sensor signal, $\pm$ 10V MP6: Controller output, $\pm$ 10V All monitor points are short-circuit proof. In all cases: R(out) = 10 k $\Omega$

Solenoid current for EEA-PAM-523/525-E models.

#### Table 25. continued

Alarm output: z12	
Set alarm Signal	Enable amplifier (on pin z24) when switching power on HIGH when alarm is activated Output = Supply volts minus 2 volts I = 50 mA max. LOW when solenoid overload has occurred. (Maintained until reset) Output = 0 to +/-2 volts Output resistance = 50 ohms
Reset after failure	Disable and re-enable on pin z24
Test facilities	3-position switch for: - Valve test mode - Controller test mode - Automatic operation mode Caution: Before setting the mode switch to either "Test valve" or "Test loop"ensure that the test potentiometer is set to "0", otherwise sudden movements of the actuator may occur.
Operating temperature	0 to 50 °C (32 to 122 °F)
Storage temperature	-25 to +85 °C (-13 to +185 °F)
Mass	0.4 kg (0.88 lb) approx.
Installation wiring requirements for Vickers electronic products	2468
Cardholder F48	02-104808

### **Circuit and Connections**

### EEA-PAM-533/535-E-33 example A

Note: Read circuit in conjunction with that for relevant base amplifier EEA-PAM-5\*\*-A

![](_page_42_Figure_4.jpeg)

🛓 Customer's protective ground connection.

See footnote at bottom of "Application Examples"

Solenoid current for EEA-PAM-523/525-E models.

## Solenoid and LVDT connections for proportional valves

#### Table 26.

	Solenoid with		Pilot-	stage L'	VDT, (b	lack plug):	Main-stage LVDT, (gray plug):			
Amplifier type	flow P to B	or on pilot valve	Pin 1	Pin 2	Pin 3	Pin 4	Pin 1	Pin 2	Pin 3	Pin 4
EEA-PAM-523-E-33	b26/b28	z26/z28	-	-	-	Not connected	-	-	-	Not connected
EEA-PAM-525-E-33	b26/b28	z26/z28	-	-	-	Not connected	-	-	_	Not connected
EEA-PAM-533-E-33	b26/b28	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-535-E-33	b26/b28	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-541-E-33	-	z26/z28	z14	z22	z16	Not connected	b14	z22	b16	Not connected
EEA-PAM-553-E-33	-	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-561-E-33	-	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-568-E-33	-	z26/z28	-	-	-	Not connected	b14	z22	b16	Not connected
EEA-PAM-581-E-33	-	z26/z28	z14	z22	z16		b14	z22	b16	Not connected

## Installation dimentions in mm (inches)

Plug-in Unit of 3U Height, to IEC 297

![](_page_43_Figure_6.jpeg)

![](_page_43_Picture_7.jpeg)

### **Application examples**

EEA-PAM-533/535-E amplifiers with KFDG4V-3/5 valves

#### Strip guidance control, stack height control

Position sensor with current output

![](_page_44_Figure_5.jpeg)

#### Position sensor with voltage output

![](_page_44_Figure_7.jpeg)

#### Strip-center guidance control

Position sensor with current output

![](_page_44_Figure_10.jpeg)

#### Position sensor with voltage output

![](_page_44_Figure_12.jpeg)

▲ Other amplifier/valve combinations differ in respect to the LVDT and solenoid connections; see catalog 2464 for the relevant base amplifier EEA-PAM-5\*\*-A-33.

 $\perp$  Customer's protective ground connection.

# Dedicated installation recommendation for Type E card

The operation of this amplifier has been factory-checked before dispatch as meeting the specification shown in in this catalog

#### 1. Configuration

The controller has to be configured for the application by the DIL switches. When replacing an existing amplifier, set the DIL switches in the same positions as the old amplifier.

![](_page_45_Figure_5.jpeg)

1	On Off	0-10V or 0-20 mA sensor signal ± 5V or ± 10V or 2 sensors
2	On Off	Non-inverted sensor signal Inverted sensor signal
3	On Off	KDG4V-3/5 or KFDG4V-3/5 valves KSDG4V-3 or KFDG5V or KHDG5V valves
4		Not connected

#### 2. Wiring sizes

Use 3-core screened cable  $\geq$  0.5 mm² (20 AWG) per wire for signal and LVDT wiring.

