# ATH 400M / ATH 1000M Maglev hybrid turbomolecular pump

#### Welcome

Dear Customer,

You have just purchased an Alcatel maglev hybrid turbo pump.

We would like to thank you and are proud to count you as one of our customers.

This product has benefited from Alcatel's many years of experience in the field of turbomolecular pump design.



In order to ensure the best possible performance of the equipment and your complete satisfaction in using it, we advise you to read this manual carefully before any intervention on your pump and to pay particular attention to the equipment installation and start-up section.

Edition 07 - January 02

Manual Reference : 101 688 Edition : 07 - January 2002

#### **APPLICATIONS:**

SEMICONDUCTOR APPLICATIONS Plasma etching, Ion implantation, Sputtering, Plasma deposition.

OTHERS APPLICATIONS

Electron microscopes, Surface analysis, Research and development, High energy physics, Space simulation, Accelerators.

#### ADVANTAGES:

High throughput - Quiet and clean vacuum - Corrosion proof - High MTBF - Minimum size, volume and weight -Smart and compact electronic controller - Reliability -Maintenance free - Battery free - Easy integration.

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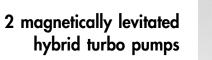
 $M_{\text{ANUAL}}$  reference :  $101\ 688$ 

 $\mathsf{EDITION}\,:\, \textbf{07 - January 02}$ 

\* These chapters are reserved for the Customer Service.

# A 10

Introduction to the ATH 400M/ATH 1000M and their associated ACT controllers





# ATH 400M and ATH 1000M

Five active axes ACTIDYNE® Maglev bearings type (S2M Patent) Rotor position control in 5 directions.

#### Automatic balancing system

Lowest possible levels of noise and vibration. Compensation for any imbalance of the rotor.

#### **Inverted dynamic seal** High compression ratio.

ATH 400MT ATH 1000MT

# Integral heater band

Maintaining the pumps internal surface up to 75°C to prevent the condensation effect. Temperature regulated by the ACT controllers.

Exclusive protection.

#### Inert gas purge

Eliminate corrosion of the motor and magnetic bearing coils.

#### Maintenance free

#### Battery free

In case of a power failure, the pump motor acts like a generator to transform the rotor energy into

# A 10

Introduction to the ATH 400M/ATH 1000M and their associated ACT controllers



#### ACT 600M and ACT 1000M controllers

#### The new generation of ACT controller family

**Especially designed for maglev turbopumps** Light and small controllers. Battery free.

#### **Convenient interface** Handy keyboard;

Alphanumeric display.

#### Modern pump monitoring

Monitoring of testing and troubleshooting parameters; RS 232/485 serial links; Automatic power supply detection from 85 to 265 V, 48/63 Hz single phase.

#### Large range of interface

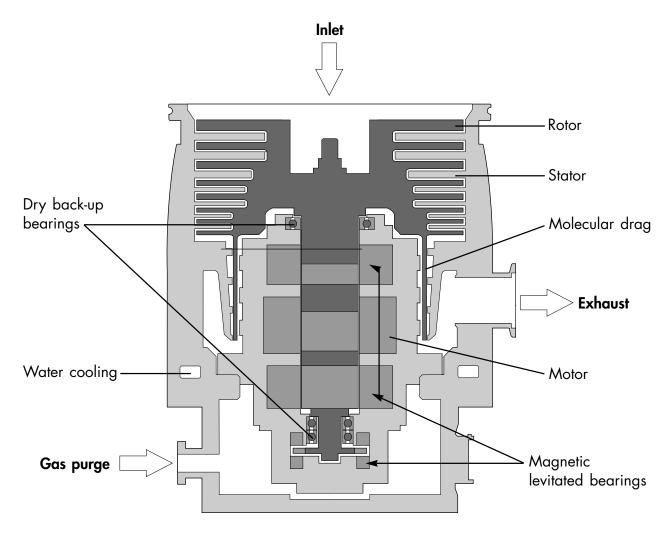
Dry contacts interface for status signals and optocoupled control inputs; Selectable Analog 0-10 V output.

#### The pump operating principle

**A hybrid technology** The ATH 400M and ATH 1000M integrate the advantages of a multi-staged turbomolecular pump with a spiral helix molecular drag section to enhance ultra high-vacuum (UHV) and ultra clean technology (UCT).

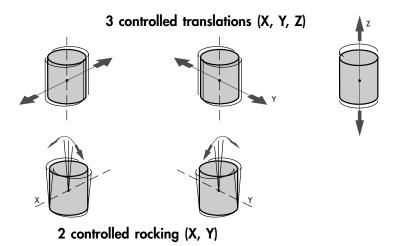
The turbomolecular section provides high pumping speeds and UHV ultimate vacuum.

The molecular drag section provides a high compression ratio and extends forevacuum tolerance up to 5 mbar.

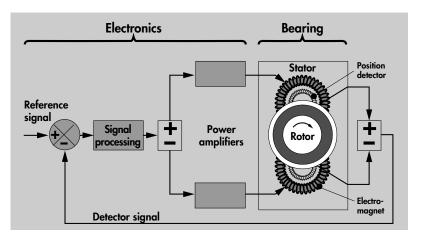


#### The pump operating principle

**5 actives axis** The mobile assembly formed by the turbo rotor and the shaft is known as the rotor. This rotor is driven by the motor and held in suspension by magnetic fields generated by electromagnets housed in active bearing, type ACTIDYNE® maglev bearing (S2M Patent). The mobile rotor has five axes of freedom monitored by 5 active bearings.



Movements in relation to these axes are monitored by position sensors. According to the position data recorded, the ACT controller corrects differences to bring the rotor back to its optimum position, by varying the current in electro-magnets.

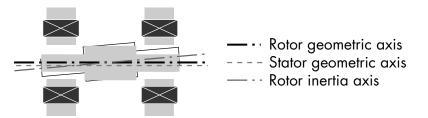


#### The pump operating principle

#### Automatic Balancing System

The **Automatic Balancing System** is an electronic device. That monitors the rotor position, allowing it to rotate on its own axis of inertia.

Changes in the rotor balance, due to deposit built-up during the life time of the pump, are automatically compensated by the **Automatic Balancing System**. Therefore, there is a total absence of vibration.



The back-up bearingsThey are dry-lubricated ceramic ball bearings.They are never used in normal operation, since the rotor<br/>is not in contact with the bearings.The back-up bearings are only used to protect the pump in<br/>accidental air in-rushes, accidental shocks or power failure.

**No maintenance** By design, the pump doesn't include parts liable to wear and doesn't need preventive maintenance. However, the back-up bearings used in case of accidental shut-downs have to be changed when the controller indicates it: the percentage of landing time to be deducted depends on its frequency of use (see D 10).

**Battery free** In case of a power failure, the motor acts like a generator, supplying enough power for the magnetic bearings. When the rotation speed is lower than the minimum setpoint, the pump lands and shuts down on the back-up bearings: the emergency breaking valve opens.

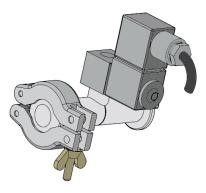
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#### The pump operating principle

#### Emergency braking valve

The valve is fitted in parallel with purge port and opens in case of events such as: - uncontrolled violent shocks applied to the pump; - large accidental air in-rushes. It will also put the pump to atmospheric pressure when the controller is stopped. This valve will slow down

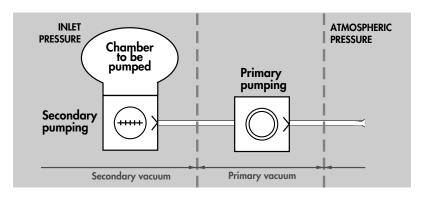
the pump in complete safety.



#### The hybrid-turbo pump in an installation

At the pump exhaust, the gases are evacuated to atmosphere by a primary pump. Since the ATHM compression ratio is set by the design,

the ATHM limit the pressure is given by that of the primary pump used.



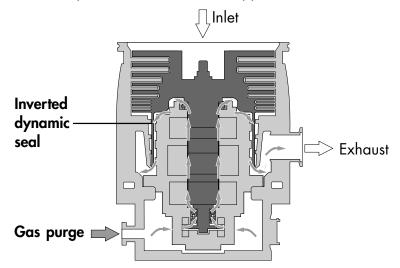
# The different versions

#### Standard version ATH 400M - ATH 1000M

#### An inverted dynamic seal

It creates a high compression ratio between the bearings and the pump exhaust and thus minimizes the quantity of corrosive gases in contact with the bearings.

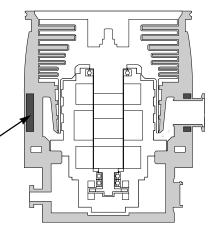
When used with **a gas purge** for high flow rate applications, the dynamic seal can, on its own, provide excellent protection for corrosive applications.



#### ATH 400MT ATH 1000MT

In high pressure and high throughtput processes such as metal etch, deposit can build up in the lower compression stages of the rotor, leading the pump to early failure.
 The built-in heater band allows pump heating up to 75°C, which is sufficient to prevent the condensation effect.

This device is thermally controlled by the ACT controllers.



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# The different versions

Variation of the pump rotational speed	The ATHM pump rotation speed can be selected and set between a standby speed and the maximum speed. This makes it possible to optimize pumping characteristics according to each customer application (for example, high pressure pumping).
	A distinction is made between the following speeds: - <b>reduced speed (STANDBY speed)</b> which can be set between the low speed value and the maximum speed. - <b>maximum speed</b> preselected at factory which corresponds to the pump model.

depending on operating conditions:	Pump model	Min. speed	Max. speed
Inlet pressure ≥ 10 <sup>-2</sup> mbar or Housing temperature ≥ 50°C	ATH 1000MT (with temperature control)	15000 rpm	30000 rpm
Inlet pressure ≤ 10 <sup>-2</sup> mbar or Housing temperature < 50°C	ATH 1000M	15000 rpm	33000 rpm
Inlet pressure $\leq$ 10-1 mbar	ATH 400M ATH 400MT	18000 rpm	39000 rpm

# ACT 600M and ACT 1000M controllers

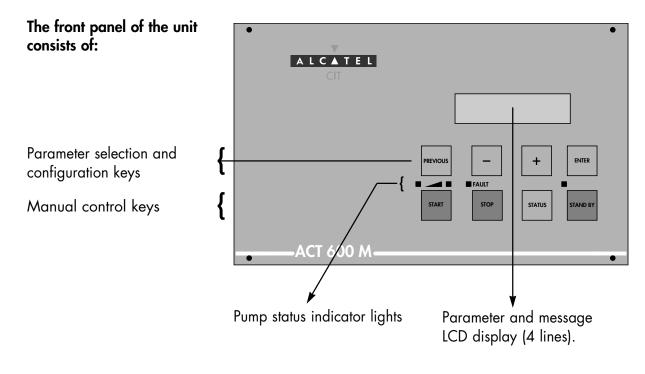
The ACT 600M and the ACT 1000M controllers belong to the new generation of ACT controller family.

Compact and functional Di

Dimension: **1/2 Rack**. Weigth: **8.5 kg** (18 lb).

All functions to monitor the ATHM are integrated into the controller.

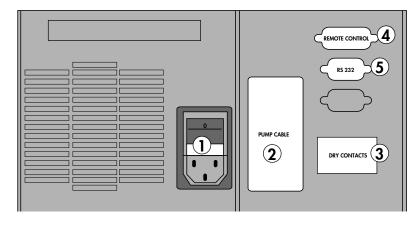
Convenient interface



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# ACT 600M and ACT 1000M controllers



- to replicate the monitoring parameters available in the form of dry contacts.

- The rear panel of the unit consists of:
- 1) Power supply connector
- 2 Pump connector
- (3) Relay terminal strip (Wiring characteristics on B 80.)
- (4) Remote control connector/RS 485

(Wiring characteristics on B 90.)

- for the remote control of the START, STOP, STANDBY functions;
- selectable 0 10 Volts output for speed, pump current or temperature;
- heater band control temperature;
- external safety taken in account.

RS485 serial link allowing many pump installations in a network.

(5) RS 232 connector (Wiring characteristics on B 100.) The RS 232 serial link is used to control and monitor the pump **using a computer**.

#### The accessories

#### Pump accessories

Screen filter	This filter protects the pump against solid particles. Mesh size 2.5 mm.	Inlet flange 100 ISO-KF (FPM)* 100 ISO-KF (NBR)* 100 CF-F 160 ISO-KF (NBR)* 160 CF-F 200 ISO-KF (FPM)* 200 ISO-KF (NBR)* 200 CF-F ASA 6"	P.N. 056844 103070 056845 056942 103071 056928 063158 103072 063159 102933
Compact filter	This filter stops particles ≥ 20 microns and is used in the event of high densities of dust or risks of implosion when pumping tubes or lamps.	Inlet flange 100 ISO-KF 160 ISO-KF 200 ISO-KF	P.N. 063215 063216 063911
Purge reduction device	This device is used to reduce the purge gas flow rate to 25 SCCM in some processes.	Flow rate 25 SCCM	P.N. <b>066950</b>
Isolation valve at inlet pump	The secondary isolation valve is used to maintain the vacuum in the chamber while the pump is reset to atmospheric pressure.	See the Alcatel ca	talog.
	An antira range of connection accessories ar	a available in the Alcatel cat	مامم

An entire range of connection accessories are available in the Alcatel catalog (clamping ring, centering ring, etc.).

# The accessories

#### **Controller** accessories

Connection cable	Interconnecting cable between pump and	Length	P.N.
		1 m	104624
	controller.	3.5 m	103719
		5 m	103720
		10 m	103721
		15 m	104587
Thermo. cable	Interconnecting cable between heater band and controller.	Length	P.N.
		1.0 m 115 V	104627
		1.0 m 230 V	105206
		3.5 m 115 V	103728
		3.5 m 230 V	103729
		5.0 m 115 V	103730
		5.0 m 230 V	103731
		10 m 115 V	103732
		10 m 230 V	103733
		15 m 115 V	105202
		15 m 230 V	105204

# The technical characteristics

# The performances of the pumps

Model characteristics		ATH 400M ATH 400MT		ATH 1000M		ATH 1000MT			
Inlet flange		DN	100 ISO-K	160 ISO-K	160 ISO-K	200 ISO-K	160 ISO-K	200 ISO-K	
Rotation speed		rpm	390	000	330	000	300	30000	
	N2	l/s	320	410	710	850	610	800	
Pumping speed*	He	l/s	290	360	650	750	600	650	
	H2	l/s	180	230	430	450	330	350	
	N2		1x1	0+8		2x1	0+8		
Compression rate*	He		2x1	0+3		1x1	0+4		
	H2		1x1	0+2		4x1	0+2		
Ultimate pressure without pur	ge, n	neas.							
according to Pneurop standa	rd m	nbar	8x10 <sup>-9</sup>		8×10 <sup>-9</sup>				
Maximum pressure at inlet									
in continuous operation** mbar		1		1×10 <sup>-1</sup>					
Maximum permissible									
pressure at exhaust**	m	nbar	5		5				
Noise level	(	dBA	$\leq$	39		$\leq \frac{1}{2}$	39		
Start-up time		min	<	3		<	5		
Maximum start-up power		W	65	50	650				
Maximum operating power		W	30	00	300				
N2 purge flow rate	SC	CM	50		50				
Cooling water flow rate		l/h	< 60		< 60				
Water temperature		°C	15 < T < 25°C		15 < T < 25°C				
Maximum ambient temperature °C		°C	40		40				
Weight		kg	19		28				
Recommended forepump		ADP 31		ADP 81					

\* See curves in G 10 and G 20.

