



21st Century Assessment & Differentiated Learning



Director of Curriculum
Development

PCS Edventures, Inc.



Jon Bender





**We make
children's lives
better through
engaging
educational
experiences.**



PCS Edventures: What do we do?



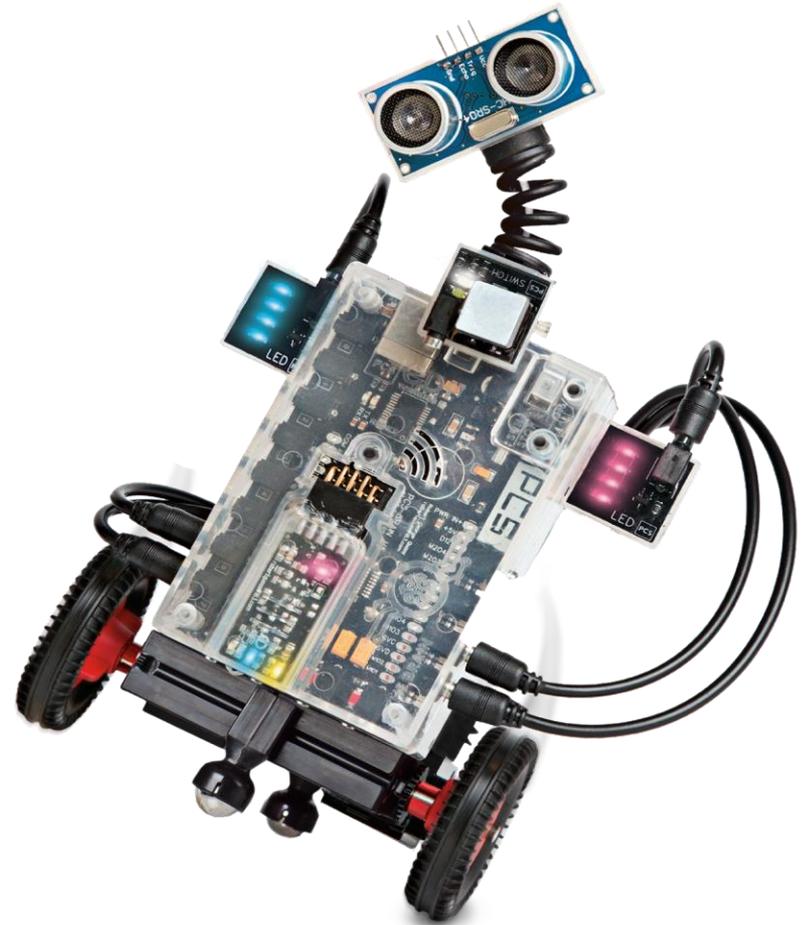
Improve the lives of 10,000,000 children per year with what we do.

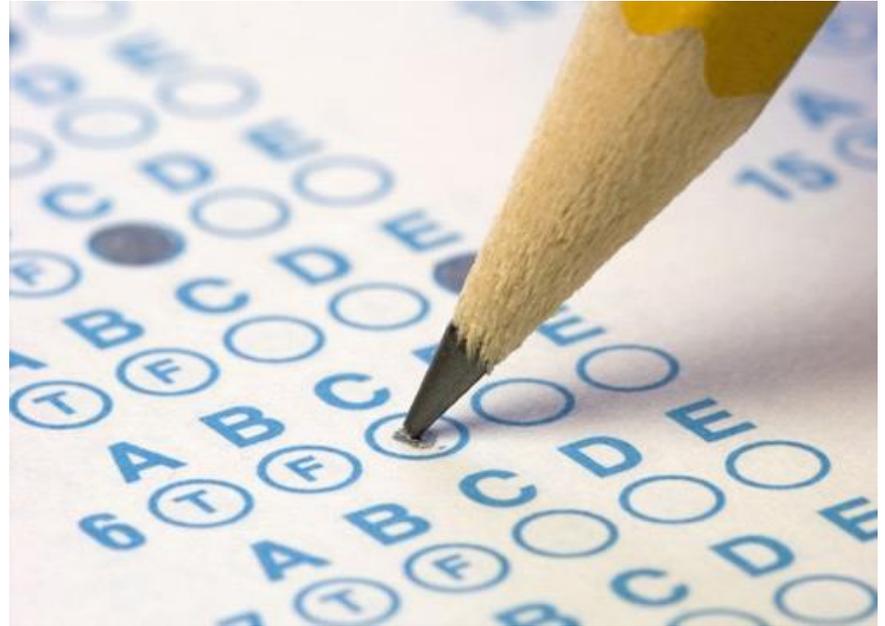
- Leader in K–12 robotics education
- PCS STEM products in every elementary classroom
- Establish a global network of Edventures Labs
- Build a virtual community of experiential learners



What's to come?

- Traditional Assessment
- Process Assessment
- Objectives-Driven Curriculum + Assessment
- Journaling & Portfolio
- Project-Based Learning (PBL)
- Pedagogical Needs
- Curriculum Solutions
- Winner of 1 set of LABCards!