For wiring runs between amplifier and solenoid up to 25 metres (82 ft), use wire of  $\ge 1 \text{ mm}^2$  (18 AWG) cross-section.

#### 3. Sensor calibration

The amplifier is factory-set to suit a sensor with a 0-20 mA output.

Set the sensor signal to minimum (by covering) and adjust the "offset" potentiometer to read -10V  $\pm$ 1% at monitor point 5 (MP5).

Set the sensor signal to maximum (fully illuminated) and adjust the "gain" potentiometer to read +10V  $\pm1\%$  at MP5 on the front panel.

Re-check offset and repeat above as necessary.

#### 4. Front panel controls

Any of the following controls may be on the front panel (depending on the amplifier type) and can be adjusted as described.

#### 1. Set zero:

On amplifier types 541 and 553 this sets the electrical  $\ensuremath{\text{null}}$  of the valve

#### 2. Deadband compensation:

(not available on types 541 and 553)

The two potentiometers are factory set at 10% (20% for types 523 and 533) of valve maximum spool stroke. The setting may be optimized for your application as follows:

Apply a small command signal (e.g. 250 mV) and check for hydraulic response from the valve. (For 2-stage valves the correct pilot pressure must be available to obtain response from the main-stage spool.) If this does not occur then adjust the applicable potentiometer clockwise until it does. Alternatively, to reduce valve hydraulic response turn the potentiometer counter-clockwise.

#### 3. Ramps

The ramp generator is available as a separate unit and

can be used to ramp the command signal. The factory settings of ramp potentiometers are minimum ramp time. Turning the controls clockwise increases ramp time, turning counter-clockwise decreases ramp time.

#### 4. Integrated test unit

The basic operation of the valve, the hydraulic actuator and the whole closed loop system can be tested by using the integrated test facilities on the front panel.

**Note:** to select different modes, the toggle switch must be lifted slightly before moving to a new position.

**Caution:** Before setting the mode switch to either "Test valve" or "Test loop", make sure the test potentiometer is set to "0". Otherwise sudden movements of the actuator may occur.

#### 5. Test valve

With the 3-position switch set to "Test valve", ensure that

the front panel test potentiometer controls the actuator speeds in both directions.

#### 6. Auto

In this mode, the controller operates in closed loop using the external sensor signal. The test potentiometer is disconnected.

#### 7. Test Loop

The test potentiometer can be used to simulate the sensor signal. The external sensor signal is disconnected.

#### 8. Open loop command potentiometers

These are used to set the velocity when pin 20 or pin 22 are used by the machine controller to move the ctuator.

#### 9. Max. Closed loop velocity potentiometers

There are used to set the maximum velocity when in "Auto" mode.

#### 5. Front panel indicator lights (LEDs)

Amplifiers may have some, or all, of the following LEDs, depending on amplifier type:

#### Table 27.

Panel symbol	Function indicated	Color	Normal working state
24V	Power supply ON	Green	ON
15V	Internal supply ON	Green	ON
д	Output enabled	Yellow	ON
ø	Overload detection	Red	OFF
<b></b>	LVDT failure	Red	OFF
л┝िт	Ramps enabled	Yellow	ON
ø	Current to solenoid (Light intensity varies with solenoid current)	Yellow	ON

