CAVITAR Welding Camera C400-H

Operating Manual





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1 Introduction

Thank you for choosing Cavitar Welding Camera C400-H (later: Welding Camera)!

Welding Camera is a Finnish quality product developed and manufactured by Cavitar Ltd. We hope you will be satisfied with your product.

Welding Camera is a highly compact and easy-to-use visualization system for the online monitoring of various welding processes, including MIG, MAG and TIG processes.

Welding Camera contains several unique features to enable highest possible image quality. These features include, among other things, spectral filtering combined with active laser illumination.

The laser source of the system doesn't require any control by the operator. Therefore, from the operation point of view, the system doesn't differ from a normal machine vision camera system. Welding Camera is a class 3R laser product with a nominal ocular hazard distance (NOHD) of 3 meters.

Please read this operating manual carefully before using Welding Camera.

Chapter 2 contains important safety information for the safe operation of Welding Camera.

Chapter 3 describes the properties of Welding Camera and Chapter 4 deals with the installation of the system.

Chapter 5 describes the operation of Welding Camera.

Chapters 6 to 8 cover issues related to maintenance, service, support and warranty.

The actual appearance of software or components may vary.

The symbols below are applied throughout this operating manual:

|--|

CAUTION! indicates potential risk of serious damage to the device

WARNING! indicates potential risk of serious injury to the user

2 Safety information

PLEASE CAREFULLY READ AND UNDERSTAND THE FOLLOWING SAFETY INSTRUCTIONS <u>BEFORE</u> USING WELDING CAMERA. IT IS OF UTMOST IMPORTANCE TO STRICTLY OBEY THESE INSTRUCTIONS. OTHERWISE SERIOUS DAMAGE TO THE USER OR TO THE DEVICE MAY OCCUR.

ONLY A PERSON, WHO HAS CAREFULLY READ AND UNDERSTOOD ALL SAFETY INSTRUCTIONS BELOW AND THE REST OF THIS OPERATING MANUAL, IS QUALIFIED FOR USING WELDING CAMERA. CAVITAR LTD. IS NOT LIABLE FOR ANY DAMAGE CAUSED BY THE IMPROPER USE OF WELDING CAMERA.

CAUTION--USE OF CONTROLS OR ADJUSTMENTS OR PERFORMANCE OF PROCEDURES OTHER THAN THOSE SPECIFIED HEREIN MAY RESULT IN HAZARDOUS RADIATION EXPOSURE.

CAUTION--USE OF OPTICAL INSTRUMENTS WITH THIS PRODUCT WILL INCREASE EYE HAZARD.





- Welding Camera is a <u>class 3R</u> laser system
 - laser class is indicated by the warning label on top of the camera unit (see the label above)
 - laser aperture is indicated by the yellow aperture label on top of the camera unit (see the label above)
 - Nominal Ocular Hazard Distance (NOHD) is 3 meters

LASER APERTURE

- Do not look into the direct, reflected or scattered laser beam
 - \circ camera unit emits visible red laser light at 645 ± 10 nm wavelength band
 - laser beam is emitted from the front of the camera unit (from the mirror-like window in Fig. 3.2). The beam generates approximately 30 mm diameter spot at the design working distance (200 mm)
 - \circ use of appropriate laser safety goggles is recommended for eye-safe operation. Suitable laser safety goggles must have an optical density of at least 3 (OD3) at the wavelength band 645 ± 10 nm
- The accidental exposure to direct/reflected/scattered laser beam has to be prevented:
 - train personnel not to stare at the laser output
 - pay special attention to possible bystanders or persons passing by

- Other instructions:
 - Changes or modifications not expressly approved by Cavitar Ltd could void the user's authority to operate the equipment
 - Welding Camera is not certified for medical use
 - Do not make ANY modifications to the device by yourself
 - Do not try to repair the device by yourself
 - It is strictly forbidden to open the cover of the camera unit. Otherwise serious damage or injury to the user or to the device may occur. Camera unit contains gallium arsenide, which is a known human carcinogen
 - Before powering the system, ensure all connections are made according to this manual and all cables are intact. Broken cables can create a risk of electric shock which can cause serious damage or injury to the user or to the device
 - o Welding Camera is intended for indoor use only
 - Do not expose the system to moisture, rain or condensing environment as this can create a risk of electric shock. Electric shock can cause serious damage or injury to the user or to the device
 - Do not expose the system (especially the signal inputs) to electrical shock or static discharge as this can create a risk of unintended laser emission, resulting in eye hazard
 - Excessive vibration or strong mechanical impact may damage the equipment.
 - The operating temperature of Welding Camera is +10...+40 °C with proper mounting. Do not expose the device to excessively low or high temperatures without appropriate means for controlling the temperature of the device
 - People prone to epileptic seizures are not allowed to operate the system nor be exposed to the laser emission (blinking frequency 100 Hz or less)
 - If you are uncertain about any issue related to safety or proper operating conditions, please contact your vendor or Cavitar
 - It is not allowed to dispose Welding Camera as unsorted municipal waste. The system must be returned to your vendor or to Cavitar for proper disposal at the end of their life. Alternatively one can consult local, state and federal regulations for proper disposal. Welding camera contains Gallium Arsenide. Gallium Arsenide is toxic and must not be released to the environment



CERTIFICATIONS AND COMPLIANCE

- Cavitar Ltd. is an ISO 9001:2015 certified company
- CE declaration of conformity
 - Welding Camera, if installed and operated in accordance with the manufacturer's instructions, is in conformity with the following European, harmonized and published directives and standards:
 - 2011/65/EU (RoHS 2)
 - 2014/30/EU (Electromagnetic Compatibility)
 - 2014/35/EU (Low Voltage Directive)
 - BS/EN 60825-1:2014 (Laser Safety)
- Declaration of conformity with 21 CFR 1040.10 and 1040.11
 - Complies with 21 CFR 1040.10 and 1041.11 except for conformance with IEC 60825-1 Ed. 3., as described in Laser Notice No. 56, dated May 8, 2019.
- Safety
 - Welding Camera meets the requirements of the following electrical equipment safety standards:
 - IEC 61010-1:2010 + Am1:2016
 - EN 61010-1:2010
 - UL 61010-1: 3rd Edition
 - CSA C22.2 No. 61010-1-12
- Electromagnetic compatibility (EMC)
 - Welding Camera meets the requirements of the following EMC standards:
 - IEC 61326-1:2020: Immunity in an industrial electromagnetic environment
 - CISPR 11:2015/AMD2:2019: Group 1, Class A emissions
 - FCC 47 CFR Part 15B: Class A emissions
 - ICES-003 Issue 7: Class A emissions

Group 1 equipment is any industrial, scientific, or medical equipment that does not intentionally generate radio frequency energy in the frequency range 9 kHz to 400 GHz for the treatment of material or inspection/analysis purposes.

Class A equipment is suitable for use in all establishments other than domestic and those directly connected to a low voltage power supply network which supplies buildings used for domestic purposes.

Warning: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense. This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference that may cause undesired operation.

