



VALBIA ELECTRIC ACTUATOR S86 VB015M INSTALLATION AND MAINTENANCE INSTRUCTIONS MANUAL

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1.0 Warnings

- Please read the following instructions before making any installation of the actuator. The damages caused from the non-observance of these instructions are not covered in the warranty.
- This documentation must be kept in dry place and available for use.
- The actuator is an electronic device and during its working operations some parts are live components. The installation and maintenance of electric actuator must be made only by qualified personnel, in accordance with current electrical engineering and safety standards and all other applicable directives.
- Valbia S.r.l. reserves the right to change the data and the characteristics of this manual at any time and with no notice in the scope of a constant updating and technological improvement.
- The symbol / indicates that the instruction that follows is relevant for safety and if not observed it could pose a danger for the user or damages the actuator.

A WARNING: the mechanical and electronic parts, according to which the device is designed, are not eligible for modifications.

2.0 Transportation and storage

Valbia electric actuators are supplied in paperboard boxes which are of solid construction for a normal transport. Handle with care and keep the cover until the moment of the installation of the actuator. The storage of the actuators requires a covered, dry and ventilated environment, protected from temperature changes. The device must be stored with the cover mounted. Prior to installation, visual inspection is recommended to detect any anomalies caused by transport or storage.

3.0 Field application

VALBIA electric actuators have been designed and tested to ball and butterfly valves and dampers for the industrial sector. Actuators are available in standard version with rotation 0°-90°. On request we can supply actuators with rotation 0°-180° or 0°-270°. For applications other than that above are needed please contact VALBIA sales department.

4.0 Valve automation

The mechanical assembling between the electric actuator and the item to be automated (for example: the valve) can be done by direct mounting or by a mounting kit. Both the cases you can verify the right alignment and the correct dimensions of the part to transmit the power to avoid axial stress which can damage valve and actuator. All Valbia electric actuators are in conformity of norm EN ISO 5211 (DIN 3337). In order to have a right automation of the valve, is necessary to use a Valbia electric actuators whose range has a torque of at least 25% over the valve maximum torque. Verify the actuator duty rating suitability with the application.



WARNING: do not raise up or moved the motorized valve by using the electric actuator as point of grip or hold.



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5.0 Specifications and technical information

TECHNICAL INFORMATION	DATA		
Object of device	Electric Actuator		
Enclosure material	Aluminum alloy		
Coating	Standard polyester powder coating		
Enclosure rating	IP68		
Duty cycle	75%		
Duty cycle 12V	50%		
Ambient temperature range	-20°C ÷ +55°C -4°F ÷ +131°F		
Maximum operating altitude	2000 meters		
Relative umidity	95%		
Auxiliary limit switches	1 A @ 250Vac - 1 A @ 30 Vdc (resistive load)		
Fault auxiliary contact	1 A @ 120Vac - 1 A @ 24 Vdc (resistive load)		
Power terminal block type	Plug in connector		
Auxiliary terminal block type	Fixed connector		
Section of terminal block's conductors	14 ÷ 22 AWG 2.08 ÷ 0.32 mm ²		
Minimum conductors' temperature	+85°C		
Protection class against electric shock	Class I		
Restriction of continue operation time (timeout)	Standard		
Power supply voltage tolerance	± 10%		
Multiple parallel actuators wiring	Standard (*)		
Cables entries	2 x M20 x 1.5 2 x ½" NPT		
Standard stroke	90°		
Position indicator	Dome indicator		
Manual override	Standard		

(*) It is important to verify that the application and its components are properly sized with the actuator characteristics and requirements.