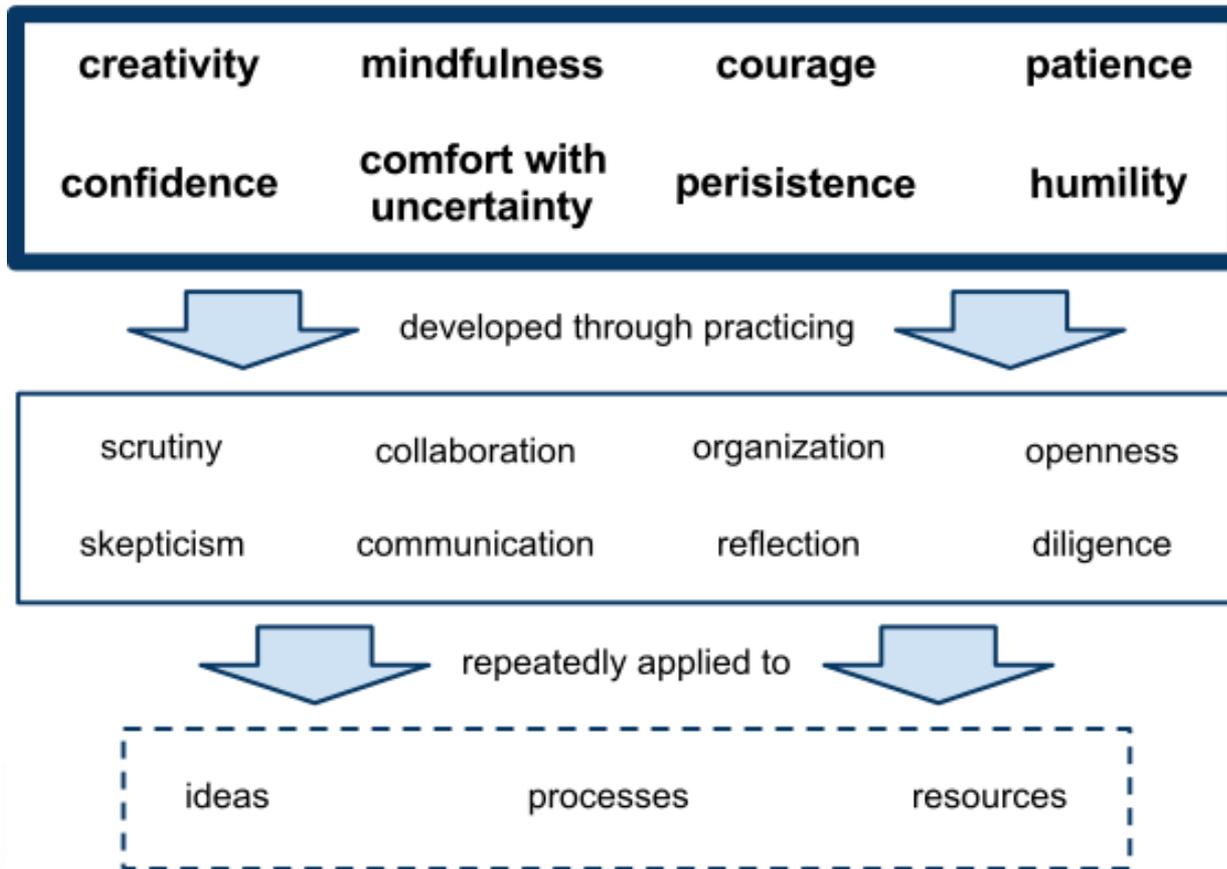




Benefits vs. Drawbacks



Development



Implementation

Status Rubric (how am I doing now?)

<u>Skill/Character:</u>	<u>beginning</u>	<u>developing</u>	<u>succeeding</u>
academic persistence - what do you do when you're frustrated? Do you independently pursue understanding?	I tend to try one or two things. I give up more easily than I should	I try to stick with things, but I sometimes feel unsuccessful. Sometimes I seek new approaches to help.	I look for new ways to think about a problem. I find a way to persist despite obstacles
intellectual courage - how do you respond to uncertainty? What do you do when you're feeling overwhelmed (which can be scary)? Do you take intellectual risks?	I don't like to try things unless I'm reasonably certain what the outcome will be	I take some risks, but I sometimes miss out on good opportunities	I <u>make a decision to trust</u> that I'll learn something from each experience, even if I'm unsure at times.
mental resourcefulness - where do you turn for ideas? Are you open to new ideas? Do you look for connections between ideas? Do you apply past experiences to new situations?	When something seems unfamiliar, I often assume it's not useful.	There have been times when I disregarded new ideas before considering them fully. I don't often see connections between what I'm doing and what I've done	I always try to consider ideas and sources, even if they <u>seem odd or surprising at first</u> . I often relate new ideas to old ones.
communication – can you clearly convey an idea to someone else?	It seems like others don't understand what I'm	I can usually convey my ideas, but often, others don't seem to	When I'm not feeling understood, I search for new

Individualized Learning

Progress Rubric (how am I growing as a learner?)

Skill:	beginning	developing	succeeding
identification - do you recognize when something about your behavior and methods needs to change?	some of the time. I don't take the time to think about what happened or what is happening much	most of the time. I'm generally reflective and like to prevent problems from recurring	almost every time. I'm in the business of growing and learning from mistakes. When something goes wrong, it's an opportunity to learn and grow.
implementation - when you've recognized an area that requires attention, what do you do?	I <u>sometimes</u> dismiss or ignore it for a while, hope it goes away by itself, or think "I should really do something about that"	I tell myself what needs to happen, and think of some ways to get it done.	I create a plan with concrete steps , then proceed to get organized. Later, I <u>check in</u> to see that I'm following the plan.
consistency - once you have made an action plan for change, one that will work, how long do you stick to it?	Maybe a week at most. Habits are nearly impossible for me to change.	I can usually keep it up for a while, but then my efforts start to dwindle	I'm pretty good at making change stick, though I might modify (improve) the plan as necessary. When I commit to something, I mean it
connections - when you want to change your habits, do you enlist the support of your community?	I tend to go it alone	I sometimes tell people about what I'm working on	I keep people informed as I go about the very <u>difficult</u> job of making positive changes. When possible, I ask others for support.
frequency - how often do you evaluate your growth as a learner?	rarely	about every couple of weeks	at least weekly
self-compassion - when you're having trouble making a change, what do you do?	I often feel like giving up. small setbacks can have a big impact on me	I try harder, in hopes that I can do better	I modify my approach and/or seek resources to support my success. I recognize that <u>change is difficult</u> and that small/incremental progress is worth celebrating

