



GHM-ONE

Combines the modules of automation



Members of GHM GROUP

GREISINGER HONSBERG *Martens* IMTRON

Measuring – Controlling – Regulating – Automate Operate – Observe – Visualize – Communicate Calculate – Record – Analyze – Document





Multifunction controller GHM-ONE MSR9696H



Compact automation system

The GHM-ONE is a multifunction unit that can be specifically adapted to process and control requirements with the GHM-CAT configuration software. Therefore, the system becomes an ideal control, regulating, and operating unit.

- Visualisation system with 3.5" TFT display
- Control unit with 4 function keys and touch display
- Modular I/O concept
- Universal PID control function
- Multi-Loop system
- Profiler function
- Process control and PLC functions
- Process calculation with mathematical library
- Screen recorder function
- Data logger function
- Communication with various fieldbuses

At home in all processes

The GHM ONE gives the user the possibility of effectively implementing their ideas in the areas of automation and visualisation without the need for programming skills. The platform is an ideal basis for a wide range of applications, including:

- Industrial furnaces
- Laboratory ovens
- Heat treatment systems
- Microbreweries
- Dryers

- Test applications
- Building automations
- Climate control
- Pasteurisation systems
- Manufacturing plants

Powerful standalone concept

The GHM-ONE is based on a powerful processor which, in combination with a relay card and mains adapter card, serves as the base unit. The base unit can be adapted to applications with a communications card and up to two I/O cards.

The number of physical inputs and outputs can be expanded with external I/O's. This modular layout enables specific adaptation of the hardware to the automation task.

The creation of the application itself takes place in the GHM-ONE with the "Configuration and Application Tool" GHM-CAT. The software assists the user with more than 100 complete function blocks and intuitive operation for the implementation of their ideas.



This saves time when creating applications with high operational reliability.

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Device Libraries Arithmetic Functions Non linear functions SIN - Sinus COS - Cosine TAN - Tangent COT - Cotangent ARCUS - Accus Cosinus ARCCOS - Accus Cosinus ARCCOT - Accus Cosinus Communication functions Signal Converter Multiple alarm Communication functions Porgrammer Additional functions Porcerd type 1 slot A ID-card type 1 slot B ID	

Quick and easy to put ideas into practice

The application production is particularly easy with the GHM-ONE. Based on the concept of connecting of existing function blocks, the user creates applications comprising process controls, mathematical calculations and process regulation in the shortest possible time.

For this purpose the GHM-CAT configuration software provides a function library with more than 100 tested functions from many areas.

Input and output signals

- Computing functions
- Logic functions
- Signal conversion
- Time functions
- Memory functions
- Communications functions
- Profiler functions
- Regulating PID functions

Unique simulation function – The GHM-CAT editor

The user only has to combine and connect these functions in the editor and thereby implement their idea without the need for any programming skills.

Therefore, the user can concentrate entirely on implementing their idea. In addition to the support provided to the user by the function library, the GHM-CAT configuration tool offers additional functions in the editor.

For instance, the user can structure their application in order to maintain an overview, create their own function blocks for recurring functions in order to save time, and test sub-areas of their application independently of other project areas with simulation functions.



With the GHM-CAT the user implemented their application without much training time.





Individual operating side with process-synchronous animation of picture elements (Illustration 2)



Individual process picture (Illustration 3)

Individual operating and monitoring concepts

The work does not end with the creation of pure process control and regulation for modern machine and system parts. The process technician must provide the operator on site with the possibility of effectively monitoring and operating the system.

The user must also remain well-informed in the event of a fault in order to keep the system downtime to an absolute minimum. Standard operating concepts are of little help in this connection.

Therefore, the GHM-ONE is based on a concept that enables individual design of the operation and visualisation.

The HMI editor of GHM-CAT

For this purpose, the GHM-CAT software provides an image editor that makes it possible to realise the widest range of operating and monitoring concepts with a few simple standard functions.

In addition to the individual operating sides also standard sides are available in the screen editor.

- PID control operation
- Profiler operation
- Trend visualisation
- Parameter dialogue
- Alarm management

With the combination of standard operating screens and individually designed screen, an efficient interface between the operator and the process is created in the shortest time.



Complex operating structures be easily realized with the HMI editor.



