

### **MLFB-Ordering data**

#### 6SL3210-1KE23-8AB1



Client order no. : Order no. : Offer no. :

Remarks:

Item no. : Consignment no. : Project :

**Power loss** 

Cooling

Rated	data

Input	
Number of phases	3 AC
Line voltage	380 480 V +10 % -20 %
Line frequency	47 63 Hz
Rated current (LO)	48.20 A
Rated current (HO)	45.20 A
Output	
Number of phases	3 AC
Pated voltage	400 V

Rated current (HO)	45.20 A	
Output		
Number of phases	3 AC	
Rated voltage	400 V	
Rated power IEC 400V (LO)	18.50 kW	
Rated power NEC 480V (LO)	25.00 hp	
Rated power IEC 400V (HO)	15.00 kW	
Rated power NEC 480V (HO)	20.00 hp	
Rated current (IN)	38.00 A	
Rated current (LO)	37.00 A	
Rated current (HO)	31.00 A	
Max. output current	62.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

### **Overload capability**

#### Low Overload (LO)

 $150\ \%$  base load current IL for 3 s, followed by  $110\ \%$  base load current IL for 57 s in a  $300\ s$  cycle time

#### High Overload (HO)

 $200\,\%$  base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

<b>_</b>	
Power factor λ	0.70 0.85
Offset factor cos φ	0.95
Efficiency η	0.97
Sound pressure level (1m)	66 dB

General tech. specifications

Filter class (integrated)	Class A

Air cooling using an integrated fan

**Ambient conditions** 

0.50 kW

Cooling air requirement	0.018 m³/s (0.636 ft³/s)
Installation altitude	1000 m (3280.84 ft)

## **Ambient temperature**

Operation	-10 40 °C (14 104 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-40 70 °C (-40 158 °F)

#### **Relative humidity**

9	5 % At 40 °C (104 °F), condensation
Max. operation a	nd icing not permissible

# Closed-loop control techniques

V/f linear / square-law / parameterizable	Yes
V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No



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			Figure s
Mechanical	data	Com	nmunication
Degree of protection	IP20 / UL open type	Communication	USS/MODBUS RTU
Size	FSC	Co	onnections
Net weight	4.40 kg (9.70 lb)	Signal cable	
Width	140 mm (5.51 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 10
Height	295 mm (11.61 in)	Line side	
Depth	203 mm (7.99 in)	Version	Plug-in screw terminals
Inputs / out	tputs	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6
andard digital inputs		Motor end	
Number	6	Version	Plug-in screw terminals
Switching level: 0→1	11 V	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG
Switching level: 1→0	5 V	DC link (for braking resistor	)
Max. inrush current	15 mA	Version	Plug-in screw terminals
ail-safe digital inputs		Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG 6
Number	1	Line length, max.	15 m (49.21 ft)
igital outputs		PE connection	On housing with M4 screw
Number as relay changeover contact	1	Max. motor cable length	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)
Number as transistor	1	Unshielded	150 m (492.13 ft)
Output (resistive load)	DC 30 V, 0.5 A	S	tandards
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		, , , , ,
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Volt Directive 2006/95/EC
witching threshold as digital in	out		
0→1	4 V		
1→0	1.6 V		
nalog outputs			

# PTC/ KTY interface

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^\circ\text{C}$ 

1 (Non-isolated output)



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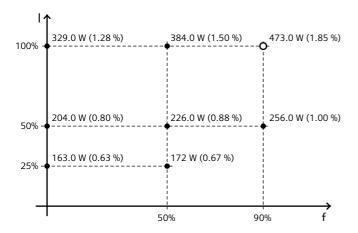
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Figure similar

# Converter losses to EN 50598-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-63.37 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values