3 Properties

Welding Camera C400-H system typically consists of the following components:

CAMERA UNIT

- laser aperture label
- laser class 3R warning label
- easy-to-replace protective window
- adjustable working distance
- mounting threads
- integrated channels for air or liquid cooling

TEMPERATURE WARNING UNIT (TWU)

- generates audible and visible warning if camera temperature exceeds specified boundaries
- power on/off button for the camera system
- sound off button for muting audible warning
- enables the use of an optional warning light system

POWER SUPPLY

• power supply DC 24 V, max 40 W, including 1,8 m long fixed cable

CABLES

- GigE cable (between camera unit and computer), standard length 10 m
- power cable (between camera unit and TWU), standard length 10 m
- power supply cable (between power supply and AC mains), standard length 2 m

ACCESSORIES

- 2x spare protective window
- 2x cooling hose connector with O-ring
- 2x hose clamp for cooling connector
- 1x hex key (1,5 mm) for working distance adjustment

INSTALLATION CD

- CAVITAR Capture-H software for controlling Welding Camera
- Operating manual
- Additional instructions:
 - Guide for cooling
 - Guide for external control via COM-port
 - Guide for working distance adjustment



Camera related	
Default working distance	200 mm (good image quality within ± 15 mm)
Field of view (at default working distance)	approx. 40 mm x 30 mm
Max resolution	1440 pxl x 1080 pxl
Max frame rate (at full resolution)	Typically approx. 70 fps (computer dependent)
Max frame rate (with laser illumination)	100 fps
Optical	
Wavelength	645 ± 10 nm
CW/Pulsed	Pulsed
Max average power	< 5 mW
Max pulse energy	< 22,9 µJ
Max pulse duration	< 2,7 μs
Laser class (according to BS/EN 60825-1:2014)	3R
Nominal ocular hazard distance (NOHD)	3 m
Audial	
TWU warning sound frequency	29003500 Hz
TWU warning sound pressure level	max 100 dB at 30 cm distance
Electrical	
Power supply input voltage	AC 100-240 V, 47-63 Hz
Power supply output voltage	DC 24 V
Power supply power rating	Max 40 W
Mechanical	
Camera unit dimensions (W x H x L)	38 mm x 48 mm x 99 mm (excl. connectors)
Camera unit weight	~ 360 g
Camera unit attachment	6x M3 and 4 x M4 mounting threads
TWU dimensions (W x H x L)	80 mm x 40 mm x 120 mm (excl. connectors)
TWU weight	~ 400 g
TWU attachment	4 x M3 and 2x M4 mounting threads
Environmental	
Storage temperature	0+50 °C
Operation temperature	+10+40 °C ⁽¹⁾
Indoor/outdoor use	Indoor use only
Humidity	max 80 % RH non-condensing
Altitude	max 2000 m above sea level
Pollution degree	PD2
Supply voltage fluctuations	±10 %
Overvoltage category	Ш
Pressure in integrated cooling circuitry	max 4 bar
Cooling liquid	mixture of pure water and inhibited glycol ⁽²⁾
Inner diameter of the cooling hose	6 mm

- (1) The camera heats up during operation. Please follow these guidelines to ensure proper cooling:
 - a. Immediate action is needed if Temperature Warning Unit (TWU) generates an alarm (for more details, see Section 5.1). Warranty doesn't cover damage caused by overheating due to inadequate cooling of the camera. More detailed information about cooling can be found from separate document "Guide for cooling"
 - b. Remarks for passive cooling (low heat load and low ambient temperature):
 - i. The camera must be mounted/clamped in such a way that heat can be removed from the camera housing as efficiently as possible. In some cases it is possible to use a metallic (e.g. aluminium) mounting plate/arm with a good thermal contact to a larger heat sink such as metallic body of machinery
 - ii. For optimal heat transfer, the mounting/clamping should cover as large portion of the camera side(s) as possible (good thermal contact to both camera sides is the most efficient passive cooling configuration)
 - iii. It is strongly recommended to apply a thin thermally conductive sheet between the camera side(s) and the mounting as well as between mounting and larger heat sink to maximize heat transfer
 - iv. If the mounting doesn't enable efficient heat transfer from the camera to a larger heat sink and if the ambient temperature doesn't exceed ~30...35 °C, separate heat sinks mounted to camera sides can be applied (Cavitar offers dedicated heat sinks as optional items)
 - c. Remarks for active air and/or liquid cooling (high heat load or high ambient temperature):
 - i. Never cool the camera to temperatures below dew point to prevent condensation (warranty doesn't cover damage caused by condensation). 25...30 °C is usually a safe temperature for the coolant to enter the camera
 - ii. Ensure continuous and sufficient flow of the coolant (a clear warning is needed if the flow is reduced/stopped to avoid damage to the camera)
 - iii. Carefully insulate the camera and the cables from the environment with appropriate thermally insulating protective sleeves. Also place the cooling hoses inside the same protective sleeve as this will keep the other cables cooler and reduce the required cooling power
 - iv. Vortex pipes enable efficient air cooling. However, with vortex pipes special care must be taken not to cool the camera to temperatures below dew point
- (2) The camera contains integrated cooling channels for liquid cooling. Please follow these guidelines to ensure appropriate liquid cooling:
 - a. Cooling channels inside the camera are made of aluminium. Only use cooling liquids and cooling equipment that are compatible with aluminium
 - b. Always ensure that the cooling connectors are properly fastened and free from any leaks. Leaking cooling liquid can get in contact with the back of the camera and may enter the camera, thus breaking the camera. Such damages are not covered by warranty
 - c. A mixture of pure water and inhibited glycol is recommended to avoid corrosion and algae growth
 - i. Pure water can be distilled, demineralised, de-ionised or reverse osmosis water
 - 1. Never use pure water without inhibited glycol since this causes corrosion
 - ii. Glycol must be inhibited (to avoid corrosion) and the glycol content in the mixture must be at least 20 volume % (to prevent algae growth)
 - 1. Ethylene glycol has better cooling performance than propylene-based glycol but is more toxic
 - 2. Modern industrial glycols contain inhibitors alongside a pH buffer and biocide to prevent corrosion, algae growth and rust
 - 3. Never mix different glycols
 - d. The cooling system must be properly flushed and cleaned before adding suitable inhibited glycol and pure water mixture as well as when the mixture needs to be changed
 - e. Prevent any contamination of the cooling liquid and cooling circuitry
 - f. A chiller with temperature and flow rate monitoring and alarm feature is recommended
 - g. Regular maintenance intervals are needed to ensure proper operation (e.g. checking the condition of filters and cooling liquid)
 - h. Never use automotive antifreeze liquids



Fig. 3.1. Camera unit (top view).



Fig. 3.2. Camera unit (front view).



Fig. 3.3. Camera unit (back view).



In Figs. 3.1-3.3:

- A Laser aperture label
- B Laser warning label (laser hazard symbol and explanatory label)
- C Camera unit device label
- D Working distance adjustment screw (for more details see separate document "Guide for working distance adjustment")
- E Protective window (slide to either side to replace)
- F Mounting threads (2x M4, see Fig. 3.4 for more details)
- G Power led (green)
- H Connector for power cable (M12, A-coded, 8-pin, male)
- I Connector for GigE cable (M12, X-coded, 8-pin, female)
- J Threads (2x M6x0.75) for air or liquid cooling (do not use for mounting!)
- K Chassis ground (2x M4 mounting threads)



Fig. 3.4. Camera unit mechanical drawing.



