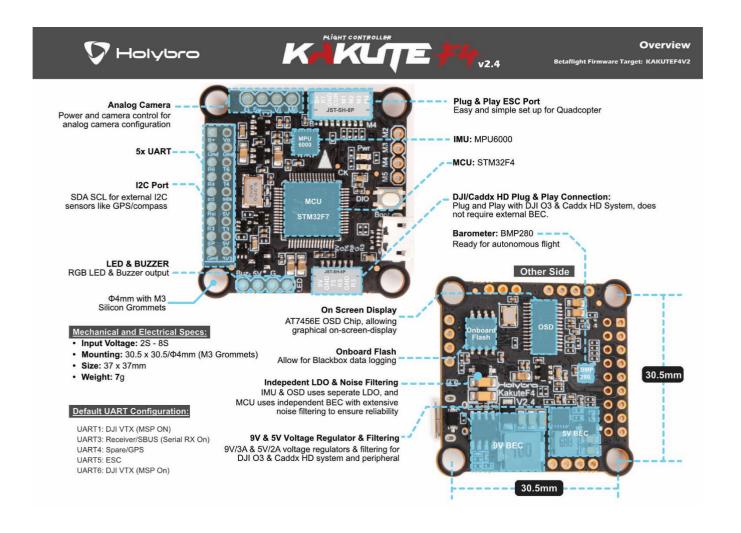


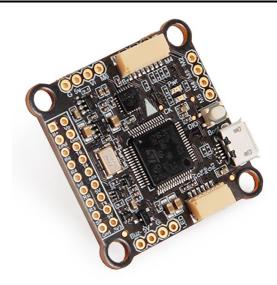
#11066

Kakute F4 V2.4

User Manual & Installation Guide



Overview



The Holybro Kakute F4 V2.4 Flight Controller includes plug-and-play DJI O3 HD camera plug, 4in1 ESC ports, barometer, OSD, 5x UARTs, logging capability with built-in flash, 5V and 9V/3A BEC, easy soldering layout and much more.

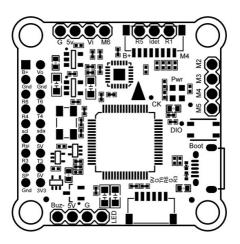
The Kakute F4 V2.4 is DJI HD ready. It has an easy plug-and-play port with an on-board 9V/A regulator designed to power your HD video transmitter like DJI O3 Air Unit & Caddx Vista while supporting analog system. It has 5x dedicated UART ports with built-in inversion for peripherals. It is also ready for autonomous flight with the on-board barometer. There are LED & buzzer pad, I2C pad (SDA & SCL) for external GPS/Magnetometers

Specification:

- MCU STM32F405
- IMU MPU6000
- Barometer BMP280
- OSD AT7456E
- 5x UARTs (1,3,4,5,6,)
- 128 Mbit Dataflash chip
- Battery input voltage: 2S-8S
- BEC 9V/3A Optimized for DJI O3 Air unit
- BEC 5V/2A
- 7x PWM Outputs (6 Motor Output, 1 LED)
- Supports serial receivers (SBUS, iBus, Spektrum, Crossfire, ESLR).
- Mounting 30 x 30mm, Φ4mm hole with M3 Grommets
- Dimension 37x37mm
- Weight 7g
- JST-SH1.0_8pin port (For 4in1 ESCs)
- JST-SH1.0_6pin port (For DJI/Caddx HD System and other VTX)



Pinout Diagram

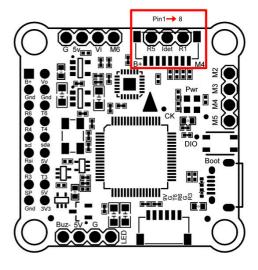


Pin	Function
Buz-	Piezo buzzer negative leg
Led	WS2812 addressable LED signal wire
SP	FrSky SmartPort Telemetry (UART 1, inverted)
R3, T3	UART3 RX and TX (automatic inversion)
R4, T4	UART4 RX and TX (uninverted)
R5	UART5 RX (uninverted)
R6, T6	UART6 RX and TX (uninverted)
Scl	I2C SCL pin
Sda	I2C SDA pin
Rsi	Analog (0-3.3v) RSSI input
Idet	Current Sensor (0-3.3v) input
3V3	3.3v output (200 mA max)
5v	5v output (1.0 A max)
M1 to M4	Motor signal outputs
M5 to M6	Motor signal outputs(need to resource)
RX	UART 5 RX (uninverted, for ESC Telemetry)
VO	Video output to video transmitter
VI	Video input from FPV camera
Boot	Bootloader button
G or Gnd	Ground
B+	Battery positive voltage (2S-6S)



Pinout Diagram

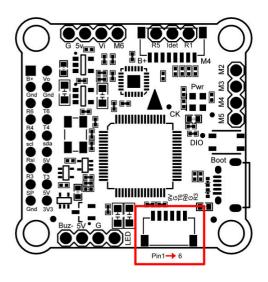
JST SH 8 Pin Port



Pin	Function
1	Battery Voltage
2	R5 (for ESC telemetry)
3	Ground
4	Current Sensor Input
5	M1
6	M2
7	M3
8	M4

The 8PIN SH connector can be used to connect directly to compatible 4-in-1 ESCs. However, you might need to use the SH connector even if you are not using a 4-in-1 ESC, because some pins are only present in the SH connector, not as pads on the board.