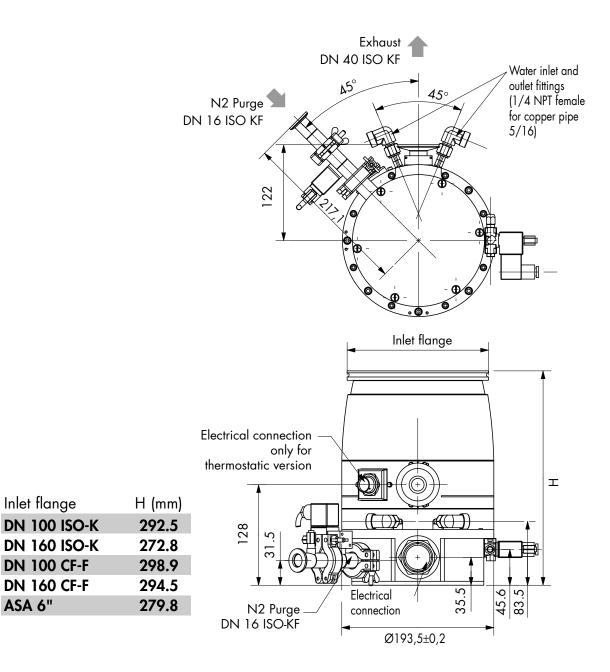
\*\* The two maximum pressure cannot occur at the same time.

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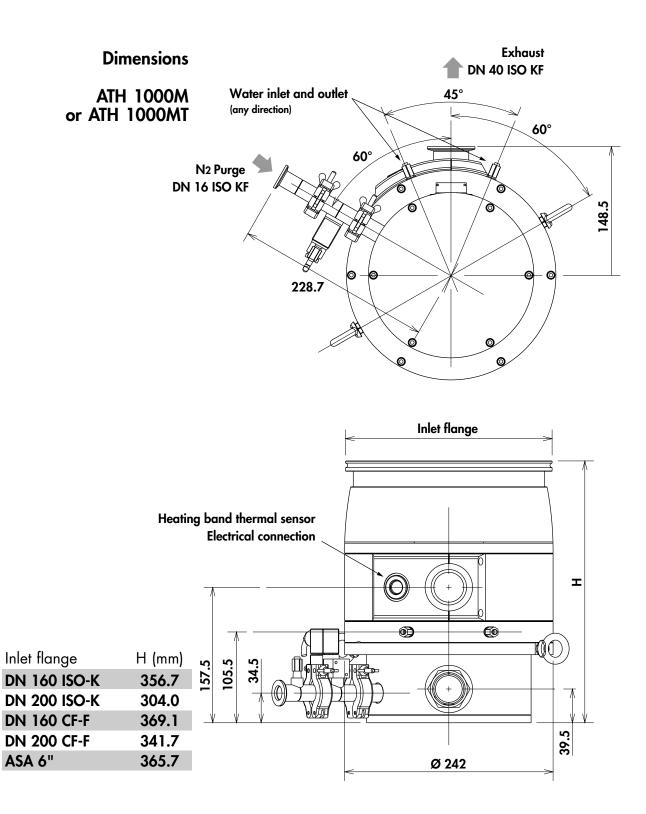
# The technical characteristics

Dimensions

ATH 400M or ATH 400MT



# The technical characteristics



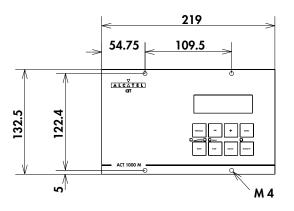
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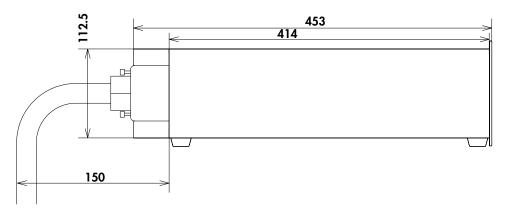
# The technical characteristics

#### **Controller characteristics**

Model characteristics	ACT 600M	ACT 1000M	
Weight	kg	8.	5
Dimensions HxWxD	mm	132.5 x 219 x 453 1/2 Rack 19"	
Power supply		17 Z Ku	
Nominal voltage	V	85 to 132 -	170 to 264
Frequency	Hz	48/	/63
Maximum power consumption VA		750	
Customer main circuit breaker	10 A		
Ambient operating temperature °C		T≤	50

**Controller dimensions** 





#### Safety instructions related to installation



Before switching on the pump, the user should study the manual and follow the safety instructions listed in the compliance certificate booklet supplied with the pump.

#### Installation Start-up

• The controllers must be connected to an electrical installation including an ground connection in compliance with decree 88.1056 of 14th November 1988.

• Our products are designed to comply with current EEC regulations. **Any modification of the product made by the user** is liable to lead to non-compliance with the regulations, or even to put into doubt the EMC (electromagnetic compatibility) performance and the safety of the product. ALCATEL declines any responsibility for such operations.

• Before any maintenance operations on a product performed by a maintenance technician who has not received safety training (EMC, electrical safety, chemical pollution, etc.), isolate the product from the various energy sources (electricity, compressed air, etc.).

The EMC performance of the product is obtained on the condition that the installation complies with EMC rules. In particular, in disturbed environments, it is essential to:
use shielded cables and connections for interfaces,
stabilize the power supply line with shielding from the power supply source to a distance of 3 m from the product inlet.

• The units containing control circuits are designed to guarantee normal safety conditions taking their normal operating environment into account (use in rack). In specific cases of use on tables, make sure that no objects enter the ventilation openings or block the openings when handling the units.

# Safety instructions related to installation

Installation	
Start-up	
(continued)	

• When switching off an item of equipment containing loaded capacitors at over 60 VDC or 25 VAC, take precautions concerning the access to the connector pins (single-phase motors, equipment with line filter, frequency converter, monitoring unit, etc.).

• When handling the equipment, use the devices provided for this purpose (hoisting rings, handle, etc.).

• Risk of toppling over: although compliance with EEC safety regulations is guaranteed (normal range  $\pm 10^{\circ}$ ), it is recommended to take precautions against the risk of toppling over during handling, installation and operation.

• The performance and the operational safety of this product are guaranteed provided that it is used in normal operating conditions.

• The vacuum pump is also a compressor: incorrect use may be dangerous.

Study the user manual before starting up the pump.

• The access to the rotor of a turbomolecular pump with an unconnected intake is dangerous. Similarly, if the pump is not switched on, it may be driven by another pump in operation (risk of injury).

• Make sure that the parts or chambers connected to the intake of our pumps withstand a negative pressure of 1 bar in relation to the atmospheric pressure.

• The leaktightness of the products is guaranteed when they leave the factory for normal operating conditions. It is the user's responsibility to maintain the level of leaktightness particularly when pumping dangerous gases.

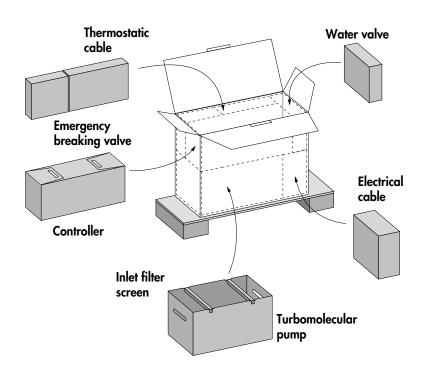
# Unpacking and storage

**Unpacking** Unpack the equipment carefully and keep the packaging. Make sure that the equipment has not been damaged during the transport. If it has been damaged, take the necessary steps with the carrier and inform Alcatel if necessary.

In all cases, we recommend that you keep the packaging (reprocessing material) to transport the equipment if necessary or for prolonged storage.

To keep your product in the clean condition in which it left our factory, we recommend to unpack the pump only on its assemby site.

#### Weight of the complete shipping crate : 50 kg maxi.



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# Unpacking and storage

The accessories	This packaging also contains other cardborad boxes, for the accessories (screen filter, emergency braking valve, water valve and purge device) and for the electric cable.
The controller	It is packaged in a separated cardboard box. Lift the device out of its packaging (weight 8.5 kg) by hand.
The pump	It is packaged in a separated cardboard box.
	Lift the ATH 1000M out of its packaging by using the hoisting rings (weight 28 kg).

**Pump storage** Our equipment can be stored without special precautions (ambient temperature between 5 and 40°C).

Inlet	ASA 6'', ISO or CF-F flange blanking and rotor holding system.	
Exhaust	Blanked with a DN 40 ISO-KF protector.	
Connection for emergency braking valve and nitrogen device	Blanked with a DN 16 ISO-KF protector.	

#### Unpacking and storage

Controller storage	The controller can be stored in its cardboard box at storage temperature between - 20°C and + 70°C.			
•				

**Storage mode** The controller is set in STORAGE mode at factory, to protect internal RAM memory during transport and storage.

When the controller is powered, the storage mode disappears automatically.

Set the storage mode for prolonged storage when the pump is stopped.

Maglev pump connection instructions Why securing MAGLEVpump installation ?

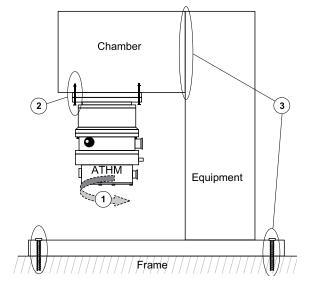
Maglev hybrid Turbopumps are designed so as to prevent any safety hazard to the user in standard operating conditions.

However, some operating conditions may generate hazards for the user and the environment: the kinetic energy stored in a maglev turbopump is very important. In case of a mechanical failure an improperly installed pump could be ejected from the equipment if the kinetic energy was tansferred to the pump body.

It is absolutely necessary to install the pump according to the following installation specifications to secure the user and the equipment.

Alcatel declines any responsibility if the pump installation is not design in accordance with these installation specifications.

#### Installation spécifications



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# Installation with bolted flange

The kinetic energy of the rotor has to be absorbed by the installation **if the pump seizes suddenly**. **The resulting maximum deceleration torque** is based on the assumption, that the rotor stops in half a turn and that

the assumption, that the rotor stops in half a turn and that the whole energy has to be taken by the pump assembling bolts.

Design and secure the pump frame so that it can withstand the maximum deceleration torque.

Maximum deceleration torque to stop the rotor in half a turn (item 1)

- 9159 Nm for ATH 400 M at nominal speed 39000 rpm
  20000 Nm for ATH 1000 M at nominal speed 33000 rpm
- Inlet flange installation conditions (item 2)

According to the housing type:

Mounting holes at inlet flanges					
Inlet flange	DN -	ISO-F	160	200	250
Type of bolts dictated			M 10	M 10	M 10
Number of bolts dictated			8	12	12
Bolt metric grade		12-9	12-9	12-9	
Installation torque per l	bolt	N.m	35+5	<b>35</b> +5	35+5



For safety reasons, it is important to tighten the bolts with a torque wrench according to the specified values :

- lower torque: risk of loosened bolts

- higher torque: risk of damaging the bolts.

# B 30

#### Pump connections to an installation

#### Inlet flange installation conditions (item 2)) (Continued)



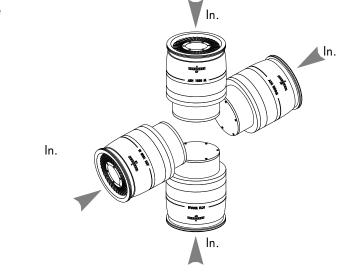
We strongly recommend the use of ISO-F or CF-F flanges. ISO-K type flanges are not recommended to fasten turbomolecular pumps with inlet flange equal or larger than DN 200 because:

- there is no visual reminder (like threaded holes on ISO-F) to signal how many clamps are needed to secure the pump,
- it is not as easy to fasten claw clamps on ISO-K flanges as to secure bolts on ISO-F flanges,
- the ISO-K flanges do not prevent accidental rotation of the pump on the equipment flange in case of pump rotor crash. This rotation could damage the foreline and the purge gas line which would generate hazards for the user.

#### Equipment installation conditions (item 3)

The equipment frame on which the pump is installed must be sufficiently rigid to absorb the kinetic energy of the rotor in case of pump rotor crash. For this, take into account:

- the maximum deceleration torque to calculate the equipment attachment devices,
- the flange dimensions,
- the quality and the number of screws,
- no reducing adaptater or bellows should be installed between pump inlet flange and the chamber.



The pump can operate in any position

# Rotor flanging device disassembly

To prevent the pump maglev bearings from being damaged due to shocks during transport, **the rotor is flanged to the pump housing.** 



Welcome

The pump must never be swiched in this condition. This flanging must only be removed when the pump is to be installed.

We recommend that you keep the flanging to transport the equipment.

Vacuum connections	Remove the protective parts blocking the inlet, exhaust and purge openings: these components prevent foreign bodies from entering the pump during transport and storage. It is dangerous to leave them on a pump in operation.			
At inlet:				
Screen filter		compact filter accessory on mp to the installation or connect ve.		
Secondary isolation valve		Secondary isolation valve V2		

isolation valve.

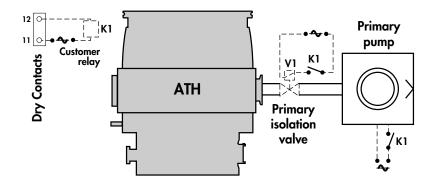
#### At exhaust:

#### Primary isolation valve (closed with power off) between the ATH pump and the roughing circuit.

The valve is closed using the « START » contact on the controller. If the valve is missing, the time taken to slow down in the event of an accident is increased, thereby reducing the service life of the back-up bearings.

Connect this valve such as an Alcatel bracket valve **as near the pump exhaust as possible** depending on the space available and the accessories installed.

Connect the valve to the primary pumping circuit\*.



\* Different connection accessoiries can be found in the Alcatel Catalog.

