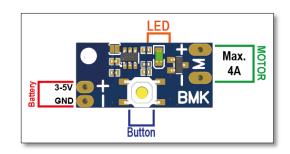
BMK Servo/ESC Timer

Servo e-Timer is an essential servo/ESC controller timer for free flight models or rubber to the electric conversation.

- The Servo version changes the servo position when the countdown is completed.
- The ESC version(RED DOT for the identification) starts the motor when the button is released then stops at the end.

Both versions are configurable between 1-250 seconds.



Features

- Maximum Timer Duration: 250 seconds (4 minutes 10 seconds)
- Timer Steps: 1 second
- Timer Tolerance: +-1% typical
- Timer Activation Method: Hold the onboard button for at least 2 seconds, the timer will start when the button is
 released.
- Timer Cancel Method : Click the onboard button
- Operation Voltage: 3.0 5.0v (compatible with 1S LiPo battery)
- Power Consumption : 0.
- Maximum Output Current : 5A continuous
- Low Battery Warning: <3.7v (double flashes @ idle mode)
- **Dimensions**: 15mm x 11mm x 5mm
- Weight: 1.2g

How To Set the Timer?



- 1. Press and hold the button before plugging the battery.
- 2. Plug the battery when holding the button. (The LED will turn ON.)
- 3. Release the button and the (LED will turn OFF.)
- 4. Press and hold the button and count the LED blinks for the timer duration
 - *Each Blink adds 1 second to the timer. For example, 30 flashes = 30 seconds. (Max. 250 seconds)
- 5. Release the button when you rich the desired timer duration. (The LED will fast flash 3 times when saving the time)
- 6. The timer will return to normal running mode automatically. Now you can remove the battery or use your timer.

Using Your Timer



- 1. Plug the battery
- 2. the LED will flash once every 2 seconds.
 - *The double flash menas the battery voltage is below 3.7v and you must recharge the battery.
- 3. Press and hold the button for at least 2 seconds to arm the timer before launch. (The LED will turn ON.)
- 4. Release the button when launching and the timer countdown will start. During the countdown, the LED will flash fast.
- 5. When the countdown is complete, the timer will turn on the pager motor (or solenoid) for 2 seconds.
 *Click the button to cancel If you have accidentally released the button or your model has landed before the countdown is complete. The servo will return to start position automatically.