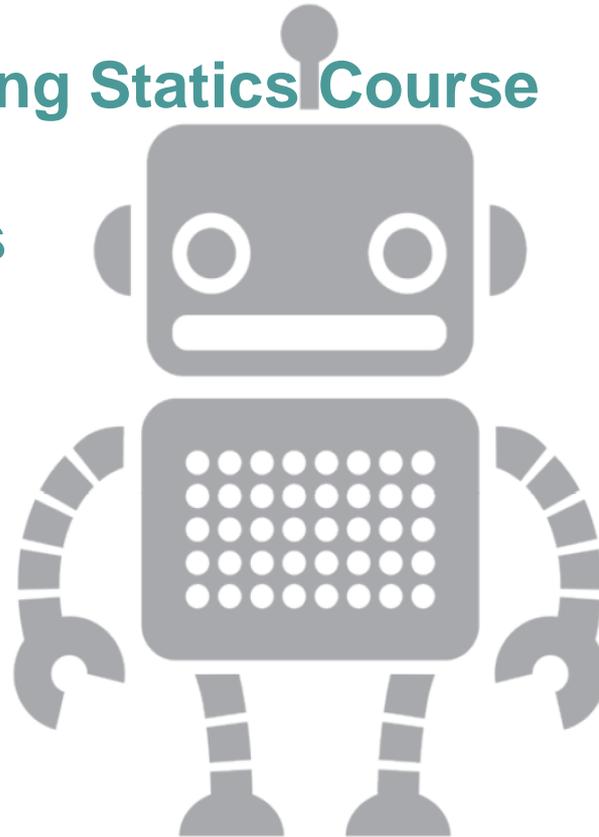
Logistical Constraints



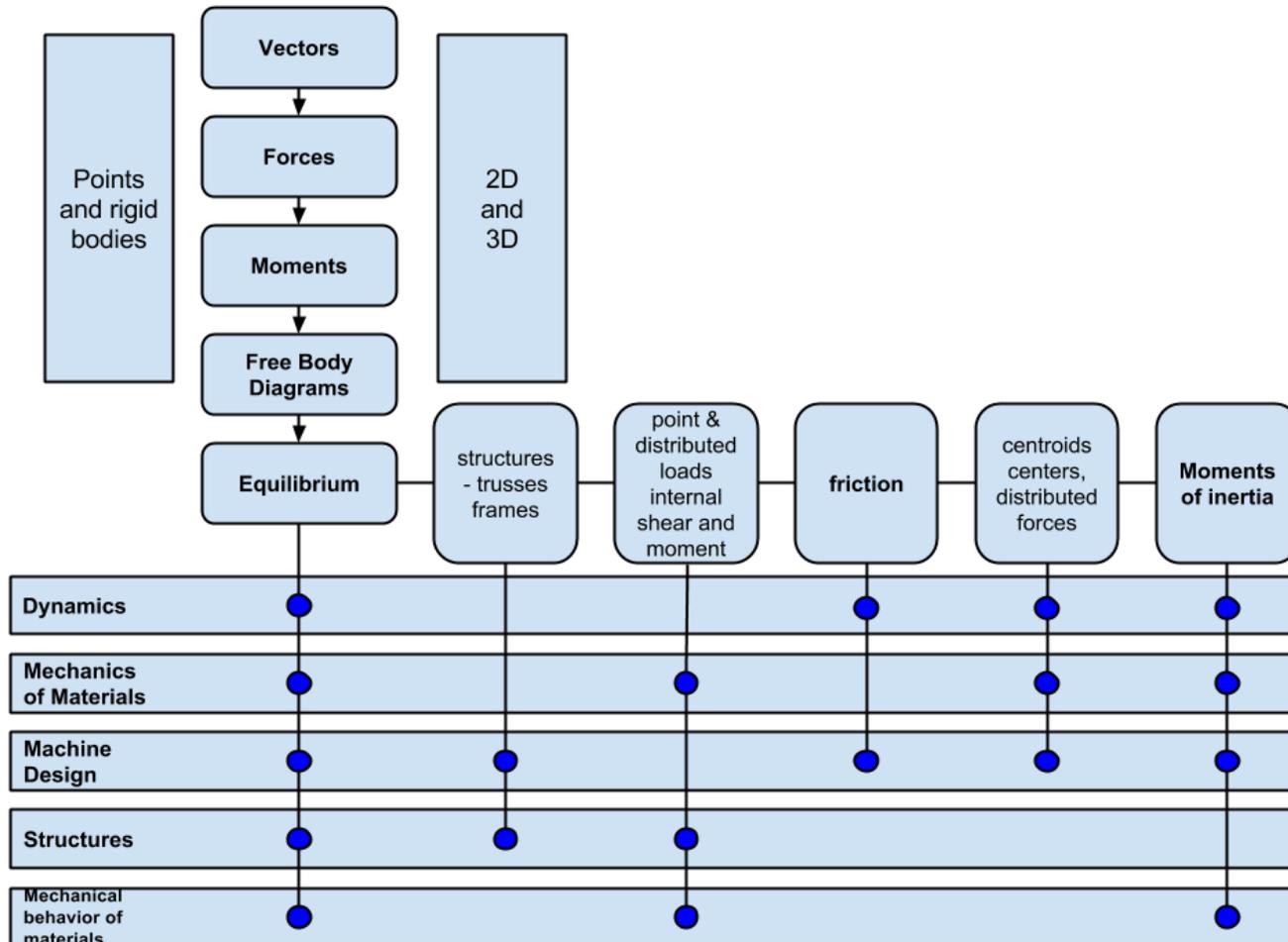
College Engineering Statics Course

Content Mandates

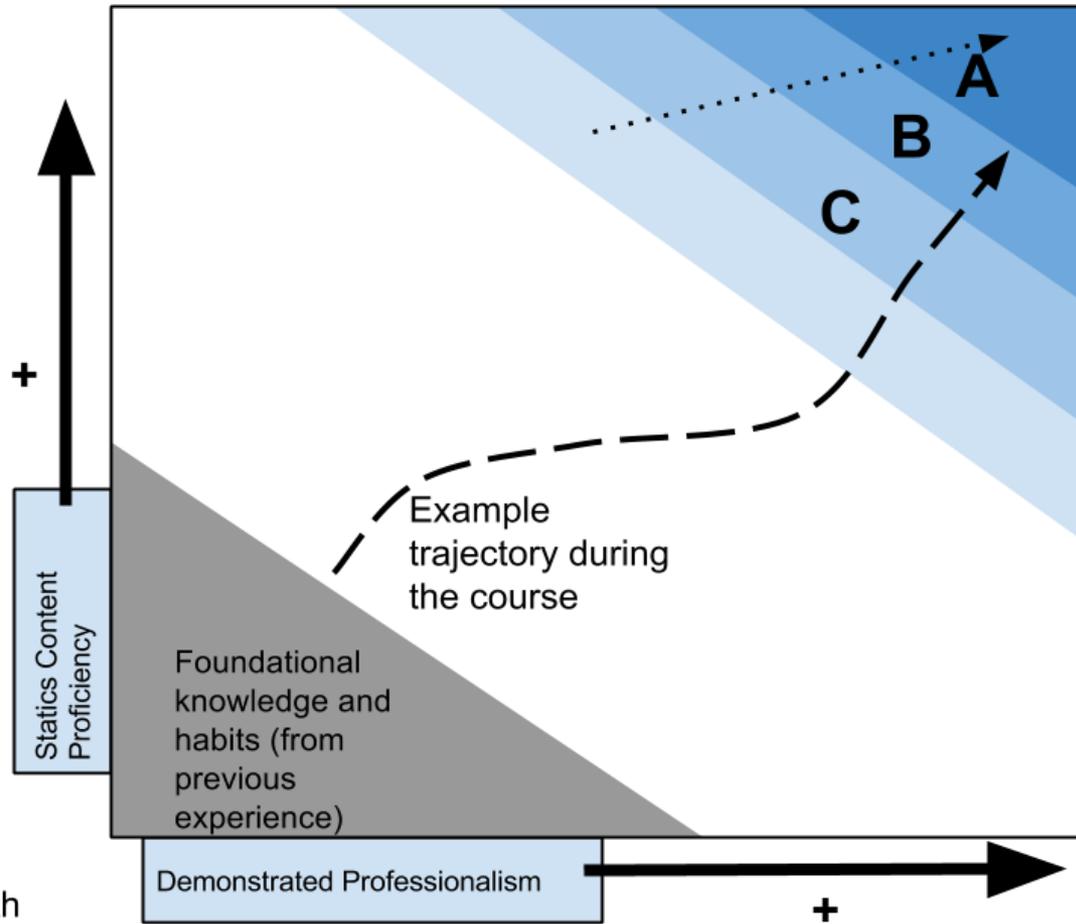
Large class size



Course Structure



Learning arc



Demonstrated personal growth

Pre assessment

The moment of a force 1

* Required

This door is typical, with hinges visible. You are looking down from the top (imagine directly down, I wanted the hinges visible so I actually took the pic at an angle)

Gallery + ↶ ↷ ↻ 📄 ⚙️ ⓘ

There are 2 forces, F_1 and F_2 . F_1 acts on the middle of the door with 100 lb of force, and F_2 acts on the free end of the door, with a force of 50 lb. *

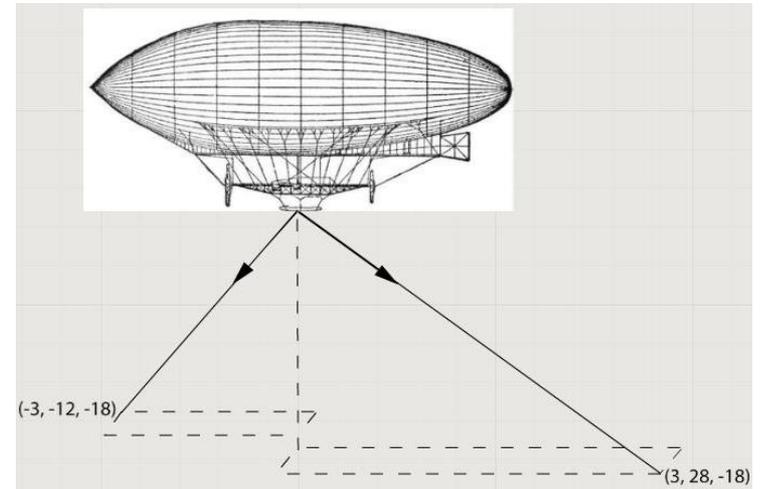
What do you think the door will do?

- Rotate clockwise (F_1 wins)
- Rotate counter-clockwise (F_2 wins)
- Remain stationary (the forces will balance)
- Other:

Last name *

Submit

Assessment



- ___ Vector notation
- ___ 2D vector addition
- ___ 3D vector addition
- ___ Equilibrium (forces)
- ___ Unit vectors



The Common Core concentrates on a clear set of math skills and concepts. Students will learn concepts in a more organized way both during the school year and across grades. The standards encourage students to solve real-world problems.



PREPARING AMERICA'S STUDENTS FOR COLLEGE & CAREER



ITERATIVE DISCOVERY ENGINEERING PROCESS

**TRIAL
& ERROR**



**ACADEMIC
ANALYSIS**

MOST EFFICIENT



A decorative graphic consisting of a teal outline of a rectangular shape on the left, with several dotted lines extending from it in various directions across the top and left sides of the page.