# **Typical connection**

- In this installation, we use: A primary isolation valve V1 between the ATH and the roughing pump; - a secondary isolation valve V2 between the ATH and the chamber to be pumped; - a relay K1, their contacts drive the valve V1 and the primary pump power supply; - the thermostatic option.
- Primary isolation valve V1 ×. ×. ₽ Primary pump X ATH Minimum electrical connection
   Thermostatic cable for ATH MT
   - - - Customer supplies recommended by Alcatel ; ; ; ; ; ; ; ; ; ; Heating band Secondary isolation valve V2 Ę Emergency breaking valve V3 Legend Water valve 1 Xq Customer relay Customer wiring ₹ Щ ł Stand-by 12 Control 3 Start 10 Start 2 External 9 Start 10 Temp. 7 0-sensor 6 0-supphy 5 0-Storr 12 -Power supply Ξ Pump cable ACT Stand-by Air Inlet Is a lation Valve Remote Dry Contacts

7/7

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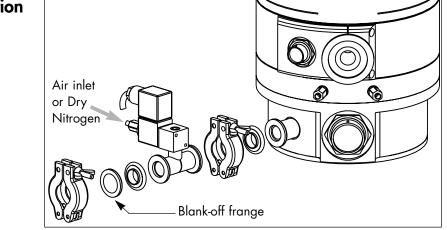
#### Emergency braking valve connection

The braking valve must be connected to ensure the pump's safety and durability.

Function In the event of a major problem (magnetic bearings fail, external shock...), the pump must be stopped as soon as possible to prevent damage to the back-up bearings. The emergency braking valve is calibrated to reset the volume of the pump to atmospheric pressure. When the pump is isolated (at inlet and exhaust) the rotor slow down efficiency is increased.

The reset to atmospheric pressure takes place when faults are registered on the controller which stops the pump and controls the air inlet *(see D 20)*.

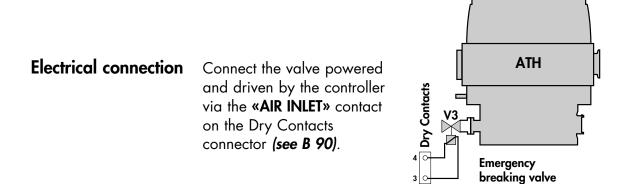
#### Vacuum connection



Install the calibrated emergency braking valve on the DN 16 fitting of the pump.

The valve must be connected to an air inlet line which can be for example dry nitrogen (Pressure between 1 and 1.5 bars absolute) (see B 50 for nitrogen characteristics).

#### Emergency braking valve connection



#### Nitrogen purge device connection

#### Characteristics of of filtered dry nitrogen supply

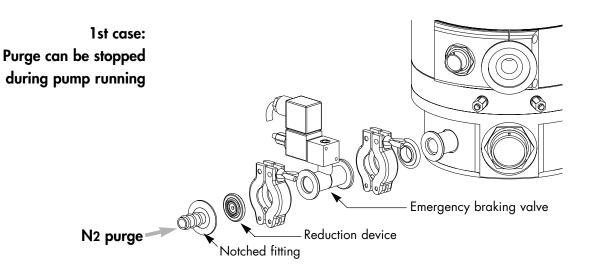
A filtered dry nitrogen supply with the following characteristics is required:

- Dew point < 22°C
- Dust < 1 μm
- Oil < 0.1 ppm
- Absolute pressure of 1 to 1.5 bar.

#### **Purge connection**

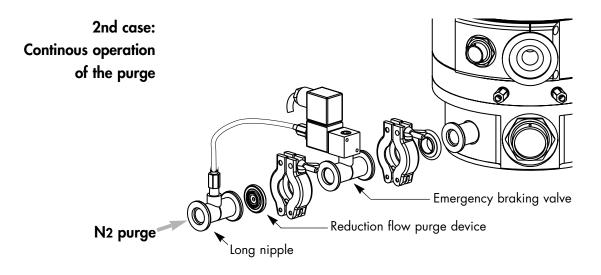
The nitrogen purge must be connected to the braking valve so as not to disturb its operation and not between the valve and the pump.

Connect the nitrogen supply to the DN 16 purge fitting\*. The nitrogen flow reduction device controls the pressure and guarantees a flow rate of 50 SCCM at pressure 1.1 bars.

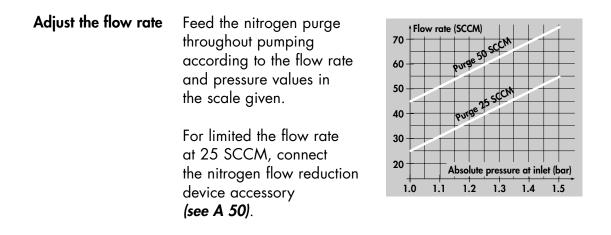


\* Différent connection accessories can be found in the ALCATEL catalog.

#### Nitrogen purge device connection



Connect the little flexible pipe between the long nipple and the valve.



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#### Water cooling connection

Characteristics of water cooling	In order to limit the corrosion and clogging of the cooling pipes, it is recommended to use cooling water with the following characteristics: - treated soft water or non-corrosive industrial water - pH between 7.5 and 11 - hardness < 7 milli-equivalent/dm <sup>3</sup> - Resistivity > 1500 Ω.cm - Solid pollution < 100 mg/dm <sup>3</sup> - Max. pressure: 7 bars - Temperature: 15 < T < 25°C - Flow rate: 60 l/h
For ATH 1000M models	<ul> <li>Provide a water inlet pipe and a tap to adjust the flow rate.</li> <li>Install the two male connector delivered on the cooling device (connector 1/8 NPT)</li> <li>Connect the water inlet line to one of the cooler nipples, with the other nipple connected to the water draining circuit via a flexible tube (ext. diam 1/4') (supplied by customer).</li> </ul>
For ATH 400M models	- Connect the water inlet line to one of the cooler

water fittings 1/4 NPT female on the pump, with the other fitting connected to the water draining circuit via a tube (supplied by customer).

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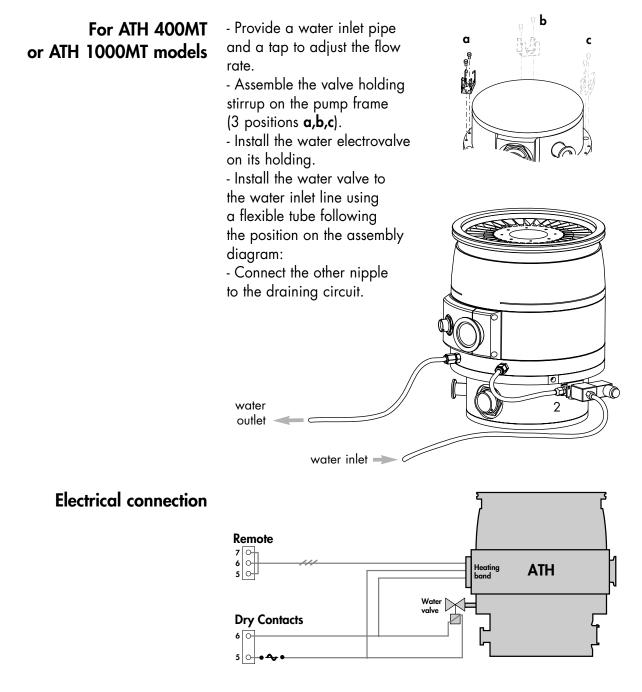
Alcatel - High Vacuum Technology - User's Manual ATH 400M / ATH 1000M

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## **B 60**

#### Water cooling connection

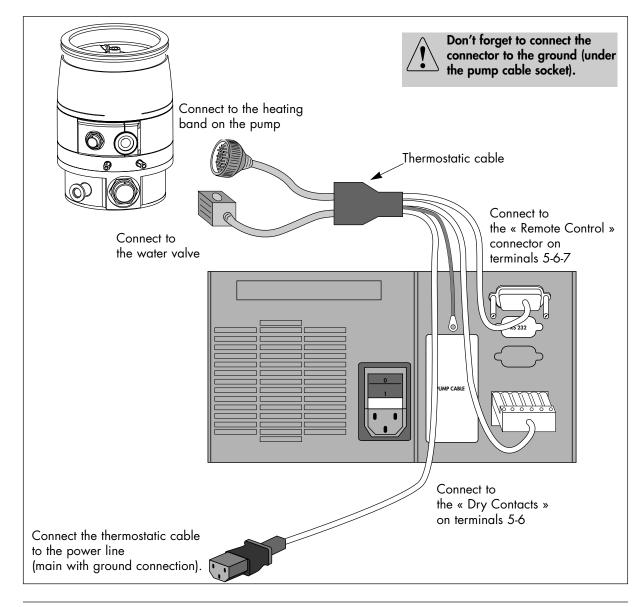


Connect the water valve via the «THERMOSTAT» contact on the DRY CONTACTS connector and supply it via the thermostatic cable.

#### Heating band connection

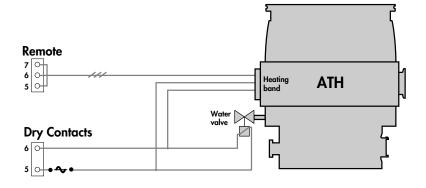
**For ATH 400MT** and ATH 1000MT These pumps are equipped with an heating band, a thermal sensor and a valve to regulate the water flowrate. The body of the pump can be heated to 75°C to avoid gas condensation in the pump on the semiconductor processes.

**Connection** Connect the thermostatic cable as follows:



#### Heating band connection

#### Heating band temperature



The temperature can be choosen on the controller (between 31 and 75°C or NO°C). By choosing «NO°C» temperature, the heating band is

switched off and the pump is cooled permanently.

If there is a failure on the temperature sensor on the heating band, the controller display indicates:

PUMP-TEN	1P2	0 0 ° C
DEF 38	TEMP.SE	NSOR 2

The heating band is switched off and the pump is cooled permanently.

The temperature of the heating band can be read on the display of the controller *(see C 30)*.



#### **Electrical connection**

**Controller** installation

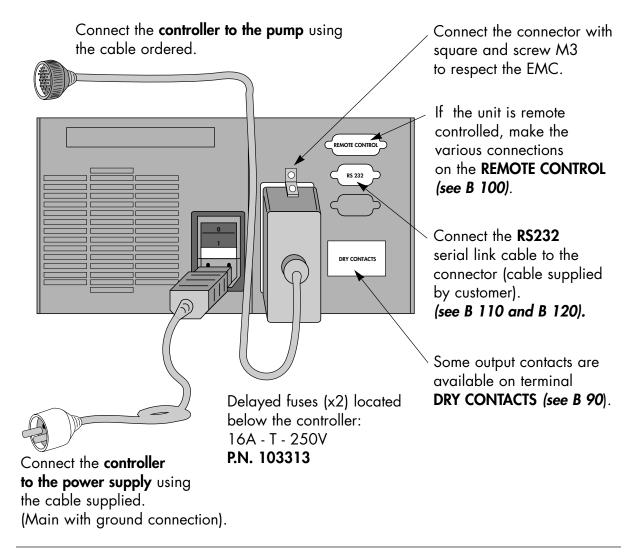
The unit must be installed in an environment ventilated either by natural convection or by the movement of forced air. Cooling is normally performed by an internal fan which ventilates air from the inside to the outside of the unit. **Make sure that:** 

- the openings on the bottom, top and rear of the unit are not blocked;

- the ambient temperature does not exceed 50°C;

- a free space of at least 15 mm is left behind and below the unit.

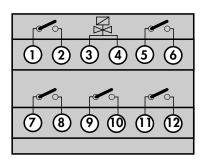
#### Connections



## «Dry contacts» relay wiring

## Signaling using output contacts:

These are dry contacts (220VAC - 3A): their functions are to copy the data concerning the pump operating status.



Isol. valve <b>1 - 2</b>	When the controller detects a bearing operating fault or after a stop, it opens the contact. <b>This contact must be used to control a secondary</b> <b>isolation valve</b> which is used to maintain the pressure in the chamber while the pump is reset to atmospheric pressure.
Air inlet <b>3 - 4</b>	
Speed <b>7 - 8</b>	The contacts is closed when the pump reaches the selected speed.
Fault <b>9 - 10</b>	The contact is opened if a faults appears.
Thermostat <b>5 - 6</b>	The contact is opened or closed, depending on the pump temperature and the selected temperature.
Start <b>11 - 12</b>	The contact is closed when the «START» control is activated on the controller. The contact can be used to control a primary isolation valve, and via a power relaying device, to control a primary pump.

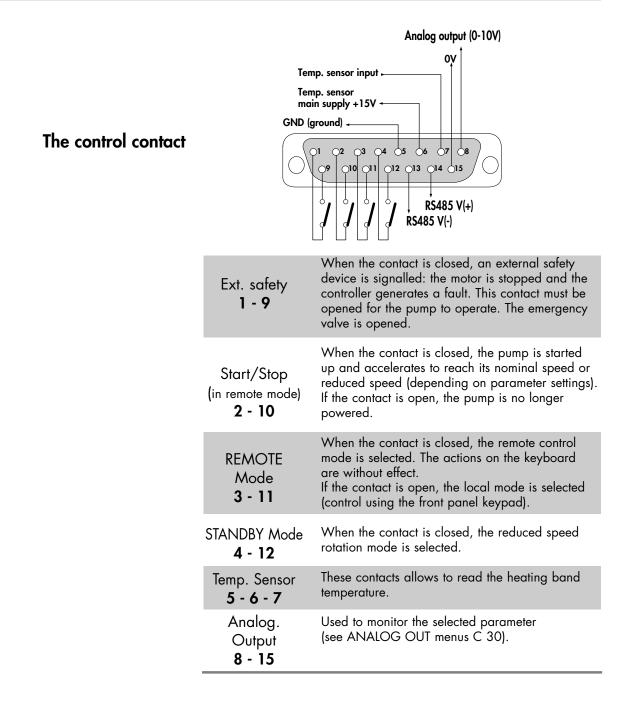
## Contact functionnal status

	Power off	Power on	Stop	Start on	Nominal speed	Alarm	Defect
ISV.							
Thermos.			===	Depending on tem	perature parameter	===	===
Speed						Depending on speed	l
opcor 0							
Fault							
a1							
Start 0							

#### "Remote Control" connector wiring



When the units containing the control circuits are equipped with dry contact outputs, it is the customer's responsibility to use the outputs in compliance with safety regulations.



### "Remote Control" connector wiring

Analog output signal	The signal is transmitte the remote connector.	ed betweer	n terminc	Il 8 and 15	of
	Five values can be use	ed to plot a	curves:		
	θ1 Pump temperature: (θ1 PUMP)	0°C	(OV) to	100°C	(10V)
	θ2 Pump temperature: (θ2 PUMP)	0°C	(OV) to	100°C	(10V)
	Pump rotation speed: ( <b>SPEED</b> )	360 rpm	(OV) to	30000 rpm	(5V)
	(37660)	360 rpm	(OV) to	33000 rpm	(5.5V)
		360 rpm	(OV) to	39000 rpm	(6.5V)
	Controller temperature: (θ <b>CONV</b> )	0°C	(OV) to	100°C	(10V)
	Motor current: (I MOTOR)	0 mA	(OV) to	8700 mA	(5.8V)
	Motor current (mA) 00000	Pump temperature 1 (°C) 00	Pump temperature 2 (°C)		
	Conver	Pump	Pum		

Voltage (V)

10

Factory configuration is setted on (SPEED).