Testing and commissioning – quickly and easily

Of course, the process technician's work is not finished with the creation of an application and its operation. The application still has to be tested and commissioned afterwards. For this important and in some cases lengthy phase, the new GHM platform provides various functions to streamline this phase.

An essential point is the PC simulation of the complete application. The entire application can be tested on a PC independently of the actual process.

For this purpose, the GHM-CAT software has a simulation environment for the GHM-ONE and for connected I/O assemblies. With this environment, the user is capable of testing the entire application, including operation on the PC, without endangering the real process. Simply test the application at a desk without risk.

There are additional testing functions available to the user for the on-site system commissioning phase.

Online trend function – Debugging und Forcing

An essential component is an integrated online trend function that allows the user to view all analogue and digital signals online in a trend and thereby quickly and easily monitor the desired functions. Of course, there are also debugging and various forcing functions available for the testing.



Online trend function (Illustration 5)



Simulation on a PC significantly shortens testing and commissioning times and increases system safety.





GHM-CAT HMI editor (Illustration 6)

Programmation – without computer language GHM-CAT software configuration tool

The GHM-CAT (Configuration and Application Tool) tool enables the user to completely configure the GHM-ONE.

It essentially comprises the function plan editor, the HMI editor, the menu editor, the simulation, and commissioning assistance with debugging function and online diagrams.

The major functions

- Creation of the application from finished functions
- Found invarious libraries
- Graphic linking of functions in the function plan editor
- Automatic alignment of connections
- Parameterisation of functions
- Creation of operating structure and visualisation (HMI)
- Creation of test menus for parameterisation on the GHM-ONE
- Creation of programs for the profiler
- Simulation of the overall application on the PC, including simulation of control paths
- Online device function with debugging functions for application
- Testing
- Transfer of applications to the GHM-ONE
- Firmware update function
- Online help for all functions



All configurations for the GHM-One takes place in a single tool.



Function plan editor with library

The core of the application creation is the function plan editor with the function module library. With the help of the function modules, the user assembles their application without the need for any programming skills.

Three are more than 100 tested functions in the library which can be easily placed on the desktop and connected using the mouse. Declaring of variables and complex assignment of functions are omitted. In this manner, the user can effectively create their system or process from finished modules.

The application operating and monitoring screens are then created based on the function block application. Therefore, specific information can be displayed for the person on site and detailed screens can be created for service technicians. These screens are freely configurable. It is even possible to integrate process screens or other graphics. The user can also create text-based operating screens in order to enable efficient input of several types of process data.

Exact simulation of the device – WYSIWYG

After the application has been created, it can also be tested in the GHM-CAT tool. With the simulation, the software offers an exact representation of the device in all its functions. Even the hardware inputs and outputs can be simulated.

The user can test the application in an initial step without any risk for the system.

Support of the user by the GHM-CAT software continues in the scope of the commissioning with various forcing and debugging functions and a refined online visualisation of analogue and digital values. With this wide variety of information and intervention possibilities, efficient commissioning is practically assured.



All configurations for the GHM-ONE takes place in a single tool. The elaborate orientation in various software packages for controllers, data monitors, data loggers, mini-SCADA and mini-PLC can be dispensed with.



DIUID	(Y	B V	
iter:		x	
a De	vice Libraries		
Þ	Arithmetic Functions		
Þ	Non linear functions		
	Trigonometric functions		
	SIN - Sinus		
	COS - Cosine		
	TAN - Tangent		
	COT - Cotangent		
	ARCSIN - Arcus Sinus		-
	ARCCOS - Arcus Cosinus		-
	ARCTAN - Arcus Tangens		
	ARCCOT - Arcus Cotangens		
Þ	Logic Functions		
Þ	Signal converter	- I	
Þ	Time functions		
Þ	Select and store		
Þ	Multiple alarm		
Þ	Communication functions		
	Controller Functions		
	CONTRU - Controller function		
	CONTRU2 - Controller function		
	PLANTTUTG - TuTg process simulation		
	PWM - Pulse width modulation		
Þ	Programmer		
Þ	Additional functions		
Þ	Device functions		
	IO-card type 1 slot A		
	DINPOUT_A - Digital I/O		
	AINP_A1 - Universal Input channel 1		
	AINP_A2 - standard signal Input channel 2		
	AINP_A3 - Universal Input channel 3		
	AINP_A4 - standard signal Input channel 4		
	AOUT_A1 - Analogue Output 1		
	AOUT_A2 - Analogue Output 2		
	COUNTER_A1 - Counter Input 1		
	COUNTER_A2 - Counter Input 2		
P	IO-card type 1 slot B		
Þ	IO-card type 1 slot A {2 ?}	- I	
Þ	IO-card type 1 slot B (3 ?)		
Þ	HIMOD-System	- I	
Þ	Block functions	- I	
Þ	Variables		
Þ	HMI Variables		



