

MLFB-Ordering data

6SL3210-1KE23-8AP1



Figure similar

Client order no. :		
Order no. :		
Offer no. :		
Remarks :		

		7	• • •	.•	
Rated da	nta	General tech	n. specifica	tions	
Input		Power factor λ	0.70	0.85	
Number of phases	3 AC	Offset factor cos φ	0.95		
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.97		
Line frequency	47 63 Hz	Sound pressure level (1m)	66 d	В	
Rated current (LO)	48.20 A	Power loss	0.50	kW	
Rated current (HO)	45.20 A	Filter class (integrated)	Class	A	
Output			. 1		
Number of phases	3 AC	Ambien	t condition	S	
Rated voltage	400 V	Cooling	Air cooling	using an integrated fan	
Rated power IEC 400V (LO)	18.50 kW	Casling sings with a second	0.0103/-	(0.636 (13 1-)	
Rated power NEC 480V (LO)	25.00 hp	Cooling air requirement		(0.636 ft³/s)	
Rated power IEC 400V (HO)	15.00 kW	Installation altitude	1000 m (32	280.84 ft)	
Rated power NEC 480V (HO)	20.00 hp	Ambient temperature			
Rated current (IN)	38.00 A	Operation	-10 40 °C	(14 104 °F)	
Rated current (LO)	37.00 A	Transport	-40 70 °C	(-40 158 °F)	
Rated current (HO)	31.00 A	Storage	-40 70 °C	C (-40 158 °F)	
7		Relative humidity			
Max. output current	62.00 A		95 % At 40	95 % At 40 °C (104 °F), condensation and icing not permissible	
Pulse frequency	4 kHz	Max. operation	and icing n		
Output frequency for vector control	0 240 Hz				
		Closed-loop co	ontrol tech	niques	
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / paramete	erizable	Yes	
		V/f with flux current control (FCC	E)	Yes	
Overload capability		V/f ECO linear / square-law		Yes	
o verious cupubility					

Item no.: Consignment no. :

Project :

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load 300 s cycle time

current IH for 3 s,	followed by	150 % base	load current IH	for 57 s in a

Yes

No

No

No

Sensorless vector control

Vector control, with sensor

Encoderless torque control

Torque control, with encoder



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Mechanical	data	Com	munication
Degree of protection	IP20 / UL open type	Communication	PROFIBUS DP
Size	FSC	Connections	
Net weight	4.40 kg (9.70 lb)	Signal cable	
Width	140 mm (5.51 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Height	295 mm (11.61 in)	Line side	
Depth	203 mm (7.99 in)	Version	Plug-in screw terminals
Inputs / out	puts	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)
Standard digital inputs		Motor end	
Number	6	Version	Plug-in screw terminals
Switching level: 0→1	11 V	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6)
Switching level: 1→0	5 V	DC link (for braking resistor)	
Max. inrush current	15 mA	Version	Plug-in screw terminals
Fail-safe digital inputs		Conductor cross-section	6.00 16.00 mm ² (AWG 10 AWG 6)
Number	1	Line length, max.	15 m (49.21 ft)
Digital outputs		PE connection	On housing with M4 screw
Number as relay changeover contact	1	Max. motor cable length	Off flousing with MH sciew
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)
Number as transistor	1	Unshielded	150 m (492.13 ft)
Output (resistive load)	DC 30 V, 0.5 A	Standards	
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC
Switching threshold as digital in	out		
0→1	4 V		

Number

PTC/ KTY interface

Analog outputs

1 → 0

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

1.6 V

1 (Non-isolated output)



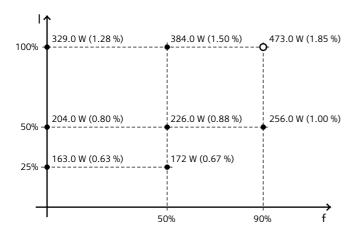
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-63.37 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values