0

0

0

0

0

0

#### RS 232 or RS 485 serial link wiring

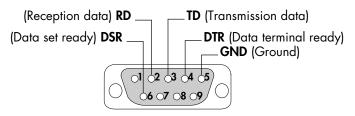
At the first power-up, the user finds the default configuration. The serial link parameters can be modified by accessing the corresponding unit menu (see C 30).

The default configuration of the serial link is as follows:

■ Type: **RS 232** ■ Transmission speed: 9600 bauds ■ Data length: 8 bits ■ Parity: **NONE** Stop bit: 1

Refer to C 30 to customize the parameters.

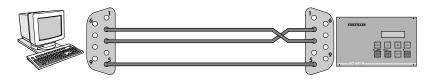
#### **RS232** connector wiring:



DB 9 contacts, male connector.

**Connection examples:** 

RS232 type serial link with a single controller

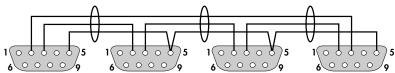


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The multiple link is obtained by creating a loop:

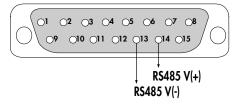
## Multiple RS232 serial link:

several units (up to 999) can be controlled on a single link.



## RS 232 or RS 485 serial link wiring

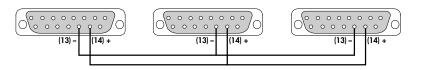
RS485 connector wiring:



«Remote Control» connector 13 and 14 pins DB 15 contacts, male connector.

#### Multiple RS485 serial link:

several units (up to 999) can be controlled on a single link.



(valid from V.2.03 version controller)

Conventions applicable to the syntax of all commands:	<ul> <li>adr = address, from 000 to 255</li> <li><cr> Carriage Return (ascii 13)</cr></li> <li><lf> Line Feed (ascii 10); between square brackets: this character is not compulsory.</lf></li> </ul>
Status values	<b>OK</b> : command executed correctly
Error messages	<ul> <li>Err0 : adjustment error (out of bounds)</li> <li>Err1 : command error (syntax)</li> <li>Err2 : parameter error (e.g. non-hexadecimal character)</li> <li>Err3 : context error</li> <li>Err4 : checksum error</li> </ul>
ADR	Specifies the address of the device for networking.
Syntax	#adr <b>ADR</b> ,aaa <cr>[<lf>] adr = address of the device before the command aaa = new address of the device condition : 000 ≤ aaa ≤ 255</lf></cr>
Result	#aaa,OK or Err2
	This command is used to allocate a specific number to each of the products making up a network (loop for RS 232 or parallel for RS 485).
	Note : it is important to note down the number allocated to each device.
	the dealer for the
DEF	List the faults
Syntax	#adr <b>DEF</b> <cr> List the faults separated by the separator character.</cr>
Result	#adr,OK if there is no fault

DLI	Defines the DataLogger transmission interval
Syntax	#adr <b>DLI</b> ,xxx <cr>[<lf>] xxx: DataLogger send interval in seconds condition: 001 ≤ xxx ≤ 255</lf></cr>
Result	#adr,OK or Err2
See also: <b>DLR</b>	Note: if OK, the interval sent is stored in user memory.
DLR	Enables DataLogger operation (only with RS232)
Syntax	#adr <b>DLR</b> <cr>[<lf>]</lf></cr>
Result	#adr,OK
	The main characteristics of the pump and its controller are sent over the RS link, at the rate defined by the <b>DLI</b> command.
	Note: any new characters arriving on the serial port (RS 232) will cancel the automatic DataLogger transmission.
GET	List the data (data only)
Syntax	#adr <b>GET</b> AI <cr>[<lf>] : List analog inputs #adr<b>GET</b>LI<cr>[<lf>] : List logical inputs #adr<b>GET</b>LO<cr>[<lf>] : List logical outputs</lf></cr></lf></cr></lf></cr>

IDN	Identifies the device which is communicating, and its software version
Syntax	#adr <b>IDN</b> <cr>[<lf>]</lf></cr>
Result	#adr, ACT1000M Vx.zz
	Returns the type of Variable drive Supervisor, the software version (x), the software edition (zz).
LEV10	Returns the state of the parameters defined by SET
Syntax	#adr <b>LEV</b> 10 <cr>[<lf>]</lf></cr>
Result	#adr,nnnnn,sssss,00000,0,ccccc,eeeee,ddddd,pppp,qqqq, jj,kk,000,mmm
	Returns current values: nnnnn : nominal speed set point (in rpm) sssss : stand-by speed set point (in rpm) 00000: not used 0 : not used ccccc : pump working time (in hours) eeeeee : electronic working time (in hours) ddddd : start delay (max 14459 s, that is 240 mn 59 s) pppp : time to venting (max 3599 s, that is 59 mn 59 s) qqqq : venting time (max 3599 s, that is 59 mn 59 s) ii : speed threshold for relay (3 to 50 %) kk : control temperature (30 to 75°C) 00 : not used

mmm : bearing current value (0 to 100 %)

NOW	Display date and time	
Syntax	#adr <b>NOW</b> <cr>[<lf>]</lf></cr>	
Result	MM/DD/YY HH:MM:SS	
NSP	Switches the speed set point to the nominal speed value	
Syntax	#adr <b>NSP</b> <cr>[<lf>]</lf></cr>	
Result	#adr,OK	
	The speed set point for the pump is set to its nominal value.	
OPT	Used to select possible user choices	
Syntax	<pre>#adrOPT01,n<cr>[<lf>] choice of parameters on the analog output:     n = 0 : real pump speed     n = 1 : pump current     n = 2 : temperature of pump body     n = 3 : temperature of internal electronics</lf></cr></pre>	
Result	#adr,OK	
	Comment: The choice of the temperature unit affects the results of the DLR and STA strings and the display	

(if cabinet fitted).

RPM	Defines the speed set point in stand-by mode		
Syntax	#adr <b>RPM</b> ,nnnnn <cr>[<lf>]</lf></cr>		
Result	#adr,OK <i>or</i> #adr,ErrX 1, out of range; 2, parameters ; 3, context (not in Stand-by mode)		
	Comment: if OK, the new speed is automatically stored in user memory.		
SBY	Switches the speed set point to the stand-by value		
Syntax	#adr <b>SBY</b> <cr>[<lf>]</lf></cr>		
Result	#adr,OK		
	Resets the stand-by speed to its last stand-by stored value, and allows it to be modified if an «RPM» command is sent. This configuration is automatically stored in user memory.		
SEL10	Returns the state of the parameters defined by OPT		
Syntax	#adr <b>SEL</b> 10 <cr>[<lf>]</lf></cr>		
Result	<pre>#adr,a,0,0,0 a : Returns choice of parameters on the analog output:     a = 0 : real pump speed     a = 1 : pump current     a = 2 : temperature of pump body     a = 3 : temperature of internal electronics 0,0,0 : not used</pre>		

SCR	List all the data (titles and data)	
<b>Syntax</b> #adr <b>SCR</b> <cr>[<lf>] : List all the data #adr<b>SCR</b>AI<cr>[<lf>] : List all the analog inputs #adr<b>SCR</b>AO<cr>[<lf>] : List all the analog outputs #adr<b>SCR</b>LI<cr>[<lf>] : List all the logical inputs #adr<b>SCR</b>LO<cr>[<lf>] : List all the logical outputs</lf></cr></lf></cr></lf></cr></lf></cr></lf></cr>		
SET	Defines the internal operating	parameters
Syntax	#adr <b>SET</b> 10,ccccc <cr>[<lf>] :</lf></cr>	pumping working time (in hours)
	#adr <b>SET</b> 11,eeeee <cr>[<lf>] :</lf></cr>	• •
	#adr <b>SET</b> 13,ddddd <cr>[<lf>] :</lf></cr>	start delay (max 14459s, that is 240mn 59s)
	#adr <b>SET</b> 14,pppp <cr>[<lf>] :</lf></cr>	time to venting (max 3599) that is 59mn 59s)
	#adr <b>SET</b> 15,qqqq <cr>[<lf>] :</lf></cr>	venting time (max 3599s, that is 59mn 59s)
	#adr <b>SET</b> 30,jj <cr>[<lf>]:</lf></cr>	speed threshold for relay (3 to 50 %)
	#adr <b>SET</b> 31,kk <cr>[<lf>]:</lf></cr>	· · · ·
	#adr <b>SET</b> 33,mmm <cr>[<lf>] :</lf></cr>	· · · ·

**Result** #adr,OK or ErrX

SEP	Defines the character which separates the parameters in a reply
Syntax	#adr <b>SEP</b> ,nnn <cr>[<lf>] nnn: 3-digit decimal value of the ascii code of the desired character (with leading zeros). condition : 000 ≤ nnn ≤ 255</lf></cr>
Result	#adr,OK or #adr,ErrX if error
	Allows the user to select the character which separates the parameters returned by the <b>DLR</b> , <b>STA</b> and <b>LEV</b> commands. Default value: comma «,» ascii code = 044 If ok, the selected value is automatically stored in user memory.
	memory.

SPD	Returns the current speed	
Syntax	#adr <b>SPD</b> <cr>[<lf>]</lf></cr>	
Result	#adr,nnnn	

#### STA Returns the status of the internal dynamic parameters

Syntax #adrSTA<CR> or STA<CR>

#### Result

#adr,s,rrrrr,vvv,www,xxx,yyy,zzz,aaa,bbbbb,cccc,ddd,eee, fff,ggggggggggggggggggggg<CR>

adr: address

#### s: order status

Bit	7	6	5 LOCAL	4 STOP	3 RS	2 REM	1 STDBY	0 START
0	-	OFF	OFF	OK	OFF	OFF	OFF	OFF
1	1	-	ON	fault	ON	ON	ON	ON

rrrrr:	speed in rpm	aaa:	Motor voltage V
vvv:	Radial v13	bbbbb:	Motor current mA
www:	Radial w13	cccc:	Motor load W
	Radial v24	ddd:	Pump temp 1 (°C)
	Radial w24		Pump temp 2 (°C)
zzz:	Axial z12	fff:	Controller temp (°C)

g	0 = OK	1 = ALERT	2 = FAULT
0	0=OK	D02: motor overheat	
1	0=OK	D03: converter overheat	
2	0=OK		D04: hall sensor
3	0=OK		D05: permanent fault
			sensor
4	0=OK		D06: external safety
5	0=OK		D31: jump DT0/DT1/DT2
6	0=not used		
7	0=not used		
8	0=not used		
9	0=OK		D14: v13
10	0=OK		D15: w13
11	0=OK		D16: v24
12	0=OK		D17: w24
13	0=OK		D18: z12
14	0=OK	D23: hot pump	D21: overheat-1
15	0=OK	D22: controller temp.	
16	0=OK		D26: wires disconnected
17	0=OK	D27: converter memory	
18	0=OK	D28: pump memory fault	
19	0=OK		D29: input power failure
20	0=not used		

TIT	List the data titles			
Syntax	#adr <b>TIT</b> LI <cr>[<lf>] : List la</lf></cr>	<b>TIT</b> AI <cr>[<lf>] : List analog inputs <b>TIT</b>LI<cr>[<lf>] : List logical inputs <b>TIT</b>LO<cr>[<lf>] : List logical outputs</lf></cr></lf></cr></lf></cr>		
ТМР	Defines the operating state of the turbomolecular pump			
Syntax	#adr <b>TMP</b> ON <cr>[<lf>] #adr<b>TMP</b>OFF<cr>[<lf>]</lf></cr></lf></cr>	start pump rotation stop pump		

#### Safety instructions related to operation



Before using the controller, make sure that the mechanical and electrical connections have been made *(see chapter B)*. If an error message is displayed during operation, *see D 20*.

The machines are designed so as not to present a thermal risk for the user's safety. However, specific operating conditions can generate temperatures which require particular care to be taken by the user (external surfaces > 70°C).

Avoid moving or causing a shock on a pump in operation. There is a risk of seizing if the pump rotates in an axis perpendicular to its axis of rotation.

The emergency braking valve must be connected (see B 40) to ensure the pump's safety and durability.

As long as the pump is running, the emergency braking valve has to be supplied with neutral gas.

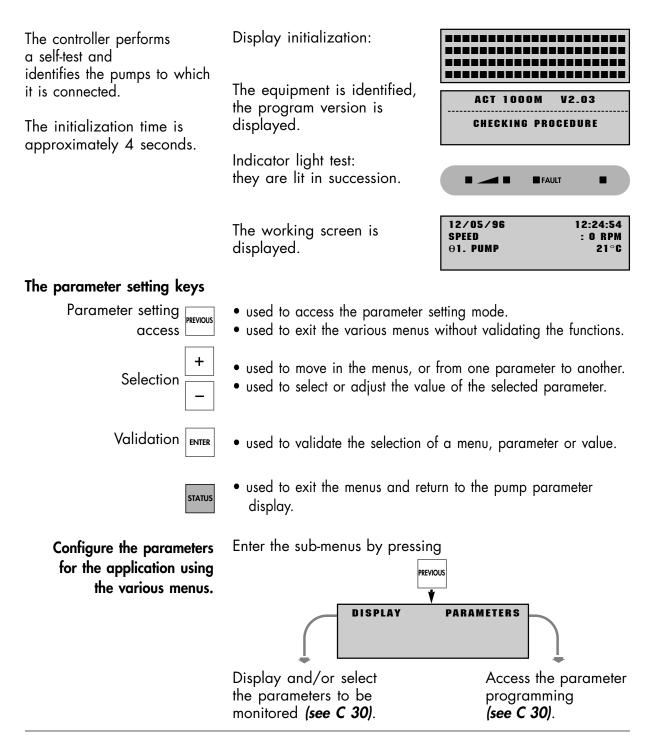


The controller should never be switched off as long as the rotor is moving.

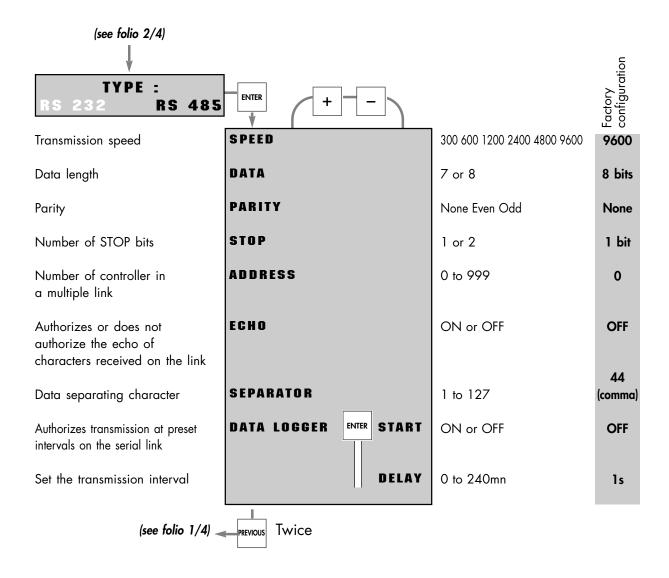
- It is highly recommended to install:
- a screen filter at the pump inlet;
- an isolation valve between the chamber to be pumped and the ATH pump;
- an isolation valve between the ATH pump and the backing pump.