JOURNALING & REFLECTION

Rationale

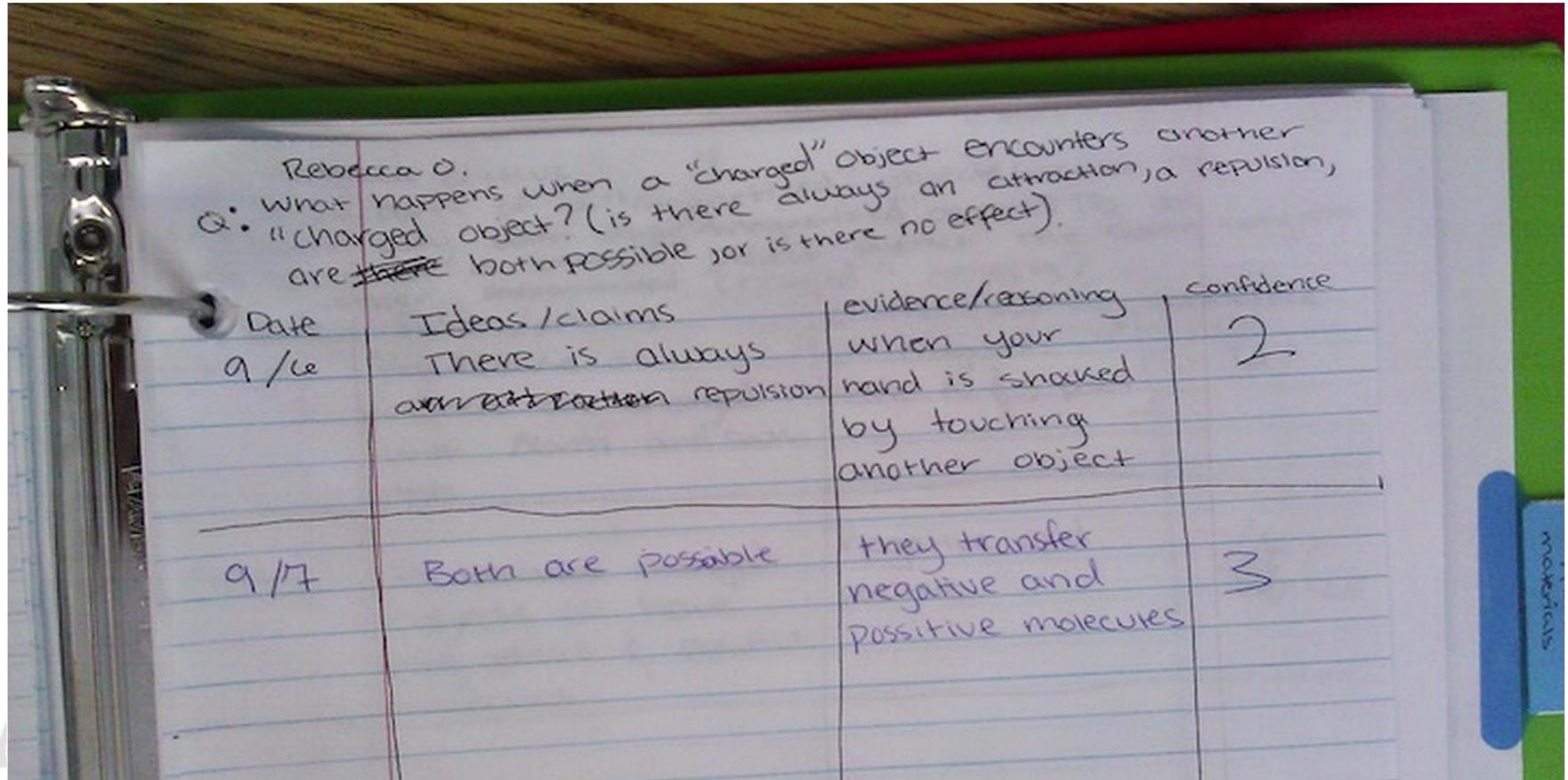
Reflection is another means of adding value to a learning experience. Both content and meta-level insight are available through the process of evaluating your work after it has been done. We recommend that journaling be a central and significant part of this curriculum. Our journal structure is by no means the only one that accomplishes the goals of reflection; we provide it as a default—a starting point. If students are already journaling in the classroom, we encourage modification to our prompts and categories to fit into the existing structure.

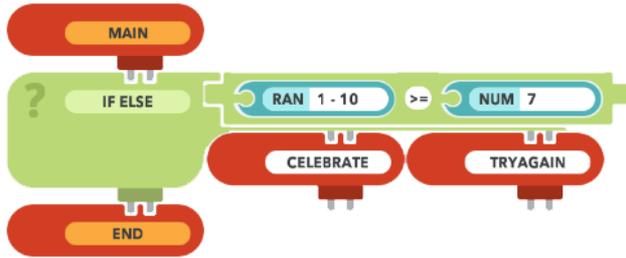
Journaling and Portfolio

- Varying degrees of management and control
- Authentic accountability is best

YOUR NAME:		UNIT NAME:	
QUESTIONS / HYPOTHESES:			
TESTS / EXPERIMENTS PERFORMED:		RESULTS:	







edventures! LABCards

1 Programming for Robotics 5

2 Programming for Robotics 5

3 Programming for Robotics 5

4 Programming for Robotics 5

Card 2 Overview
Global
Some code
span to all
they are.

Card 3 Overview
LEDP and
REPEAT on
physical LD

Card 4 Overview
LEDS, LIGHT ON and LIGHT OFF
Lights are used all the time in robotics. The Brain has many lights that indicate its functions. Learn to use LEDs and RIO with LIGHT ON and LIGHT OFF as indicators, or just to give RIO more personality!

P1 Turning the LED LIGHT ON
Lights can be used to indicate things, such as a warning light for a vehicle or to add visual effects to brighten a project.
This is an LED, which stands for light emitting diode, and like most lights, they can be controlled through programming. LEDs must be used in ports 0 through 5 (6 and 7 are input only) as they require output from the Brain.

P2
LEDs are repeating in most pre-p program files.
Open Cortex
This has M
turn ON F
and then M
turn ON F
immediat

P3
Compile and
program
results.

LEDs
The sensor cable is used to connect The Brain to the LED in the same way a touch sensor is connected.
LED lights do not turn on automatically when connected, they must be programmed using Cortex.
Open Cortex and go to the Blue SENSOR command tab to locate the LIGHT ON and LIGHT OFF commands.
These commands allow you to turn on and off LEDs connected to the corresponding sensor ports.

Light ON
Create the program to the left:
Add the LIGHT ON command under MAIN, followed by a WAIT and NUM 20, 2 seconds.
Compile and run this program which turns the LED LIGHT ON.
The LED turns on for NUM 2 seconds (using WAIT) before the program ends and the light turns off.
The LIGHT ON stays for the remainder of the program because it is a global command, the LIGHT ON remains until told to turn off, or the program ends.