#### 6. Fault diagnosis

# If the amplifier fails to work the following checks should be made:

- Check that all wiring is correct to the machine designer's instructions.
- Check that there is a 24V supply and that the 24V LED is ON.
- Check that the 15V internal voltage LED is ON (if 24V LED is ON and this 15V LED is OFF then the amplifier should be replaced.)
- Check that the amplifier is enabled and the LED is ON.
- Check that the LVDT failure LED is OFF. (If ON check the LVDT wiring and connections.)
  - To check correct function of the amplifier, disconnect all valve connections and link z22 (+15V) with a 1.2 k $\Omega$ resistor to b14. (To check the double feedback amplifiers EEA-PAM-581/541, make an additional link between z22 (+15V) and z14 with a 1.2 k $\Omega$  resistor.) After installation of resistor link(s), the LVDT failure LED should be OFF. If not, replace the amplifier (caution: a link without resistor damages the amplifier).
- Check that the overload LED is OFF. (If ON, check the wiring to the solenoids and the solenoid resistance by an ohmmeter. Compare the measured value with the catalog data.)
- Check that the "automatic" signal is applied to pin d18.
- The solenoid current (non-feedback valves) or the LVDT signal (feedback valves) can be measured at the front panel monitor point MP2.
  - Solenoid current can be measured as a voltage signal (1 volt per amp)
  - ±10V LVDT signal at monitor point represents
     ± 100% stroke.

**Note:** Due to the effect of spool overlap, the working range is typically 3 to 9 volts for the flows from zero to maximum.

- Check the DIL switches are set correctly, corresponding to the application.
- Check the sensor output signals on MP3, MP4 or MP5 as appropriate.

#### 7. Valve connection table

This table shows how the different valves have to be connected to the associated amplifier.

#### Table 28.

		Solenoid with LVDT	Solenoid without LVDT or hydraulic B	Pilot s	tage l	VDT		Main stage LVDT				
Value type	Amplifier type	or hydraulic A		Pin 1	2	3	4	Pin 1	2	3	4	
K*G4V-3 and KDG5V-5/7/8	EEA-PAM-523-E-33	b26/b28	z26/z28	-	-	-		-	-	-		
K*G4V-5	EEA-PAM-525-E-33	b26/b28	z26/z28	-	-	-	_	-	-	-	_	
KF*G4V-3	EEA-PAM-533-E-33	b26/b28	z26/z28	-	-	-		b14	z22	b16	-	
KF*G4V·5	EEA-PAM-535-E-33	b26/b28	z26/z28	-	-	-	– Not	b14	z22	b16	- Not	
KHDG5V-5/7/8 zero lapped	EEA-PAM-541-E-33	-	z26/z28	z14	z22	z16	connected	b14	z22	b16	connected	
KSDG4V-3	EEA-PAM-553-E-33	-	z26/z28	-	-	-	_	b14	z22	b16	-	
KFDG5V-5/7	EEA-PAM-561-E-33	-	z26/z28	-	-	-		b14	z22	b16	-	
KFDG5V-8	EEA-PAM-568-E-33	-	z26/z28	-	-	-		b14	z22	b16	-	
KHDG5V-5/7/8	EEA-PAM-581-E-33	-	z26/z28	z14	z22	z16		b14	z22	b16	_	

Note: If valves are fitted with the "B" type LVDT, the screen will be grounded at the valve end by the shell of the connector.

### EEA-PAM-5\*\*-F-33 Series

### **General description**

**Front panel** 

The EEA-PAM-5\*\*-F-33 Eurocards are power amplifiers with integrated CNC adaptation modules. Each card replaces two conventional electronic cards. These power amplifiers are used for high accuracy positioning systems with inexpensive standard proportional valves and CNC axis or PLC position controls.

### **Features and benefits**

- Includes all features of "A" amplifiers
- Hysteresis compensation for valves with/without feedback
- Enhanced deadband adjustment for closed-loop position control using valves with overlap
- This particular configuration reduces the amount of external wiring, saves space in the rack enclosure and requires only one 24V power supply
- Smooth transition between the overlap region and working region
- Low cost, high accuracy positioning systems with overlapped proportional valves. Non-linearities and inconsistencies (friction) in the overlap region are compensated by the electronic linearization
- Simple set-up procedure
- A built-in test function significantly simplifies commissioning (start-up) and fault-diagnosis
- CE electromagnetic compatibility.- 2014/30/EU
- RoHS Compatibility-DIRECTIVE 2011/65/EU

![](_page_48_Figure_15.jpeg)

Ø2,0 mm (0.0787 "dia.) sockets.

Solenoid current for EEA-PAM-523/525-F models.