GENERAL FEATURES OF THE ELECTRIC ACTUATOR FOR UL STANDARD				
UL listedfienumber	NMTR.E303174			
Enclosure Type	Type 4x (*)			
Connection conductor/wires	Listed flexible cord (ZJCZ) minimum SW or SJW 6÷12mm diameter			
Green terminal block screws maximum tightening capacity of model 100-240 Vac	0.56Nm	5Lbln		
Black terminal block screws maximum tightening capacity of model 100-240 Vac	0.50 Nm	4.50 Lbln		
100-240 Vac 0.50 Nm 4.50 LbIn Terminal block screws maximum tightening capacity of model 12-24 Vac/dc	0.50 Nm	4.50 LbIn		
Enclosure screws maximum tightening capacity	11.30 Nm	100 Lbln		
External pollution degree	3			
Internal pollution degree	2			
Overvoltage category	2			

Product in conformity with the European Community norms LOW VOLTAGE 2014/35/UE (LVD) ELECTROMAGNETIC COMPATIBILITY 2014/30/UE (EMC) MACHINERY 2006/42/CE ROHS 2011/65/UE REGULATION N° 1907/2006 (REACH) Use copper (CU) conductor

(*) in order to guarantee the declared "Type", the following models of electric connectors should be used: HSK-M (1.609.1200.70) or HSK-K (1.209.1202.70) produced by Hummel AG (E103997). On request the cable glands can be supplied by Valbia.





5.1 Technical features

Technical characteristics of Valbia electric actuators as below:

- Heater: all actuators are standard equipped with heater to avoid condensation into the actuator (paragraph 6.3).
- a safety system detects when the actuator supplies a torque higher than expected (torque limiter): the device makes three triggering attempts. In case of negative results, it makes a short rotation in the opposite direction to relieve the mechanical tension to the gears. The torque limiter intervention is indicated by a red color LED (paragraph 6.4) and by the opening of the remote signal an auxiliary contact (paragraph 6.2).
- a safety system intervenes to shut off the actuator in case the motor works past over the allowable operation time value (the time value depends on the actuator models). The maximum working time fault is indicated by a red color LED (paragraph 6.4) by the opening of the auxiliary contact of the remote signal (paragraph 6.2).
- duty rating: the electric actuator was designed to work with a nominal duty rating of 75%, referred to the working time, the maximum temperature and to the nominal load. This parameter defines the rest time after an operation. The use of the actuator with a higher duty rating or with a temperature above 55°C (131°F) can cause the improper torque limiter intervention or the failure of electronic components.
- "Captive" cover screws are permanently attached to the cover and simplify installation in awkward conditions.

5.2 Power requirements and current draw information

MODEL	VB015M		
Nominal torque [Nm]	15		
Nominal torque [LbIn]	133		
Nominal voltage (version H) [V]	100 ÷ 240Vac		
Absorbed current (version H) [A]	0.22-0.12		
Absorbed power (version H) [VA]	22-28.8		
Nominal voltage (version L) [V]	12Vac/dc	24Vac/dc	
Absorbed current (version L) [A]	1.9 - 1.1	0.8 - 0.5	
Absorbed power (version L) [VA]	23 - 13.5	20 - 12	
Frequency [Hz]	50/60		
Rotation time	9		
0° - 90° [sec]			

6.0 Installation instruction



Fig.1 External view of the actuator

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MARNING: the actuators should be properly grounded and wired in accordance with local electrical code.

WARNING: before performing any maintenance on the actuator, always make sure to shut off the power supply first.

MARNING: make sure that the power supply is set between the values indicated as indicated on the label on the side of the actuator.

WARNING: Valbia electric actuators may be mounted in many positions, however, we do not suggest using it with the cable glands positioned upright, since it cannot guarantee a perfect wiring tightness. We also recommend to avoid using it with the indicator facing down. If the actuator assembly and the respective electrical connection are provided in different moments, make sure that the cable entries are hermetically sealed.

WARNING: please ensure suitably rated cable glands and protection plug are used, according to IP protection rating. Properly seal the electrical connectors to prevent any liquid and dust infiltration. Warranty is voided if this warning is not respected. The cables must be of the appropriate size to the type of electrical connector selected. Verify the correct tightening of the electrical connectors.