Fig. 3.5. Temperature warning unit (top view).





Fig. 3.6. Temperature warning unit (front view). Fig. 3.7. Temperature warning unit (back view).

- In Figs. 3.5-3.7:
- A POWER led (green)
- B CAM OK led (green)
- C CHECK COOLING led (orange)
- D CRITICAL ERROR led (red)
- E CAM ON/OFF button
- F SOUND OFF button
- G Connector for power supply (M12, A-coded, 8-pin, male)
- H Connector for power cable (M12, A-coded, 8-pin, female)
- I Connector for optional warning light system (WLS) (M12, A-coded, 5-pin, female)
- J Temperature warning unit device label



Fig. 3.8. Temperature warning unit mechanical drawing.



4 Installation

4.1 Software installation

Recommended computer properties are listed in Table 4.1:

Operating system	Windows 10
Processor	Intel i5 or higher, preferably latest generation multicore processor
RAM memory	8 GB or more (depending on the recording requirements)
Hard disk	SSD with sufficient capacity (depending on the recording requirements)
Display	High quality display with wide viewing angle
Ethernet adapter	Intel ethernet adapter (I350/I210 or similar); at least two connectors, if two cameras are to be connected to the same computer
Cooling	Efficient cooling (e.g. ventilation or conductive cooling) to prevent heating

Table 4.1. Recommended computer properties.

If applicable, please uninstall old software version completely before installing new software version!

Insert the CAVITAR Capture-H software CD into the CD drive and run the setup file (if the setup doesn't start automatically).

In some cases it may be necessary to disable firewall and/or virus software. As an example, in Windows 10 the "Check apps and files" feature under Windows Security App & Browser Control may need to be turned off. Please consult your IT support if needed.

The screenshots below show a typical installation procedure for Windows 10. The actual appearance of the windows may vary.

Installer L	anguage	×
E	Please select a language.	
	English	~
	ОК	Cancel

Fig. 4.1. Select language and click "OK".



Fig. 4.2. Close all other applications and click "Next" to start installation.

🧲 Cavitar Capture-H Setup -	×
License Agreement	
Please review the license terms before installing Cavitar Capture-H.	E.
Press Page Down to see the rest of the agreement.	
CAVITAR CAPTURE SOFTWARE	~
LICENSE TERMS	
With respect to any software contained in Goods or supplied by the Company and to be used in connection with Company's products (together, "Software"), the Company grants to the Purchaser a non-exclusive, non-transferable right to use the object code of the Software only in the manner described in the written materials accompanying the applicable products. The Purchaser understands and agrees that the Company owns the Software and that If you accept the terms of the agreement, click I Agree to continue. You must accept the agreement to install Cavitar Capture-H.	*
< Back I Agree	el

Fig. 4.3. Click "I Agree" to continue.

🧲 Cavitar Capture-H Setup		- 🗆 X
Choose Components		
Choose which features of Cavi	tar Capture-H you want to install.	
Check the components you wa install. Click Next to continue.	nt to install and uncheck the comp	onents you don't want to
Select components to install:	 ✓ 64-bit Cavitar Capture H Support for two cameras ✓ Install Hikrobot camera ru 	Description Position your mouse over a component to see its description,
Space required: 127.9 MB	< >	
	< Back	Next > Cancel

Fig. 4.4. Select "Support for two cameras" if two systems will be used with the same computer. Click "Next" to continue.

Cavitar Capture-H Setup		- 🗆 🗡
Choose Install Location		
Choose the folder in which to install Ca	vitar Capture-H.	
Setup will install Cavitar Capture-H in the Browse and select another folder. Click	ne following folder. To inst Next to continue.	all in a different folder, dick
Destination Folder		
Destination Folder	Capture-H 1.0	Browse
Destination Folder	Capture-H 1.0	Browse
Destination Folder C:\Program Files\Cavitar\Cavitar C Space required: 127.9 MB Space available: 1746.8 GB	Capture-H 1.0	Browse

Fig. 4.5. Choose install location and click "Next" to continue.

Cavitar Capture-H Setup		1		×
Choose Start Menu Folder				-
Choose a Start Menu folder for the Cavita	r Capture-H shortcuts.			E,
Select the Start Menu folder in which you can also enter a name to create a new fol	would like to create the pro der.	ogram's sho	ortcuts. Yo	bu -
Cavitar Capture-H 1.0 (64-bit)				
Accessories				
Administrative Tools				
CAVILUX CONTROL 5. 1				
Foxit PDF Reader				
F-Secure Client Security				
Generic DisplayLink Driver for USB Docks	and Adapters			
Inkscape				
Lenovo				\mathbf{v}
Do not create shortcuts				

Fig. 4.6. Choose start menu folder and click "Install" to continue.

Cavitar Capture-H Setup					×
Installation Complete					
Setup was completed successfully.					E
Completed					
Output folder: C:\Program Files\Cavitar\Cav	itar Capture-H	1.0			~
Output folder: C:\Program Files\Cavitar\Cavitar Capture-H 1.0					
Created uninstaller: C:\Program Files\Cavita	r\Cavitar Capt	ure-H 1.0\0	Capture	IUninst	
Create folder: C:\ProgramData\Microsoft\Wi	ndows\Start M	enu\Progra	ams\Cavi	itar Ca	
Output folder: C:\Program Files\Cavitar\Cav	itar Capture-H	1.0			
Create shortcut: C:\ProgramData\Microsoft\	Windows\Star	Menu Prog	grams\C	avitar	
Create shortcut: C:\Users\Public\Desktop\Ca	avitar Capture	H 1.0.lnk			
Create shortcut: C:\ProgramData\Microsoft\	Windows\Star	Menu Prog	grams\C	avitar	
WriteRegStr SOFTWARE\Microsoft\Windows	NT\CurrentVe	rsion \AppC	ompatFl	ags\La	
Completed					\checkmark
L					
	< Back	Next	t > _N	Can	ncel
			5		

Fig. 4.7. After installation is completed, click "Next" to continue.



Fig. 4.8. Click "Finish" to complete installation.

4.2 Hardware installation

Installation of camera unit

The camera unit should be mounted or clamped with an appropriate fixture in such a way that the object is located at the working distance of the camera unit. **The mounting must enable as efficient conductive** (low ambient temperature or heat load from process) **or active** (high ambient temperature or heat load from process) **cooling of the camera unit as possible.**

In case of conductive cooling, it is important to apply thermally conductive sheets between the camera side(s) and the mounting as well as between the mounting and larger heat sink (such as the body of machinery). Optimal thermally conductive sheets are offered by Cavitar as optional accessories. It is also beneficial to maximize the area between camera side(s) and mounting. The mounting should be made of material with high thermal conductivity (such as aluminium).