Application structure (Illustration 7.2)

Application designer GHM-CAT



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	Two-point operation to permitted. Disabling of the control function can be done via the diplatileput as not as the fixed galaxy. The commany to disable the control function togotal = () has periody.
later.	Control eigned for sufficting the central mode (huts / Manual) D. Automatic mode 1. Istenail mode
	The operation is particular, burneliner can be some via the digital input or via the fitter particle. The operation for manual specifics, bright = 1) has priority.
Dyna	Control signal for setseting the setsetif source bortenar/ reserve) 0. External 1. Internal
	Two-point spenation is permitted, Switchover can be done you the district incur or you the trans parent.

On line help (Illustration 7.4)

10140



Graphic program editor (Illustration 7.3)



Regulation technical functions

The function library provides controller modules as a basis for control-related tasks.

- 2-point controllers
- 3-point controllers
- Motor step controllers
- Steady regulator

it is possible to operate the controllers as constant or switching controllers. A wide spectrum of setpoint and actual value functions and setpoint functions round out the scope of module functions. Other functions are ready for specific duties to support the user by the realisation of the duties.

- Boost function
- Soft start
- Smooth switching
- PID parameter adaptation

With the help of several regulator stones complicated structures can be also moved in the area of the mesh control circuits.

- Cascade control
- Limit control
- Ratio control
- Multi-Loop control

Other control strategies can be implemented using the standard functions. Of course all controllers offer the possibility for self-optimization.

But that is not all when it comes to control technology and process control. The library also provides a profiler that is needed in many cases to adopt the control for certain processes.

This is necessary whenever the material structure must be influenced over the course of a process. The profiler comprises up to 20 programs with 60 segments each.

One analogue and 6 digital tracks are available per segment. The program structure is realised in GHM-CAT with simple input of the segment times and setpoints.



With the help of ready to use controller modules, realisation of control technology tasks is possible without extensive knowledge in the area of control technology.







GHM-ONE trend representation (Illustration 11)

L alarm	
high alarm heater	2
error conveyer be	lt 🗸
door unlooked	1
over temperature exhaust	4

Alarm management (Illustration 12)

Data recording

In many areas of industry, the recording of process data is an essential element of quality assurance. The GHM-ONE library offers the possibility of realising a data logger and a data recorder in the device. Configuration of the data logger takes place directly in GHM-CAT with function blocks. This makes it possible to log digital and analogue signals in various time periods.

The analogue data can be recorded as minimum, maximum or mean values over a specific time period. The data is saved in the device on an eMMC-chip and can be read via the Ethernet port via FTP. The device has a data storage capacity of 2 GB. The readout of data via USB port on the front side is possible.

The data is provided to the user in a standard ASCII format (csv) for further processing and analysis.

Trend representation

The trend representation on the device takes place on predefined operating screens. Up to 4 curves can be represented in one trend.

By cascading the function, various time periods can be represented. Since the trend block can be opened multiple times in the visualisation, it is possible to use the GHM-ONE as a multi-channel recorder.

The trend representation is independent of the logger function, and so various process signals can be displayed and recorded. The library also provides an alarm block. this block can be used to display alarm lists in plain text on the device.

A function block can be used on the device to display alarm lists in plain text. The Alarm Management includes a reset function.



Data recording, data logging and alarming round out the performance spectrum of GHM-ONE. No additional devices are required for visualisation and data backup.



Communication

The GHM-ONE can be expanded with additional analogue and digital signals from the field with the optional communications card.

The expansion can take place with the GHM I/O system, wherein no additional bus couplers are required in the field. The hardware concept of the GHM-ONE also includes the possibility of connecting external I/O or other fieldbus participants via various fieldbus systems.

- Modbus TCP
- Modbus RTU

In the modern world of automation it is increasingly important that devices exchange data M2M with other devices. The user can approach this task with various interfaces to the PLC and control system level. For this purpose, the GHM-ONE offers various fieldbus systems.

