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1.0 WHAT'S IN YOUR KIT?





AC POWER CABLE



ARDUINO MOTOR & SHIELD



CHAINS(2)



DC POWER SUPPLY



RING BEARINGS(4)



RING BRACKET



RING BRACKET MOUNTS(3)



RING CARRIAGE(2)



USB CABLE



USB FLASH DRIVE



X/Y MOTOR CABLES



X/Y Motor Mounts(2)



X/Y MOTORS



Z AXIS MOTOR



Z AXIS MOTOR CABLE



Z AXIS MOTOR MOUNTS(2)

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HARDWARE BAGS



BAG #1

Attaches chains to frame



Cords, hardware for attaching Holds bricks in place on sled to frame





Multiple uses



BAG #5

Fastens motor to mounts



Attaches Arduino to frame



Attaches carriages to ring



Fastens L-brackets to ring, and to sled



Attaches Z axis to router and sled



DESIGN BY THE MASLOW COMMUNITY, PARTICULARLY USERS DLANG AND MADGRIZZLE

1.1 BUILDING THE FRAME



TOOLS NEEDED:

Saw Power Drill Screwdrivers Safety goggles

MATERIALS LIST:

(7) 10' long 2x4s
(1) 8' long 2x4
(1) 6' long 2x4
(1) 4X8 sheet .75" plywood
(75-100) 2.25" wood screws
Wood glue
Hardware & parts from kit

BUILD TIME:

About 5 hours, plus glue drying time

CUT LIST:

34"
30"
28"
7"
8.5"

Difficulty Level

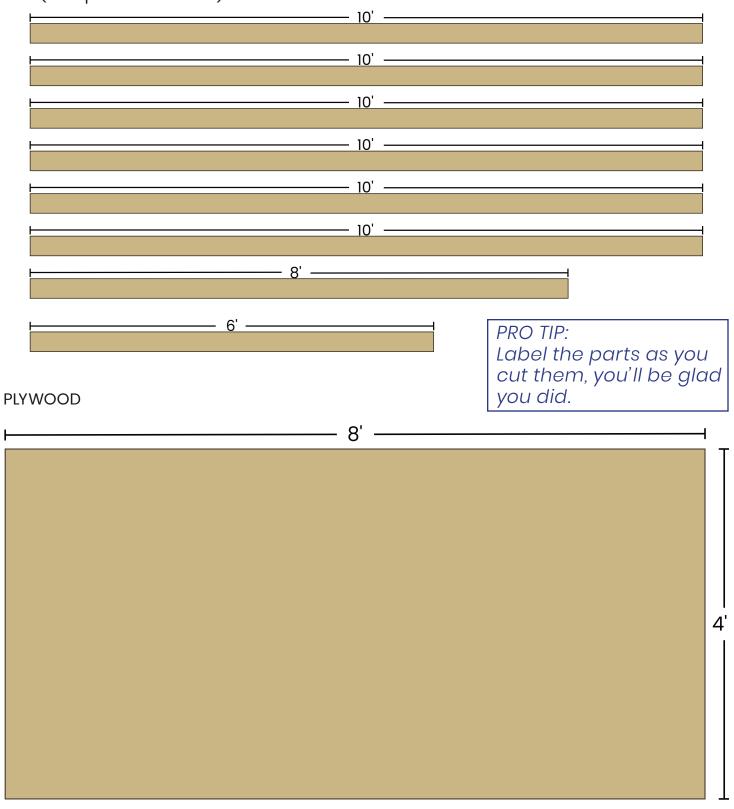
COST: Approximately \$90

BEFORE BEGINNING Acquaint yourself with standard practices for workshop safety.

Note: Lumber dimensions are not critical, if 2x4s are not available in your area the local equivalent will work. When cutting, try to keep the ends as square as possible, but small errors in the lengths of any of the parts will not affect accuracy of the machine.

STEP 1: BUY MATERIALS

2X4 (or equivalent lumber)





STEP 2: CUT OUT PIECES AS SHOWN 2X4 (or equivalent lumber)

120" TOP BEAM		
		3.5" SPACER
82" FRONT CROSSMEMBER: UPPER	34" VERTICAL	•
		3.5" SPACER
82" FRONT CROSSMEMBER: LOWER	34" VERTICAL	•
7" BEAM		3.5" SPACER
↓ 79" FRONT LEG	30" KICKER	•
7" BEAM		3.5" SPACER
↓ 79" FRONT LEG	30" KICKER	↓ I

60" BACK LEG

60" BACK LEG

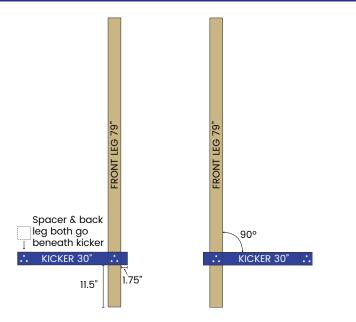
88" REAR CROSSMEMBER

28" DIAGONAL 28" DIAGONAL

PLYWOOD

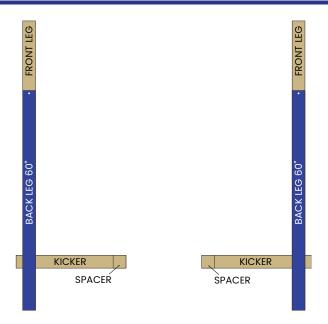
4' X 8'





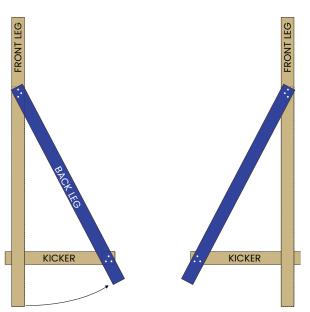
STEP 3/4A ATTACH KICKERS TO FRONT LEGS

- •Kickers at 90° angle to front legs
- •Kickers 11.5" from bottom of front legs, and overhanging by 1.75"
- Screw through top of kickers into front legs
- Screw through top of kickers into spacers
- •Flip each assembly over for next step



STEP 3/4B ADD BACK LEGS

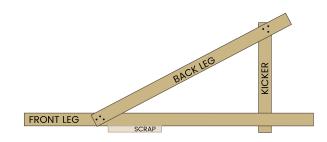
- •Place back legs on top of front legs, aligning bottom ends
- •Mark center of back legs 1" from top end
- •Screw through top center of back legs into front legs at marked spot
- •Only 1 screw per leg, NO GLUE



STEP 3/4C POSITION BACK LEGS

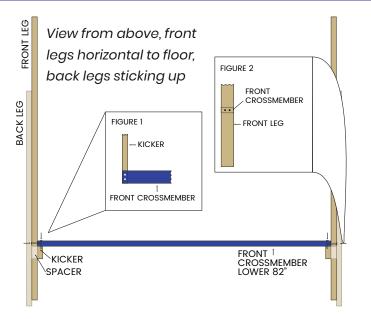
- •Rotate back legs out to end of kickers
- •Screw bottom of back legs to kickers
- •Add more screws to top of back legs

LEGS ARE NOW COMPLETE!