If active cooling is applied, connect the cooling connectors (see Fig. 4.9H) to the threads of the camera unit (see Fig. 3.3J, ensure the O-rings are in place; maximum torque 1 Nm) and attach appropriate cooling system (air or liquid) to the connectors (suitable for hoses with inner diameter of 6 mm). Always ensure that the cooling connectors and cooling hoses are properly fastened and free from any leaks. Leaking cooling liquid can get in contact with the back of the camera and may enter the camera, thus breaking the camera. Only use cooling liquids and cooling equipment that can be in contact with aluminium (electro-chemical corrosion must be prevented). The coolant must be sufficiently warm (e.g. 25-30 °C) to avoid problems related to condensation. For more details, see Table 3.1 and the notes related to it as well as the separate document "Guide for cooling".

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In order to minimize the effects of external electromagnetic fields, connect the chassis of the camera to an appropriate grounding point via the grounding threads (see Fig. 3.3K). The same grounding point should be used for both the camera and the computer to avoid ground loops. If the machinery chassis is in different ground than the computer, the camera should be electrically isolated from the machinery chassis. If the camera is powered by the power supply provided with the camera, camera will not be grounded via the power supply (attach grounding wire to the grounding threads of the camera and the other end of the grounding wire to the same grounding point as the computer).

The camera unit must be properly protected from excessive radiation, heat/cold, condensation, vibration or mechanical forces (see Table 3.1 for more detailed specifications). If you feel uncertain about the correctness of the installation and/or about the suitability of the environment, please contact your vendor or Cavitar. Warranty does not cover damage caused by improper installation.

Installation of temperature warning unit

Temperature warning unit should be mounted to an appropriate fixture in such a way that the indicator leds and buttons are visible and accessible to the operator. If this is not possible, an additional warning light system (optional) should be applied to ensure that possible alarms will be noticed and reacted on without delay.

Electrical connections

The electrical connections shall be made in the following way:

- connect the power cable (Fig. 4.9A) between camera unit (Fig 3.3H) and temperature warning unit (Figs. 4.9B and 3.6H)
- connect the power supply output cable (Fig. 4.9C) to temperature warning unit (Fig. 3.6G)
- connect the power supply input cable (Fig. 4.9E) to the power supply (Fig. 4.9D)
- connect the GigE cable (Fig. 4.9F) between camera unit (Fig. 3.3I) and computer (computer is not included in the standard system)
- ensure the camera unit housing (Fig. 3.3K) is firmly connected to an appropriate grounding point. Also ensure the computer is grounded to the same grounding point to avoid ground loops

Fig. 4.9 shows a typical welding camera system configuration after the connections have been made. Also spare protective windows (Fig. 4.9G), cooling connectors for air or liquid cooling (Fig. 4.9H), heat sinks for passive cooling (Fig. 4.9I, optional), thermally conductive sheets for heat sinks (Fig. 4.9J, optional) and installation CD (Fig. 4.9K) are shown.



Fig. 4.9. Welding Camera system after the connections have been made.

CAUTION!

- Do not connect other than the provided power supply to temperature warning unit.
- Only connect the power supply to a wall socket with protective grounding.
- Power supply can be disconnected from the mains supply by removing the power supply plug from the wall socket.

WARNING!

- Ensure the locations of all operation and adjustment controls as well as other system components are such that neither the operator nor anybody else can be accidentally exposed to laser radiation. Pay special attention to the placement of camera unit, temperature warning unit and computer.
- Ensure all system components are placed in such a way that the applicable mains plugs are always easily removable from the electrical network.

5 Operation

After proper installation the welding camera system is ready for operation. Before operation the following preliminary issues need to be performed:

- check that camera unit and temperature warning unit are properly installed
- check that the replaceable protective window of the camera unit is clean
- power up the computer
- check that the electrical connections are as described in Section 4.2.
- make sure that the safety instructions (Chapter 2) have been properly followed
- connect the power supply cable to AC mains. This will switch on the green POWER led on the temperature warning unit (Fig. 3.5A)

5.1 Temperature Warning Unit

The welding camera system can be powered up by pressing the CAM ON/OFF button (Fig. 3.5E). This will initiate internal checks which can take up to 3 seconds. After successful initialization the green CAM OK led (Fig. 3.5B) will switch on and the camera is ready for operation (see Section 5.2).

In case of an unsuccessful initialization either the orange CHECK COOLING led (Fig. 3.5C) or the red CRITICAL ERROR led (Fig. 3.5D) will switch on. Whenever CHECK COOLING or CRITICAL ERROR activates, TWU will generate an audible warning sound. The audible warning sound can be momentarily muted by pressing the SOUND OFF button (Fig. 3.5F).

CHECK COOLING led will activate if the internal temperature inside the camera unit exceeds 55 °C. At the same time the audible warning sound will be activated. Pressing SOUND OFF button will silence the audible warning sound. The audible warning sound will not re-activate unless CRITICAL ERROR activates. If CHECK COOLING activates, check the cooling system without delay and ensure the camera is properly cooled.

CRITICAL ERROR led will activate if the internal temperature inside the camera is either above 65 °C or below 10 °C or if some other critical error is present. CRITICAL ERROR will always activate the audible warning sound which can be silenced by pressing the SOUND OFF button. In case of CRITICAL ERROR the power will be disconnected from the camera and image acquisition will be stopped as the connection between camera and computer will be lost. The camera will automatically try to restart after 30 seconds (unless the camera has been switched off by pressing the CAM ON/OFF button). If CRITICAL ERROR remains active, the audible warning sound will restart. If CRITICAL ERROR activates during operation, urgent measures are needed to avoid damage to the camera. Switch off the system by pressing CAM ON/OFF button and remove any heat loads from the camera or remove the camera from the process as quickly as possible. After this the operation of the cooling system should be examined in detail. If CRITICAL ERROR remains even if the camera is properly cooled, please contact your vendor or Cavitar.

Table 5.1 summarizes the features of temperature warning unit.

Feature	Function	Sound
CAM ON/OFF button	Switch on the camera	-
SOUND OFF button	Switch off audible warning sound	-
POWER led (green)	Temperature warning unit is powered	No
CAM OK led (green)	Camera is powered and ready for use	No
CHECK COOLING led (orange)	Camera temperature exceeds 55 °C	Yes
	Camera temperature exceeds 65 °C	
CRITICAL ERROR led (red)	Camera temperature is below 10 °C	Yes
	Other critical error	

Table 5.1. Overview of temperature warning unit features.

5.2 CAVITAR Capture software

Welding Camera is operated with CAVITAR Capture software. The appearance and available features may vary depending on the software version. The software designed specifically for CAVITAR Welding Camera C400-H is named CAVITAR Capture-H.

Before launching CAVITAR Capture, ensure that possible firewall or virus protection programs do not prevent the use of CAVITAR Capture (Welding Camera contains a GigE camera with a GigE interface).

In some cases the following actions may be needed:

- disconnect any network connections the computer may have. Also wireless networks should be disabled if firewall and virus protection settings need to be relaxed
- adjust firewall and virus protection settings in such a way that all network traffic is allowed
- connect the GigE cable to your computer after which the computer starts searching for the camera (this may take some time, depending on the computer). Typical announcements in Windows taskbar are "Identifying...No network access" (before connection to the camera is established) and "Unidentified network, No network access" (after connection to the camera is established).
- after the camera is found, CAVITAR Capture can be started

CAUTION!

• If firewall and virus protection settings need to be relaxed in order to enable the operation of the system, the settings must be restored to the normal settings before connecting the computer back to external network.