### 🛕 WARNING

#### **Electromagnetic Compatibility (EMC)**

It is necessary to ensure that the valve is wired up in accordance with the connection arrangements shown in this leaflet. For effective protection, the user's electrical cabinet, the valve subplate or manifold and the cable screens should be connected to efficient earth (ground) points. In all cases, both valve and cable should be kept as far away as possible from any source of electromagnetic radiation such as cables carrying heavy current, relays and certain kinds of portable radio transmitters, etc. Difficult environments could mean that extra screening may be necessary to avoid the interference.

#### EURO PAM 33 CATALOG E-VLVI-CC004-E1-December 2019 www.eaton.com

# Model codes

#### Table 29.

Amplifier model	For valves
EEA-PAM-523-F-33	KDG4V-3 and KDG5V-5/7/8 👌 With type "H"
EEA-PAM-525-F-33	KDG4V-5 <b>J</b> coils only
EEA-PAM-533-F-33	KFDG4V-3
EEA-PAM-535-F-33	KFDG4V-5
EEA-PAM-561-F-33	KFDG5V-5/7
EEA-PAM-568-F-33	KFDG5V-8
EEA-PAM-581-F-33	KHDG5V-5/7/8

# **Operating data**

#### Table 30.

Power (input) supply bdz3	2 See appropriate base amplifier, e.g. for EEA-PAM-535-F-33 see EEA-PAM-535-A-33
Control (output) supplies: Z2	2 +15V for LVDTs only
Reference voltages 2	2 +10V x 5 mA 2 -10V x 5 mA
Analog inputs	
Command inputs	
Direct-voltage inputs b6, b8, b10, z	3
Inverting-voltage input z1	
Voltage range	± 10V
Input impedance (voltage)	47 κΩ
Current input d2	3
Current range	± 20 mA
Input impedance (current)	100Ω
Input ramp	Can be inverted using jumper on plug X30 on circuit board.
Voltage range	± 10V
Input impedance	10 kΩ
Velocity demand signal d10, d1	6
Voltage range	± 10V
Input impedance	15 kΩ
Digital inputs:	
Drive enable (power available to solenoid) z2	4
Ramps enable b2	4
Enabled	17 to 40V
Disabled	0 to 3.5V
Load current	< 10 mA
Analog outputs:	
P-controller output	
Voltage range d1	2 ± 10V
Load impedance	$\geq$ 10 k $\Omega$ ; short-circuit proof
Output ramp generator d2	6
Voltage range	± 10V
Load impedance	$\ge$ 10 k $\Omega$ ; short-circuit proof

# **Operating data**

#### Table 30. continued

Alarm output: z12	
Set alarm	Enable amplifier (on pin z24) when switching power on.
Signal	HIGH when alarm is activated.
5	Output = Supply volts minus 2 volts.
	I = 50 mA max.
	LOW when solenoid overload has occurred.
	(Maintained until reset).
	Output = 0 to $+/-2$ volts.
	Output resistance = 50 ohms.
Reset after failure	Disable and re-enable on pin z24.
Potentiometers:	
Deadband compensation, separate control	
for each solenoid	0 to 50%
Gain, separate control for each solenoid	40 to 90%
P₀-Deadband gain	15 to 43 times
P <sub>EXT</sub> -Gain controller:	
Without link	0,1 to 5 times
Link d18 to d20	2 to 100 times
Integrated P-controller	The input circuit of the power amplifier card is used as a differential amplifier between the demand and feedback signals. The ramp signal generator can be used as profile generator.
	<b>Caution:</b> When using "TEST LOOP" the command signal has to be connected to d8, and d14 has to be connected to the command signal input of the input stage.
Hysteresis compensation:	
Link d2 to d6	For KDG4V-* valves only
Monitor points:	
Conditioned command signal power	
amplifier MP1	
LVDT (spool) position 🔺 MP2	
Voltage range	± 10V
Monitor point impedance	10 kΩ
Ambient conditions:	
Storage temperature range	-25 to +85C (-13 to +185F)
Operating temperature range	0 to 50C (32 to 122F)
Mass	0.4 kg (0.88 lb) approx.
Installation wiring requirements for Vickers electronic products	2468
Cardholder F48	02-104808
Integrated test modes	See Test Mode details below

▲ Solenoid current for EEA-PAM-523/525-F models.