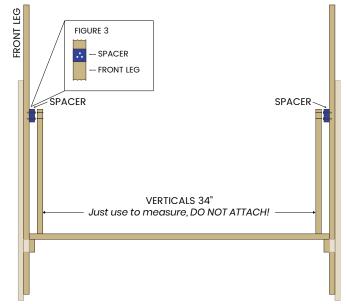
Next steps are most easily done with front legs horizontal to floor, as shown. Prop with scraps to keep things level.





STEP 5A ATTACH LOWER FRONT CROSSMEMBER

- •Rest lower front crossmember on kickers
- •Screw from top of crossmember into each kicker- see Figure 1
- •Screw from side of each front leg into crossmember- *see Figure 2*



STEP 5B ADD SPACERS

- •Use verticals to measure placement of spacers on inside of front legs
- •DO NOT ATTACH VERTICALS IN THIS STEP
- Screw through spacers into front legs

CROSSMEMBER

VERTICAL

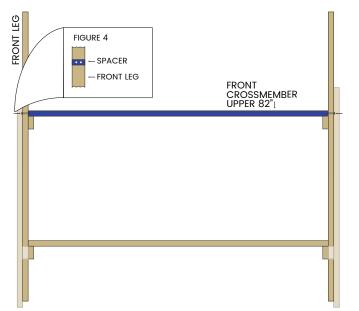
FRONT CROSSMEMBER UPPER |

DIAGONAL 28

FRONT[†] CROSSMEMBER LOWER

FIGURE 5

VERTICAL



STEP 5C ATTACH UPPER FRONT CROSSMEMBER

- •Rest upper front crossmember on spacers
- •Screw through sides of front legs into crossmember

STEP 6 ATTACH VERTICALS

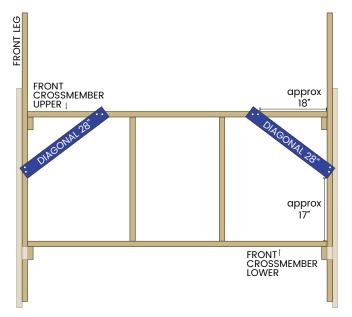
DIAGONAL 28

- •Use diagonals to place verticals
- DO NOT ATTACH DIAGONALS IN THIS STEP

VERTICALS 34"-

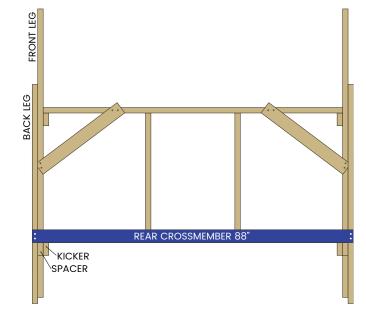
- •Screw through top crossmember into verticals
- •Screw through bottom crossmember into verticals





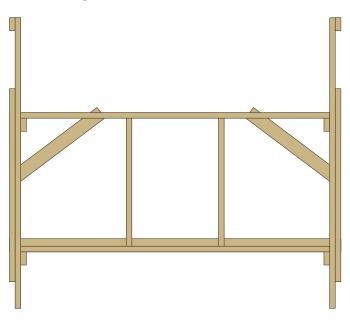
STEP 7 ATTACH DIAGONAL BRACING

- •Rest diagonals with one end on front leg, one leg on upper crossmember
- •Screw diagonals in place on each end
- •Placement of diagonals need not be exact



STEP 8 ATTACH REAR CROSSMEMBER

- •Rest rear crossmember on top of kickers where they protrude from back legs
- Screw through rear crossmember into back legs



ALMOST FINISHED!

STEP 9 ATTACH SIDE BEAMS

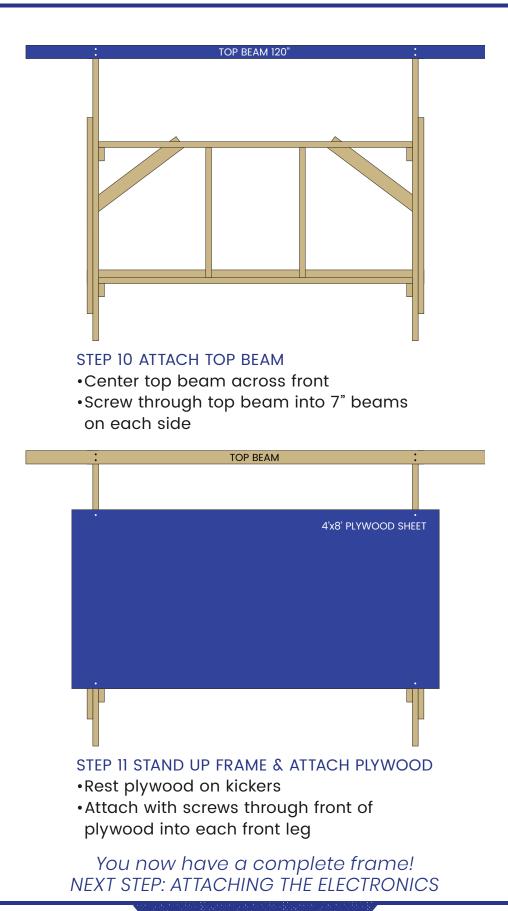
KICKER

900

BEAM

- •Beams were placed on cut list to have one factory end, this end should face out so top beam has a flat surface to rest on
- Place beams at 90° angles to each front leg
- Screw through beams into front legs







DESIGN BY THE MASLOW COMMUNITY, PARTICULARLY USERS DLANG AND MADGRIZZLE

1.2: ADDING THE ELECTRONICS



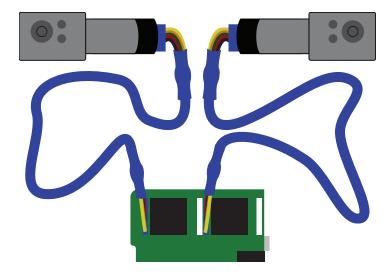
TOOLS NEEDED:

Power Drill Screwdrivers Safety goggles Computer or tablet Internet connection BUILD TIME: About 1 hour

MATERIALS LIST:

Part #1 AC Power Cable Part #2 Arduino with Heat Shield Part #4 DC Power Supply Part #9 USB Cable Part #10 Flash Drive (optional) Part #11 X and Y Motor Cables Part #12 X and Y Motor Mounts Part #13 X and Y Motors Hardware Bag #5 Hardware Bag #6

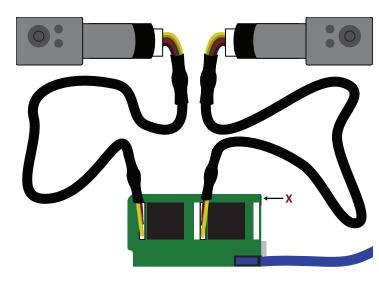
Before adding the electronics to the frame, there's a bit of setup- downloading and adding programs and information, that needs to be done



STEP 1: CONNECT THE MOTORS

PART #2 Arduino with Heat Shield PART #11 X & Y Motor Cables PART #13 X & Y Motors

- •X and Y motor cables, as well as motors, are interchangeable at this point
- Insert one end of a cable into each motor
- Insert other ends into to Ports 1 and 3 on Arduino with yellow wire at bottom as shown
- •Port 3 controls left motor Port 1 controls right motor as viewed when facing the Maslow CNC.