LEVEL ONE SCHEDULE

- Project 1: Build and Program a Motor Test Station
 - Connect It
- Challenge 1: Create 3 Programs
 - Reflect
- Project 2: This Way/That Way
 - Challenge 2: This Way/That Way
 - Reflect
- Personal Project: Computational Multitasking
 - Reflect
- Key Concepts

LEVEL 1: Programming for Robotics



Project 1

Build and Program a Motor Test Station

In this project students build a **DC motor** testing station, connect everything properly and identify all **ports** and **cables**. Also begin writing the first set of commands in Cortex.

Example Project

1

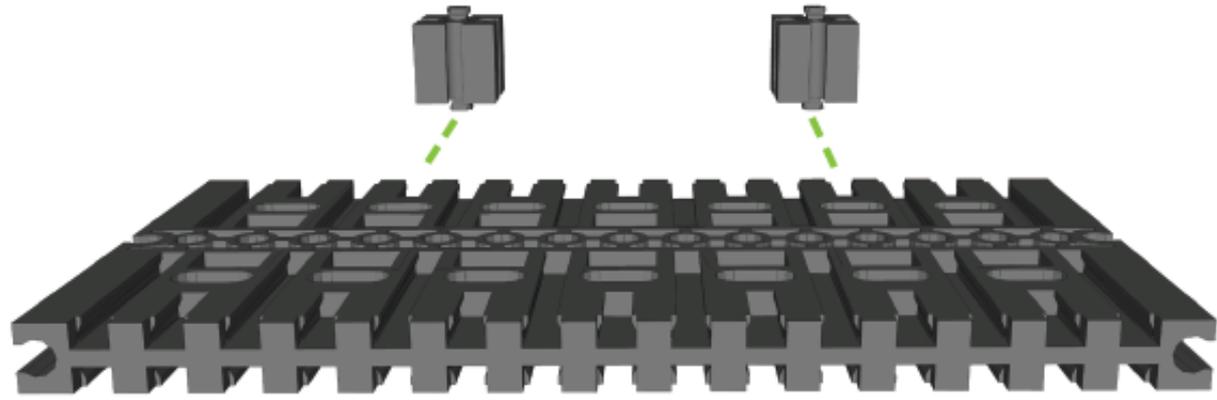


x1

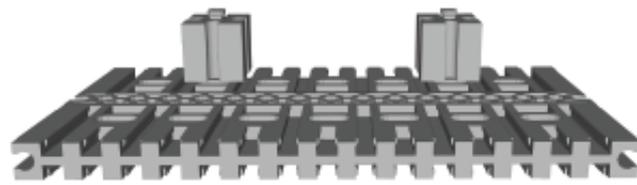


x2

All steps have an "exploded view" which helps with assembly.



The assembly should look like this before proceeding to the next step.



Challenge 1

Create Three Programs



LEVEL 1: Programming for Robotics

Using your motor testing station, create three separate programs to do the following:

Program 1: Make motor A run for 10 seconds and motor B run for 5 seconds.

Program 2: Make motor B run for 5 seconds and then reverse for 8 seconds.

Program 3: Make motors A and B run simultaneously for 5 seconds and then reverse simultaneously for 5 seconds.

Adjust the value of **NUM** so that the wheel spins around exactly 3 times and stops where it started.

Try the same challenge for motor B. Is the value that you used for motor A lesser (<), greater (>) or equal (=) to the value used in motor B for the same result? Explore the answer in the next challenge.





Personal Project

Computational Multitasking

Computers are great at following instructions; often better than our own bodies. Program four different motors to do four different things, but have them all run at the same time. Decide what four actions to program the motors to do. Here are the requirements:

1. Add two more motors to the motor testing station.
 - a. Decide how to connect them to the baseplate and be sure all motors are facing the same direction so that you can see how they run differently or the same.
 - b. All motors should be plugged into the **ports** and named A, B,C and D.
2. Before actually writing the program, predict exactly what you would like to happen to each motor (record the goals in your journal).
 - a. You must demonstrate the appropriate use of each command you learned about (**MOTOR**, **REVERSE**, **THIS WAY**, **THAT WAY**, **SET PWR** and **ON FOR**).

This project requires that students combine groups and use two kits (so they'll have four motors). You may have them simply take turns using the motor sets, but write individual codes in Cortex.

Extension

1. Using a stopwatch and 60cm line previously measured and marked with tape, calculate the **speed** of your **robot** at maximum power (remember that one motor will probably need to run with less than 100% to get a straight line).

$$\text{Speed} = \text{Distance} / \text{Time}$$

2. Once you have decided on a method of figuring this out, share it with at least one other group. The goal is to agree that your method, and theirs, work. Do not calculate the **speed** until you are confident of the method (at least an 8 out of 10 confidence).

*For this activity, produce a table on a board in the front of the room where each group can post their speed. The purpose of this extension is to discuss sources of error, comparing random (e.g. motor variability) vs. **systematic** (e.g. measurement/precision error). Secondly, this will provide some exposure to the inherent variability of the mechanical elements of their robots. They will refer to this later when they explain some of the difficulties that they might encounter with the more advanced programs.*



Granular in Nature

Programming for Robotics

P2 Switch the polarity/direction of motors.

- Switch the red and black ends of your motor cables between MOTOR(s) A & B and run the same program again.
- This changes the polarity and thus the direction of the motor. You can use this to adjust motors in order to achieve your goals; for example, if you wish to make both wheels default to forward.



C1 Make RiQ drive in a straight line and return to its original position. Adjust the speed and (if needed) the polarity of one or both motors.

C2 Program RiQ to drive in a curve starting and ending in the same position. Figure out how to make it by experimenting with RiQ's speed and (if needed) the polarity of one or both motors.

DP Now that you have a program that makes RiQ go in a straight line, program RiQ to go in a curve and/or trickier and/or more complex paths.

Key Terms

- Program: A collection of commands that tell the robot what to do.
- Polarity: The direction of the motor cables (red and black) and the direction the motor(s) will turn.
- SET PWR: A command that sets the power level of the motor(s).