### **Circuit and Connections**

### EEA-PAM-5\*\*-F-33

Note: Read circuit in conjunction with that for relevant base amplifier EEA-PAM-5\*\*-A

![](_page_51_Figure_4.jpeg)

L Customer's protective ground connection.

## Solenoid and LVDT connections for proportional valves

#### Table 31.

	Solenoid with		Pilot-s	tage LV	DT, (bla	ck plug):	Main-stage LVDT, (gray plug):				
Amplifier type	LVDT and/or for flow P to B	Solenoid without LVDT, or on pilot valve	Pin 1	Pin 2	Pin 3	Pin 4	Pin 1	Pin 2	Pin 3	Pin 4	
EEA-PAM-523-F-33	b26/b28	z26/z28	-	_	_	Not connected	_	_	_	Not connected	
EEA-PAM-525-F-33	b26/b28	z26/z28	_	_	_	Not connected	_	_	_	Not connected	
EEA-PAM-533-F-33	b26/b28	z26/z28	_	_	_	Not connected	b14	z22	b16	Not connected	
EEA-PAM-535-F-33	b26/b28	z26/z28	-	_	_	Not connected	b14	z22	b16	Not connected	
EEA-PAM-561-F-33	-	z26/z28	-	_	_	Not connected	b14	z22	b16	Not connected	
EEA-PAM-568-F-33	-	z26/z28	-	_	_	Not connected	b14	z22	b16	Not connected	
EEA-PAM-581-F-33	-	z26/z28	z14	z22	z16	Not connected	b14	z22	b16	Not connected	

### Installation Dimensions in mm (inches)

Plug-in Unit of 3U Height, to IEC 297

![](_page_52_Picture_6.jpeg)

![](_page_52_Figure_7.jpeg)

![](_page_52_Figure_8.jpeg)

### **Operation of the integrated test mode**

The basic operation of the hydraulic actuator can be tested by using the 3-position mode switch mounted on the front panel. To select different modes the toggle switch must be lifted slightly before moving to a new position.

### A CAUTION

Before setting the mode switch to either "Test valve" or "Test loop" make sure the test potentiometer is set to "0". Otherwise sudden movements of the actuator may occur.

The mode switch has three positions:

#### Auto

The controller operates in closed-loop mode, using the external command signal. The test potentiometer is disconnected.

#### **Test valve**

An open-loop command signal for the valve comes directly from the potentiometer. The external input signal is disconnected. The hydraulic part of the system may be tested in this configuration.

#### Test loop

The test potentiometer can be used to drive the separate P-controller, if "Test loop" (closed spool) is selected. The external input signal is disconnected. See wiring example. "Test loop" is usable only if the separate P-controller is used.

## **A** CAUTION

When using "TEST LOOP" the command signal has to be connected to d8, and d14 to be connected to the command signal input of the input stage.

![](_page_53_Figure_14.jpeg)

# **Application example**

#### Positioning module with CNC axis controller

![](_page_54_Figure_3.jpeg)

#### EEA-PAM-533/535-F

# Dedicated installation recommendation for Type F card

The operation of this amplifier has been factory-checked before despatch as meeting the specification shown in this catalog.

#### 1. Wiring sizes

Use screened cable  $\geq$  0.5 mm2 (20 AWG) per wire for signal and LVDT wiring.

For wiring runs between amplifier and solenoid up to 25 metres (82 ft), use wire of  $\geq$  1 mm2 (18 AWG) cross-section

# 2. Installation requirements according to European EMC regulations

The wiring to the machine controller should be screened. The screen should be connected to an efficient ground point at the amplifier end.