- PROFINET
- PROFIBUS DP
- Modbus TCP

With this communication concept, the device can be integrated into various process areas. Of course, in addition to I/O systems, fieldbus compatible sensors and actuators can also be connected directly to the GHM-ONE with the standard systems.

The entire configuration of process values for external communication is created in GHM-CAT.

The files necessary for the master systems are provided for systems such as PROFINET and PROFIBUS DP. Integration takes place with the respective manufacturer's standard systems. Integration into an existing system is thus possible without a major additional expense. The user can use standards that have been established in the market.



Time-saving integration of the GHM-ONE in a superordinate leading calculator or PLC environment using standard fieldbuses. Simple expansion of the GHM-ONE I/O with external fieldbus systems.





Entering Industrial Age 4.0 with GHM-ONE

With "live streaming" in the music industry, the fundamental digitalisation of production processes – i.e. Industry 4.0 / Smart factory – has already been implemented.

However, in many traditional sectors such as machine construction and other industries, the horizontal and vertical networking of production processes are yet to come. With the GHM-ONE multifunction controller and the corresponding GHM-CAT software, Erolzheim-based GHM Messtechnik offers an up-to-date solution for process automation for the production application.

In tune with the times

Anyone looking to lead in the global competition must be able to respond immediately to changing demands with fully developed models. Consequently, manual production systems have already reached their limits.

For implementation in the concept of Industry 4.0, it is necessary to monitor processes more intensively. The initial step in the implementation is the proper equipment of processes with the correct sensors. GHM-ONE takes care of the integration, regardless of whether it is smart or conservative.

Changing requirements

For implementation in the structures of Industry 4.0, it becomes increasingly necessary for process experts to also be programmers. The modern engineering tool GHM-CAT enables graphically-oriented, intuitive operation for configuration of the compact GHM-ONE multifunction controller instead of software that is complex to operate.

Therefore, the GHM-ONE multifunction controller independently manages the process and communicates the relevant process data to superordinate systems via modern interfaces such as PROFINET and Modbus TCP. The new GHM-CAT software paired with the GHM-ONE multifunction controller is a possible solution for step-by-step travel on the road to Industry 4.0 in the area of process automation.

Smart solutions for automation

- Compact automation system
- Direct connection of sensors and actuators
- Communication with field bus and Ethernet networks
- Intuitively operating GHM-CAT engineering tool
- Individual, multi-variable and ratio control
- For temperatures, pressures, flow rates, fill levels, moisture, pH, conductivity, etc.
- Integrated typical PLC tasks
- Decentralised and autarkic automation in the Industry 4.0 concept



Control Engineering

The GHM-ONE is the centrepiece of the process control development of the GHM Group and serves as a basis for further developments for industrial compact controllers.

The GHM-ONE is a multi-function platform with a modern, innovative concept for measuring, controlling, computing, recording data, visualising, operating and regulating.

Adaptation to system requirements takes place with a single "GHM-CAT" software package, which can be operated without any programming skills.

All illustrated graphics are taken of the GHM-ONE On-line help.

Highlights

PID controller with self-optimisation

The core of the GHM-ONE is a precise PID controller with self-optimisation that can be adapted for the widest range of control tasks. In the process, the aim is optimal regulation of the process according to the operating company's requirements. Product quality and process stability, as well as a minimisation of process times, are the major areas of emphasis.

The GHM-ONE offers various controller functions that can be combined using efficient functional blocks to create an overall application in order to meet these requirements.

The newly developed algorithm for self-optimisation independently finds the optimal controller parameters for many applications and thus reduces commissioning times. The controller algorithm developed especially for the GHM-ONE is the basis for short regulating times with only minor fluctuations of the control variable. (Illustration 14).

The control accuracy can be influenced by the user or the process in order to always ensure optimal utilisation of energy and material during the operating time.

Shock-free switching

Sensitive adjustment of the setpoint in order to avoid endangering product quality or overstress the switching equipment is a recurring challenge. For this reason, the GHM-ONE controller offers the possibility of a setpoint ramp. In this case, the setpoint jump from the user or the SCADA system is automatically implemented as a ramp (Illustration 15.).



paste

mixer



Automatic change-over of the control parametre sentences PID (Illustration 16)



Regulation of non-linear segments or systems with various load states is normally a challenge.