STEP 2: CONNECT THE POWER SUPPLY PART #1 AC Power Cable

PART #3 DC Power Supply

- Plug DC power supply into shield
- Arduino also has a power supply port, plugging power supply into it will not damage it, but will not provide power to motors
- •Connect power cable to DC Power Supply
- •Plug power cable into surge protected electrical outlet

STEP 3: CONNECT THE USB CABLE PART #9 USB Cable

Computer or tablet

- •Plug USB cord into Arduino
- •Plug other end into your computer
- •USB light will come on to indicate that board is connected and receiving power from your computer



STEP 4: DOWNLOAD THE ARDUINO IDE Internet connection Computer or tablet

- •In your browser, navigate to https://www.arduino.cc/en/Main/Software
- Download latest version of Arduino IDE
- •Note: Some users have reported problems with "Windows App" version
- •Open zip folder
- Install program on your computer
- •Open program

STEP 5: DOWNLOAD MASLOW FIRMWARE

- In your browser, navigate to http://github.com/MaslowCNC/Firmware/releases/
- Download latest version of firmware
- Open zip folder
- Install program on your computer

STEP 6: SET UP FIRMWARE

- •Click File -> Open
- Select cncctrlvl.ino
- Click Tools -> Board
- •Select Arduino/Genuino Mega or Mega 2560 STEP 9: CONNECT GROUND CONTROL TO
- Click Tools -> Port -> Your Port
- •Select port- on Windows, COM3, on Mac and Linux computers dev/tty/
- •If unsure, disconnect USB cable from Arduino, check which option disappears.

STEP 7: ADD FIRMWARE TO ARDUINO

- Click upload button in top left corner
- This uploads firmware to Arduino
- •Linux users: if getting timeout or permissions errors, try adding username to dialout group then logging out and back in
- •When upload finishes, close Arduino IDE

NOTE: Ground Control is the program which runs on your computer and lets you control your Maslow CNC.It's free and is updated often.

STEP 8: INSTALL GROUND CONTROL

- In your browser, navigate to https://github.com/MaslowCNC/ GroundControl/releases
- •Download latest version of Ground Control WINDOWS USERS
- Open zip folder
- •Click Launch Ground Control" shortcut MAC USERS
- Install Ground Control by moving it into your applications folder
- •Click icon in applications folder
- •Select "Open"

Linux and Raspberry Pi users:

•Reference instructions online at http:// maslowcommunitygarden.org/ GroundControl.html?instructions=true

STEP 9: CONNECT GROUND CONTROL TO MASLOW

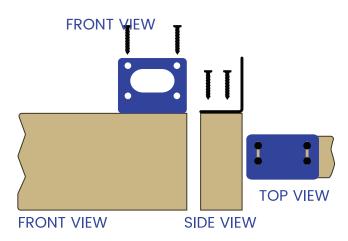
- •In Ground Control, click ACTIONS on top left
- •Click PORTS, a list of ports will appear
- •Select same port you used in Step 6
- Click CONNECT

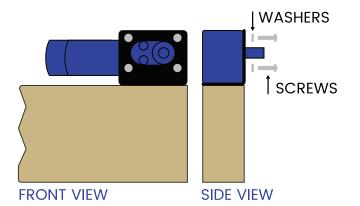
THAT PART'S DONE! YOU'RE NOW READY TO INSTALL THE ELECTRONICS ON THE FRAME. BEFORE PROCEEDING DISCONNECT POWER CABLES, USB CABLES, AND MOTOR CABLES.



Image: Side view Image: Side view

STEPS 12-14 TAKE PLACE ON THE TOP BEAM OF THE FRAME, REPEATED ON EACH END





STEP 12: INSTALL MOTOR MOUNTS ON FRAME

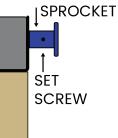
BAG #4 (8) wood screws PART #12 X/Y Motor Mounts

- •Position motor mounts on beam flush with front and side edges
- •Using two screws per slot on base of each motor mount, fasten motor mounts to beam with wood screws

STEP 13: ATTACH MOTORS TO MOUNTS BAG #5 (8) small screws, (8) lock washers PART#13 X/Y Motors

- •Place one motor in each bracket
- Slide lock washers over screws
- •Fasten screws through front of motor mount into aligned holes in motor

FRONT VIEW SI



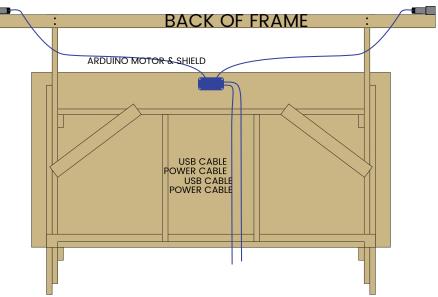
SIDE VIEW

STEP 14: INSTALL SPROCKETS ON MOTOR SHAFTS

BAG#1 (2) sprockets, (2) set screws Allen wrench

- Insert set screw in hole on side of sprocket
- •Screw in slightly with allen wrench
- Place sprocket over motor shaft
- Tighten set screw with allen wrench





STEPS 15-16 TAKE PLACE ON THE BACK OF THE FRAME

STEP 15 ATTACH THE ARDUINO

BAG #6 screws, standoffs PART #2 Arduino

- •Gently remove shield from Arduino
- Position Arduino in center of plywood
- Insert screws through holes
- Slide standoffs over screws
- Screw into plywood
- •Re-attach shield

STEP 16 RECONNECT ELECTRONICS

PARTS #1-2 Power Cable, Power Supply PART #9 USB Cable PART #11 X/Y Motor Cables

- •Attach Arduino to motors with cables
- •Connect power supply to Arduino
- •Connect USB cord to Arduino
- •For more details review electronics setup guide

NEXT STEP: BUILDING THE TEMPORARY SLED



DESIGN BY THE MASLOW COMMUNITY, PARTICULARLY USERS DLANG AND MADGRIZZLE

1.3 BUILDING THE TEMPORARY SLED



TOOLS NEEDED:

Router, .25" router bit Handsaw or Circular Saw Phillip's Head Screwdriver Power Drill, .25" & .5" drill bits Socket Wrench, various sizes

MATERIALS LIST:

4x8 Plywood, .75" thick*
 Bricks**
 Size 10-32 Machine Screws
 Part #5 Ring Bearings
 Part #6 Ring Mount
 Part #7 Ring Bracket Mounts
 Part #8 Ring Carriage
 Hardware Bags #3,6,7,8

_ _ _ _ _ _ _ _ _

Pencil

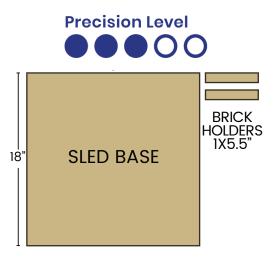
CUT LIST: (1) 18x18" square (2) 1x5.5" rectangles**

5/16 Allen Wrench

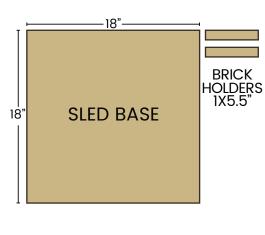
Clamps (optional)

