

MLFB-Ordering data

6SL3210-1KE14-3UP1



Client order no. :	Item no. :
Order no. :	Consignment no. :
Offer no.:	Project :

Rated data		General tech. specifications	
nput		Power factor λ	0.70 0.85
Number of phases	3 AC	Offset factor cos φ	0.95
Line voltage	380 480 V +10 % -20 %	·	
Line frequency	47 63 Hz	Efficiency η	0.97
Rated current (LO)	5.50 A	Sound pressure level (1m)	52 dB
Rated current (HO)	4.50 A	Power loss	0.07 kW
	4.50 A	Filter class (integrated)	Unfiltered
Output		Ambient conditions	
Number of phases	3 AC		
Rated voltage	400 V	Cooling	Air cooling using an integrated fan
Rated power IEC 400V (LO)	1.50 kW	Cooling air requirement	0.005 m³/s (0.177 ft³/s)
Rated power NEC 480V (LO)	2.00 hp		·
Rated power IEC 400V (HO)	1.10 kW	Installation altitude	1000 m (3280.84 ft)
Rated power NEC 480V (HO)	1.50 hp	Ambient temperature	
Rated current (IN)	4.30 A	Operation	-10 40 °C (14 104 °F)
Rated current (LO)	4.10 A	Transport	-40 70 °C (-40 158 °F)
Rated current (HO)	3.10 A	Storage	-40 70 °C (-40 158 °F)
	6.20 A	Relative humidity	
Max. output current			95 % At 40 °C (104 °F), condensation
Pulse frequency	4 kHz	Max. operation	and icing not permissible
Output frequency for vector control	0 240 Hz	Classification	
		Closed-loop c	ontrol techniques
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parameterizable Yes	
		V/f with flux current control (FC	C) Yes
Overload capability		V/f ECO linear / square-law	Yes
Low Overload (LO)		Sensorless vector control	Yes
150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a		Vector control, with sensor	No

High Overload (HO)

300 s cycle time

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

No

No

Encoderless torque control

Torque control, with encoder



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			Figur	
Mechanical data		Com	Communication	
Degree of protection	IP20 / UL open type	Communication	PROFIBUS DP	
Size	FSA	Connections		
Net weight	1.70 kg (3.75 lb)	Signal cable		
Width	73 mm (2.87 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG	
Height	196 mm (7.72 in)	Line side		
Depth	203 mm (7.99 in)	Version	Plug-in screw terminals	
Inputs / out	puts	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG	
tandard digital inputs		Motor end		
Number	6	Version	Plug-in screw terminals	
Switching level: 0→1	11 V	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG	
Switching level: 1→0	5 V	DC link (for braking resistor))	
Max. inrush current	15 mA	Version	Plug-in screw terminals	
ail-safe digital inputs		Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG	
Number	1	Line length, max.	15 m (49.21 ft)	
igital outputs		PE connection	On housing with M4 screw	
Number as relay changeover contact	1	Max. motor cable length	g	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)	
Number as transistor	1	Unshielded	150 m (492.13 ft)	
Output (resistive load)	DC 30 V, 0.5 A	Standards		
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)			
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Vo Directive 2006/95/EC	
witching threshold as digital in	out			

Analog outputs

0→1

1→0

Number	1 (Non-isolated output)

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$

4 V

1.6 V



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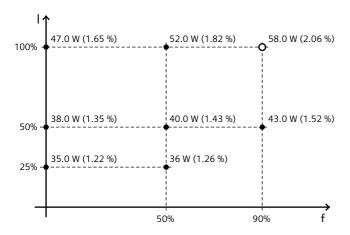
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-74.91 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values