WARNING: if the device is used not respecting the manufacturer specifications, the provided protection may be impaired. For the wiring, it is necessary to open the upper cover "A" in order to locate the terminal block on the power supply board.

MARNING: before opening the upper cover shut down the power supply voltage. To remove the upper cover "A" untighten the screws "B" and

make sure to avoid collisions with the internal electrical parts. Insert the power supply cables inside the lower enclosure entries "C", tighten by the user. The terminal block "F" is composed by two parts, one of which removable. To simplify the procedure, it is possible to remove the removable part, wiring it and insert it once the wiring is done. Proceed to the cable connections in the appropriate terminal block "F" following the wiring diagram (paragraph 6.1 or 10.0).

WARNING: please pay attention during the wiring and setting phases of the electromechanical limit switches, in order to avoid fluids or other substance from getting on or around any electronic components. Moreover, before assembling the upper cover please make sure that the O-ring is seated in the proper groove and there are no impediments that could compromised the enclosure sealing.

6.1 Power / command wirings

The wiring diagram, which should be followed for proper wiring of the actuators, is shown in paragraph 10.0 and it can be found also on the label inside in modothe upper cover. Please follow the maximum allowed electrical rating values. The terminal block "F" is shown in Fig. 2. The cables through the connector must be of the proper size.

- the signal cable of "closing (clockwise rotation)" (positive supply +24Vdc or phase 24Vac / 100-240Vac) must be connected to the terminal "1" of the terminal-block "F".
- the signal cable of "opening (counter-clockwise rotation)" (positive supply +24Vdc or phase 24Vac / 100-240Vac) must be connected to the terminal "3" of the terminal-block "F".
- the signal cable "common" (0V / neutral) must be connected to the terminal "2" of the terminal-block "F".
- the grounding cable must be connected to the properly signaled terminal.

In addition to the 3-points control mode, the 2-points control mode is also available.

MARNING: the ground wiring system is mandatory (Fig.2).

MARNING: the actuator has not any built-in power supply switch disconnector, therefore such device must be inserted in the electric plant and must be clearly identified. It shall be marked as switch disconnector of the actuator.







Fig.2 power supply board, focus on terminal block "F"

6.2 Auxiliary switches wirings

The "G" terminal block is connected to two auxiliary and independent limit switches (SPDT free contacts), FCU1 and FCU2, which indicate the position of the actuator to the final user.

Connect to the terminal block "G" between the following terminals:

- "B" and "C" to obtain the signal of closing position.
- "E" and "H" to obtain the signal of opening position.

The opening or closing signal comes when the blue cams push the auxiliary electromechanical limit switch on the logic board. The cams adjustment procedure is described on paragraph 6.5.

WARNING: during the installation (in the limit switch positions) it is recommended to verify the alignment between limit switch cams and auxiliary limit switch cams by using a multimeter/tester.

The terminal block "R" is connected to a free contact NO which closes in case of powered actuator and no detected anomaly. In case of anomalies or not powered actuator, the contact is open. Terminal block "R" is composed by two parts, one of which removable for easier wiring. To simplify the procedure, it is possible to remove the removable part, wiring it and insert it once the wiring is done.



Fig.3 Control/logic board, focus on terminal blocks "G" and "R"



Heating resistor



6.3 Heating resistor

All the actuators are equipped with "RIS" heating resistor which works only if the actuator is connected to the power supply, when the motor is not rotating and the temperature inside the actuator goes down to 25°C / 77°F. It protects the actuator from the formation of condensation due to temperature changes. The resistor is part of the electronics, it does not require additional wiring and it is disabled when the internal temperature exceed 25°C / 77°F.

WARNING: to guarantee the normal operation of the resistor, it is necessary to keep the actuator connected to the power supply even in the open/close positions.



Fig.4 Heating resistor

6.4 Signal lamp unit

- On the power supply board there is a green LED indicating that the power is on.
- On the logic board there is a multicolor LED which indicates the following actuator modes.