#### 3. Front panel indicator lights (LEDs)

Amplifiers may have some, or all, of the following LEDs, depending on amplifier type:

#### Table 32.

Panel symbol	Function indicated	Color	Normal working state
24V	Power supply ON	Green	ON
15V	Internal supply ON	Green	ON
д	Output enabled	Yellow	ON
ø	Overload detection	Red	OFF
- <b></b>	LVDT failure	Red	OFF
л₩	Ramps enabled	Yellow	ON
¢	Current to solenoid (Light intensity varies with solenoid current)	Yellow	ON

#### 4. Front panel controls

#### 1. Gain

The two gain potentiometers are factory set to maximum, and operate separately on positive and negative demand signals

#### 2. Deadband compensation:

The two potentiometers are factory set at 10% (20% for type 523 and 533) of valve maximum spool stroke. The setting may be optimized for your application as follows: Apply a small command signal (e.g. 250 mV) and check for hydraulic response from the valve. (For 2-stage valves the correct pilot pressure must be available to obtain response from the main-stage spool.) If this does not occur then adjust the applicable potentiometer clockwise until it does. Alternatively, to reduce valve hydraulic response turn the potentiometer counter-clockwise.

#### 3. Ramps

The ramp generation is used to ramp the command signal. The factory setting of ramp potentiometers are minimum ramp time. Turning the controls clockwise increases ramp time, turning counter-clockwise decreases ramp time. The ramp signal may be inverted by changing a jumper on the circuit board.

#### 4. Offset

This potentiometer is used to set the value to null

#### 5. Deadband gain

Potentiometer  $P_o$  is used to set the electrical gain within the deadband region. The gain factor is very high (30 to 90). This increased gain in the deadband has the effect of linearizing the valve characteristic. This potentiometer is normally set to maximum gain. In the event of stability problems in the deadband region, the gain factor must be reduced.

#### 6. P-Gain controller

The  $\mathsf{P}_{\text{EXT}}$  potentiometer adjusts the gain of the P position controller.

#### 5. Fault diagnosis

If the amplifier fails to work the following checks should be made:

- Check that all wiring is correct to the machine designer's instructions.
- Check that there is a 24V supply and that the 24V LED is ON.
- Check that the 15V internal voltage LED is ON (if 24V LED is ON and this15V LED is OFF then the amplifier should be replaced.)
- Check that the amplifier is enabled and the LED is ON.
- Check that the LVDT failure LED is OFF. (If ON check the LVDT wiring and connections.)

To check correct function of the amplifier for a feedback valve, disconnect all valve connections and link z22 ( +15V) with a 1.2 k $\Omega$  resistor to b14. (To check the double feedback amplifiers EEA-PAM-581, make an additional link between z22 (+15V) and z14 with a 1.2 k $\Omega$  resistor.)

After installation of resistor link(s), the LVDT failure LED should be OFF. If not, replace the amplifier

Caution: a link without resistor damages the amplifier

- Check that the overload LED is OFF. (If ON, check the wiring to the solenoids and the solenoid resistance by an ohmmeter. Compare the measured value with the catalog data.)
- Check that an appropriate valve driving signal is available (monitor point MP1 at the front panel).
  - ±10V at monitor point represents ± 100% output of the valve.
- The solenoid current (non-feedback valves) or the LVDT signal (feedback valves) can be measured at the front panel monitor point MP2.
  - Solenoid current can be measured as a voltage signal (1 volt per amp)
  - ±10V LVDT signal at monitor point represents ±100% stroke.

**Note:** Due to the effect of spool overlap, the working range is typically 3 to 9 volts for the flows from zero to maximum.

#### 6. Valve connection table

This table shows how the different valves have to be connected to the associated amplifier.

#### Table 33.

		Solenoid with LVDT	Solenoid without	Pilot stage LVDT				Main stage LVDT				
Value type	Amplifier type	or hydraulic A	LVDT or hydraulic B	Pin 1	2	3	4	Pin 1	2	3	4	
K*G4V-3 and KDG5V-5/7/8	EEA-PAM-523-F-33	b26/b28	z26/z28	-	-	-		-	-	-		
K*G4V-5	EEA-PAM-525-F-33	b26/b28	z26/z28	-	-	-	_	-	-	-	-	
KF*G4V-3	EEA-PAM-533-F-33	b26/b28	z26/z28	-	-	-	– Not	b14	z22	b16	- Not	
KF*G4V·5	EEA-PAM-535-F-33	b26/b28	z26/z28	-	-	-	connected	b14	z22	b16	connected	
KFDG5V-5/7	EEA-PAM-561-F-33	-	z26/z28	-	-	-	_	b14	z22	b16	_	
KFDG5V-8	EEA-PAM-568-F-33	-	z26/z28	-	-	-	_	b14	z22	b16	=	
KHDG5V-5/7/8	EEA-PAM-581-F-33	-	z26/z28	z14	z22	z16	_	b14	z22	b16	_	