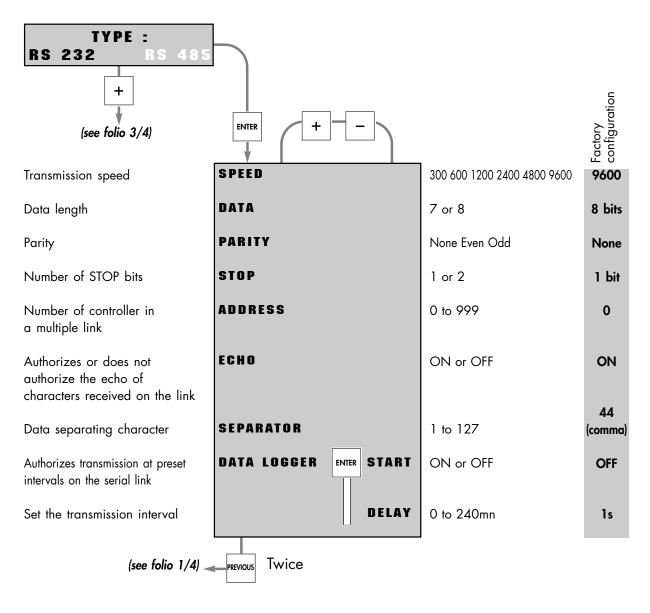
#### **Controller start-up**

Once the various electrical connections have been made, set the main switch on the rear panel to "I".



Programming the parameters PARAMETERS					
PARAMETERS					
Modify the date	DATE				
Modify the STANDBY speed	SPEED		(see A 30)	15000 ATH 1000M <b>18000</b> ATH 400M	
Modify the time before starting up the pump	START	DELAY	0 to 59mn 59s	Omn Os	
Modify the heating temperature	TEMP		31 to 75°C or NO°C (for ATH MT)	65°C	
Modify the RS232 serial link or RS485	RS 232 ENTER	RS 485	(see details page 2/4)		
Configure the 0-10V output	AN.OUT ENTER	SPEED I.MOT 01.PUMP 0.Conv 02.Pump	SPEED         1 V per 6000 rpm           I.MOT         1V per 1.5 A           0.PUMP         0.1V per 1°C           0.CONT         0.1V per 1°C           0.PUMP         0.1V per 1°C	SPEED	
For Alcatel Customer Support	RESET	CONVERTER Bearing			
Modify the time before opening the air inlet valve		DELAY	0 to 59mn 59s	ls	
Modify the air inlet valve opening time		VENTING TIME	0 to 59mn 59S	]s	
For Alcatel Customer Support	RELAY			-3%	
Change to storage mode (see B20).	STOCK				
Parameter menu — PREVIOUS					





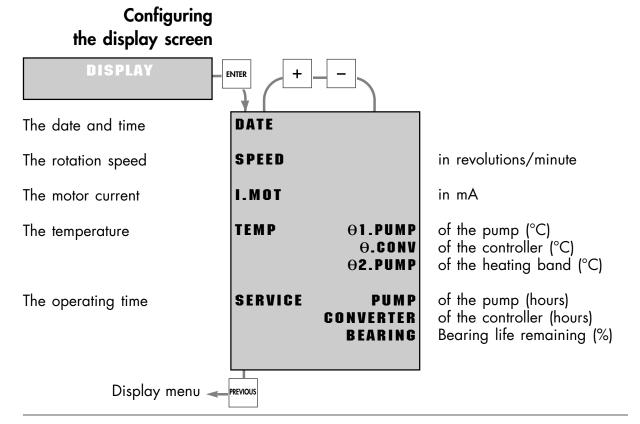
#### The various indicators on the display:

12/05/96	12:24:54	Ist parameter
SPEED	: 33000 RPM	2nd parameter
01.PUMP	75°C	3rd parameter
HOT	PUMP - HOT PUM	Messages

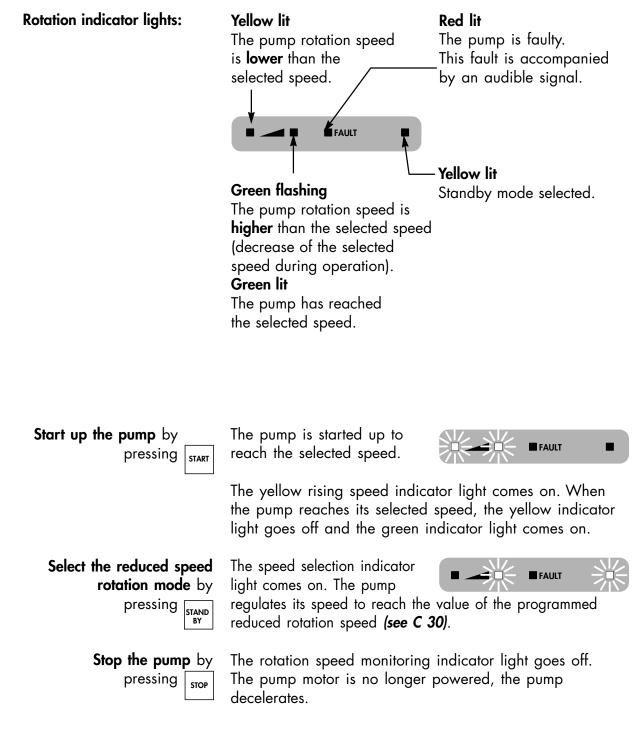
## 3 parameters can be selected in the pull-down menu from the list below:

- the current date and time;
- the rotation speed of the pump in «rpm»;
- the current pump motor (mA);
- the pump internal temperature and the housing temperature of the pump (°C);
- the temperature of the controller (°C);
- the number of hours that the pump is in operation (h);
- the number of hours that the controller is in operation (h);
- the % life remaining on the back-up bearings (%) before changing the bearings.

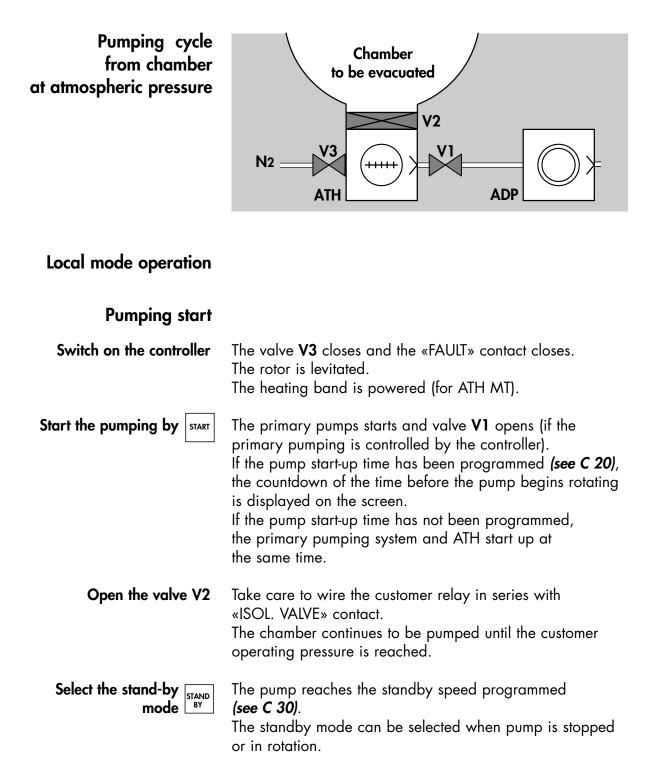
When switched on, the controller displays: the date and time, the rotation speed and the pump temperature.



#### Controlling the pump using the controller front panel



# Pump operation in a pumping application



# Pump operation in a pumping application

#### Pumping stop

Stop the pumping by STOP	This closes the primary isolation valve <b>V1</b> and the primary pump stops. If the ISV contact is connected, <b>V2</b> closes.
Close the valve V2	The level of vacuum in the chamber is maintaining.
	Allow the purge to flow through after pumping has stopped in order to eleminate the dead volume in the pump with neutral gas. Eventually, make an air inlet on the pump to brake its rotation. Without air inlet, the duration of the rotor slow-down until its complete stop could be more than 30 minutes.
Remote control mode operation	
Remote control mode selection	Close the contact «REMOTE» on the Remote Control connector <b>(see B 90)</b> . The keyboard control keys on the front panel (Start, Stop, Standby) are deactivated.
	In this mode, the functions are the same to the local mode.

# Pump operation in a pumping application

Immediate restarts	If the pump has been stopped by an air inlet, we advise to limit to 2 the number of immediate restarts.
	If the pump has been stopped without air inlet, immediate restarts are not limited.

Event of a power cut If a power cut occurs, the rotor remains suspended by the energy emitted by the motor's counter-electromotive force, until the rotor rotation speed is low enough (around 9000 rpm) so that it can rest on the back-up bearings without being damaged.

# Short power cuts The controller display indicates temporarily: D 29 : INPUT POWER

If the power is restored before this minimum speed (9000 rpm) is reached, the pump resumes its initial speed without any disturbance. The landing's time counter doesn't decrease.

Long power cuts	Otherwise, the minimum speed is reached before the
	power is restored:
	- «ISOL.VALVE» contact is open (V2 closes);
	- «START» contact is open (V1 closes);
	- the emergency braking valve is open by power failure;
	- the pump lands on its back-up bearings;

- the controller is stopped;
- the landing's time counter decreases (see D 10).

The normal start-up procedure is to be resumed after power has been restored *(see page 1)*.

If the pump is remote controlled, open the START contact and close it again.

### «External safety» contact operation

If the «EXT. SAFETY» contact on the Remote Control connector (*see B 90*) is closed:

- the controller display indicates: D 06 : EXT.SAFETY

- the pump is stopped and the emergency braking valve opens.

To restart the pump, open the «EXT. SAFETY» contact and start the pump:

- in local mode: push the START key;

- in remote control mode: open «START/STOP» contact then, close it *(see B 100)*.

# Safety instructions related to maintenance



It is important to isolate the machine from the electrical power supply source before any interventions inside the equipment (for maintenance reasons).

Before any maintenance operations, check the pumping conditions of the installation: toxicity, possible corrosion of the pumped gases. Depending on the case, we recommend:

- to purge the pumping installation with dry nitrogen before any intervention

- to wear gloves, protective goggles and breathing masks, if necessary

- to ventilate the room well and disassemble the equipment under a fume hood.

Before restart, follow all the safety instructions concerning start-up.



The controller should never be switched off as long as the rotor is moving (speed = 0 rpm).

# Safety instructions related to maintenance

Back-up bearings	When the pump is running, the rotor is levitated magnetically. There is therefore no friction between moving and fixed parts.
	When the pump is stopped from the controller, the back-up bearings are not used. The rotor remains levitated by magnetic bearings.
	Only the back-up bearings require maintenance: they are designed to withstand many accidental shut-downs, or many landings of the rotor on the bearings at full speed. These accidental shut-downs occur only in exeptional circumstances: broken power supply cable, strong shocks, faulty electronics. It is advisable to check the bearing counter and provide ball bearings maintenance, when needed.
The bearing counter	Life time of these bearings depends on the duration and number of landing. The initial percentage displayed by the controller is 100.00%. When this percentage reaches 0%, the pump can't restart and the back-up bearings have to be changed. The decrementation of the counter is done by: - a landing after a magnetic bearing trouble, nearly 0.20% per landing; - a landing at 9000 rpm after a prolonged power failure, nearly 0.04%.
	However, the decrementation depends on the bearings rotation duration: - if the braking valve is not connected or, - if the gas supply is closed on it or, - if there are no exhaust or inlet isolation valves or, - if theses valves are not driven by the controller, the counter can count down 30% since the first landing.
	The internal memory of the controller informs the operator when the bearings require maintenance by displaying:

D 24: BEARINGS MUST BE CHANGED

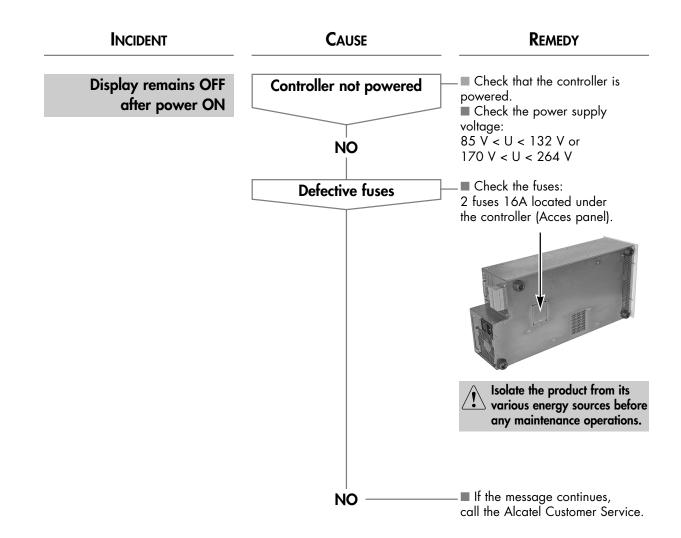
# Diagnosis and troubleshooting

The screen is blocked on a display		
(At start-up or during operation)	D 30	

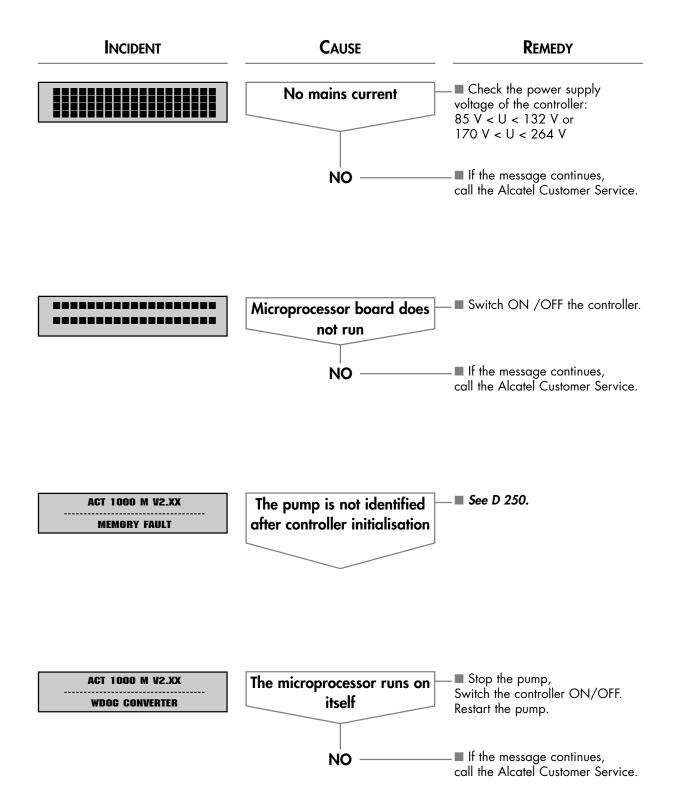
The default is indicated by the controller	D 40 to	Ì
	D 270	

