

# HD74HC95

## 4-bit Parallel Access Shift Register

# HITACHI

### Description

This 4-bit register features parallel and serial inputs, parallel outputs, mode control, and two clock inputs. The register has three mode operation:

- Parallel (broadside) load
- Shift right (the direction  $Q_A$  toward  $Q_D$ )
- Shift left (the direction  $Q_D$  toward  $Q_A$ )

Parallel loading is accomplished by applying the four bits of data and taking the mode control input high. The data is loaded into the associated flip-flops and appears at the outputs after the high-to-low transition of the clock-2 input. During loading, the entry of serial data is inhibited. Shift right is accomplished on the high-to-low transition of clock-1 when the mode control is low; shift left is accomplished on the high-to-low transition of clock-2 when the mode control is high by connecting the output of each flip-flop ( $Q_D$  to input C, etc.) and serial data is entered at input D. The clock input may be applied commonly to clock-1 and clock-2 if both modes can be clocked from the same source. Changes at the mode control input should normally be made while both clock inputs are low: however, conditions described in the last three lines of the function table will also ensure that register contents are protected.

### Features

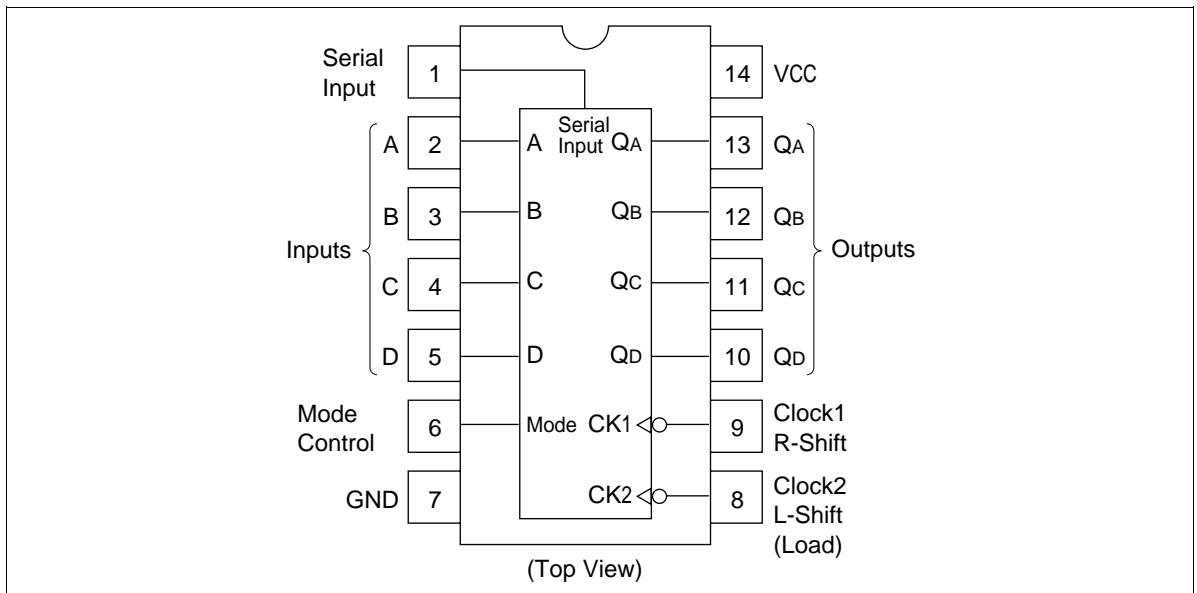
- High Speed Operation:  $t_{pd}$  (Clock to Q) = 17 ns typ ( $C_L = 50$  pF)
- High Output Current: Fanout of 10 LSTTL Loads
- Wide Operating Voltage:  $V_{CC} = 2$  to 6 V
- Low Input Current: 1  $\mu$ A max
- Low Quiescent Supply Current:  $I_{CC}$  (static) = 4  $\mu$ A max ( $T_a = 25^\circ\text{C}$ )