Note: If valves are fitted with the "B" type LVDT, the screen will be grounded at the valve end by the shell of the connector.

# EURO PAM card offerings

Table 34.

Model No	33- Series Assembly Number	32 -Series Assembly Number
EEA-EDC-436-A1-33	105EC00004	02-326120
EEA-EDC-436-A2-33	105EC00005	02-326132
EEA-EDC-436-A3-33	105EC00006	02-326133
EEA-EDC-436-D1-33	105EC00007	02-326129
EEA-EDC-436-D3-33	105EC00008	02-326131
EEA-PAM-511-A-33	105EC00009	02-326000
EEA-PAM-511-A-33-EN8 🔺	105EC00010	02-326095
EEA-PAM-511-B-33	105EC00011	02-326019
EEA-PAM-511-D-33	105EC00012	02-326036
EEA-PAM-513-A-33	105EC00013	02-326016
EEA-PAM-513-A-33-EN49 🔺	105EC00014	3041111
EEA-PAM-513-A-33-EN53 🔺	105EC00015	6025852-001
EEA-PAM-513-B-33	105EC00016	02-326020
EEA-PAM-513-D-33	105EC00017	02-326037
EEA-PAM-523-A-33	105EC00018	02-326001
EEA-PAM-523-A-33-EN18	105EC00019	02-326116
	105EC00020	02-326021
EEA-PAM-523-C-33	105EC00021	02-326029
EEA-PAM-523-D-33	105EC00022	02-326038
EEA-PAM-523-E-33	105EC00023	02-326048
EEA-PAM-523-E-33	105EC00024	02-326057
EEA-PAM-525-A-33	105EC00025	02-326017
EEA-PAM-525-B-33	105EC00026	02-326022
EEA-PAM-525-C-33	105EC00027	02-326030
EEA-PAM-525-D-33	105EC00028	02-326039
EEA-PAM-525-E-33	105EC00029	02-326049
FFΔ-PΔM-525-F-33	105EC00030	02-326058
FFΔ-PΔM-533-Δ-33	105EC00031	02-326002
EEA-PAM-533-B-33	105EC00032	02-326023
EEA-PAM-533-C-33	105EC00033	02-326031
ΕΕΛ-ΡΔΜ-533-D-33	105EC00034	02-326040
ΕΕΛ-ΡΔΜ-533-Ε-33	105EC00035	02-326050
FFΔ-PΔM-533-F-33	105EC00036	02-326059
FFΔ-PΔM-535-Δ2-33	105EC00037	02-326104
ΕΕΛ-ΡΔΜ-535-Δ-33	105EC00038	02-326003
EEA-PAM-535-A-33-EN3	105EC00039	02-326172
EEA-PAM-535-R-33	105EC00040	02-326024
EEA-PAM-535-B-33-EN9 ▲	105EC00041	02-326101
ΕΕΛ-ΡΔΜ-535-C-33	105EC00042	02-326032
ΕΕΛ-ΡΔΜ-535-D2-33	105EC00042	02-326105
EEA_PAM_535_D_33	105EC00044	02-326041
	105EC00045	6029720 001
EEA-PAM-535-D-33-EN53	105EC00045	30/1101
	105EC00047	02 226051
EEA.PAM.535-E-33	105EC00049	02-326060
EEA DAM 5/1 A 22	105200040	02 320000
ELA-1 AIVI-341-A-33 EEA_PAM_5/1_D_22	1052000043	02-320000
EEA DAM 541 E 22	1052000000	02 320042
EEA DAM 552 A 22	1052000001	02 226004
LLATI AIVI-JJJJ-A-JJ	1032000032	02-320004