Check For Understanding

- How do you create a program in Cortex?
- What do MAIN & END do in your program?
- What new commands did you use in this level?
- If RiQ's wheels are running in opposite directions, what should you check?

Programming for Robotics

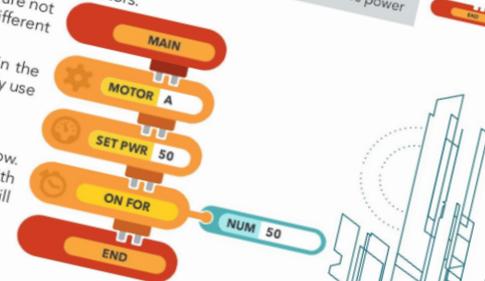
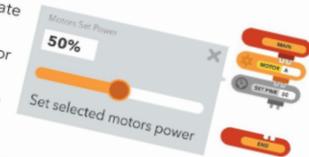
Badge Overview

Robotics incorporates mechanical engineering, electrical engineering, and computer science, which deals with the design, construction, operation, and application of robots. The world of robotics is vast, and provides endless possibilities for those who pursue it!

P1 Use set power command to drive RiQ in a straight line.

- Open Cortex and click on your user profile, then click on new program. Create the program pictured below.
- Use the SET PWR command, which is found under the Orange motor command tab.
- Open the motor commands tab and drag the SET PWR command onto the user interface canvas.
- You use SET PWR to set the power differently for your motors.

- All motors are set to run at 100% power, but all motors are not created equally. Even if they are new they may run at different speeds.
- To adjust the power, click on the SET PWR command in the canvas and type the value into the dialogue box or simply use the slider (see picture left).
- Compile and run the program.
- You'll notice that MOTOR A is moving much more slowly now. You can adjust output power in this way, when working with DC operators (motors in this case). Motor B, meanwhile, is still running at the default 100% power.





Programming for Robotics

5
POINTS
FOR EDP

Yellow Level Overview

Robotics incorporates mechanical engineering, electrical engineering and computer science - all of which deal with the design, construction, operation and application of robots. The world of robotics is vast and provides endless possibilities!

Robotics Level 1 introduces the hardware used for RiQ including The Brain microcontroller and DC motors. Program The Brain and RiQ using the Cortex programming environment in the following projects. Learn the basics of motor control through an introduction to the language and logic used by computers.



Skills & Learning Objectives

Card 1:

RiQ: Introduction to fischertechnikTM and PCS Robotics: The Brain and Cortex
Build with fischertechnikTM manipulatives, start basic programming with The Brain in Cortex software.

5 POINTS

Card 2:

Cortex, New Project, New User, Save and Bluetooth Connectivity
Create a new project and new user as you write and save your first program.

5 POINTS

Card 3:

Motor Commands: **ON** and **ON FOR**
Learn motor control and adjust the motors on RiQ.

5 POINTS

Card 4:

Motor Controls: **SET PWR** and **MOTOR** polarity
More advanced motor commands are added to your programming skill set.

5 POINTS

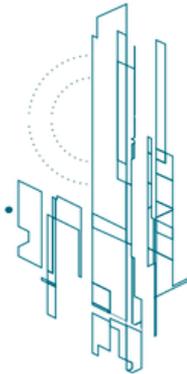


End Design Project / EDP *

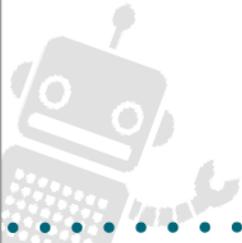
Now that you understand basic motor control, demonstrate your mastery by programming RiQ to draw a recognizable shape using the Engineering Design Process; plan your program, test and modify until it works. The only criteria for your drawing is that a peer or instructor can look at the shape and quickly identify it!

** After completing the skills and activities on cards 1-4, return to this final project to test the knowledge you've gained throughout the yellow level.*

5 POINTS



PCS edventures! LABCards



- After school programs, libraries, maker spaces, home use, and student-driven classrooms.
- Easy to follow activities push students to expand and create.
- Mastery through incremental concept acquisition



There are limitless opportunities to incorporate new assessment techniques into your different educational programs. Let us help you uncover yours!

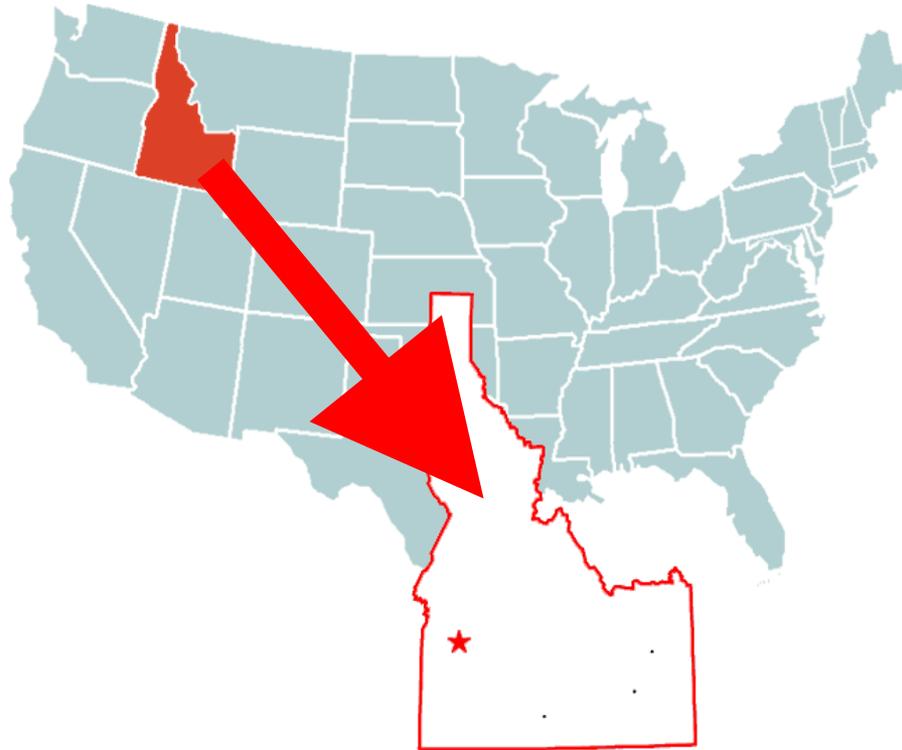
Questions?