Function Table

Inputs

Mode Control	Clocks		Serial	Parallel				Outputs			
	2 (L)	1 (R)		A	B	C	D	Q <sub>A</sub>	Q <sub>B</sub>	Q <sub>C</sub>	Q <sub>D</sub>
H	H	X	X	X	X	X	X	Q <sub>A0</sub>	Q <sub>B0</sub>	Q <sub>C0</sub>	Q <sub>D0</sub>
H		X	X	a	b	c	d	a	b	c	d
H		X	X	Q <sub>B+</sub>	Q <sub>C+</sub>	Q <sub>D+</sub>	d	Q <sub>Bn</sub>	Q <sub>Cn</sub>	Q <sub>Dn</sub>	d
L	L	H	X	X	X	X	X	Q <sub>A0</sub>	Q <sub>B0</sub>	Q <sub>C0</sub>	Q <sub>D0</sub>
L	X		H	X	X	X	X	H	Q <sub>An</sub>	Q <sub>Bn</sub>	Q <sub>Cn</sub>
L	X		L	X	X	X	X	L	Q <sub>An</sub>	Q <sub>Bn</sub>	Q <sub>Cn</sub>
	L	L	X	X	X	X	X	Q <sub>A0</sub>	Q <sub>B0</sub>	Q <sub>C0</sub>	Q <sub>D0</sub>
	L	L	X	X	X	X	X	Q <sub>A0</sub>	Q <sub>B0</sub>	Q <sub>C0</sub>	Q <sub>D0</sub>
	L	H	X	X	X	X	X	Q <sub>A0</sub>	Q <sub>B0</sub>	Q <sub>C0</sub>	Q <sub>D0</sub>
	H	L	X	X	X	X	X	Q <sub>A0</sub>	Q <sub>B0</sub>	Q <sub>C0</sub>	Q <sub>D0</sub>
	H	H	X	X	X	X	X	Q <sub>A0</sub>	Q <sub>B0</sub>	Q <sub>C0</sub>	Q <sub>D0</sub>

Pin Arrangement

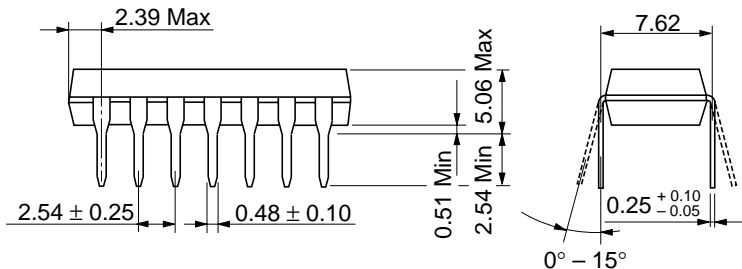
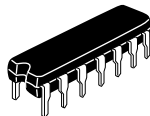
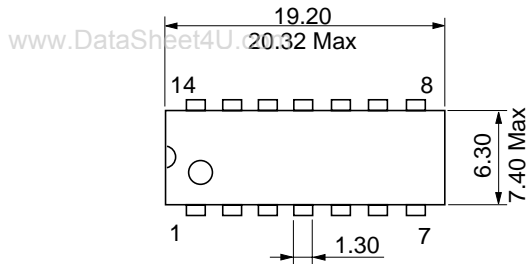


## DC Characteristics

Item	Symbol	V <sub>CC</sub> (V)	Ta = 25°C		Ta = -40 to +85°C		Unit	Test Conditions		
			Min	Typ	Max	Min			Max	
Input voltage	V <sub>IH</sub>	2.0	1.5	—	—	1.5	—	V		
		4.5	3.15	—	—	3.15	—			
		6.0	4.2	—	—	4.2	—			
	V <sub>IL</sub>	2.0	—	—	0.5	—	0.5		V	
		4.5	—	—	1.35	—	1.35			
		6.0	—	—	1.8	—	1.8			
Output voltage	V <sub>OH</sub>	2.0	1.9	2.0	—	1.9	—	V		Vin = V <sub>IH</sub> or V <sub>IL</sub> I <sub>OH</sub> = -20 μA
		4.5	4.4	4.5	—	4.4	—			
		6.0	5.9	6.0	—	5.9	—			
		4.5	4.18	—	—	4.13	—		I <sub>OH</sub> = -4 mA	
		6.0	5.68	—	—	5.63	—		I <sub>OH</sub> = -5.2 mA	
		V <sub>OL</sub>	2.0	—	0.0	0.1	—		0.1	
	4.5		—	0.0	0.1	—	0.1			
	6.0		—	0.0	0.1	—	0.1			
	4.5		—	—	0.26	—	0.33	I <sub>OL</sub> = 4 mA		
	6.0	—	—	0.26	—	0.33	I <sub>OL</sub> = 5.2 mA			
Input current	I <sub>in</sub>	6.0	—	—	±0.1	—	±1.0	μA	Vin = V <sub>CC</sub> or GND	
Quiescent supply current	I <sub>CC</sub>	6.0	—	—	4.0	—	40	μA	Vin = V <sub>CC</sub> or GND, I <sub>out</sub> = 0 μA	