5.2.1 Registration

When starting CAVITAR Capture for the first time, registration procedure will start (see Figs. 5.1 - 5.5). Proceed by following the instructions and email the registration file to your vendor or Cavitar.

Registration	X	C Registration	>
tep 1. Step 2. Step 3		Step 1. Step 2. Step 3.	
Fill in required registratio from the bottom	n information or load registration file	Check information and click next	
First name	Jim	First name Jim	
Last name	Smith	Last name Smith	
Email	jim.smith@aaabbbccc.ddd	Email jim.smith@aaabbbccc	.ddd
PhoneNr	+1234556789	PhoneNr +1234556789	
Company	Company Itd.	Company Company Itd.	
Address / Additional information	1 ^	Address / Additional - information	<
Load registration file Load Close	Back Next	Back	Next L

Fig. 5.1. Registration: step 1.



Fig. 5.3. Registration: step 3.

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Fig. 5.2. Registration: step 2.



Fig. 5.4. Registration: file saved notification.



After receiving the registered file from your vendor or Cavitar, start CAVITAR Capture. The screen shown in Fig. 5.1 will appear. Click "Load" and select the file sent by your vendor or Cavitar. After this a notification appears (see Fig. 5.6) and CAVITAR Capture starts after pressing "OK" (see Fig. 5.7).

New regi	station file loaded!	×
1	New registation file load	led!
	0	K

Fig. 5.6. Registration completed successfully.

Cavitar Capture 4.0 File View Settings Help START Src: C RAM CREC Tag:	P	100 % 🎤 🗊	FIT MAX ROI	Preview fps:)	30 + MAX Ga	in:0	× □ ×
No camera opened.							
						RAM:	

Fig. 5.7. CAVITAR Capture user interface.

5.2.2 Opening the camera

When CAVITAR Capture starts for the first time, it has to be connected with the camera. This procedure has to be repeated if a different camera is connected to the computer. However, as long as the same (previously selected) camera is connected to the computer, there should be no need to repeat this procedure.

Select "Open Camera..." from "File" menu. This will open the window shown in Fig. 5.8. Select the correct camera and click "OK" (if the camera hasn't been found by Windows, there will be no camera in the "Select a camera to open" list; in this case wait a while and try again). A view as in Fig. 5.9 will appear.

elect camera system	
Baumer Cameras	~
elect a camera to open	

Fig. 5.8. Opening the camera.

Cavitar Capture 4.0 File View Settings Help		₽ ₽		— I	×
	P	100 % 🌮 💬 FIT MAX ROI	Preview fps: - 30 + MAX	Gain: - 1+	XY
Waiting for picture					
waiting for plotare.					
		31.0 °C	Connected to VCXG-15M	RAM:	

Fig. 5.9. View after camera has been successfully opened.

5.2.3 Overview of CAVITAR Capture

The typical graphical user interface (GUI) of CAVITAR Capture is shown in Fig. 5.10 (after Start-button has been pressed). The actual appearance of the GUI as well as the contents of the menus depend on the software version and selected features.



Fig. 5.10. Overview of CAVITAR Capture.

In Fig. 5.10:

- A Start/Stop button (for starting and stopping image acquisition)
- B Source buttons (source can be camera, hard disk or RAM)
- C Snapshot button (for single snapshots) and Record button (starts recording according to recording settings)
- D Tag field (text in this field can be added to recording destination folder and file names)
- E Zoom controls (for adjusting the size of the image on screen)
 - Note: It is also possible to set desired zoom directly from the GUI in the following way: move the mouse cursor to the upper-left corner of the desired area → press and hold down left mouse button → move the mouse cursor to the lower-right corner of the desired area → release left mouse button → press right mouse button and select "Zoom"
- F Preview controls (for adjusting the image refresh rate on screen)
- G Gain control (for adjusting the brightness of the image)
- H Guideline buttons (for adding horizontal and vertical guidelines)
- I Image resolution and bit depth information
- J Cursor location and the grey scale value of the pixel at cursor location
- K Image refresh rate on screen (equals Camera capture rate (Section 5.2.4) if Preview fps \geq Camera capture rate and equals Preview fps if Preview fps \leq Camera capture rate)
- L Camera temperature (this value shouldn't exceed 55 $^{\circ}$ C)
- M Camera connection information
- N RAM usage information

The menus contain the following features (available features depend on software version):

File	Open camera Close camera Open image Save as Exit
View	 Show toolbar Show zoom tools Show preview fps buttons Show statusbar Show capture frame rate Show recording controls Show sources Show camera capture rate tune controls Show camera capture rate tune controls Show histogram View grid Rotate image by 90 degrees Fullscreen mode (Alt + Enter) This mode can also be entered/exited by pressing right mouse button Autofit image for fullscreen mode Show zoom controls in fullscreen mode
Settings	Snapshot Recording Camera Image adjustment Calibration Guideline and grid properties External control • See separate guide for detailed instructions
Help	Registration information Language About

5.2.4 Camera settings

After a connection to the camera has been established, it is time to adjust camera settings. To do this, select "Camera..." from "Settings" menu. This will open the window shown in Fig. 5.11 (the window shown in Fig. 5.12 can be opened by clicking "Image" tab).

ming & sync Image			Timing & sync	Image		
			Thinking & Syric			
			Bit depth	Mono8	~	
+ -	2	au 🖨	Mode	1440x1080	~	
Camera capture rate	25.0	🗘 frames/s		11		
Sync mode	 internal 		ROI			
	◯ external		XO:	0	-	
Sync polarity	() rising edge		YO:	0		
	Galling edge		X1:	1440	Set ROI	
Sync out	Off	~	Y1 :	1080	Set Max ROI	
Laser	• enabled		Disasian			
	🔘 disabled		Binning	None: Ix I	~	
Automatically reconr	nect camera after network f	ailures		Mirror	Flip	
Connection aliv	e poll interval 1	seconds				
S	ave Load	Default		Save	. Load	Default

Fig. 5.11. Camera settings (Timing & sync).

Fig. 5.12. Camera settings (Image).

For optimal results, make the following adjustments on the "Timing & sync" tab:

- set "Exposure" to "2 μs" or "3 μs", depending on which value gives better results
 o to make the arc brighter, it is possible to increase the exposure time further
- set "Camera capture rate" e.g. to "25 fps" (or your preferred frame rate)
- set "Sync mode" to "internal"
 - the use of external sync mode (e.g. synchronization to arc) requires a special power&sync cable instead of the standard power cable
 - if external sync mode is used, select correct "Sync polarity"
 - external sync signal: 0...4,5V low, 11...24V high, input impedance ~680 ohm
- set "Sync out" to "Off
 - the use of "Sync out" feature (e.g. to synchronize welding cameras together) requires a special power&sync cable instead of the standard power cable
 - the receiving camera must be set for external sync mode
 - set "Laser" to "enabled" in order to have laser illumination in the images
- automatic reconnect feature can be used in case there are connection problems between camera and PC

"Image" tab (Fig. 5.12) contains the following features:

- Bit depth (higher bit depth enables larger dynamic range but increases image file size)
- Mode (different preset resolutions are available)
- ROI (reducing the region-of-interest reduces image file size)
 - It is also possible to set the ROI directly from the GUI in the following way:
 move the mouse cursor to the upper-left corner of the desired ROI → press and hold down left
 mouse button → move the mouse cursor to the lower-right corner of the desired ROI →
 release left mouse button → press right mouse button and select "ROI"
- Binning (for reducing image file size and for increasing sensitivity)
- Mirror and Flip: for changing the orientation of the image

5.2.5 Image adjustment

Image adjustment tool can be used for optimizing the visual appearance of the image. Image adjustment window can be opened by selecting "Image Adjustment..." from "Settings" menu. This will open the window shown in Fig. 5.13.