Safety goggles

Difficulty Level



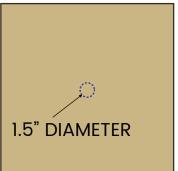
*If you have scrap plywood on hand, it's not neccesary to buy a whole sheet of plywood **If using MakerMade metal brickholders bricks should be no more than 4.5" wide



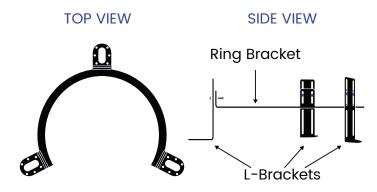
STEP 1 CUT OUT PLYWOOD PARTS

Saw, ruler

- •Mark dimensions of parts on plywood
- •Exactness is not critical for temporary sled
- •Using hand or circular saw, cut out parts



CAP BEHIND CAP BEHIND CAP NOTE: These steps are for the Rigid router, other routers may differ



STEP 2 CUT CENTER HOLE FOR BIT

Router, .25" router bit, pencil

- •Mark 1.5"x1.5" hole in center of sled
- •Use router to cut out hole, going down approx 1/10" per pass

STEP 3 REMOVE ROUTER HANDLES, BASEPLATE

5/16 allen wrench, screwdriver

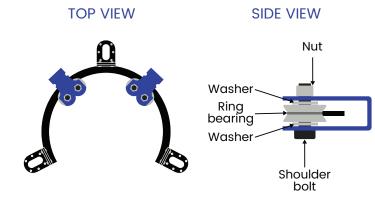
- •Remove cap on side of handle
- •Bolt inside hole may be unscrewed with a 5/16 allen wrench
- •Turn router over so baseplate is up
- •Use Phillips-head screwdriver to remove 3 machine screws from bottom of baseplate
- •Set router and baseplate aside

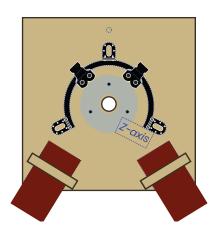
STEP 4 ATTACH L-BRACKETS TO RING

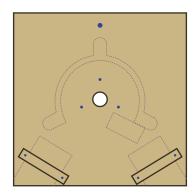
BAG #8 (6)nuts, (6)bolts, allen wrench PARTS #6-7 Ring bracket, (3)L-brackets

- •Line up L-brackets as shown with rectangular brackets on ring
- Insert bolts from inside of ring bracket out through L-brackets, two per bracket
- •Secure with nuts, using allen wrench to tighten









STEP 5 ATTACH CARRIAGES TO RING

BAG #7 (4) shoulder bolts, (4) nuts, (8) washers, allen wrench PART #2 Ring Bearings

PART #5 Carriage mounts

- •Place one carriage on either side of ring
- Insert shoulder bolt up through bottom of carriage, slip one washer over bolt, then one ring bearing, then another washer
- •Push shoulder bolt through top of carriage, fasten with nut
- •Do this twice for each carriage
- •Use allen wrench to tighten bolts
- •Bearings should still rotate freely

STEP 6 MARK PLACEMENT OF COMPONENTS Pencil

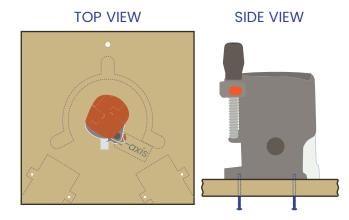
- •Place components on sled as shown above
- •Baseplate of router in center of sled
- •Ring assembly centered around baseplate
- •Bricks and holders in corners, exact placement not critical
- •Use pencil to mark 3 holes in baseplate
- •Mark placement of ring and brick holders
- •Mark .5" circle as shown, middle of sled, halfway between top edge and ring
- •If using Z-axis with temporary sled, leave room for that as marked above

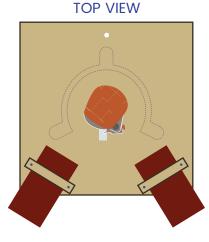
STEP 7 DRILL HOLES

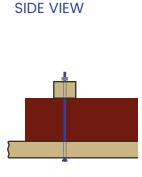
Power drill, .25" and .5" drill bit, optional clamps

- •Place brick holders in marked spots, clamp into place (optional but helpful)
- •Mark a spot on each end of holder just outside of where the brick will be
- •Drill through holders and sled with .25" bit
- •Drill 3 holes where marked for router with .25" bit
- •Drill top hole with .5" bit









SIDE VIEW

T T 1

STEP 8 ATTACH ROUTER, TO SLED

(3) 10-32 machine screws

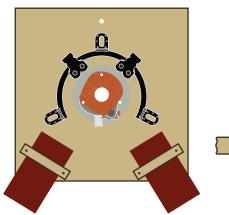
- Insert screws through pre-drilled holes from bottom of sled into router
- •Tighten with Phillips-head screwdriver

STEP 9 ATTACH BRICKS TO SLED

Bag #3 Nuts, bolts

- (2) brick holders
- •Insert bolts through pre-drilled holes from bottom of sled through to the top
- Place bricks between bolts
- Place wooden brick retainers over bolts
- Secure with nuts

TOP VIEW



STEP 10 ATTACH RING TO SLED

BAG #8 (18) small screws

- Place ring on sled centered around router
- •Each L-bracket has six small holes, insert a small screw through each hole
- •Fasten with Phillips-head screwdriver

NEXT STEP: INSTALLING THE Z-AXIS

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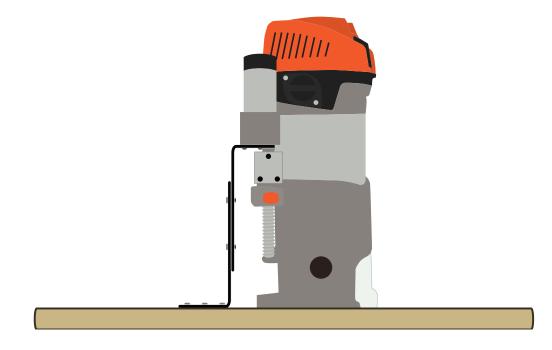
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1.4 INSTALLING THE Z AXIS



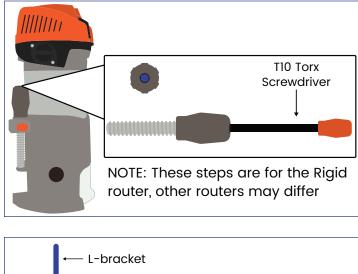
TOOLS NEEDED: Phillips-head screwdriver T10 Torx Screwdriver Safety goggles Computer or tablet Ground Control software (free)

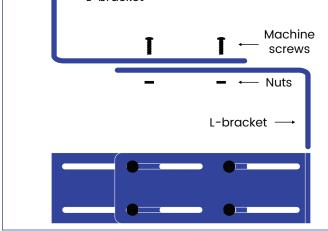
MATERIALS LIST:

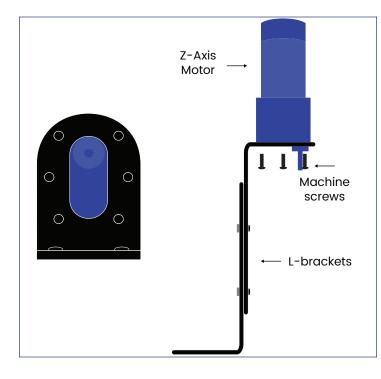
Part #14 Z Axis Motor Part #15 Z Axis Motor Cable, Part #16 Z Axis Motor Mounts (2) Hardware Bag Z (2) Zipties

In manual use, your router has a knob/screw assembly that you turn in order to move the bit up and down. The Z axis is designed to replace that, saving you painstaking manual adjustments

These instructions are tailored to the Rigid router, if you have a different router, procedure may vary.







