

Direct starter, 3RM1, 500 V, 0 - 0.12 kW, 0.1 - 0.5 A, 24 V DC, screw terminals



Product brand name	SIRIUS
Product category	Motor starter
Product designation	Direct-on-line starter
Design of the product	with electronic overload protection
Product type designation	3RM1

General technical data	
Trip class	CLASS 10A
Product function	
• Intrinsic device protection	Yes
Suitability for operation Device connector 3ZY12	Yes
Power loss [W] for rated value of the current at AC in hot operating state per pole	0.01 W
Insulation voltage	
• rated value	500 V
Surge voltage resistance rated value	6 kV
maximum permissible voltage for safe isolation	
• between main and auxiliary circuit	500 V
• between control and auxiliary circuit	250 V
Protection class IP	IP20

<b>Shock resistance</b>	6g / 11 ms
<b>Vibration resistance</b>	1 ... 6 Hz, 15 mm; 20 m/s <sup>2</sup> , 500 Hz
<b>Operating frequency maximum</b>	1 1/s
<b>Mechanical service life (switching cycles)</b>	
• typical	30 000 000
<b>Reference code acc. to DIN 40719 extended according to IEC 204-2 acc. to IEC 750</b>	Q
<b>Reference code acc. to DIN EN 81346-2</b>	Q
<b>Reference code acc. to DIN EN 61346-2</b>	Q
<b>Product function</b>	
• direct start	Yes
• reverse starting	No
<b>Product function Short circuit protection</b>	No

### Electromagnetic compatibility

<b>Conducted interference</b>	
• due to burst acc. to IEC 61000-4-4	3 kV / 5 kHz
• due to conductor-earth surge acc. to IEC 61000-4-5	2 kV
• due to conductor-conductor surge acc. to IEC 61000-4-5	1 kV
• due to high-frequency radiation acc. to IEC 61000-4-6	10 V
<b>Electrostatic discharge acc. to IEC 61000-4-2</b>	4 kV contact discharge / 8 kV air discharge
<b>Conducted HF-interference emissions acc. to CISPR11</b>	Class B for the domestic, business and commercial environments
<b>Field-bound HF-interference emission acc. to CISPR11</b>	Class B for the domestic, business and commercial environments

### Safety related data

<b>Protection against electrical shock</b>	finger-safe
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### Main circuit

<b>Number of poles for main current circuit</b>	3
<b>Design of the switching contact as NO contact for signaling function</b>	OUT, electronic, 24 V DC, 15 mA
<b>Adjustable pick-up value current of the current-dependent overload release</b>	0.1 ... 0.5 A
<b>Minimum load [%]</b>	20 %
<b>Type of the motor protection</b>	solid-state
<b>Operating voltage</b>	
• rated value	48 ... 500 V
<b>Relative symmetrical tolerance of the operating voltage</b>	10 %
<b>Operating frequency 1 rated value</b>	50 Hz
<b>Operating frequency 2 rated value</b>	60 Hz

<b>Relative symmetrical tolerance of the operating frequency</b>	10 %
<b>Operating current</b>	
<ul style="list-style-type: none"> <li>• at AC at 400 V rated value</li> </ul>	0.5 A
<ul style="list-style-type: none"> <li>• at AC-53a at 400 V at ambient temperature 40 °C rated value</li> </ul>	0.5 A
<b>Ampacity when starting maximum</b>	4 A
Operating power for three-phase motors at 400 V at 50 Hz	0 ... 0.12 kW

### Inputs/ Outputs

<b>Input voltage at digital input</b>	
<ul style="list-style-type: none"> <li>• at DC rated value</li> </ul>	24 V
<ul style="list-style-type: none"> <li>• with signal &lt;0&gt; at DC</li> </ul>	0 ... 5 V
<ul style="list-style-type: none"> <li>• for signal &lt;1&gt; at DC</li> </ul>	15 ... 30
<b>Input current at digital input</b>	
<ul style="list-style-type: none"> <li>• with signal &lt;0&gt; typical</li> </ul>	0.001 A
<ul style="list-style-type: none"> <li>• for signal &lt;1&gt; typical</li> </ul>	0.011 A
<b>Input current at digital input</b>	
<ul style="list-style-type: none"> <li>• for signal &lt;1&gt; at DC</li> </ul>	11 mA
<ul style="list-style-type: none"> <li>• with signal &lt;0&gt; at DC</li> </ul>	1 mA
Number of CO contacts for auxiliary contacts	1
<b>Operating current of auxiliary contacts at AC-15 at 230 V maximum</b>	3 A
<b>Operating current of auxiliary contacts at DC-13 at 24 V maximum</b>	1 A