For this purpose, the GHM-ONE supports the user with, among other things, the possibility of process-dependent PID parameters. Therefore, the appropriate set of parameters can be used various phases of the process (Illustration 16). In the process, switching takes place either automatically or by user command.

Ratio and multi-component regulation

In addition to the regulation of process variables, there is always a need to regulate the ratio of process variables. The control module supports the user in this connection with special functions for actual value processing. Therefore, the user can, for instance, regulate the mixture ratio of materials (*Illustration 17*) or regulate a stoichiometric combustion air ratio. (*Illustration 18*)



Stoichiometric combustion air ratio (Illustration 18)

Pv1/((Pv1+Pv2)*S)

Ratio closed loop control regulation (Illustration 17)

water (Pv1)

flour (Pv2)



Cascade control / override control / multi-loop system

Since the control module in the GHM-ONE can be used repeatedly, the user can also create more complex regulating structures, such as cascade control for increased control accuracy of intricate processes or an override control (forced control) to prevent excessive stress. Of course, a multi-loop control system is also possible.

Integrated profiler

In many processes a temperature profile or various mixture ratios play an important role during production. In order to ensure that the user does not have to create an elaborate programmer, the GHM-ONE already offers a profiler with profile editor. (Illustration 20).





Temperature profiles without harmonics finish function (Illustration 21)

Profiler

This profiler can be used repeatedly within an application. An important element for setpoint profiles is the ramp function. With an external programmer, the user repeatedly faces a situation where there is a heavy overshoot at the end of a ramp.

The GHM-ONE compensates for this with a connection between the profiler and controller modules (Illustration 21).

Finish line function

The controller module has a newly developed finish line function. This function ensures that undesired jumps in variables at the end of a ramp are avoided. The setpoint is approached more gently as a result.

Process computer

The computing functions of the GHM-ONE can be used for calculation of process variables, such as a heat quantity. It is also possible to use the results for additional control processes.

For instance, limiting regulation for chemical applications or C-level regulation for carbonisation processes can be effectively implemented. The logic modules can also be used optimally in this connection.

In addition to the control functions currently expected in industry, the GHM-ONE controller offers numerous additional functions

- Customised operation and visualisation
- Capability of integrating process control units
- Recording and representation of process variables
- Communication modules for integration into various process landscapes





Functions in detail

- 1. Definable red/green status indicator LEDs
- 2. 3.5" TFT colour graphic touch display
- 3. Freely configurable operating keys
- 4. USB device
 - Load / read applicatio
 - Debugging functions (online representation)
 - Write / read parametersn

General

- Protection rating IP 65 (Front side)
- Protection rating IP 20 (Rear side)
- Outside dimensions:
 96 mm x 96 mm x 115 mm (HxWxD) (installation length without plugs and wires)

- 1. Ethernet communication interface (see detailed description under "Communication")
- 2. Serial RS485 Modbus / HPR bus communication interface
- Relay card with 4 changeover contact (see detailed description under "Relay outputs")
- 4. I/O card slot B
- (see detailed description under "Standard I/O card")
- 5. I/O card slot A
- 6. USB host
- 7. Transmitter feed
- 8. Voltage supply



- Coding protection of the terminals
- Easy-to-use spring-type terminals
- Lockable wire terminal plate for relay connections





Relay card with 4 changeover contacts





Dimensions

General specifications (base unit)

Controls/device front

Keys: Touch function: 4 freely assigned keys Resistive touch display

Display Front LEDs:

1 red freely assigned LED 1 green freely assigned LED 3,5" TFT display 320 × 240 Pixel QVGA resolution

Display:

Data logger

Storage medium: Storage capacity: Storage rate:

Auxiliary energy

Supply voltege: Power consumption: Electrical connection: Conductor cross-section: Galv.anic isolating: approx 1 GB ≥ 1 second

eMMC chip

100 ...240 V AC oder 24 V DC Typically 10 W Spring-type terminal, 3-pin 0,25 mm to 2,5 mm E/A-level / auxiliary energy / processor

Enviromental conditions

Operating Temperatur: Storage temperatur: Relative air humidity: 0...+55 ℃ -20...+70 ℃ 95 %, non-condensing

Air- and creep distances

Degree ofcontamination:2Overvoltage category:IIMaximum elevation:2000 m

Rated voltagecategory a:230 VTest voltage category a:3000 VAC 1 min.Rated voltagecategory b:category b:50 VTest voltage category b:520 VAC 1 min.