STEP 1 REMOVE ROUTER ADJUSTMENT KNOB T10 Torx Screwdriver

- •In the Rigid router, adjustment knob is dark gray, located on side of router
- Insert T10 torx screwdriver into hole in top of adjustment knob
- ·Loosen screw, remove knob
- •Save knob/screw in case you want to restore your router to manual control

STEP 2 JOIN MOTOR MOUNTS

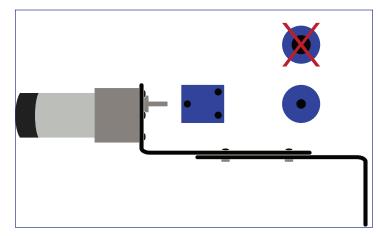
Bag Z (4) bolts, (4) nuts Bag #8 allen wrench Part #16 Z Axis Motor Mounts (L-brackets) •Place I-brackets back to front as shown, with lengthwise slots lined up

- Insert bolts through slots in both brackets
- Hold bolts steady with allen wrench
- •Twist nuts over end of bolts to secure
- Leave loose for later adjustment

STEP 3 ATTACH MOTOR TO MOUNTS

Bag Z (6) screws Part #14 Z Axis Motor Phillips-head screwdriver

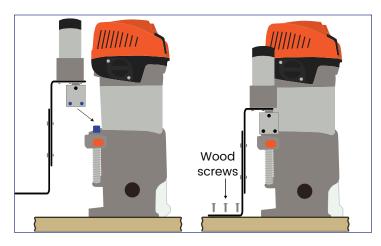
- Insert motor shaft through opening in bottom of L-bracket, from outside to inside
- Align six small holes in bracket with matching holes in motor
- Insert screws through holes
- •Tighten with Phillips-head screwdriver



STEP 4 ATTACH THE SHAFT COUPLER

Bag Z shaft coupler Bag #8 allen wrench

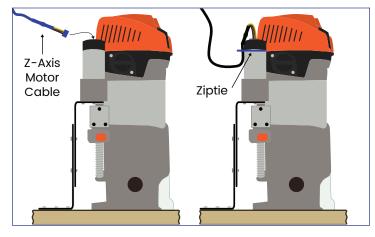
- •Shaft coupler has a larger hole on one end, a smaller hole on the other end
- •Slide end with smaller hole over motor shaft
- Use allen wrench to tighten set screw nearest to motor
- •Leave other 2 set screws as is until Step 5



STEP 5 ATTACH Z AXIS TO ROUTER AND SLED

Bag Z (6) wood screws Bag #8 allen wrench Phillips-head screwdriver

- •Slide free end of shaft coupler over adjustment screw on router
- •Use allen wrench to tighten 2 set screws to engage shaft coupler with router
- •If unable to reach a screw, leave it for later when the motor gets rotated
- Adjust/slide L-brackets so bottom bracket rests on sled
- Insert wood screws through small holes in bottom of L-bracket, screw into wood of sled



STEP 6 ATTACH MOTOR CABLE

Bag #2 ziptie

Part #15 Z Axis Motor Cable

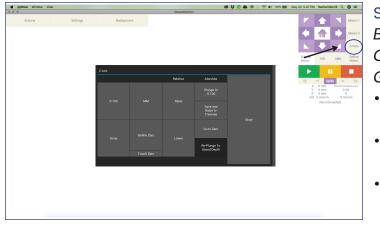
- Insert one end of motor cable into end of Z Axis motor
- Insert other end of cable into MP2 slot on Arduino
- •Use ziptie to secure cable to motor to provide relief from strain as sled moves

Window View		● ¥ © ♣ ⊕ ⊨ ≤ ≤	📚 🛋 0 - 100% (BSB)	May 20 5:47 PM	Rachel Merrill C	20=
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g python Window View		@ Ų (3 & # * 9	• 4 0 702% (59)	May 20 5:49 PM	Rechel M
000	GroundControl					-
Maslow Settings						
Serial Connection Select the COM port to connect to machine default attring:				(dev)	tty.usbmodem1434	401
Distance Between Motors The horizontal distance between the center of the motor shafts in AMA. default setting: 25/96.4						
Work Area Width in MM The width of the machine working area (normally 8 feet), default setting 2400-4						
Work Area Height in MM The Height of the machine working area (normally 4 feet). default setting: 1219.2						
Motor Offset Height in MM The vertical distance from the edge of the work area to the level of the rectors. default setting: 463						
Distance Between Sled Mounting Points The hotizontal distance between the points where the chains mount to the sled. details retring 310						
Vertical Distance Sled Mounts to Cutter The vertical distance between where the chains mount on the sled to the outring tool. default setting 139						
Center Of Cravity How for below the cutting bit is the center of gravity. This can be found by resting the sted on a round oby default action; 79		1				
z-axis installed Does the machine have an automatic z-axis? default sering 0				\rightarrow	ON	
2-Axis Pitch The number of min messed per rotation of the z-axis default setting 3.17					3.17	
Color Scheme Switch between the light and dark color schemes. Restarting GC is needed for this change to take effect default setting: Light.					Light	

STEP 7 ENABLE THE Z AXIS IN SETTINGS

Computer or tablet Ground Control software

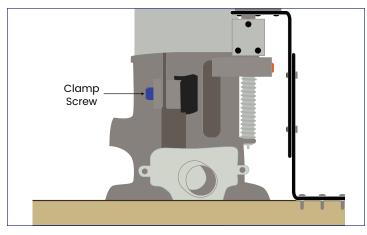
- •Open Ground Control
- •From main screen, click Settings
- Scroll down to "z-axis installed"
- Click switch to "on"
- •Directly below, check "z-axis pitch" setting
- •For Rigid router, setting should be 3.17
- If using another router, check markings on knob removed from router. It should indicate the distance per-rotation, ie how far down the bit goes each time the handle is fully rotated



STEP 8 TIGHTEN SHAFT COUPLER

Bag #8 allen wrench Computer or tablet Ground Control software •If a set screw in the shaft coupler still needs to be tightened-•Rotate shaft coupler to access it using

- Rotate shaft coupler to access it using z-axis buttons in Ground Control
- Tighten with allen wrench



STEP 9 LOOSEN ROUTER CLAMP

Phillip's head screwdriver

- •On Rigid router, clamping mechanism must be adjusted to allow movement
- Loosen screw on inside of clamp
- •Correct tension will allow router to move freely but not wiggle

NEXT STEP: CALIBRATING YOUR MASLOW



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1.5 CALIBRATING YOUR MASLOW



TOOLS NEEDED:

Maslow CNC Router, .25" bit Safety goggles Protective gloves Screwdrivers Power Drill, .5" bit Hardware and components from kit Computer or tablet Ground Control software

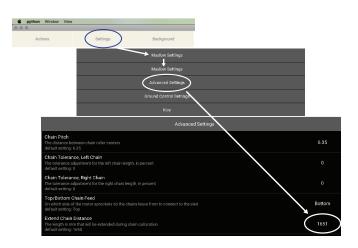
MATERIALS LIST:

(1) 4x8 plywood, .75" thick*(1) .5" carriage bolt

Calibration is the step that sets your machine up so it will cut designs accurately. Calibration is of paramount importance and is probably the most difficult, and sometimes frustrating, part of owning a Maslow. Because every user sets up their own frame, there are a lot of varying factors that may cause temporary hiccups. If you do get frustrated, take a break and come back to it.