### Control circuit/ Control

<b>Type of voltage of the control supply voltage</b>	DC
<b>Control supply voltage 1</b>	
<ul style="list-style-type: none"> <li>• at DC rated value</li> </ul>	24 V
<b>Operating range factor control supply voltage rated value at DC</b>	
<ul style="list-style-type: none"> <li>• initial value</li> </ul>	0.8
<ul style="list-style-type: none"> <li>• Full-scale value</li> </ul>	1.25
<b>Control current at DC</b>	
<ul style="list-style-type: none"> <li>• in standby mode</li> </ul>	25 mA
<ul style="list-style-type: none"> <li>• when switching on</li> </ul>	150 mA
<ul style="list-style-type: none"> <li>• during operation</li> </ul>	70 mA

### Response times

<b>Switch-on delay time</b>	60 ... 90 ms
<b>Off-delay time</b>	60 ... 90 ms

### Installation/ mounting/ dimensions

<b>Mounting position</b>	vertical, horizontal, standing (observe derating)
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<b>Mounting type</b>	screw and snap-on mounting onto 35 mm standard mounting rail
<b>Height</b>	100 mm
<b>Width</b>	22.5 mm
<b>Depth</b>	141.6 mm
<b>Required spacing</b>	
<ul style="list-style-type: none"> <li>• with side-by-side mounting <ul style="list-style-type: none"> <li>— forwards 0 mm</li> <li>— Backwards 0 mm</li> <li>— upwards 50 mm</li> <li>— downwards 50 mm</li> <li>— at the side 0 mm</li> </ul> </li> <li>• for grounded parts <ul style="list-style-type: none"> <li>— forwards 0 mm</li> <li>— Backwards 0 mm</li> <li>— upwards 50 mm</li> <li>— at the side 3.5 mm</li> <li>— downwards 50 mm</li> </ul> </li> </ul>	

#### Ambient conditions

<b>Installation altitude at height above sea level</b>	
<ul style="list-style-type: none"> <li>• maximum 4 000 m</li> </ul>	
<b>Ambient temperature</b>	
<ul style="list-style-type: none"> <li>• during operation -25 ... +60 °C</li> <li>• during storage -40 ... +70 °C</li> <li>• during transport -40 ... +70 °C</li> </ul>	
Relative humidity during operation	10 ... 95 %
<b>Air pressure</b>	
<ul style="list-style-type: none"> <li>• acc. to SN 31205 900 ... 1 060 hPa</li> </ul>	

#### Communication/ Protocol

<b>Product function Bus communication</b>	No
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#### Connections/ Terminals

<b>Type of electrical connection</b>	screw-type terminals for main circuit, screw-type terminals for control circuit
<ul style="list-style-type: none"> <li>• for main current circuit screw-type terminals</li> <li>• for auxiliary and control current circuit screw-type terminals</li> </ul>	
<b>Type of connectable conductor cross-sections</b>	
<ul style="list-style-type: none"> <li>• for main contacts <ul style="list-style-type: none"> <li>— solid 1x (0,5 ... 4 mm<sup>2</sup>), 2x (0,5 ... 2,5 mm<sup>2</sup>)</li> <li>— finely stranded with core end processing 1x (0,5 ... 4 mm<sup>2</sup>), 2x (0,5 ... 1,5 mm<sup>2</sup>)</li> </ul> </li> <li>• at AWG conductors for main contacts 1x (20 ... 12), 2x (20 ... 14)</li> </ul>	
<b>Connectable conductor cross-section for main contacts</b>	

<ul style="list-style-type: none"> <li>• single or multi-stranded</li> <li>• finely stranded with core end processing</li> </ul>	0.5 ... 4 mm <sup>2</sup> 0.5 ... 4 mm <sup>2</sup>
<b>Connectable conductor cross-section for auxiliary contacts</b> <ul style="list-style-type: none"> <li>• single or multi-stranded</li> <li>• finely stranded with core end processing</li> </ul>	0.5 ... 2.5 mm <sup>2</sup> 0.5 ... 2.5 mm <sup>2</sup>
<b>Type of connectable conductor cross-sections</b> <ul style="list-style-type: none"> <li>• for auxiliary contacts <ul style="list-style-type: none"> <li>— solid</li> <li>— finely stranded with core end processing</li> </ul> </li> <li>• at AWG conductors for auxiliary contacts</li> </ul>	1x (0,5 ... 2,5 mm <sup>2</sup> ), 2x (1,0 ... 1,5 mm <sup>2</sup> ) 1x (0.5 ... 2.5 mm <sup>2</sup> ), 2x (0.5 ... 1 mm <sup>2</sup> ) 1x (20 ... 14), 2x (18 ... 16)
<b>AWG number as coded connectable conductor cross section</b> <ul style="list-style-type: none"> <li>• for main contacts</li> <li>• for auxiliary contacts</li> </ul>	20 ... 12 20 ... 14