WORKING STATE	LED COLOR	FLASHING DURATION (sec)	PAUSE BETWEEN FLASHES (sec)
Actuator powered in limit switch position	green	0.1	0.9
Actuator powered in rotation	green	0.6	0.4
Power shut off in limit switch position	yellow	0.1	0.9
Power shut off in rotation	yellow	0.6	0.4

Every anomaly has a different number of flashes of the RED led on the logic board:

ANOMALY	EFFECT	NUMBER OF FLASHES	FLASHING DURATION (sec)	PAUSE BETWEEN FLASHES (sec)	PAUSE BETWEEN FLASHING CYCLES (sec)
Torque limiter alert	Actuator block	1			
Max torque alert	Actuator block	2			
Minimum threshold voltage alert	Resettable	3	0.1	0.3	1
Time-out operation intervention alert	Actuator block	4			
Fault driver alert	Actuator block	5			

WARNING: to reset the anomalies it is recommended to shut off the power supply for more than 10 seconds to ensure the full discharge of the capacitors on the electronic boards.



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6.5 Setting actuator stop positions

The opening or closing operation of the electric actuator is reached when the black cams push the electromechanical limit switches on the logic board (POS1 for closing position and POS2 for opening position). The signal of opening and closing operation is obtained when the blue cams push the electromechanical limit switches on the logic board.

The procedure necessary to adjust the actuator stroke is the following:

1. M make sure that the power supply is off;

2. remove the upper cover of the actuator (paragraph 6.0);

3. make sure that the automated device (for instance the valve) is in the "OPEN" position. For a more accurate and precise adjustment, use the square for manual override "Q" (paragraph 7.0);

4. loosen the set screw in the cam 1 (black color), and rotate the cam until it pushes the limit switch POS2 and until the "click" of the electromechanical micro switch. Then tighten the set cam screws;

5. loosen the set screw in the cam 3 (blue color), and rotate the cam until it pushes the limit switch FCU2 and until the "click" of the electromechanical micro switch). Then tighten the set cam screws;

6. use the square for manual override "Q" (paragraph 7.0) to rotate the actuator to the "CLOSED" position and jump to instruction 8.; **OR** close the actuator with the upper cover, power it on and carry out the closing operation;

7. Mait for the completion of the closure maneuver, shut off the power supply and remove the upper cover of the actuator (paragraph 6.0);

8. make sure that the automated device (for instance the valve) is in the "CLOSED" position. For a more accurate and precise adjustment, use the square for manual override "Q" (paragraph 7.0);

9. loosen the set screw in the cam 2 (black color) and rotate the cam until it pushes the limit switch POS1 and until the "click" of the electromechanical micro switch. Then tighten the set cam screws;

10. loosen the set screw in the cam 4 (blue color) and rotate the cam until it pushes the limit switch FCU1 and until the "click" of the electromechanical micro switch. Then tighten the set cam screws.



Fig.5 Limit switches cams and auxiliary cams

6.7 Actuator cover assembly

- After making proper connection, please proceed to the assembling of cover "A" (Fig.1), by paying close attention not to hit any electronic parts;
- secure the cable tightening by screwing the electrical connector;
- complete the closure of cover "A" by tightening the captive screws "B";

In case of difficulties in assembling the upper cover, it is recommended to:

- untighten the three dome indicator screws "D" and remove the dome transparent cover;
- remove the open/closed plastic insert;
- mount the upper cover "A" making sure the shaft is properly positioned in the hole;
- reposition the indicator "D" in the proper position on the shaft, place the transparent dome and tighten the three screws.





7.0 Manual override

The actuator is supplied with a 10mm (0.39In) square "Q" manual override located on the bottom cover (Fig.6). There are no selectors to switch from automatic to manual mode and vice versa. To manually move the actuator, it is enough to remove the supply voltage and to rotate the square by means of a special tool. The direction of rotation of the square is clockwise for the opening and counter clockwise for the closing.