NOTE: SLED/ CHAINS SHOULD NOT BE ATTACHED TO FRAME AT THIS POINT! If they were attached previously, remove them before proceeding

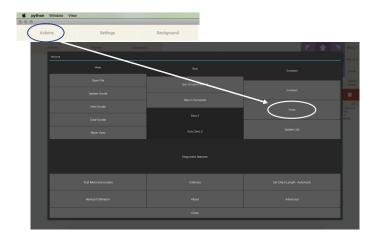
Observe proper safety precautions, including wearing safety goggles and protective gloves especially anytime chains are attached and moving



STEP 1: OPEN GROUND CONTROL TO BEGIN!

STEP 2: CHANGE EXTEND CHAIN DISTANCE

- Go to SETTINGS at top left of screen
- •Find Extend Chain Distance
- Click MASLOW SETTINGS at top of screen
- Click ADVANCED SETTINGS
- •Find EXTEND CHAIN DISTANCE, set to 1651
- •If using an alternate setup, setting should be a multiple of 63.5 MM, approximate distance from motor sprocket to where ring sled will rest in center of plywood.



STEP 3: CONNECT PORT

- •Go to ACTIONS->PORT
- •Click on the port that you set up previously when you set up the electronics
- •If you don't see the correct port, click UPDATE LIST
- Once port is selected, click CONNECT

STEP 4: INTRODUCTION

•Read instructions,

Click BEGIN

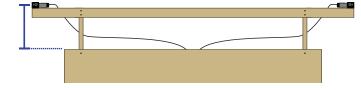
NOTE: For a variety of reasons you may have to run the calibration process more than once. If so, there are some steps you can skip. This manual will give you guidance on which you can skip and which you can't. YOU MAY ONLY SKIP STEPS IF IT'S NOT YOUR FIRST TIME CALIBRATING

STEP 5: CHAIN ATTACHMENT METHOD

- If using the ring that MakerMade shipped with your kit, choose TRIANGULAR
- If using a custom setup, it's probably still TRIANGULAR

SKIP if you've done this before, and haven't changed your setup. This is true for all subsequent "Skip" instructions.





.01 Degree

Rotation

1 Degree Rotation

5 Degree

Rotation

STEP 6: DISTANCE FROM MOTOR TO PLYWOOD

- •Measure approximate distance from center of motor shaft to top of plywood, value will be fine tuned during calibration
- •CONVERT TO MM! 1 IN = 25.4 MM
- •Click ENTER MEASUREMENT

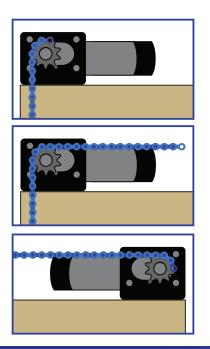
•Enter measurement, click DONE SKIP, if measurement hasn't changed since previous calibration procedures

STEP 7: SET SPROCKETS VERTICAL

- The goal is to get one tooth on each motor sprocket pointing straight up, 12:00 position
 Buttons rotate sprocket to specified degree
 CW = clockwise) CCW = counter-clockwise
 Eyeballing is fine, just get it close
 Click SET 7EPO
- Click SET ZERO

•Don't use AUTOMATIC button SKIP, if there have been no "location lost" errors in previous procedures or errors with chains skipping or tangling

NOTE: USE EXTEND BUTTON TO FEED OUT CHAIN for the following steps. Draping chains over sprocket manually then clicking PULL CHAIN TIGHT & MEASURE will not work.



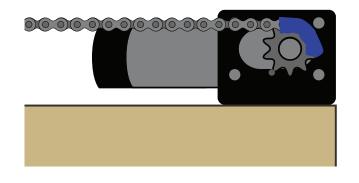
STEP 8: DISTANCE BETWEEN MOTORS

- Place first link of left chain on left sprocket
- Click EXTEND
- •Left sprocket will rotate clockwise and feed out 100 mm of chain
- •Hold chain to make sure it doesn't wrap around sprocket.
- •Change value to "1000 mm"
- •Click EXTEND 3 times more, still holding onto chain, keeping tension on it
- •Chain should now reach first link on right sprocket
- •If not, change 1000 mm value to 10 mm, click it until it does
- •Place end of left chain on right sprocket

STEP 9: SCREEN 5 MEASURING DISTANCE BETWEEN MOTORS

If value is still at 1000mm change to 10 MMClick RETRACT until most, but not all slack is gone





CAUTION: during the next step, the chain may come off the right sprocket. It can be under a lot of tension and if it comes off, make sure you're not within range

A carefully placed small piece of duct tape may provide some stability. Just be sure the tape doesn't interfere with movement of the sprocket.

STEP 10: SCREEN 5 MEASURING DISTANCE BETWEEN MOTORS

- •Pay attention to motors and frame during this time, if motors move or frame flexes, make adjustments to your frame so this doesn't happen
- •Click PULL CHAIN TIGHT AND MEASURE. During this step, slack will be taken up and software will determine, distance between motors based upon how much chain is fed out.



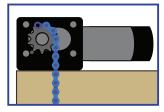
•Chain will slacken up when operation is done

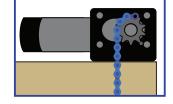


•Remove chain from frame, set aside until later



STEP 11: SCREEN 6: PICK CHAIN FEED ARRANGEMENT •If using default frame, Click CHAIN OFF BOTTOM SKIP- if you've done this before	 STEP 13: SCREEN 8- GENERATE CALIBRATION PROCEDURE The machine is doing all the work here, Take a deep breath, relax for a minute DON'T SKIP
 STEP 12: SCREEN 7- REVIEW THE MEASUREMENTS For future reference- jot down numbers, screenshot, or take a picture If numbers look off, click back button to go back and redo steps related to any numbers that look off If numbers look good, click LOOKS GOOD 	 STEP 14: SCREEN 9- SET SPROCKETS VERTICAL Same procedure as Step 4 This time it may work to hit AUTOMATIC If it doesn't work, don't panic Re-adjust sprockets with buttons as before When sprockets are in place, click SET ZERO SKIP only if chains are attached to sled because you skipped other steps
SOME BALLPARK PARAMETERS FOR NUMBERS: Distance btwn motors = <3048 MM if using 10' top beam, <3568 MM for 12' top beam Vertical motor offset = # entered in Step 3 Kinematic type = Triangular Chain feed type = Bottom Rotation radius = 140 mm Chain sag correction value = varies	STEP 15: SCREEN 10- ENTER ROTATIONAL RADIUS ESTIMATE •Use numbers given on screen •Click ENTER MEASUREMENT and enter appropriate value for your kit •Click NEXT SKIP- if you've done this before