Housing

Type:	Device for control panel installation
Protection rating:	IP65 front side
	IP20 tube and rear side
Width/height/depth:	$98 \times 98 \times 115$ mm (without plug)
	$98 \times 98 \times 130$ mm (with plug)
Panel cutout :	92 × 92 mm

Outputs (relay card)

The relay card is a base card with 4 relays designed as changeover contacts. It is not possible to exchange the relay card with other I/O cards.

Relay

Type:Changeover contactsNumber:4Electrical connection:Spring-type terminalConductor cross-section:0.25 mm to 1.5 mmSwitching voltage:< 250 V AC < 4 A</td>

Note

If a control contactor is connected to a relay output, an RC protective circuit (RC snubber) required according to the contactor manufacturer specifications in order to prevent high voltage peaks. Varistor protective circuits are not recommended.





Up to 2 I/O cards can be installed in the device.

Technical specifications I/O card

- 2 analogue universal inputs
 TC / RTD / -1000...+1000 mV / 0...+20 mA)
- 2 analogue standard inputs (0...+10 V / 0...+20 mA)
- 2 analogue standard outputs (0...+10 V / 0...+20 mA)
- 6 digital inputs or outputs

Analogue universal inputs

The card is equipped with 2 analogue universal inputs

Galvanic isolation

The two universal inputs are galvanically isolated from each other. There is also galvanic isolation for the power supply, the digital inputs and outputs, analogue outputs, and the processor and the communications. There is a galvanic connection to the corresponding analogue standard input (terminal X2 / terminal X4).

Converter resolution:	> 18 Bit
Cycle time:	50 ms
Galvanic isolation:	corresponding to category a

RTD measurements

Input type: Connection type: Resistance 3-wire

Measuring ranges

Pt100 / Pt1000 Ni100 / Ni1000 KTY 11-6 -200...+850 °C -60...+300 °C -50...+125 °C

Measured current

l < 0.5 mA
Ι < 50 μΑ
≤ 1 K
≤ 0.08 % / 10 K
Short-circuit and interruption

Thermocouple measurements

Input type:	Voltage measurement
Connection type:	2-Wire
Input resistance:	>10 MΩ

Thermocouple

Туре	Measuring range	Accuracy	Resolution
L	-200+900 °C	≤ 2 K	0.05 K
J	-210+1200 °C	≤ 2 K	0.05 K
К	-270+1370 °C	≤ 2 K	0.08 K
Ν	-196+1299 °C	≤ 2 K	0.08 K
S	-50+1760 °C	≤ 2 K	0.07 K
R	-50+1760 °C	≤ 2 K	0.07 K
Т	-270+400 °C	≤ 2 K	0.02 K
E	-270+1000 °C	≤ 2 K	0.04 K
В	+25+1820 °C	≤ 3 K	0.1 K
W	0+2299 °C	< 3 K	0.1 K

Temperature drift: Measuring circuit monitoring: Cold-junction compensation:

 ≤ 0.08 % / 10K

Interruption

internal / auxiliary error < 2 K





Connections of the I/O card

Communication card Ethernet / RS485

Resistance measurement

Input type: Connection type: Measuring range: Detection range: Accuracy: Temperature drift: Measuring circuit monitoring:

Resistance measurement 2-Wire 0...20 kΩ Measuring range + 10 % ≤ 0.1 % $\leq 0.08 \% / 10 K$

Exceeding the detection range

Current measurement Input type: Connection type: Measuring range: Detection range: Input impedance: Accuracy: Temperature drift: Measuring circuit monitoring:

Current 2-Wire 0...20 mA Measuring range + 10 % max. 50 Ω < 0.1 % ≤ 0.08 % / 10K

Exceeding and/or undercutting the detection range

Analogue standard input

The card is equipped with 2 analogue standard inputs.

Galvanic isolation

The two standard inputs are galvanically isolated from each other. There is also galvanic isolation for the power supply, the digital inputs and outputs, analogue outputs, and the processor and the communications. There is a galvanic connection to the corresponding analogue universal input (terminal X2 / terminal X4).