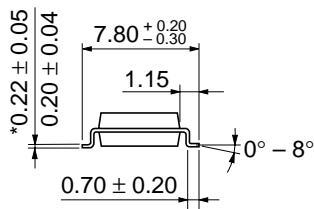
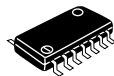
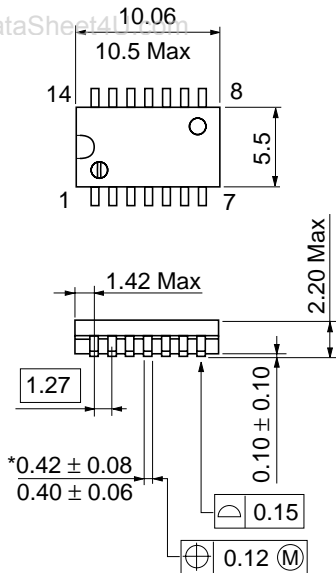
## AC Characteristics ( $C_L = 50$ pF, Input $t_r = t_f = 6$ ns)

Item	Symbol	$V_{CC}$ (V)	$T_a = 25^\circ\text{C}$		$T_a = -40$ to $+85^\circ\text{C}$		Unit	Test Conditions	
			Min	Typ	Max	Min			Max
Maximum clock frequency	$f_{max}$	2.0	—	—	4	—	3	MHz	
		4.5	—	—	20	—	16		
		6.0	—	—	24	—	19		
Propagation delay time	$t_{PLH}$	2.0	—	—	145	—	180	ns	
		4.5	—	17	29	—	36		
		6.0	—	—	25	—	31		
	$t_{PHL}$	2.0	—	—	170	—	215	ns	
		4.5	—	17	34	—	43		
		6.0	—	—	29	—	37		
Pulse width	$t_w$	2.0	80	—	—	100	—	ns	Clock
		4.5	16	6	—	20	—		
		6.0	14	—	—	17	—		
Setup time	$t_{su}$	2.0	100	—	—	125	—	ns	
		4.5	20	2	—	25	—		
		6.0	17	—	—	21	—		
Hold time	$t_h$	2.0	10	—	—	10	—	ns	
		4.5	10	-1	—	10	—		
		6.0	10	—	—	10	—		
Output rise/fall time	$t_{TLH}$	2.0	—	—	75	—	95	ns	
	$t_{THL}$	4.5	—	5	15	—	19		
		6.0	—	—	13	—	16		
Input capacitance	$C_{in}$	—	—	5	10	—	10	pF	



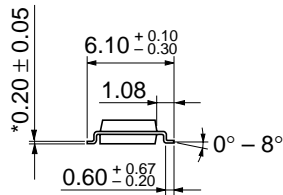
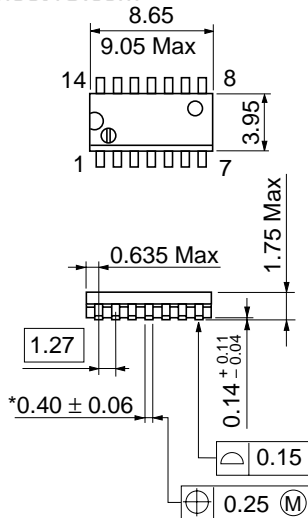
Hitachi Code	D144
JEDEC	Conforms
EIAJ	Conforms
Weight (reference value)	0.97 g

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\*Dimension including the plating thickness  
Base material dimension

Hitachi Code	www.DataSheet4U.com
JEDEC	—
EIAJ	Conforms
Weight (reference value)	0.23 g



Hitachi Code	JEDEC	EIAJ	Weight (reference value)
	Conforms	Conforms	0.13 g

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