

MLFB-Ordering data

6SL3210-1KE31-4AF1



Client order no. : Item no. :
Order no. : Consignment no. :
Offer no. : Project :
Remarks :

Rated data Input Number of phases Line voltage Line frequency Rated current (LO) Rated current (HO)	3 AC 380 480 V +10 % -20 % 47 63 Hz	Power factor λ Offset factor cos φ Efficiency η	0.90 0.95 0.99
Number of phases Line voltage Line frequency Rated current (LO)	380 480 V +10 % -20 % 47 63 Hz	Offset factor cos φ	
Line voltage Line frequency Rated current (LO)	380 480 V +10 % -20 % 47 63 Hz	·	0.99
Line frequency Rated current (LO)	47 63 Hz	Efficiency η	
Rated current (LO)			0.99
	424.00 4	Sound pressure level (1m)	68 dB
Rated current (HO)	134.00 A	Power loss	1.23 kW
nated current (110)	112.00 A	Filter class (integrated)	Class A
Output		Ambiant	conditions
Number of phases	3 AC	Ambient	CONTUNIONS
Rated voltage	400 V	Cooling	Air cooling using an integrated fan
Rated power IEC 400V (LO)	75.00 kW	Cooling air requirement	0.153 m³/s (5.403 ft³/s)
Rated power NEC 480V (LO)	75.00 hp		
Rated power IEC 400V (HO)	55.00 kW	Installation altitude	1000 m (3280.84 ft)
Rated power NEC 480V (HO)	60.00 hp	Ambient temperature	
Rated current (IN)	136.00 A	Operation	-20 40 °C (-4 104 °F)
Rated current (LO)	136.00 A	Transport	-40 70 °C (-40 158 °F)
Rated current (HO)	103.00 A	Storage	-40 70 °C (-40 158 °F)
Max. output current	206.00 A	Relative humidity	
Pulse frequency	2 kHz	Max. operation	95 % RH, condensation not permitted
Output frequency for vector control	0 240 Hz		
. , , ,		Closed-loop control techniques	
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parameterizable Yes	
		V/f with flux current control (FCC) Yes
Overload capability		V/f ECO linear / square-law	Yes
Low Overload (LO)		Sensorless vector control	Yes
150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a		Vector control, with sensor	No

Technical data are subject to change! There may be discrepancies between calculated and rating plate values.

300 s cycle time

300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a

No

No

Encoderless torque control

Torque control, with encoder



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		7	Figure similar
Mechanical data		Communication	
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP
Size	FSF	Co	nnections
Net weight	63.50 kg (139.99 lb)	Signal cable	
Width	305 mm (12.01 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Height	708 mm (27.87 in)	Line side	
Depth	357 mm (14.06 in)	Version	screw-type terminal
Inputs / out	tputs	Conductor cross-section	35.00 120.00 mm² (AWG 2 AWG -3)
Standard digital inputs		Motor end	
Number	6	Version	Screw-type terminals
Switching level: 0→1	11 V	Conductor cross-section	35.00 120.00 mm² (AWG 2 AWG -3)
Switching level: 1→0	5 V	DC link (for braking resistor)	
Max. inrush current	15 mA	Version	Screw-type terminals
Fail-safe digital inputs		Conductor cross-section	35.00 120.00 mm² (AWG 2 AWG -3)
Number	1		,
Digital outputs		Line length, max.	10 m (32.81 ft)
		PE connection	Screw-type terminals
Number as relay changeover contact	1	Max. motor cable length	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	300 m (984.25 ft)
Number as transistor	1	Unshielded	450 m (1476.38 ft)
Output (resistive load)	DC 30 V, 0.5 A	Si	tandards
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC

Switching threshold as digital input

0→1	4 V
1→0	1.6 V

Analog outputs

Number	1 (Non-isolated output)

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$



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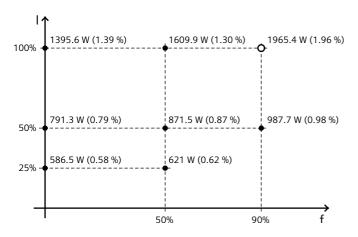
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% /	-0.42 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values