# EURO PAM card offerings

### Table 34. Continued

Model No	33- Series Assembly Number	32 -Series Assembly Number
EEA-PAM-553-A-33-EN14 🔺	105EC00053	02-326109
EEA-PAM-553-D-33	105EC00054	02-326043
EEA-PAM-553-D-33-EN27 🔺	105EC00055	02-326166
EEA-PAM-553-E-33	105EC00056	02-326053
EEA-PAM-561-A-33	105EC00057	02-326005
EEA-PAM-561-B-33	105EC00058	02-326025
EEA-PAM-561-C-33	105EC00059	02-326033
EEA-PAM-561-D-33	105EC00060	02-326044
EEA-PAM-561-E-33	105EC00061	02-326054
EEA-PAM-561-F-33	105EC00062	02-326061
EEA-PAM-568-A-33	105EC00063	02-326006
EEA-PAM-568-B-33	105EC00064	02-326026
EEA-PAM-568-C-33	105EC00065	02-326034
EEA-PAM-568-D-33	105EC00066	02-326045
EEA-PAM-568-E-33	105EC00067	02-326055
EEA-PAM-568-F-33	105EC00068	02-326062
EEA-PAM-571-A-33	105EC00069	02-326007
EEA-PAM-571-A-33-EN26	105EC00070	02-326165
EEA-PAM-571-A-33-EN55 🔺	105EC00071	3041197
EEA-PAM-571-B-33	105EC00072	02-326027
EEA-PAM-571-D-33	105EC00073	02-326046
EEA-PAM-581-A-33	105EC00074	02-326018
EEA-PAM-581-B-33	105EC00075	02-326028
EEA-PAM-581-C-33	105EC00076	02-326035
EEA-PAM-581-D-33	105EC00077	02-326047
EEA-PAM-581-D-33-EN3 🔺	105EC00078	02-326148
EEA-PAM-581-D-33-EN53 🔺	105EC00079	3041192
EEA-PAM-581-E-33	105EC00080	02-326056
EEA-PAM-581-F-33	105EC00081	02-326063
EEA-PAM-535-D-33 EN3 🔺	105EC00082	02-104849
EEA-EDC-436-D2-33	105EC00083	02-326130

# Special versions ( $\blacktriangle$ )

#### Table 35.

Details
SPECIAL VERSION OF EEA-PAM-535-A-33, EEA- PAM-535-D-33, EEA-PAM-581-D-33 WITH COMPATABILITY TO SWEDISH EMC STANDARDS
SPECIAL VERSION OF EEA-PAM-511-A-33 WITH 30 SECOND RAMP TIME
SPECIAL VERSION OF EEA-PAM-535-B-33 WITH MODIFIED RAMP TIME
SPECIAL VERSION OF EEA-PAM-553-A-33 WITH MODIFIED DITHER FOR BETTER SMALL STEP RESPONSE
SPECIAL VERSION OF EEA-PAM-523-A-33 WITH DIFFERENT DITHER SETTING FOR KTG PLUS VALVISTOR-SLIP-IN LOWER HYSTERESIS
SPECIAL VERSION OF EEA-PAM- 571- A-33WITH HIGHER DITHER
SPECIAL VERSION OF EEA-PAM-553-D-33 FOR ABB SWEDEN
SPECIAL VERSION OF EEA-PAM-513-A-33 WITH 24 HOUR RUN IN TEST CONFORMAL COATED PCB
SPECIAL VERSION OF EEA-PAM-535-D-33, EEA-PAM-581-D-33, EEA-PAM-513-A-33 WITH ONLY CURRENT COMMAND INPUT OF 4 MA20 MA
SPECIAL VERSION OF EEA-PAM-571-A-33 WITH 10 SECONDS RAMP TIME
SPECIAL VERSION OF EEA-PAM-535-D-33 WITH ONLY CURRENT COMMAND INPUT OF 4 MA20 MA

![](_page_59_Picture_0.jpeg)