AlphaAir 450 SPECIFICATIONS

| General s | ystem performance | |
|--|---|--|
| Absolute accuracy | <10 cm HZ <5 cm V | |
| Accuracy conditions | Without control points, @50 m flight altitude AGL | |
| Mounting | Skyport for DJI M300/200 External power source with the dedicated port for other UAVs (CHCNAV Alphaport interface) | |
| Weight of instrument (1) | 1 kg | |
| Dimensions of instrument | 13.6 × 12.8 × 7.7 cm 5.11 " × 4.72 " × 2.75 " | |
| Communications | 1× port for GNSS antenna Skyport interface 1× USB Type-C, copy speed up to 160 Mb/s | |
| Data storage | 256 GB | |
| Point density on UAV setup 5 m/s (18 km/h) speed | 570 pts/sqm @ 50 m AGL 280 pts/sqm @ 100 m AGL | |
| Covered area | 2 km² area by 30 min UAV fligh | |
| Operation | One-touch acquisition or remote control via DJI M300 Smart controller enterprise | |
| Transport box | 1× protected soft bag with custom precut foam | |
| Laser scanner | | |
| Laser class | 1 (in accordance with IEC 60825-1:2014) | |
| Max.range, reflectivity > 80% (2) | 450 m | |
| | | |
| Max.range, reflectivity > 10% (2) | 190 m | |
| Max.range, reflectivity > 10% (2) Max. returns supported | 190 m Up to 3 | |
| 10% (2) | | |
| 10% ⁽²⁾ Max. returns supported | Up to 3 20 mm @ 20 m | |
| 10% ⁽²⁾ Max. returns supported Accuracy ⁽³⁾ | Up to 3 20 mm @ 20 m 30 mm @100 m | |
| 10% ⁽²⁾ Max. returns supported Accuracy ⁽³⁾ Precision ⁽⁴⁾ | Up to 3 20 mm @ 20 m 30 mm @100 m | |
| 10% ⁽²⁾ Max. returns supported Accuracy ⁽³⁾ Precision ⁽⁴⁾ Field of view Scan rate | Up to 3 20 mm @ 20 m 30 mm @100 m 15 mm 70.4° (Horizontal) × 4.5° (Vertical) 240 000 pts/sec (first or strongest return 480 000 pts/sec (dual return) | |
| 10% ⁽²⁾ Max. returns supported Accuracy ⁽³⁾ Precision ⁽⁴⁾ Field of view Scan rate | Up to 3 20 mm @ 20 m 30 mm @100 m 15 mm 70.4° (Horizontal) × 4.5° (Vertical) 240 000 pts/sec (first or strongest return 480 000 pts/sec (dual return) 720 000 pts/sec (triple return) | |
| 10% ⁽²⁾ Max. returns supported Accuracy ⁽³⁾ Precision ⁽⁴⁾ Field of view Scan rate Positioning a | Up to 3 20 mm @ 20 m 30 mm @100 m 15 mm 70.4° (Horizontal) × 4.5° (Vertical) 240 000 pts/sec (first or strongest return 480 000 pts/sec (dual return) 720 000 pts/sec (triple return) and orientation system Dual-frequency GNSS GPS, GLONASS, | |
| 10% (2) Max. returns supported Accuracy (3) Precision (4) Field of view Scan rate Positioning a GNSS system | Up to 3 20 mm @ 20 m 30 mm @100 m 15 mm 70.4° (Horizontal) × 4.5° (Vertical) 240 000 pts/sec (first or strongest return 480 000 pts/sec (dual return) 720 000 pts/sec (triple return) and orientation system Dual-frequency GNSS GPS, GLONASS, BeiDou, Galileo, sampling frequency 5Hz | |
| Max. returns supported Accuracy (3) Precision (4) Field of view Scan rate Positioning a GNSS system IMU update rate Position accuracy NO GNSS outage | Up to 3 20 mm @ 20 m 30 mm @100 m 15 mm 70.4° (Horizontal) × 4.5° (Vertical) 240 000 pts/sec (first or strongest return 480 000 pts/sec (dual return) 720 000 pts/sec (triple return) and orientation system Dual-frequency GNSS GPS, GLONASS, BeiDou, Galileo, sampling frequency 5Hz 600 Hz 0.010 m RMS horizontal, 0.020 m RMS vertical, 0.01 degrees RMS pitch/roll, | |
| Max. returns supported Accuracy (3) Precision (4) Field of view Scan rate Positioning a GNSS system IMU update rate Position accuracy NO GNSS outage | Up to 3 20 mm @ 20 m 30 mm @100 m 15 mm 70.4° (Horizontal) × 4.5° (Vertical) 240 000 pts/sec (first or strongest return 480 000 pts/sec (dual return) 720 000 pts/sec (triple return) and orientation system Dual-frequency GNSS GPS, GLONASS, BeiDou, Galileo, sampling frequency 5Hz 600 Hz 0.010 m RMS horizontal, 0.020 m RMS vertical, 0.01 degrees RMS pitch/roll, 0.04 degrees RMS heading | |

24.3 MP, 11 fps

Effective pixel

| Environmental | | |
|-----------------------|---|--|
| Operating temperature | -20°C ~ +50°C | |
| Storage temperature | -20°C ~ +65°C | |
| IP rating | IP64 | |
| Humidity (operating) | 80%, non-condensing | |
| Electrial | | |
| Input voltage | DC 12 ~ 14 V | |
| Power consumption | 32 W | |
| Power source | Depending on UAV battery, or by Skyport from DJI M300 | |

^{*} Specifications are subject to change without notice

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⁽¹⁾ Weight calculated with integrated camera. (2) Typical values for average conditions. (3) Accuracy is the degree of conformity of a measured quantity to its actual (true) value. (4) Precision is the degree to which further measurements show the same results. Improved by CHCNAV COPre SW.