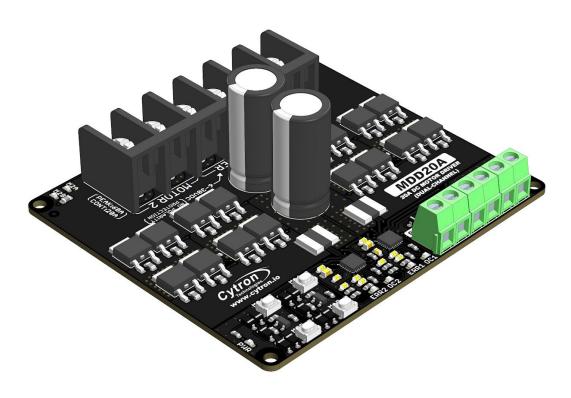


MDD20A 20Amp 6V-30V DC Motor Driver (2 Channels)



Datasheet

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1. BOARD LAYOUT & FUNCTION

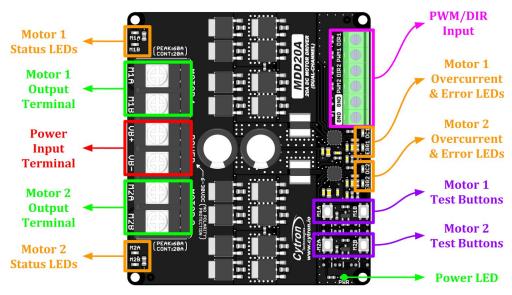


Figure 1: MDD20A Board Functions

Function	Description			
Power Input Terminal	Connect to battery. • VB+ : Positive • VB- : Negative Warning : Connecting in reverse polarity will damage the motor driver instantaneously.			
Motor Output Terminal	Connect to motor terminal. Motor direction is depending on the polarity.			
Power LED	Turn on when powered up.			
Motor Status LEDs	Turn on when the motor is running. MxA: Forward* MxB: Backward*			
Error LED	Turn on during undervoltage shutdown or hardware fault. Please contact support@cytron.io for more information.			
OC (Overcurrent) LED	Turn on when current limiting is in action. Current limit threshold is depending on the board temperature.			
Test Buttons	Press to test the functionality of the motor driver. Motor will run at full speed. MxA: Forward* MxB: Backward*			
PWM/DIR Input	Control the motor with PWM & DIR signal. Output I/DIR Input PWMx: Direction input. PWMx: PWM input for motor speed control. GND: Signal ground.			

Table 1: MDD20A Board Functions

^{*} Actual motor direction is depending on the motor connection. Swapping the connection (MxA & MxB) will reverse the direction.

2. SPECIFICATIONS

No	Parameters			Max	Unit
1	Power Input Voltage			30	V
2 Ma	Marimum Matar Current (Day shannel)	Continuous	-	20	Α
	Maximum Motor Current (Per channel)	Peak *1	-	60	Α
3 L	Lasia Innut Valtana (DIAIM O DID)	Low Level	0	0.8	V
	Logic Input Voltage (PWM & DIR)	High Level	1.5	15 *²	V
1 44 1	PWM Frequency	Standard	DC	20	KHz
	(Output frequency is same as input frequency)	Extended *3	20	40	KHz

Table 2: MDD20A Absolute Maximum Ratings

- *1 Peak current is limited by the overcurrent protection circuit. Actual current limit is depending on board temperature. Value shown is at room temperature (25 30 degree Celsius).
- *2 Maximum input voltage can be extended up to 30V by connecting a 10K ohm resistor in series.
- *3 When the PWM operates in extended frequency range, continuous motor current will be reduced.

3. DIMENSION

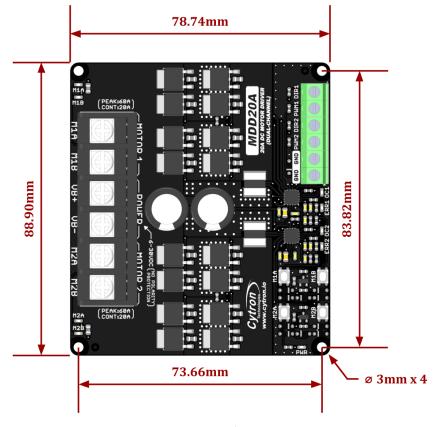


Figure 2: MDD20A Dimension

4. INTERFACE

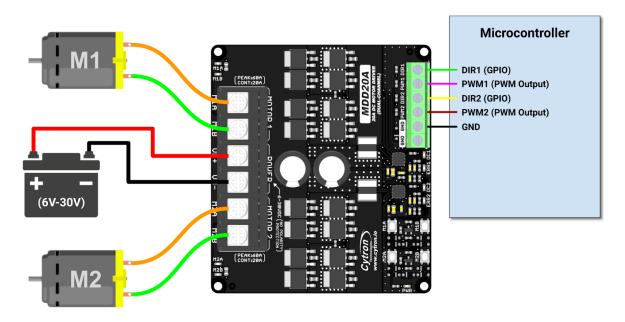


Figure 3: PWM & DIR Input Connection Diagram

PWMx	DIRx	Output A (MxA)	Output B (MxB)	Motor x	
Low	X (Don't Care)	Low	Low	Brake	
High	Low	High	Low	Forward*	
High	High	Low	High	Backward*	

Table 3: PWM/DIR Input Truth Table

^{*} Actual motor direction is depending on the motor connection. Swapping the connection (MxA & MxB) will reverse the direction.

5. PROTECTION FEATURES

• Overcurrent Protection with Active Current Limiting

When the motor is trying to draw more current than what the motor driver can supply, the PWM to the motor will be chopped off and the motor current will be maintained at maximum current limit. This prevents the motor driver from damage when the motor stalls or an oversized motor is hooked up. OC LED will turn on when current limiting is in action.

Temperature Protection

The maximum current limiting threshold is determined by the board temperature. The higher the board temperature, the lower the current limiting threshold. This way, MDD20A is able to deliver its full potential depending on the actual condition without damaging the MOSFETs.

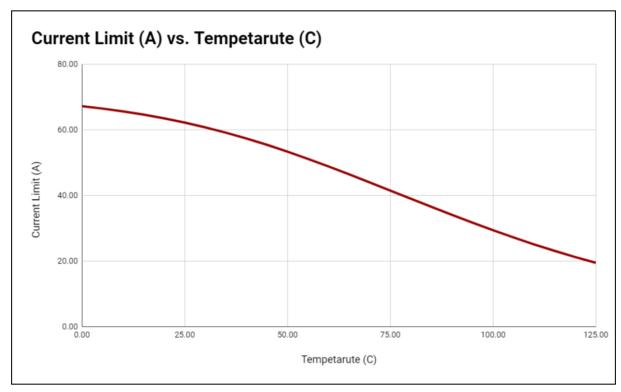


Figure 4: Maximum Current Limit vs Temperature Graph (Per channel)

• Undervoltage Shutdown

The motor driver output will be shut down when the power input voltage drops below the lower limit. This is to make sure the MOSFETs have sufficient voltage to fully turn on and do not overheat. ERR LED will turn on during undervoltage shutdown.

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