Converter resolution:	> 18 Bit
Cycle time:	50 ms
Galvanic isolation:	corresponding to category a

Current measurement

Input type: Connection type: Measuring range: Detection range: input impedance: Accuracy: Temperature drift: Measuring circuit monitoring:

Current 2-Wire 0...20 mA Measuring range + 10 % max. 50 Ω $\leq 0.1 \%$ ≤ 0.08 % / 10 K

Exceeding and/or undercutting the detection range

Voltage measurement

Input type: Connection type: Measuring range: Detection range: Input impedance: Accuracy: Temperature drift: Measuring circuit monitoring:

Voltage 2-Wire 0...10 V Measuring range + 10 % typically 1.2 $M\Omega$ ≤ 0.1 % $\leq 0.08 \% / 10 K$

Overshoot or undercut of the detection range

Analogue output

The card is equipped with 2 analogue standard outputs.

Galvanic isolation

The two standard outputs are galvanically isolated from each other. There is also galvanic isolation for the voltage supply, digital inputs and outputs, analogue inputs and for the processor and communication.

Converter resolution:	12 Bit
Linearity:	< 0.1 %
Accuracy:	< 0.2 %
Temperature drift:	\leq 0.1 % / 10 K
Cycle time:	50 ms
Galvanic isolation:	corresponding to Category a



Current output

Control range:	0+22 mA
Output resistance:	max. 500 Ω

Voltage output

Control range: Output load: 0...+11 V RL≥ 1 kΩ

Digital inputs and outputs

The I/O card is equipped with six inputs/outputs with configuration of the function executed by the respective signal in the CAT. The power supply to the inputs/outputs must be fed externally.

Galvanic isolation

The inputs/outputs are galvanically isolated from each other. There is galvanic isolation for the voltage supply, digital inputs and outputs, analogue inputs and for the processor and communication.

Supply voltage:	24 V DC +/- 20 %
Galvanic isolation:	corresponding to Category a
Digital outputs:	maximum output current 100 mA

Meter input

Two digital inputs (Input 1 and 3) can be configured as meter inputs.

Limit frequency:	10 kHz
Output signal:	Pulses per time unit
	(configurable)

Electrical connections

Spring-type terminal
0.25 mm to 1.5 mm
(with wire end ferrule /
without plastic ferrule)
0.25 mm to 0.75 mm
(with wire end ferrule /
with plastic ferrule)

Communication card Ethernet / RS485

The communication card is equipped with 2 Ethernet ports (in accordance with IEEE 802.3) and 2 RS485 interfaces.

Ethernet connection:	RJ-45
Function:	10/100 Mbit/s
	Auto-Negotiation
	Auto-MDIX
	IP via DHCP or fix
LED:	Link / Data
Protocol:	ModBus TCP Slave
	ModBus TCP Master
	FTP server

Ordering code

GHI	M-0	ONE	DEMERSION
MSI	R96	596H	0000
GH	Μ		
Mu	lti-	function controller	
1.	I/C	Card slot A	
	0	No card in slot A	
	1	I/O card with 2 universal inputs 2 standard signal inputs 2 analogue standard signal outputs 6 digital inputs or outputs	
	2	I/O card with 2 universal inputs 2 high-impedance mV inputs for O ₂ measurement 2 analogue standard signal outputs 6 digital inputs or outputs	
2.	1/0	D card slot B	
	0	No card in slot B	
	1	I/O card with 2 universal inputs 2 standard signal inputs 2 analogue standard signal outputs 6 digital inputs or outputs	
	2	I/O card with 2 universal inputs 2 high-impedance mV inputs for O ₂ measurement 2 analogue standard signal outputs 6 digital inputs or outputs	
3.	Co	ommunication card	
	0	No communication card	
	1	Communication card with 2 x Ethernet; 2 x RS485 (Modbus TCP / Modbus RTU and HPR-Bus)	
	2	PROFINET, Ethernet/Modbus RTU, HPR-BUS	
4.	Αι	uxiliary voltage	
	1	230 V AC	
	2	24 V DC	
5.	0	ptions	
	0	No options	
	Zι	ıbehör	
	0	SB connecting cable for connection of a PC,	
	lei	ngth 1.5 m	

GHM-CAT software



GHN	Λ		
1.	Softv		
	1	One license dongle	
	2	3 license dongle	
	5	5 license dongle	
	10	10 license dongle	

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Notes





Notes

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