The default is not indicated by the cont	troller <b>D 280</b>
--	----------------------

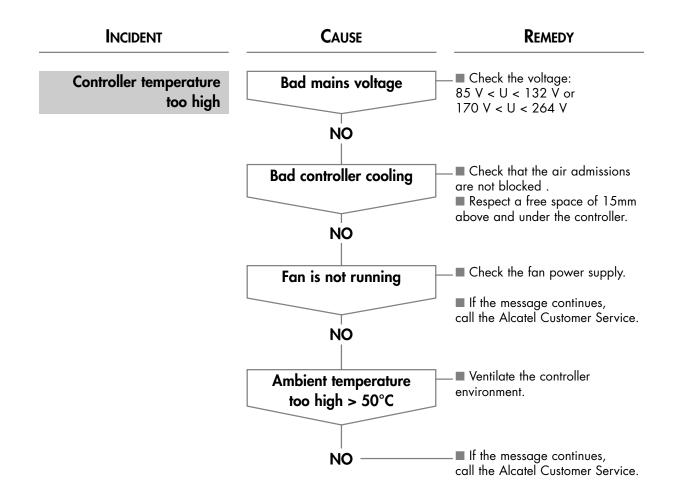
# Screen blocked on a display



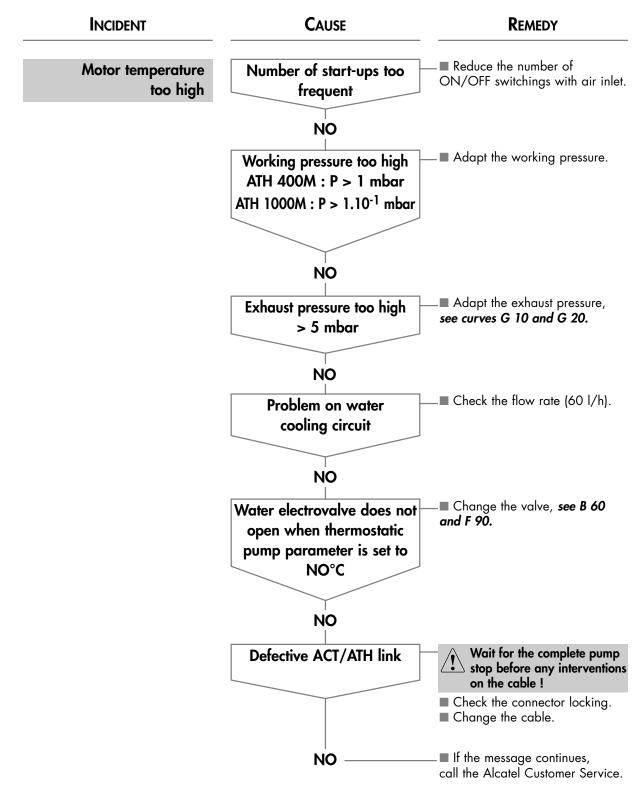
# Screen blocked on a display



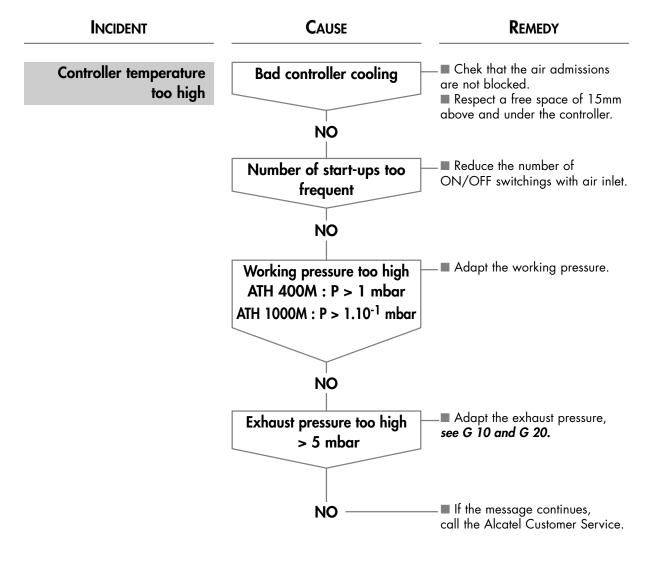
### **DO1 : POWER OVERHEAT**



### **DO2 : MOTOR CONTROL OVERHEAT**

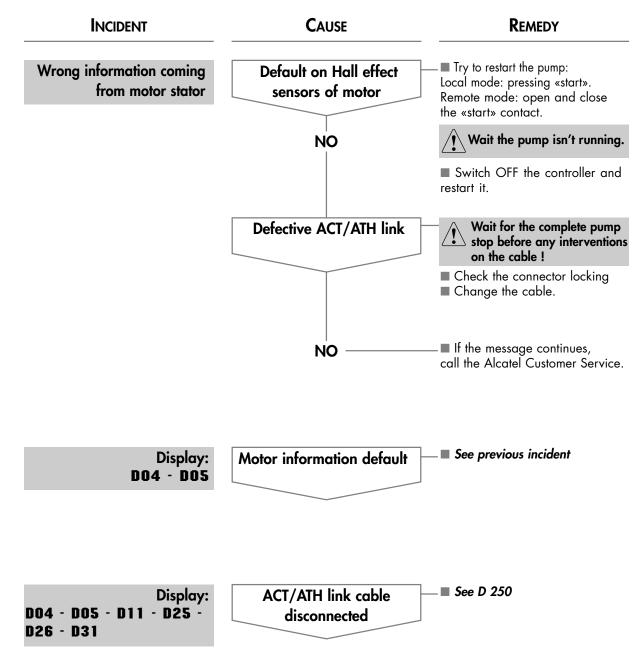


## **DO3 : MOTOR CONTROL OVERHEAT**

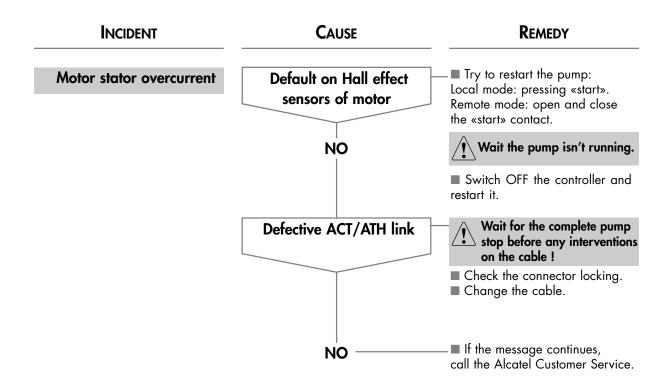


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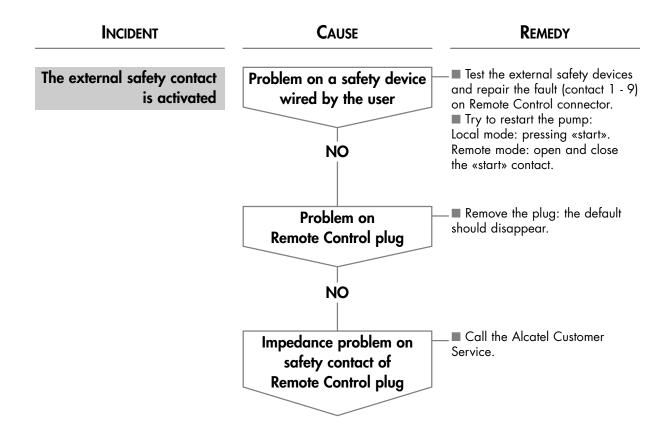
### DO4 : HALL SENSOR



## **DO5 : OVERCURRENT OR SENSOR**

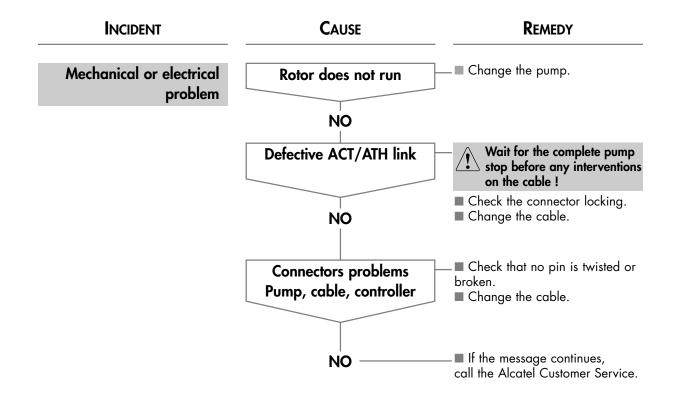


#### **DOG : EXTERNAL SAFETY**

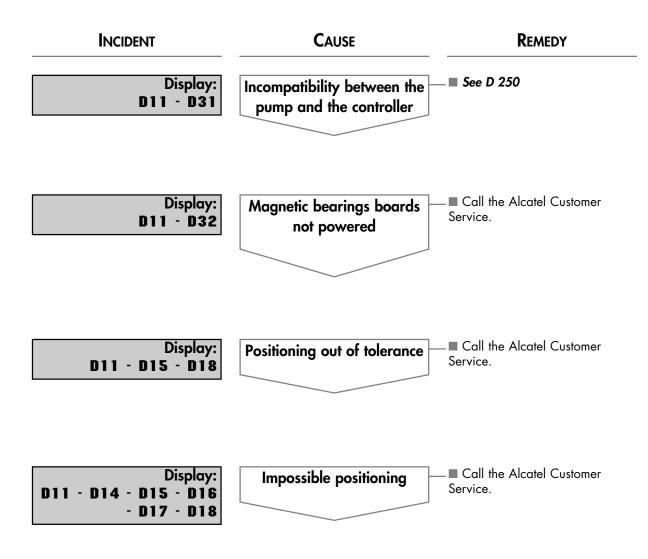


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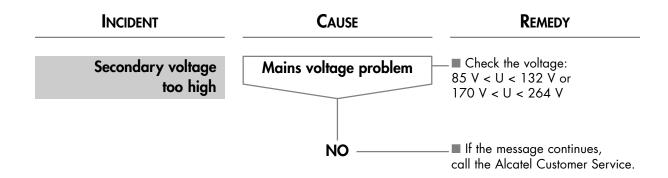
### D11 : MAG SUSPENSION