Certificates/ approvals

<b>General Product Approval</b>	<b>EMC</b>	<b>Declaration of Conformity</b>
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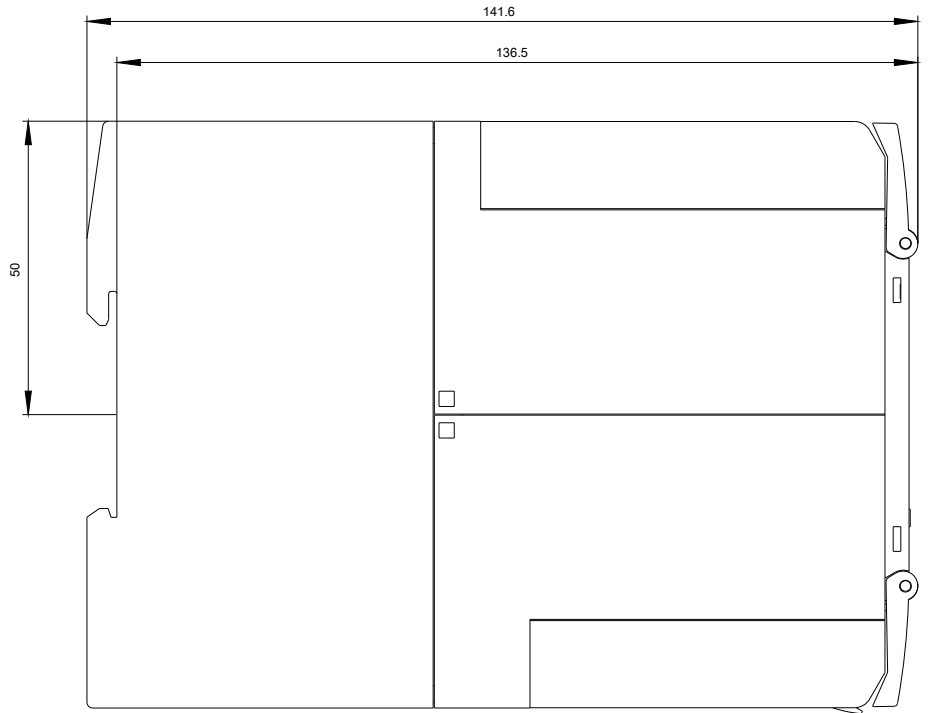
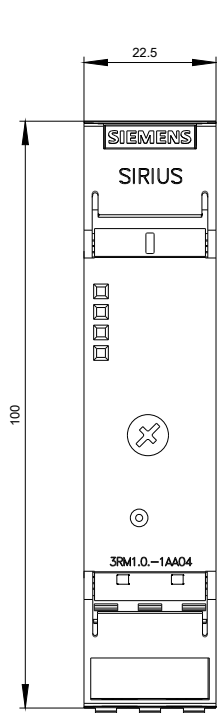