Fig. 5.13. Image adjustment window.

In order to activate Image adjustment window, press "Enable" button shown in Fig. 5.13. Image adjustment feature is disabled by default since the feature requires the loading of lookup tables whenever software connects with the camera. This loading takes a few seconds and can make the operation of the camera less fluent in certain situations. If the feature is not used, it can be disabled ("Enable" button changes after pressing to "Disable" button as can be seen in Fig. 5.14) to avoid the loading of look-up tables.

Gain can be applied to make the image brighter. However, large gain values will increase the noise in the images. Gain is typically applied if the original image is too dark (e.g. very dark or highly reflective metal surfaces). Gain can also be adjusted directly from the GUI.

Gamma is a nonlinear correction tool that increases the visibility of dark regions with respect to brighter regions. Gamma correction can often improve the visual appearance of the image.

Grayscale adjustment enables the selection of desired ranges of grayscale values that will be displayed on the screen as different ranges of grayscale values. This can have a big effect on the appearance of the image. As an example, one can assign a larger range for the interesting grayscale value range and a smaller range for the less interesting grayscale value range.



Fig. 5.14. Effect of applying gain and gamma correction (after pressing "Test").

In Fig. 5.14 two red bars (1 and 2) can be seen in the "Current image" field. Bar 1 is at grayscale value "0" and bar 2 is at grayscale value "255". These grayscale values are set to "0" and "255", respectively, in the "Grayscale adjustment" field. Therefore they have no effect. As an example, if one would move bar 2 to grayscale value "100" and keep the "Set to grayscale value" for bar 2 at "255", the grayscale range from 0...100 of the "Current image" would be spread over the grayscale range 0...255 of the "Adjusted image".

The number of bars can be also 3 or 4 (determined by selecting the desired value from the "Number of bars" field). By using 3 bars one can e.g. assign the actual grayscale range of 0...50 to be displayed on screen as grayscale range 0...150 and the actual grayscale range of 51...150 to be displayed on screen as grayscale range 151...255. With 4 bars even more detailed adjustment of grayscale ranges is possible. Once the adjusted image looks optimal, the settings can be saved and the window can be closed by pressing "Set & Exit" button.

5.2.6 Guidelines

Up to four horizontal and up to four vertical guidelines can be drawn on top of the image. These guidelines can be used for e.g. ensuring that the welding torch follows the correct path. Together with the calibration feature (described in Section 5.2.7 in more detail) guidelines also enable measurements from the images in real time.

In order to add horizontal guidelines, click "X" button (see Fig. 5.10H). Vertical guidelines can be added by clicking the "Y" button, respectively. The guideline options (Move, Lock and Delete; Delete is only available for the latest horizontal and vertical line) can be selected by pressing the left mouse button on top of the guideline. Fig. 5.15 shows the screen with four guidelines.



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Guideline properties can be adjusted by selecting "Guideline and grid properties..." under "Settings" menu. This will open the guideline and grid properties window (Fig. 5.16).

Horizontal guideline i	names				
Line H1:					
Line H2:					
Line H3:	-				
Line H4:					
Rotation:	0 🔹 degre	es			
/ertic <mark>al</mark> guideline nar	mes				
Line V1:	-				
Line V2:					
Line V3:					
Line V4:					
Rotation:	0 🖨 degre	es			
Select lines for ∆1:	From H1	~	<->	To H2	~
Celect lines for AD.	11	~	~~~	HZ	~
	VI	~	~~	VZ	~
Select lines for ∆3:	No Selection	~	<->	-	~
Select lines for ∆4:	- No Selection	~	<->		×.
Position of ∆s	top-right	~		Only show	∆s
Positions of guideline	e names and guideline	e prope	rties		
Line H1:	above-left	\sim	Line V1:	top-right	~
Line H2:	above-left	~	Line V2:	top-right	~
Line H3:	above-left	~	Line V3:	top-right	~
Line H4:	above-left	~	Line V4:	top-right	~
Number of decimal p	places shown in guide	eline inf	iomation:	0	
arid properties					
Grid spacing:				50.000	рх
				014	

Fig. 5.16. Guideline and grid properties.

Guideline and grid properties window contains the following features:

- Naming and rotation angle for horizontal guidelines
- Naming and rotation angle for vertical guidelines
- Calculation of distances between selected guidelines (up to 4 distances)
- Options for how to display guidelines, guideline names and calculated distances on the screen
- Grid spacing and precision

Fig. 5.17 shows the view after selecting lines for $\Delta 1$ and $\Delta 2$ and pressing "OK" in Fig. 5.16.



Fig. 5.17. Guidelines with calculated distances.

5.2.7 Calibration

Calibration feature enables the calibration of the image so that instead of pixel values it is possible to get actual measures from the images in the desired unit (e.g. mm or inch).

To calibrate the image, select "Calibration..." from "Settings" menu. This will open the Calibration window (see Fig. 5.18).

Set unit: mm			
Calibration mode			
Measurement			
Horizontal distance b	etween lines V1 and V2:	20.000 🜩	mm
Vertical distance betw	ween lines H1 and H2:	20.000	mm
Conversion			
Horizontal: 1 pb	el = [1.000 🜲	mm
Vertical: 1 pb	el = [1.000 🜲	mm
Last calibration date:	NA		
Calibrated by:	NA		
Project:	NA		

Fig. 5.18. Calibration mode window.

In calibration window the desired unit can be set (in Fig. 5.18 "mm" has been set).

Calibration can be made based on measurement (as in Fig. 5.18 above) or as a conversion.

Calibration based on measurement requires that two vertical and two horizontal guidelines have been placed to their correct positions (e.g. according to a precise calibration pattern or some other object with known dimensions). Once the lines are positioned to known distances from each other, these distances can be typed to the appropriate fields.

Calibration based on conversion can be made without guidelines.

In Fig. 5.17 a ruler was applied to position the vertical lines 20mm apart from each other. The distance between horizontal lines was made equal to the distance between vertical lines (in pixels). Therefore a value of 20 mm has been set to both horizontal and vertical distance between lines. After pressing "Calibrate" a new window will appear (see Fig. 5.19).

Calibration date:	20210406			(YYYYMMDD)
Calibration time:	13:53			(HH:MM)
Calibrated by:	EL			
Project:	Manual			
Camera ID:	VCXG-15M - 700005	9 <mark>60</mark> 975]	
Horizontal:	1 pixel =	0.028	mm	
Vertical:	1 pixel =	0.028	mm	
Grid spacing:		50.000	mm	
Log file name:	Test_calibration			
Current log file pa	ath: C:\capture_vide	eo_db		

Fig. 5.19. Calibration data window.

