NX510SE SPECIFICATIONS

Positioning Accuracy	
Real time kinematics (RTK)	Horizontal: 8 mm + 1 ppm RMS Vertical: 15 mm + 1 ppm RMS Initialisation time: < 5 s Initialisation reliability: > 99.9%
Velocity accuracy	0.03 m/s RMS
Performance	
Pass to pass accuracy	≤ ±2.5 cm
	Physical
External power	9 V DC to 32 V DC
Environment	Operating: -20°C ~ +70°C Storage: -40°C ~ +85°C
Electric Steering Wheel	
Power input	9 V DC to 32 V DC
Torque	7.5 N·m
Wheel diameter	410 mm
Motor height	80.5 mm
Display	
Display	10.1" touch screen, 281 mm x 181 mm x 42 mm Android 6.01 Dust and Waterproof: IP65
Rear Camera	
Pixel	1280 x 720 pixels
Camera angle of view	120°
	Receiver
Size	220 mm x 205 mm x 60 mm
Weight	< 2 kg
Power	9 V DC to 36 V DC
Dust and waterproof	IP67
Constellations	
GPS	L1/L2/L5
BDS	B1I/B2I/B3I/B1C/B2a/B2b
Galileo	E1/E5a/E5b/E6
GLONASS	L1/L2
SBAS	L1
QZSS	L1/L2/L5/L6

Communication and Data	
Yes	
RS232 x 2	
2	
1/2/5/10 Hz	
RTCM 3.0/3.1/3.2/3.3	
Integrated in receiver and in display	
Frequency: 410-470 MHz Protocol: TT450S/Transparent/CHC	
3 x LEDs (power, satellite, RTK correction) 1 × UHF antenna connector	

* Specifications are subject to change without notice.

