# MAP - MRP Series

## **Magnetic Gripper for Automation**

These permanent magnets cover individual needs and can be fitted for nearly all surfaces.

They get switched within very short cycle time by pneumatic impulse.



MAP-40







#### Application

surfaces

- For round and flat workpieces
- For workpieces with irregular
- For thin and thick sheets
- Suitable for automation, lifting operations, robotic technology, welding and clamping technology

#### **Features**

- Sector 2 Sec
- Maintenance-free
- Highest safety
- Sompressed air demand 5 8 bar
- 😕 IP Code 67
- Special pole shoes for special surface

Technical data	Dimensions [Ø x H] or [L × W x H]	Load SWL 3:1	Min. thickness	Min. Ø	● Load SWL 3:1	Required diameter	Max. residual gripping capacity (magnet OFF)
	[mm]	Fh [kg]	[mm]	[mm]	Fh [kg]	[mm]	[kg]
MAP-6	Ø 35 x 35	6	>4				0,03
MAP-40	Ø 65 x 50	40	>8				0,2
MAP-120R	Ø 120 x 80	120	>25	Ø > 0	70	Ø > 200	6
MAP-180	Ø 120 x 82	180	>25				6
MRP-28NK	80 x 55 x 126	84	>12	> 12	36		0,3
MRP-46	80 x 55 x 82,5	46	>12	Ø > 20	30	Ø > 120	4
MRP-130F	120 x 103 x 120	130	>25				40
MRP-170	103 x 120 x 140	170	>25	Ø > 25	120	Ø > 120	30



### **Professional advantages**

- Switchable permanent magnets with 3-times safety
- Custom-made pole shoes can be fitted to special forms
- 😌 Low residual magnetism
- Very short switching time by air pressure pulse
- Low energy consumption





MAP-120R

Gripping ca-



MRP-28NK



MRP-46

pacity ver- sus material thickness	<u> </u>		Load with thickness of:			Load with airgap of:				
and airgap	Load SWL 3:1	Min. thickness	2 mm	4 mm	8 mm	0,1 mm	0,2 mm	0,4 mm	Weight	No.
	Fh [kg]	[mm]		[kg]			[kg]		[kg]	
MAP-6	6	>4	12	18	18	8,1	4,5	2,2	0,19	63448
MAP-40	40	>8	22	57	120	79	58	34	0,95	63450
MAP-120R	120	>25	19	60	175	310	270	200	5,80	64324
MAP-180	180	>25	26	80	224	360	270	167	5,80	64333
MRP-28NK	84	>12	28	56	82	126	75	38	2,60	66289
MRP-46	46	>12	36	91	122	100	72	36	1,80	65011
MRP-130F	130	>25	40	119	300	340	300	260	9,50	65707
MRP-170	170	>25	47	147	400	460	410	300	10,7	64823