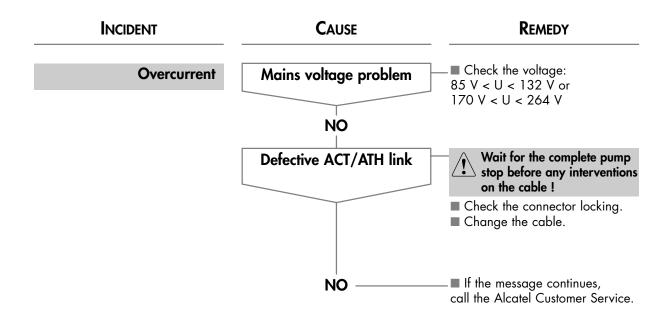
# **D11** + other defaults



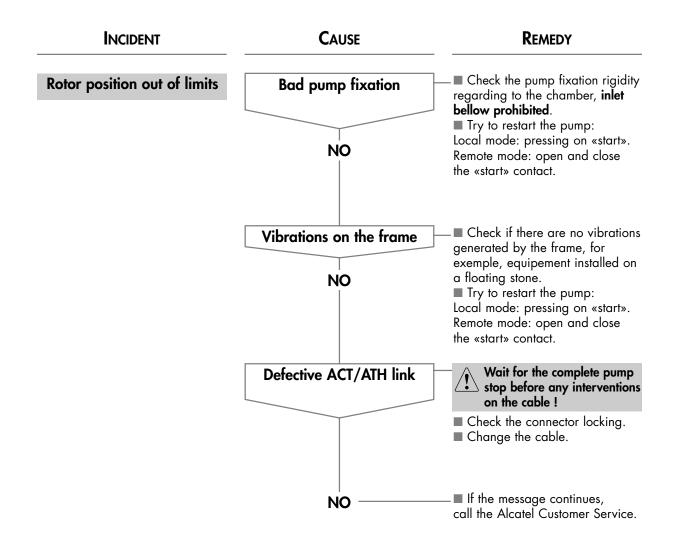
### D12 : POWER



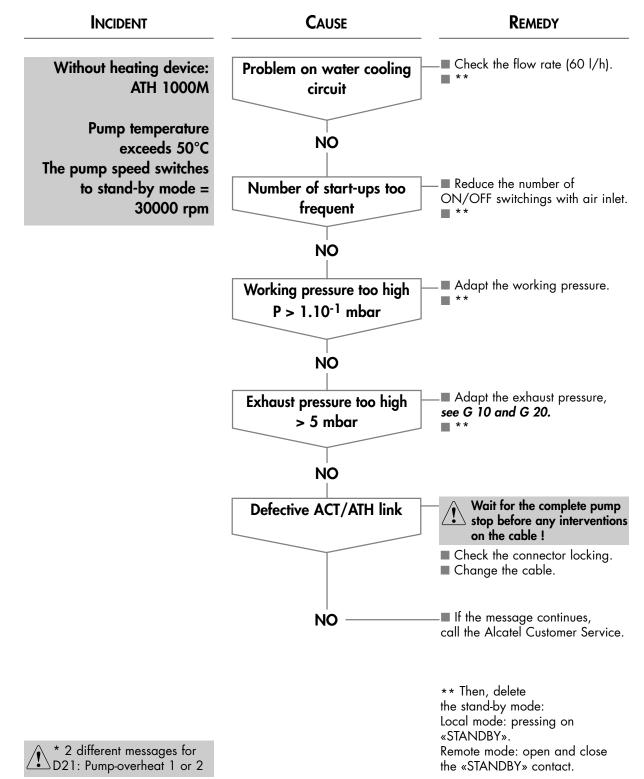
### **D13 : POWER OVERCURRENT**



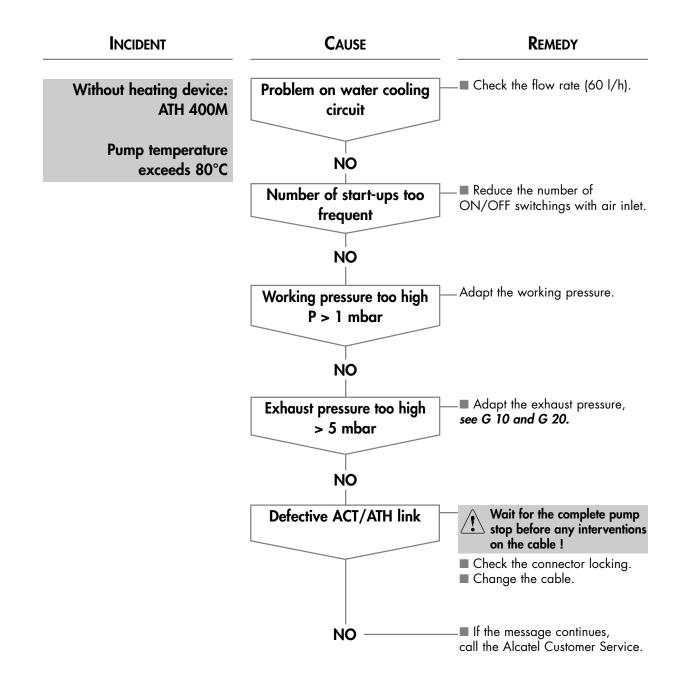
### D14 - D15 - D16 - D17 - D18



#### D21\* : PUMP OVERHEAT-1



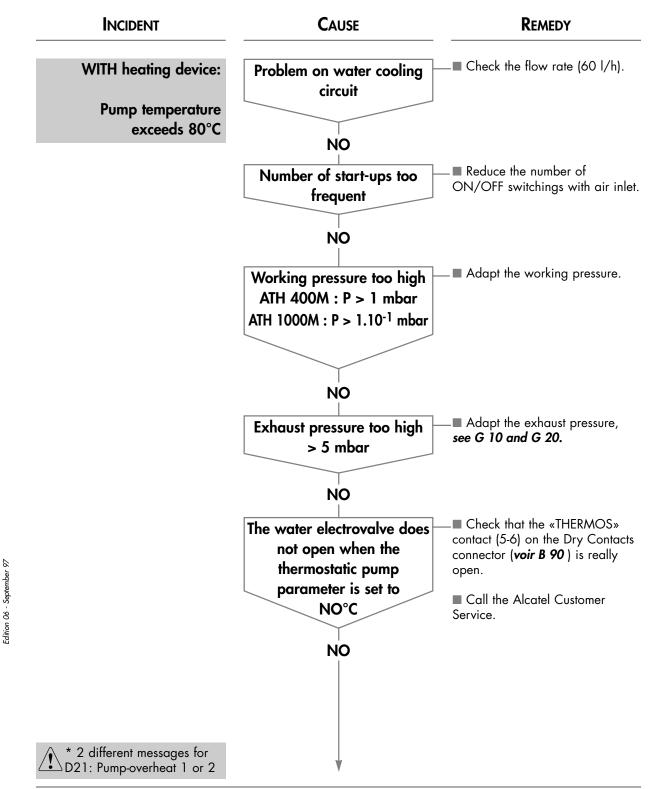
### D21\* : PUMP OVERHEAT-1



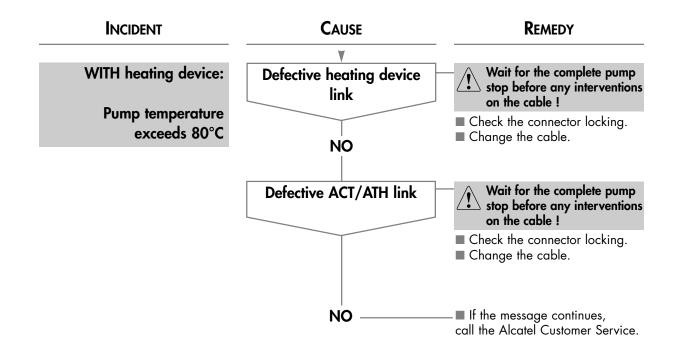
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\* 2 different messages for D21: Pump-overheat 1 or 2

#### D21\* : PUMP OVERHEAT-1

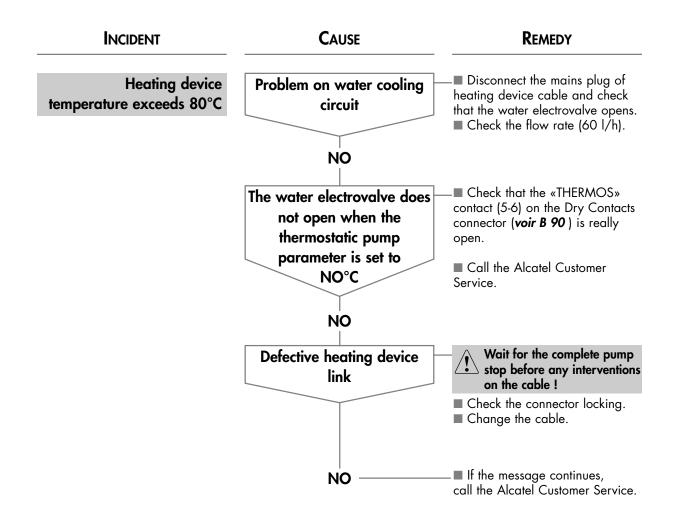


### D21\* : PUMP OVERHEAT-1



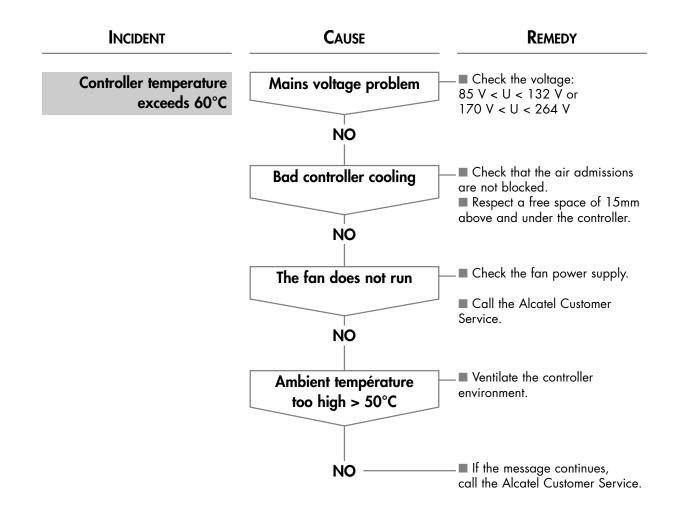
\* 2 different messages for D21: Pump-overheat 1 or 2

#### D21\* : PUMP OVERHEAT-2



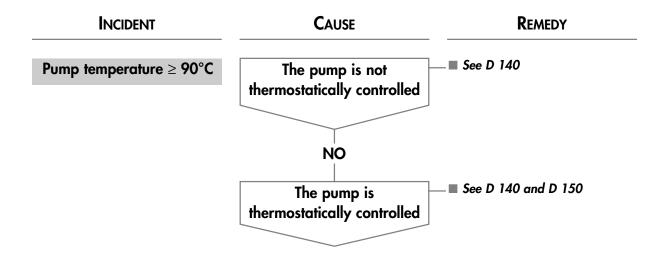
\* 2 different messages for D21: Pump-overheat 1 or 2

#### **D22 : CONTROLLER OVERHEAT**

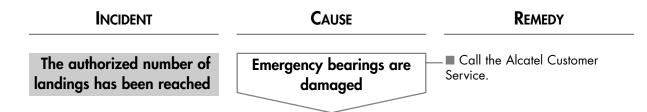


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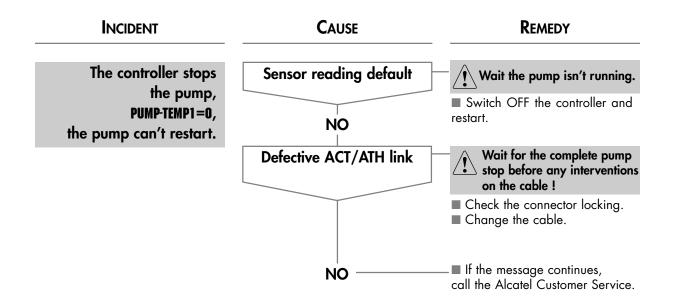
#### D23 : HOT PUMP