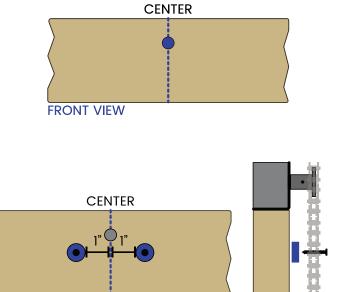
STEP 16: SCREEN 11- ADJUST CHAIN LENGTHS

- •Place left chain on left sprocket as shown
- •Click ADJUST LEFT CHAIN while holding on to left chain to prevent wrapping
- •Left sprocket will turn counter-clockwise and extend chain to a determined length
- •Repeat with right chain

SKIP only if chains are attached to sled because you skipped other steps

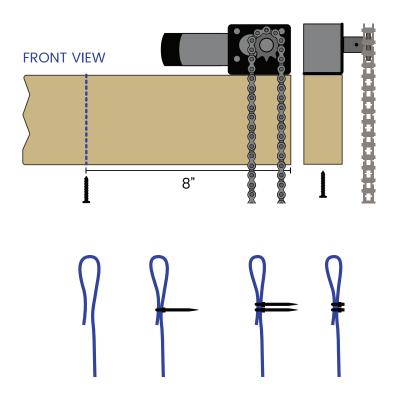
NEXT YOU'LL ATTACH THE SLED TO THE CHAINS, LEAVE CHAINS EXACTLY WHERE THEY ARE

DO NOT CHANGE THEIR POSITION ON THE SPROCKETS!



SIDE VIEW

FRONT VIEW



STEP 17: INSTALL BOLT FOR SLED

BAG #2 pulleys, BAG #4 wood screwsMark center front of top beam,

- about .5" from top edge
- •With .5" drill bit, drill hole in marked spot
- Insert .5" carriage bolt into holeSecure with nut

STEP 18: INSTALL PULLEYS FOR CABLES

BAG #2 pulleys, BAG #4 wood screws

- •Use center beam mark from Step 17
- •Mark 1" to the left, 1" to the right
- Insert a screw through center of each pulley
- Screw into marked spots

STEP 19: INSTALL CHAIN HARDWARE

BAG #4 wood screws

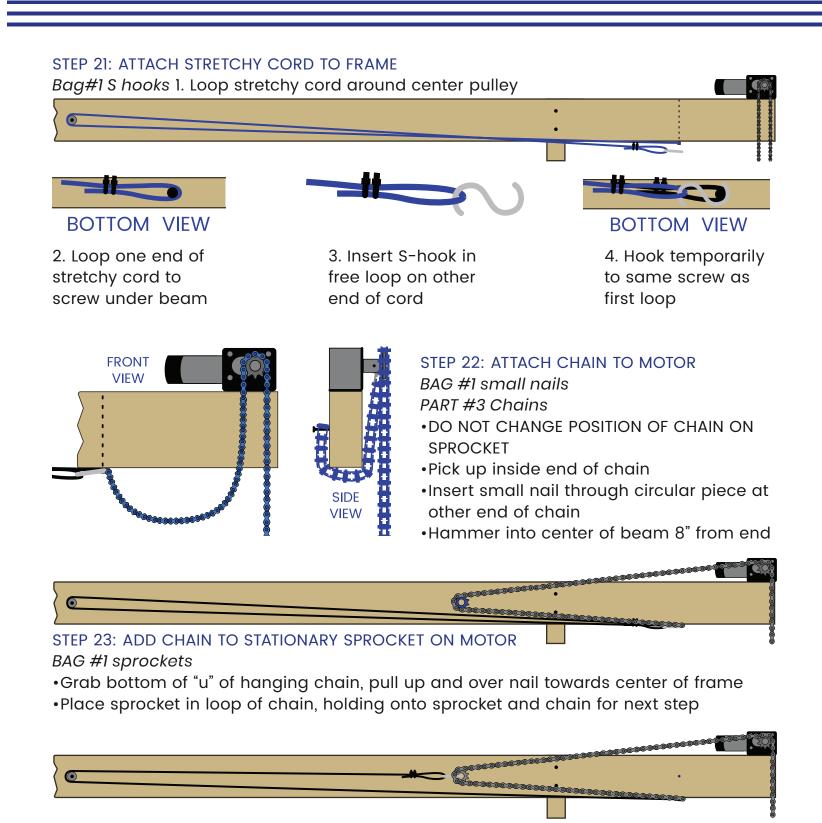
- •Mark 8" from end of top beam
- Insert wood screw in marked spot on underside of top beam
- •Leave it protruding about .25"

STEP 20: PREPARE STRETCHY CORDS

BAG #2 stretchy cord, zip ties

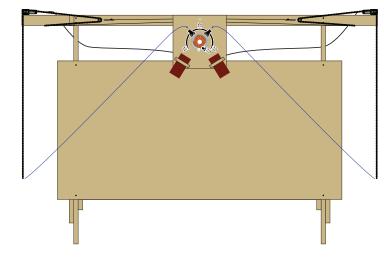
- •Fold over end of stretchy cord 3", fasten with zip ties
- •Trim ends of zip ties, repeat on all cord ends

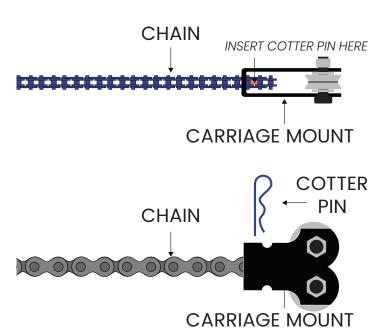


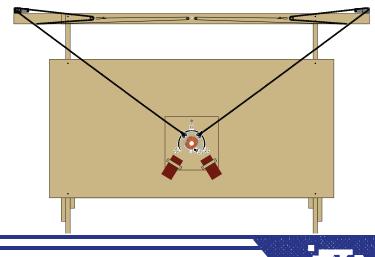


STEP 24: CONNECT CHAIN TO STRETCHY CORD

•Hold chain and sprocket with one hand, grab s-hook from bottom nail with other hand •Insert s-hook through center of sprocket







STEP 25: ATTACH CHAINS TO SLED

Carefully hang sled on bolt in top beam
This is optional, but very helpful, as it may be impossible for one person to balance the heavy sled assembly while pulling the chains through the carriage mounts
A step ladder is also helpful here

THIS IS A GOOD TIME TO MAKE SURE THAT YOU'VE LOADED A WORKING PIECE OF PLYWOOD ONTO YOU FRAME IF YOU DON'T WANT THE TEST CUTS TO BE MADE INTO YOUR BACKING PLYWOOD