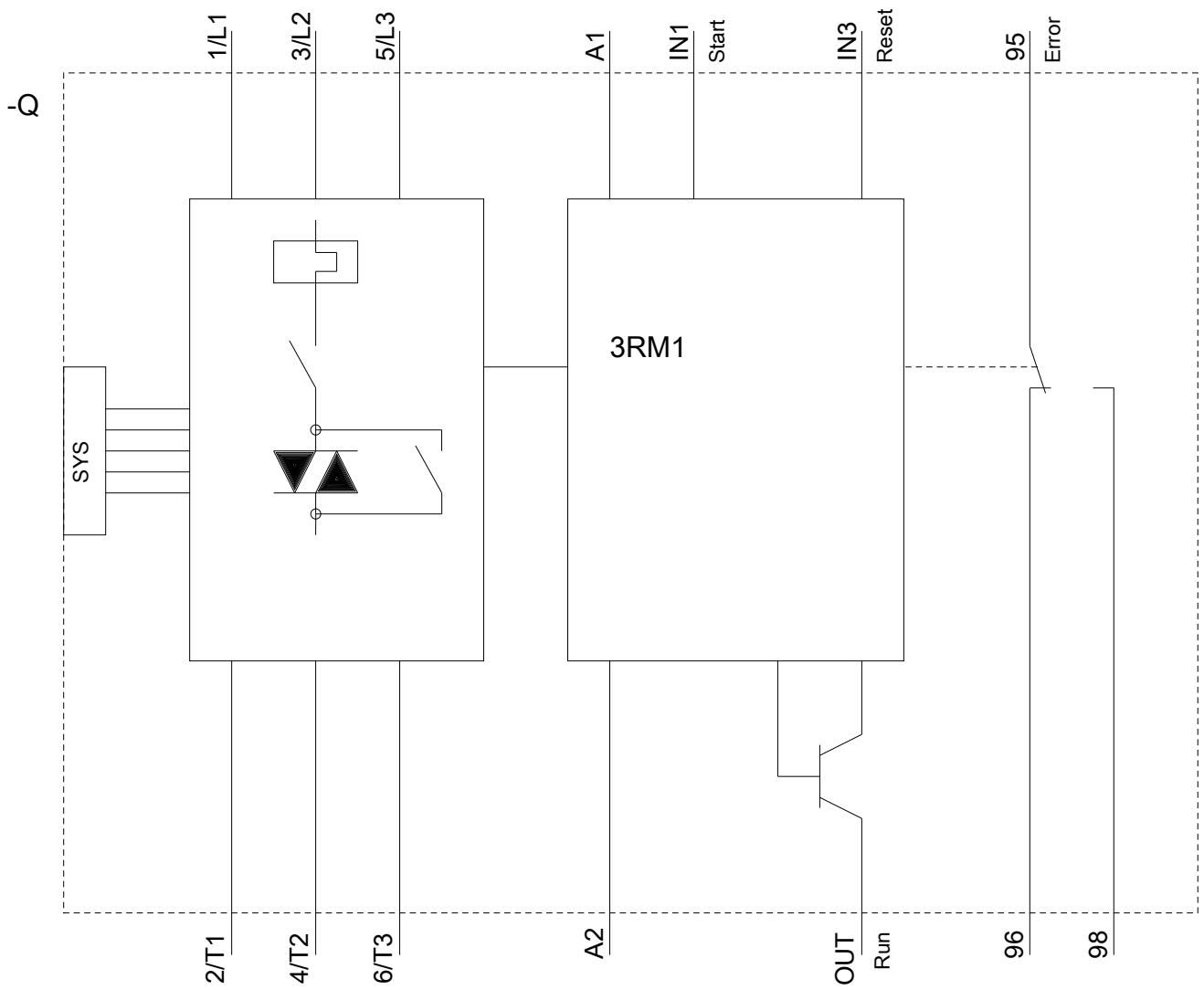
<b>Declaration of Conformity</b>	<b>Test Certificates</b>	<b>other</b>	<b>Railway</b>
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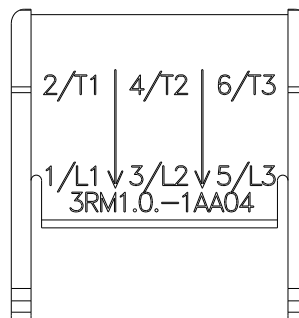
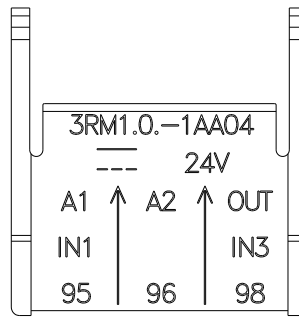
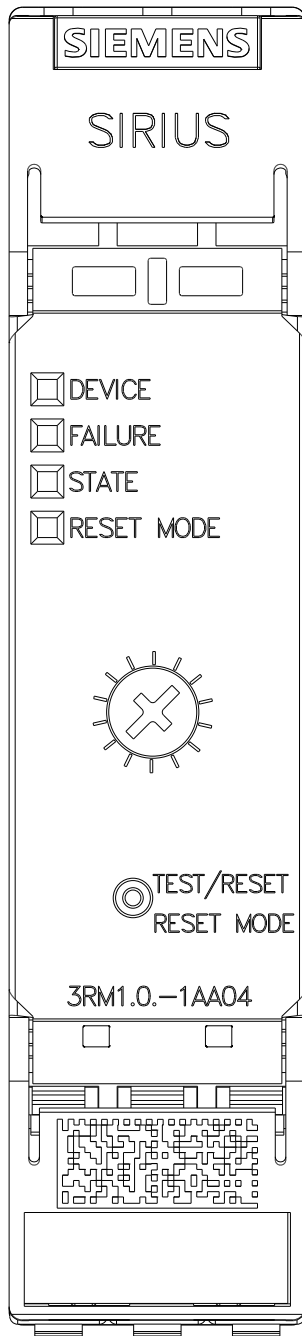
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