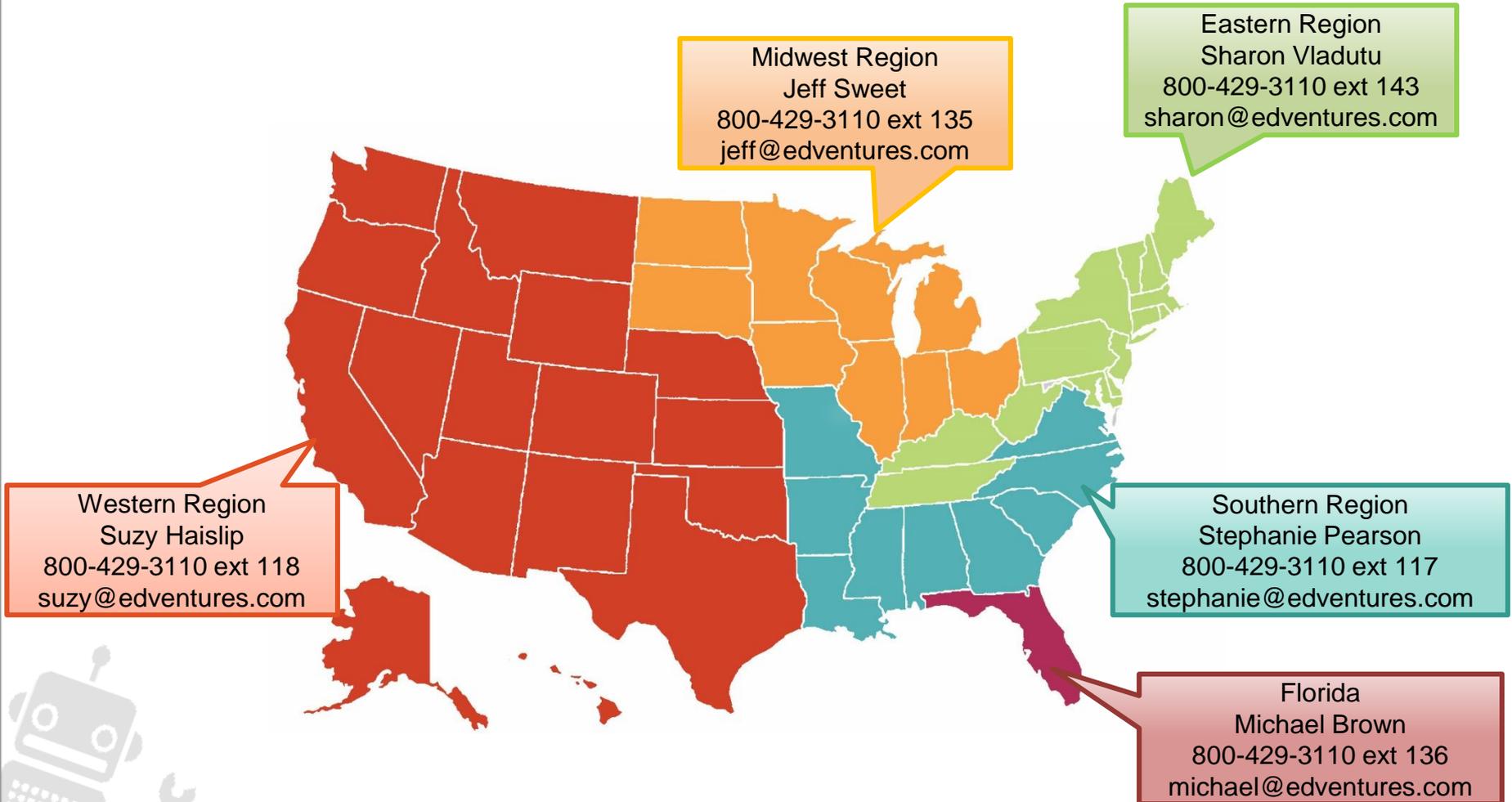
**And the winner of one set of
3D Printing LABCards is...**



Where Can You Find Us?

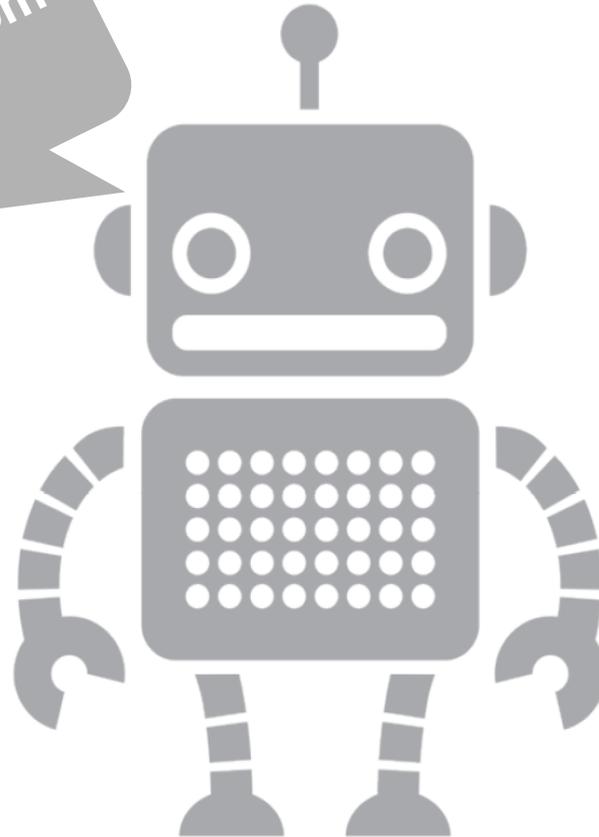


PCS in Your Neighborhood



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Thank you!

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