Fig.6 Square for manual override

WARNING: the usage of manual override when the actuator is powered can damage the device.

MARNING: during the operation of the actuator, the square "Q" is always rotating.

WARNING: if the actuator exceeds the stroke range by the manual override, to restore it is necessary to power the actuator and command in any direction until it returns to any limit switch position.

8.0 FAIL-SAFE OPERATION WITH BATTERY BACKUP (OPTIONAL)

The versions with battery of Valbia electric actuator use battery packs with series of cells in NiMh technology and nominal voltage on terminals at 24Vdc. For the actuators with battery back-up, VALBIA can set up the actuator to automatically carry out one of the following actions in the event of power outage:

• Opening: the in-progress/current operation is interrupted.

• Closing: the in-progress/current operation is interrupted.

• Completes the in-progress operation: the motor continues the in progress action until it touches the travel stops/limit switches.

Battery operation is enabled after a delay of about 1 sec, it is instantaneous only if the emergency operation is consistent with the operation in progress (for example, when the actuator is closing, the supply voltage is lost and the battery set to NC intervenes).

The action in progress with the battery power supply is interrupted by a possible mains voltage recovery.

A yellow light (LED) mounted on the power supply board indicates that the board is charging the battery in TRICKLE mode. When the battery is fully charged the LED light turn off. The LED signal is reliable if the battery back-up has not been damaged.

The battery is a component that guarantees a limited number of charge / discharge cycles (over 500), therefore its life is inversely proportional to the number of interventions.

WARNING: to guarantee the emergency battery intervention, it is necessary that the actuator remains powered for more than 3 hours.

WARNING: for the version with battery it is recommended to power the actuator within 3 months from the purchase date.

The actuator can also be used in "solenoid" mode (wiring with two wires). To use this mode it is mandatory to follow the warnings above.

9.0 Maintenance

The electric actuator does not need any kind of maintenance. The internal lubrication of the gears is enough for the device life. For enclosure cleaning, use a light non-aggressive detergent. In case of damages or operation issues, we suggest sending the actuators back to Valbia for inspection. Valbia S.r.l. declines responsibility and warranty on our actuators repaired from any third party.





10.0 Wiring diagram

The wiring diagram to be followed for the proper cabling to the actuators is showed in Fig.7 and a it is also inside the cover(as tag). In addition to the 3-points control mode it is possible the cabling of the actuator for the 2-points control mode.



Fig.7 Wiring diagram

10.0 Disposal of the electrical actuators at the end of their life cycle

According to the provisions of the European directives 2011/65/UE and 2012/19/UE, concerning the restriction of the use of hazardous substances in electrical and electronic equipment as well as waste management, all the VALBIA electric actuators are designed in order to be completely disassembled when they arrive at the end of their life cycle, separating the different materials for the proper disposal and/or recovery.



The device must not be disposed as a mixed urban waste, it must be recycled through the proper collection system for disposal and for its subsequent correct recycling. The collection system of the equipment at the end of its life is guaranteed on the national territory through the national consortia for the eco-sustainable management of WEEE. For all the information contact VALBIA S.r.I.

At the end of the life cycle of the device, for its removal, a series of precaution must be followed:

- the structure and the various components, if not usable, must be demolished and divided up according to the type of product. All this helps collection, disposal and recycling centers and minimizes the environmental impact that this operation requires.
- appropriate separate waste collection for subsequent sending of the disused equipment for recycling, treatment and compatible environmental disposal contributes to preventing possible negative effects on the environment and favors recycling of the materials of which the equipment is composed.
- the illegal disposal of the product by the user involves the application of the penalties provided by the current regulations regarding such subject.

The product at the end of its life, if properly disposed, is not potentially dangerous for human health and the environment, on the contrary, if unproperly abandoned, it could have a negative impact on the ecosystem.