In order to enable the "Calibrate" button (in Fig. 5.19), all fields in the calibration data window need to be filled. When performing calibration for the first time, also the log file path has to be defined by pressing "Change file path" button. After all information has been successfully filled, the "Calibrate" button becomes active and the calibration can be completed. A confirmation window will appear after pressing "Calibrate" button (Fig. 5.20).

Cavitar	Lapture calibration	×
0	Calibration complet	e.
		_

Fig. 5.20. Calibration complete window.

Fig 5.21 shows the view after successful calibration. As can be seen, the distances between the vertical and horizontal lines are now in millimetres (instead of pixels as in Fig. 5.17).



Fig. 5.21. View after calibration.



5.2.8 Recording settings

To define the recording settings, select "Recording..." from "Settings" menu. This will open the window shown in Fig. 5.22. The actual appearance of the window may depend on the software version in use.

Saved images file format:	tif (8-bit & 16-bit, recommended)	~
Saved images dyn <mark>am</mark> ic range:	Full range: 10- or 12-bit	~
Save guidelines to images:		
Save timestamps to images:		
Recorder root folder:	Change folder	
∑:\capture_video_db	2	
Create a new sub-folder for each Folder naming conventions Include tag File naming conventions Include tag Note: Using detailed time in file na Automatically delete old files	ch recording pass Include calibration UserID Include calibration UserID aming, e.g. 20190522-120022929:	tif
Delete enabled @ 10 🚔 Capture options	files/s Set folders and options	
Delete enabled @ 10 🖨 Capture options Max. frames to capture:	files/s Set folders and options	
Delete enabled @ 10 + Capture options Max. frames to capture: Save every Nth frame (1 = save all	files/s Set folders and options) ÷
Delete enabled @ 10 + Capture options Max. frames to capture: Save every Nth frame (1 = save all C Capture to RAM buffer	files/s Set folders and options	···
 Delete enabled @ 10 ÷ Capture options Max. frames to capture: Save every Nth frame (1 = save all Capture to RAM buffer © Capture until max. frames 	files/s Set folders and options 100 frames): 1 imit, then stop))
 Delete enabled @ 10 ÷ Capture options Max. frames to capture: Save every Nth frame (1 = save all Capture to RAM buffer © Capture until max. frames Capture continuously to a 	files/s Set folders and options) 🛊
 Delete enabled @ 10 ÷ Capture options Max. frames to capture: Save every Nth frame (1 = save all Capture to RAM buffer © Capture until max. frames ○ Capture continuously to a ○ Buffer T1 sec continuous 	files/s Set folders and options	er
 Delete enabled @ 10 ÷ Capture options Max. frames to capture: Save every Nth frame (1 = save all Capture to RAM buffer Capture to RAM buffer Capture until max. frames Capture continuously to a Buffer T1 sec continuousl 	files/s Set folders and options	er
 Delete enabled @ 10 ÷ Capture options Max. frames to capture: Save every Nth frame (1 = save all Capture to RAM buffer © Capture until max. frames ○ Capture continuously to a ○ Buffer T1 sec continuousl Buffer T1 sec continuousl 	files/s Set folders and options 100 1 frames): 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
 Delete enabled @ 10 ÷ Capture options Max. frames to capture: Save every Nth frame (1 = save all Capture to RAM buffer Capture to RAM buffer Capture until max. frames Capture continuously to a Buffer T1 sec continuous Buffer T1 sec continuous Buffer T1 sec continuous Buffer T1 sec continuous 	files/s Set folders and options 100 1 frames): 1 1 imit, then stop a ring buffer of 30 ↓ se sly, then capture T2 sec after trigg ffering time T1 60 ↓ se ffering time T2 60 ↓ se hages to disk when capture RAM recording	

Fig. 5.22. Recording settings.

Recording settings contain the following features:

- Saved images file format: available formats include .jpg, .bmp, .tif, .png and .webm
- Saved images dynamic range: available options depend on Camera settings (larger dynamic range increases the size of the saved files)
- Save guidelines to images: guideline information will be "burnt" to the images
- Save timestamps to images: time information will be "burnt" to the images
- Recorder root folder: specify the desired root folder for the recorded images
- Image file and folder naming conventions: select the desired options
- Automatically delete old files: can be used for managing disk space if needed
- Capture options:
 - Max. frames to capture: specify number of frames to capture
 - For unlimited recording, set "Max. frames to capture" to "0"
 - Save every Nth frame (1 = save all frames)
 - This feature can be applied in order to save disk space
 - Capture to RAM buffer (if selected, images will be saved in RAM memory; otherwise images will be saved on hard disk under Recorder root folder)
 - Capture until max. frames limit, then stop
 - This option captures a predefined number of images to RAM and then stops automatically
 - Capture continuously to a ring buffer of ...sec
 - This option continuously captures images to RAM memory and keeps the most recent images within the specified duration in memory, until stopped
 - Buffer T1 sec continuously, then capture T2 sec after trigger
 - This 2-part ring buffer option enables capturing images for a specified duration before and after a dedicated trigger. Trigger can come from operator or from external source (see separate guide for external control for more details)
 - This option also enables automatic save and restart
 - Do not update display while recording: selecting this option frees PC resources if needed

5.2.9 Recording images

Recording is started by pressing "REC" button (see Fig. 5.10C). This will start recording according to the recording settings (see Section 5.2.8). If "Max. frames to capture" under recording settings is nonzero, the recording will stop automatically after the specified number of frames has been captured. Otherwise the recording has to be stopped by pressing the "REC" button again or the recording continues until the destination (either hard disk or RAM) is full (except in the case of ring buffer recording).

5.2.10 Viewing and saving recorded images

Recorded images can be viewed by selecting the recording destination (either a folder on hard disk or RAM) as source (see Fig. 5.10B). The corresponding screen view is shown in Fig. 5.23 below (in Fig. 5.23 the source is RAM).





Fig. 5.23. Viewing recorded images.

The image player controls for viewing recorded images as well as the "Export" button for saving the images to a desired location have been indicated in Fig. 5.23. It is also possible to move the slider with a mouse. If some or all of the recorded images need to be saved on a hard disk, the "Export" button needs to be pressed. This opens the Export window (Fig. 5.24).

Export from frame	1	to frame	100 🖨
	Mark start		Mark end
Export images as			
Files (tif)			
Video of compre	ssed VP8 <mark>v</mark> ideo in .w	ebm file	~
Force video	frames/s to	10 🌲	
🔘 Use image t	mestamps, avg. rate	25 frames/s	
Folder Tag:			
Export folder			
C:\capture_video_dt	>\20200624-1131284	02\	

Fig. 5.24. Export window.

In the export window it is possible to:

- determine which frames will be saved
 - o pressing "Mark start" will set the current image as the first image to be saved
 - \circ pressing "Mark end" will set the current image as the last image to be saved
 - choose whether the frames will be saved as separate files or as a video
- add a folder tag, if desirable
- view (and modify, if needed) the recording settings

5.2.11 Snapshot

Snapshot means the capture of a single frame. Snapshot can be taken by pressing the "Snapshot" button on the left-hand side of the "REC" button (see Fig. 5.10C). Before taking snapshots it is good to set the snapshot settings by selecting "Snapshot…" from "Settings" menu (see Fig. 5.25).