JST SH 6 Pin Port



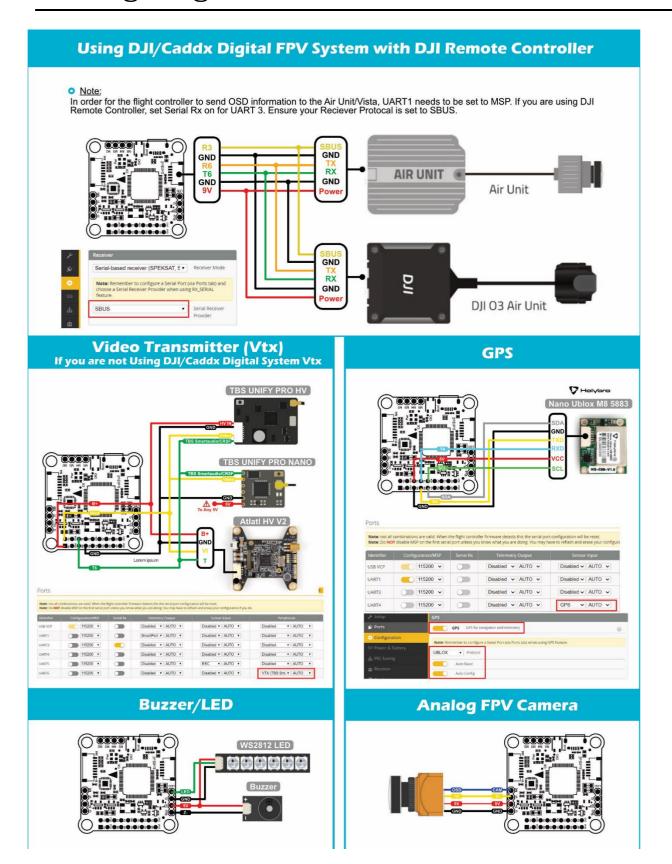
Pin	Function
1	R3
2	G
3	R6
4	T6
5	G
6	9V

The 6PIN SH port available on the board makes it much more convenient for you to connect HolyBro Kakute F4 V2 to the DJI O3 Air Unit or Caddx Vista or other Vtx, for both signal and power supply.





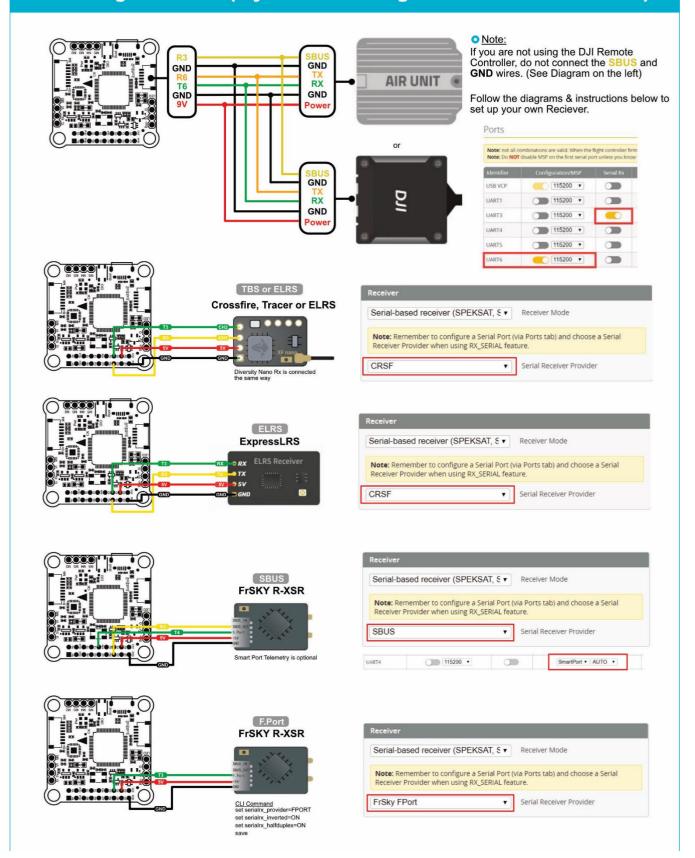
Wiring diagram







Installing a Receiver (If you are not using the DJI Remote Controller)

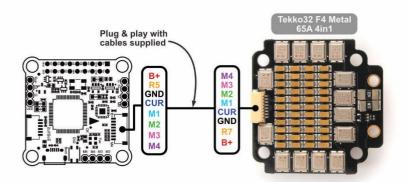






ESCs

Plug-and-Play 4in1 ESC Ports



B+: Battery Positive Voltage (2S-6s)
R5: UART5 R5 (ESC Telemetry)
GND: Ground
CUR: Current Sensor

M1: Motor 1 Signal M2: Motor 2 Signal M3: Motor 3 Signal M4: Motor 4 Signal