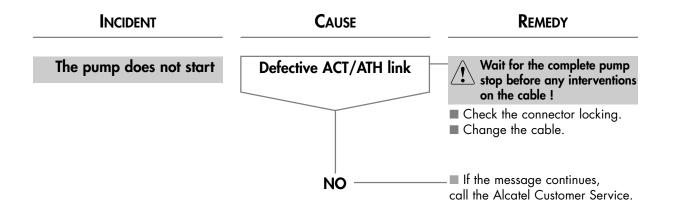
#### D24 : BEARING MUST BE CHANGED



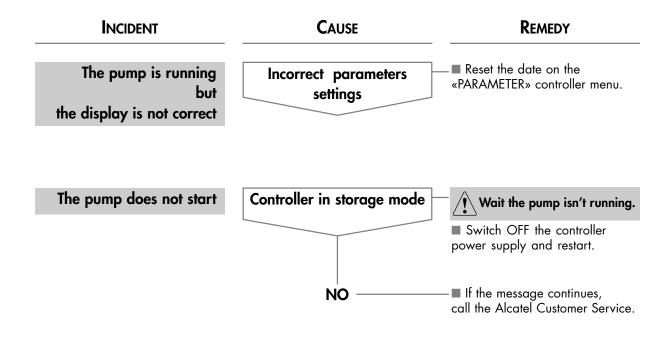
#### D25 : TEMP SENSOR-1



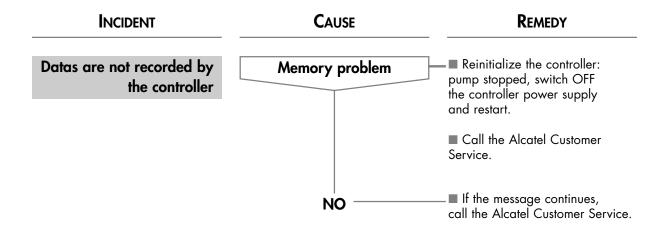
#### D26 : NO CONNECT



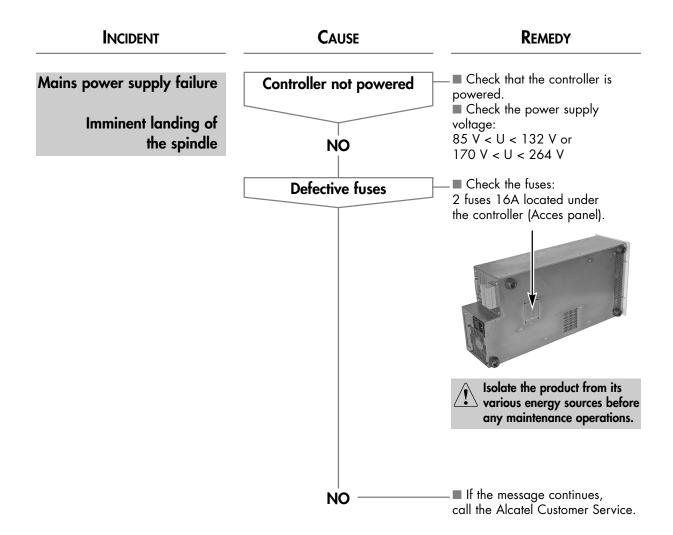
#### D27 : DATE AND TIME



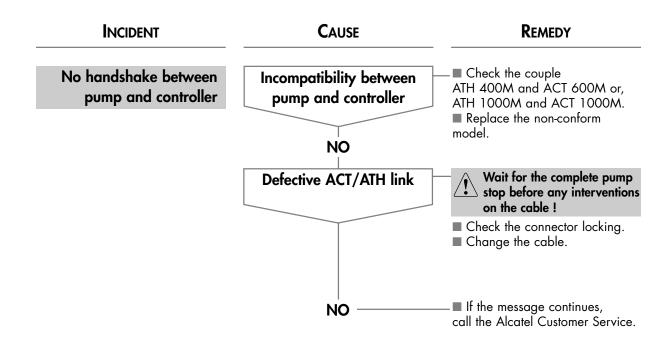
#### D28 : DISABLE WRITE



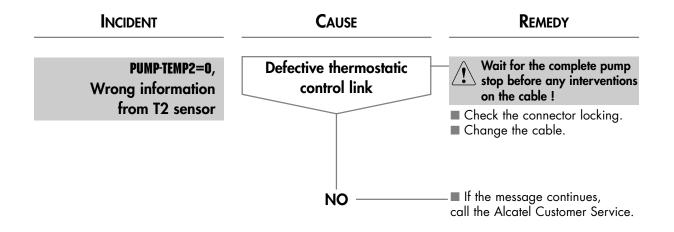
#### D29 : INPUT POWER



#### D31 : CODING



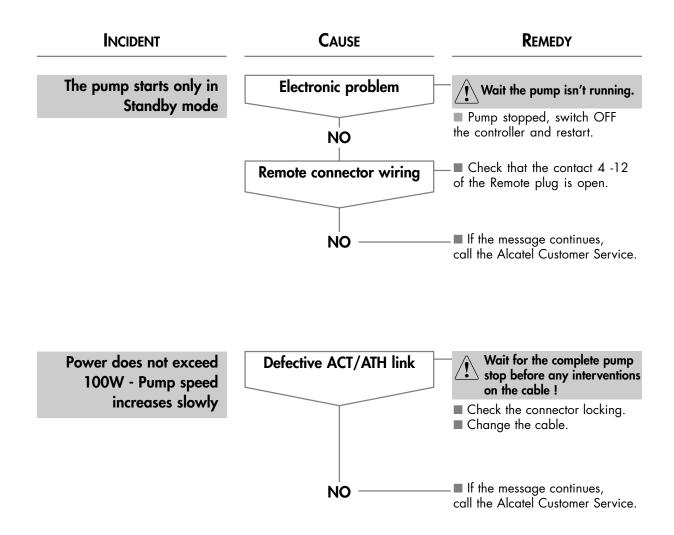
#### D38 (37) : TEMP SENSOR-2

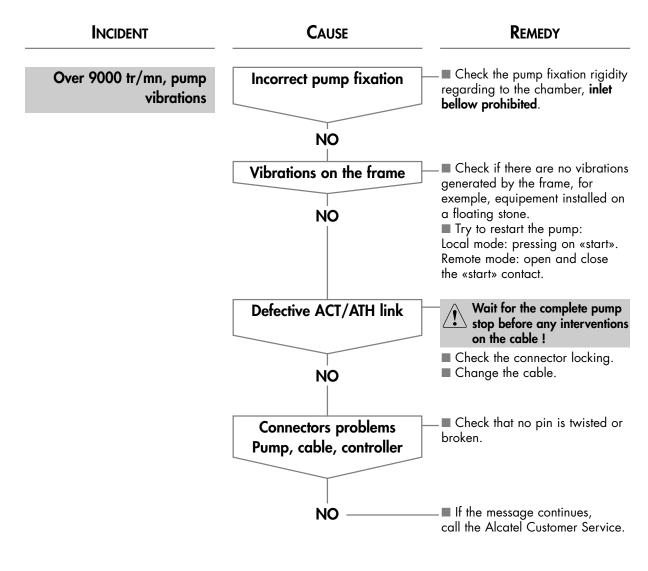


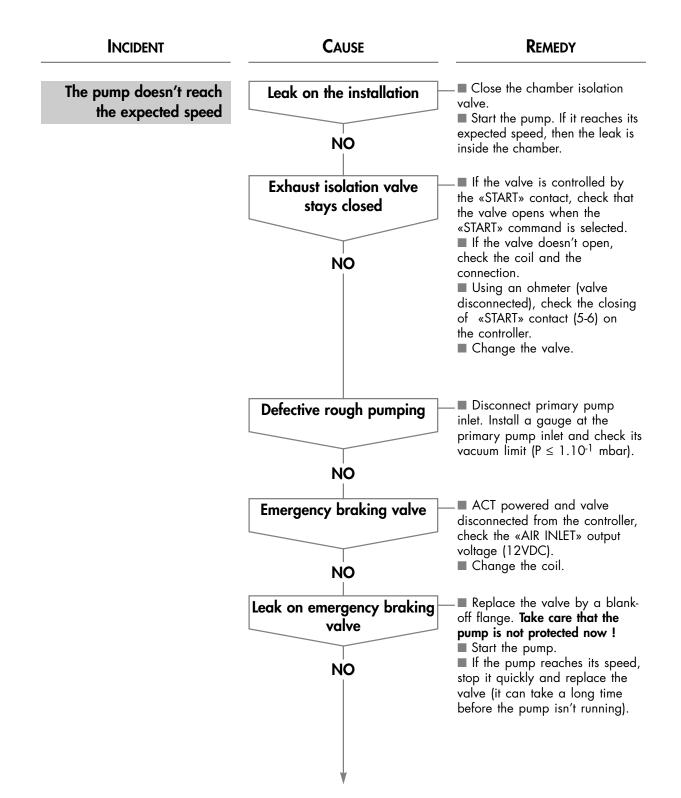
### Default not indicated by the controller

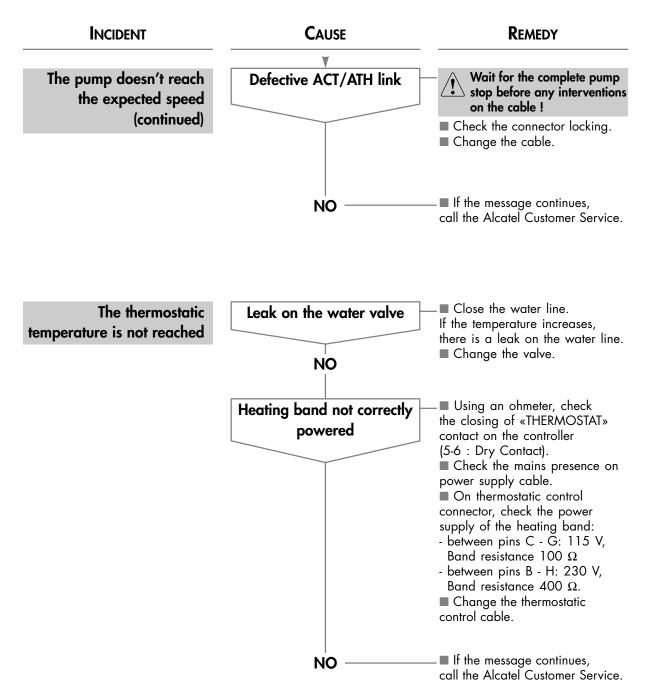
The pump starts only in standby mode	page 2	
Power does not exceed 100W	page 3	
Over 9000 rpm the pump starts to vibrate	page 3	
The pump does not reach the expected speed .	page 4	
The thermostatic temperature is not reached	page 5	
Control keys are disactivated	page 6	
Continuous controller initialization	page 6	
Partial and repetitive controller initialization	page 6	

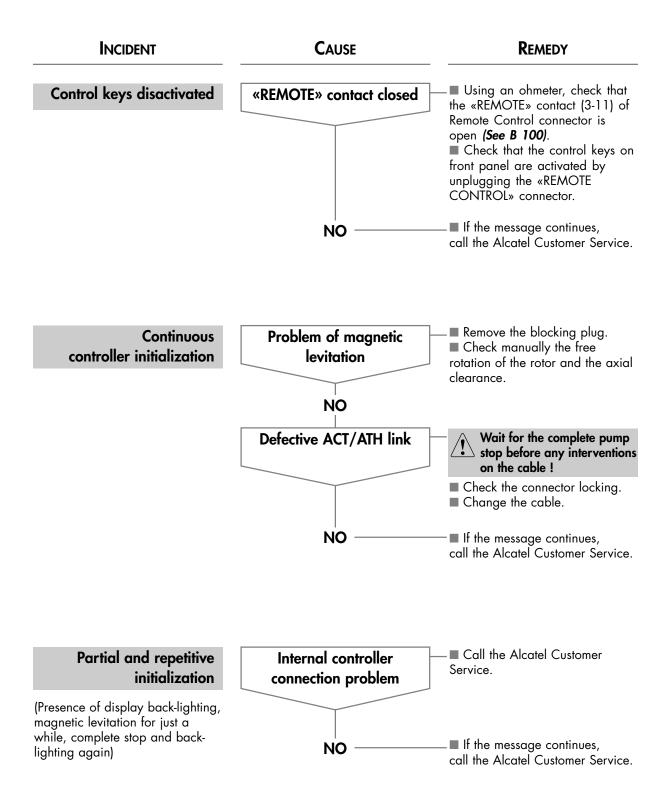
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### First level maintenance parts

#### Copper seals for pumps with CF-F flanges

; 1	Flange type	Sets of 10 parts	10 sets of 1 part (Unit packaged)
5	100 CF-F	303284	303291
	160 CF-F	303285	303292
	200 CF-F	303286	303293

#### Fuses for controllers

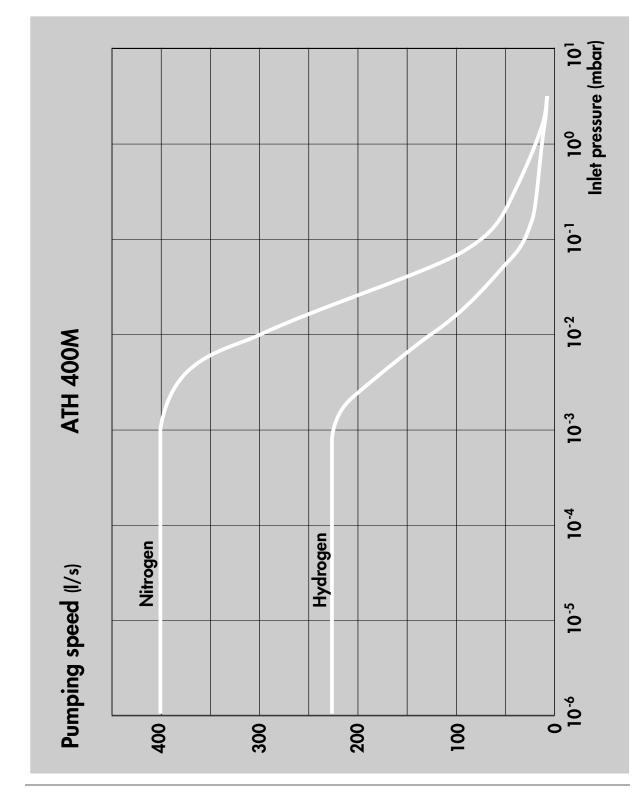
Description	Qty	ACT 600M	ACT 1000M
Fuse 6 x 32	_	16A	
T 250V	2		

# Emergency braking valve accessories

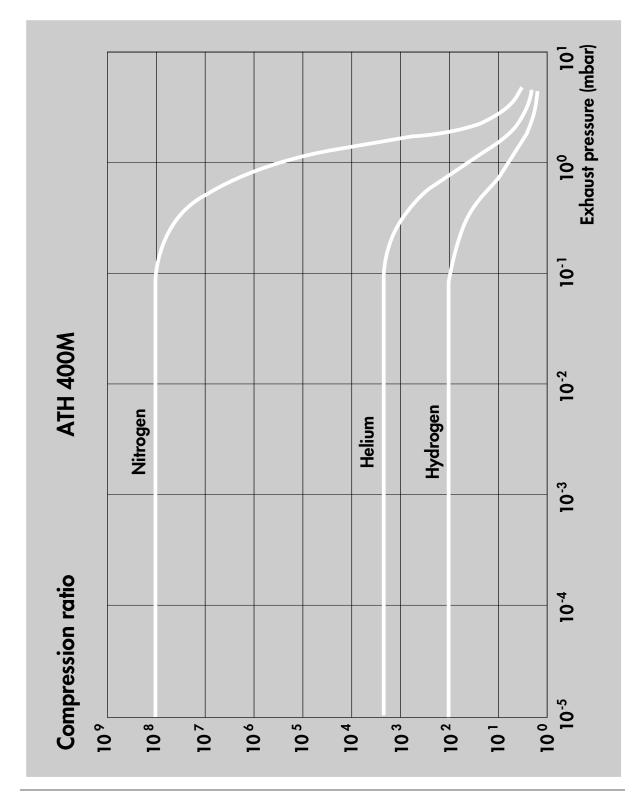
Description		Part Num.
Electrovalve coil	12V DC	038127
Equipped electrovalve I	DN 16	066935

Water electrovalve	Description	Part Num.	
	Coil	110V 50/60 Hz	103839
	Coil	220V 50/60 Hz	103840
	Electrovalve	110V	103696
	Electrovalve	220V	103697

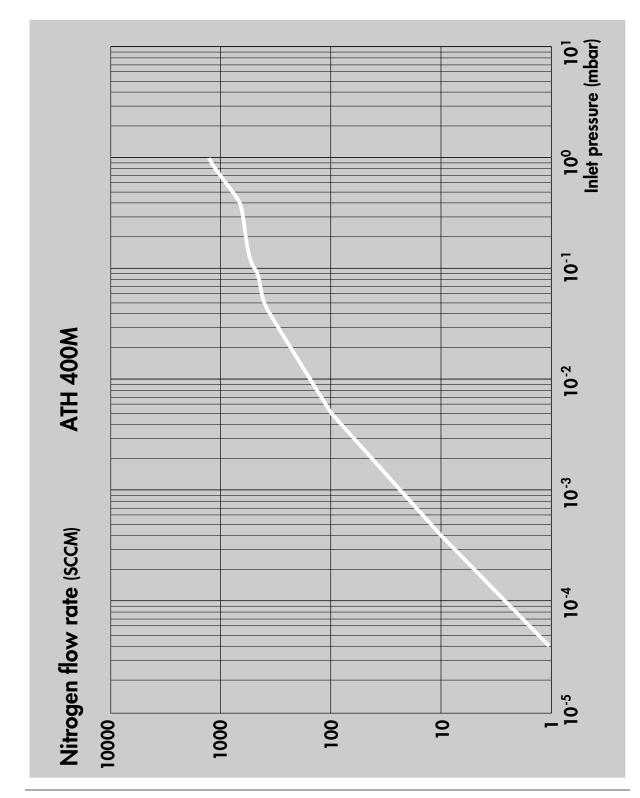
### Pumping curves ATH 400M



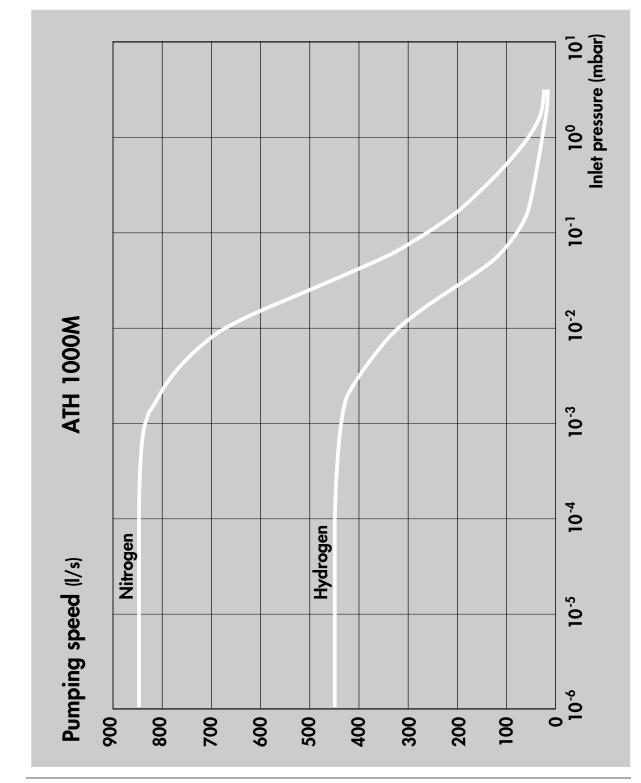
### Pumping curves ATH 400M



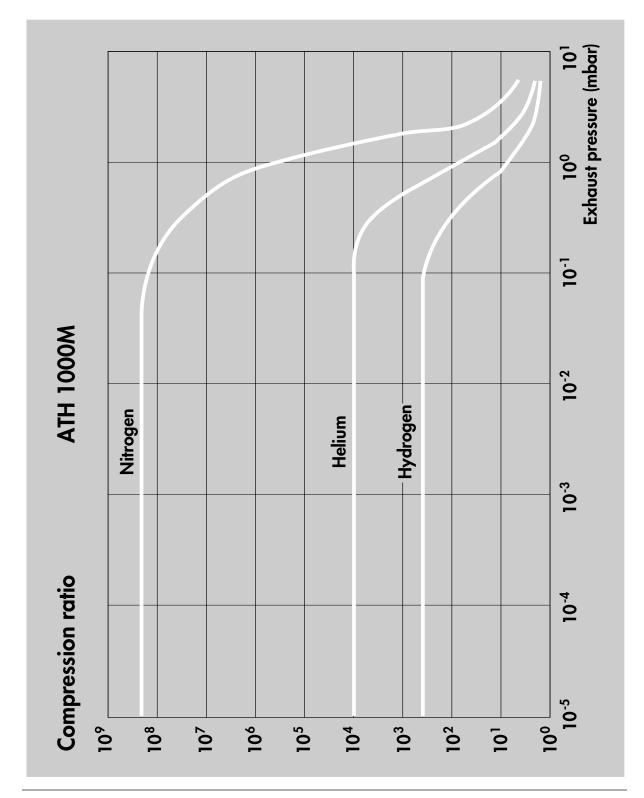
### Pumping curves ATH 400M











### Pumping curves ATH 1000M