Show image before s	aving 🗹	
Image format	ipg	~
Default path:	Browse	ù.
C:\capture_video_db		

Fig. 5.25. Snapshot settings.

5.3 Starting and stopping laser illumination

Laser illumination will start when the conditions below are met:

- "CAM OK" led on the TWU is on (camera is powered)
- "Laser" is "enabled" in Camera settings Timing & sync window ("Settings menu" → "Camera...")
- "Start" button (Fig. 5.10A) has been pressed

To stop laser illumination (and continue image acquisition):

 Set "Laser" to "disabled" in Camera settings Timing & sync window ("Settings menu" → "Camera…")

To stop laser illumination (and image acquisition):

- press "Stop" button (Fig 5.10A)
- press "CAM ON/OFF" button on the TWU or disconnect the power supply cable from AC mains (this will switch off the entire system)

5.4 After operation

After operation the following procedure should be carried out:

- ensure that "Stop" button has been pressed (camera is not taking images)
- exit CAVITAR Capture
- press "CAM ON/OFF" button on the TWU

If the system needs to be completely uninstalled, follow these steps:

- unplug all cables and unmount the camera unit and TWU
- carefully pack and store the whole system in a safe and clean place

5.5 Troubleshooting

Below are some instructions for solving certain situations if the system doesn't appear to function as expected. If these instructions don't help, please contact your vendor or Cavitar.

Camera is not found by Windows

- check control, power and GigE cables (cables intact and properly connected)
- check that the system is powered (green led in camera unit is on)
- ensure that e.g. firewall or virus protection software of the computer is not preventing camera connection. It may take some minutes (after powering the system) before the camera is found by the computer. See Section 5.2 for more details

"No camera opened." notification in CAVITAR Capture software

• from "File" menu, select "Open camera..." and select the correct camera

Images are too dark or bright

- check camera settings ("Settings" menu → "Camera...")
 o for typical settings see Section 5.2.4
- check that image adjustment settings are reasonable
 - for more information see Section 5.2.5
- check that replaceable protective window and the fixed glass window behind it are in acceptable condition (switch off the system before checking the condition in order not to be exposed to laser illumination)
- check that the system is generating laser illumination (pulsed red light). Do not stare directly at the beam!

CAVITAR Capture software image refresh rate is low

- ensure that the "Preview fps" value is sufficiently high (see Fig. 5.10F)
- ensure that the latest network adapter drivers have been installed
- reduce zoom level (e.g. to "Fit" or "1:1"), if possible
- restart the computer

6 Maintenance and service information

Under normal operating conditions the only regular maintenance task is the replacement of the replaceable protective window of the camera unit. If liquid cooling is applied, cooling liquid needs to be checked and changed regularly and also the cooling channels need to be checked and cleaned up regularly.

WARNING!

Ensure that the power supply is detached from AC mains before performing any maintenance or service operations!

Changing the protective window of camera unit

Sometimes the protective window of camera unit becomes so dirty that it must be replaced. Follow these steps to change the protective window:

- Slide the used protective window to either side to remove it
- Check the condition of the fixed glass filter behind the protective window and clean it if needed
- Slide in the new protective window from either side. Do not touch the surfaces of the window to keep it clean

Cleaning optical surfaces

For optimal performance it is important to keep the following optical surfaces clean:

- fixed glass filter in the camera unit (behind the replaceable protective window)
- replaceable protective window in the camera unit.

Clean these sensitive optical surfaces primarily by using clean and dry pressurized air. If this is not sufficient, try dry optical wipes. If needed, the optical wipe can be moisted. Do not use strong solvents as they may damage optical surfaces. Be careful not to create any scratches on optical surfaces, as this will deteriorate the performance of the system.

Cleaning the system

Clean casings with slightly moist wipe. Avoid using strong solvents. Ensure the system is fully dry before connecting it to mains supply in order to avoid the risk of electrical shock (pay special attention to connectors).

Other maintenance or service needs

In case any other needs for maintenance or service appear, please contact your vendor or Cavitar (see Chapter 7 for more details).

7 Support and end of life

Support and contact information

It is of utmost importance to Cavitar that Welding Camera will work reliably and offers the greatest possible benefit to our customers. These objectives have guided the design and manufacturing of the product. However, if problems occur despite of our efforts, it will be our first priority to solve these problems as quickly and efficiently as possible.

In case of problems please contact InterTest, Inc. by email or by telephone.

InterTest, Inc. 303 State Route 94 Columbia, NJ 07832 tel: +1 908 496 8008 email: info@intertest.com

Our current contact information is available at our website: https://intertest.com/

End of life

It is not allowed to dispose Welding Camera as unsorted municipal waste. The system must be returned to your vendor or to Cavitar for proper disposal at the end of their life. Alternatively one can consult local, state and federal regulations for proper disposal.

Welding camera contains Gallium Arsenide. Gallium Arsenide is toxic and must not be released to the environment.





8 Limited warranty

Cavitar warrants to the customer, that the product is free from defects in materials and workmanship and that the product is in good working order. Cavitar does not warrant error free or uninterrupted operation of the product.

The warranty is valid only if the serial number plate is on the product (i.e. not removed or defaced).

The warranty for the product is one year starting from the date of purchase or delivery (unless the applicable law establishes a longer period). Cavitar will provide warranty service and technical support free of charge during the warranty period.

In warranty service Cavitar will first diagnose the fault. Cavitar will repair or change the defective product either by delivering a new or refurbished product. Cavitar may give instructions regarding the return or replacement of defective products. Original packing materials should be retained for possible need during warranty period. All exchanged parts and products replaced under warranty period become the property of Cavitar. In the case that the product will be changed, the defective product has to be returned in its original packing materials to Cavitar without delay. Failure to return the defective product will be delivered without other parts, cables or options. Those parts need to be removed from the defective product and they have to be used with the replacement product.

Warranty service does not include repair or replacement caused by the following reasons:

- 1) negligence by the user of the product or overloading of the product or failure to observe the operating instructions or proper care,
- 2) transportation of the product,
- 3) unauthorized modifications or attachments have been made to the product,
- 4) the casing of the product has been opened,
- 5) circumstances outside the control of Cavitar such as freezing, fire or accident or it has been misused,
- 6) repairs or maintenance by maintenance people other than those authorized by Cavitar,
- 7) the use of other than original parts provided by Cavitar, and
- 8) normal wear and tear.

The warranty does not cover defects which are insignificant to the use of the product, such as repair of superficial scratches.

The statement of limited warranty is the exclusive warranty. All other expressed or implied warranties including merchantability and applicability for a certain purpose are excluded (except where the applicable law requires said implied warranties). Any warranty, either expressed or implied, will not apply after warranty period.

LIMITATION OF LIABILITY

To the extent of the applicable law, the sole remedy of the customer is the warranty service set forth above. Cavitar's liability for actual damages of any kind will be limited to the price paid for the product, its repair or replacement. This limitation of liability does not apply to bodily injury or property damage for which Cavitar is held legally liable. In no event will Cavitar be liable for lost profits nor for incidental, consequential or other damages even if advised of the possibility of said damages.