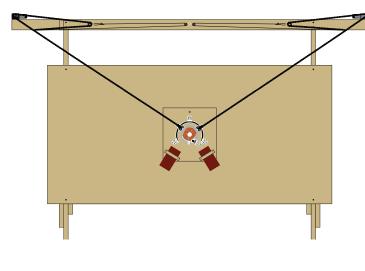
STEP 26: ATTACH CHAINS TO SLED

- •Grab dangling end of left chain, thread through hole in end of carriage mount
- Insert cottor pin to fasten chain
- •DO NOT USE OPEN LINK AT END OF CHAIN, GO BACK TO LAST FULL LINK
- •Repeat with right chain
- •Gently lift sled off bolt and allow weight of sled to hang from chains
- •Sled should rest against plywood now

STEP 27: ADJUSTING THE RING

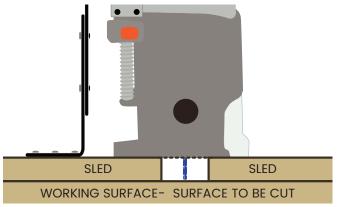
- •Router should hang vertically
- •If it's tilted, loosen bolts on L-brackets
- Move ring up or down on brackets until sled rests against plywood without tilting away





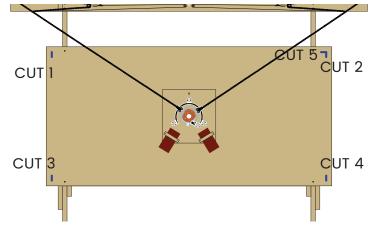
STEP 28: MOVE SLED TO CENTER

- •Return to Ground Control screen
- Click MOVE TO CENTER
- •Sled should move to center of plywood
- Click NEXT



STEP 29: SET HOME POSITION FOR Z-AXIS

- •If Z-Axis is installed, make sure ENABLE AUTOMATIC Z-AXIS is turned on
- •Click ADJUST Z-AXIS until router bit just touches surface of wood
- •If Z-Axis is not installed, adjust bit depth manually
- Click DEFINE ZERO



STEP 30: RUN TEST PATTERN

- •With router bit at zero, turn router on
- •Click CUT TEST PATTERN
- •The Maslow will now cut 5 shapes as shown

STAY CLEAR OF MACHINE WHILE PATTERN RUNS, IF CHAINS WRAP AROUND SPROCKETS OR ANYTHING ELSE HAPPENS, CLICK "STOP CUT" THEN TURN ROUTER OFF BEFORE TOUCHING CHAINS OR ANY OTHER MOVING PART

STEP 31: ENTER MEASUREMENTS

- •When pattern stops, follow onscreen instructions for measuring
- •Measuring distance and entering distance between cuts helps software dial in machine settings

STEP 32: REVIEW MEASUREMENTS

- •Same as STEP 7, if they look wonky, go back and redo steps related to numbers that are off
- •If they look good, jot them down
- •Click LOOKS GOOD

CALIBRATION COMPLETE!



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1.6 BUILDING THE FINAL SLED



TOOLS NEEDED:

Router, .25" router bit Screwdrivers Power Drill, .25" drill bit Sandpaper Socket wrench, various sizes 5/16 Allen Wrench Pencil Safety goggles Clamps (optional)

MATERIALS LIST:

- (1) 4x8 Plywood, .75" thick*
- (2) Bricks**
- (3) Size 10-32 Machine Screws If using MakerMade

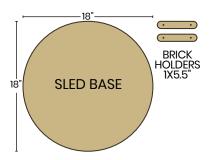
CUT LIST:

18x18" circle
 1x5.5" rectangles
 1x sing MakerMade
 metal brick holders or
 pre-made sled these
 pieces aren't needed

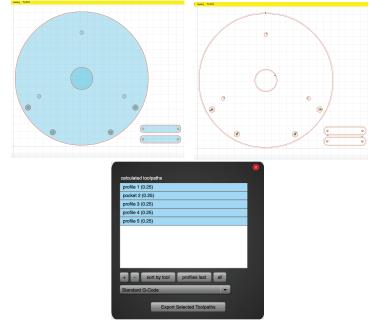
Difficulty Level

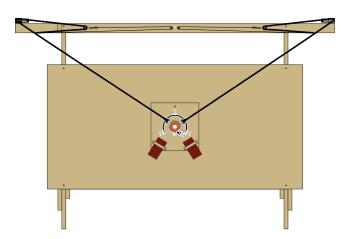
Precision Level

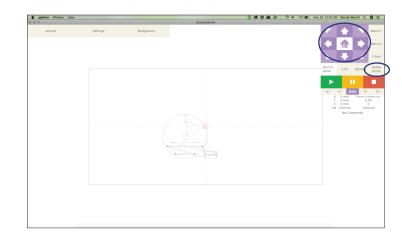
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*If you have scrap plywood on hand, it's not neccesary to buy a whole sheet of plywood **If using MakerMade metal brickholders bricks should be no more than 4.5" wide, you can re-use bricks from temporary sled







STEP 1 GENERATE G-CODE FOR SLED FILES

- •Download sledfiles.zip at Github/MaslowCNC/Mechanics/SVG Files
- •Unzip folder, locate svg file for sled- New Sled With Tool Paths.svg
- •Open makercam.com in a browser window
- •Click FILE->OPEN SVG File, select sled file, shapes should open up as shown on left
- •This file already has toolpaths set, so click CAM->CALCULATE ALL
- •Blue paths will appear, showing path of the router, green arrows indicate cut direction
- •Click CAM -> EXPORT GCODE
- •Click SELECT ALL to select all of the paths
- Click EXPORT SELECTED TOOLPATHS
- •Save to your desktop as .nc file

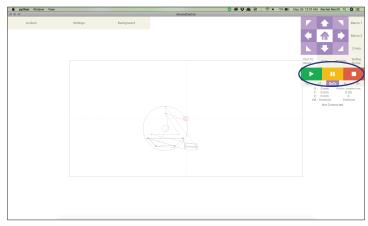
STEP 2 LOAD PLYWOOD ONTO MASLOW

- •Hang sled on bolt in center of top beam to keep it out of the way
- Load plywood onto frame
- •Remove sled from bolt and gently bring it to rest against plywood
- •A full sheet of plywood is not necessary, but may be easier to work with
- •This is a SECOND piece of plywood, in addition to the plywood used as backing for your frame

STEP 3 OPEN FILE IN GROUND CONTROL

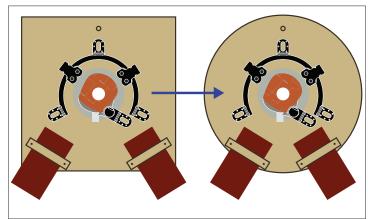
- •Click ACTIONS-> OPEN FILE
- If using scrap plywood it may be necessary to reposition the design
- •Move sled to desired position on plywood using arrow keys in top right corner of Ground Control
- •Sled will be cut to the left and down from beginning sled position
- •When router is in desired position, click DEFINE HOME





STEP 4 CUT THE SLED

- •Turn router on
- •In Ground Control, click green arrow button
- •Router will move through pattern
- •Do not leave Maslow unattended while work is in progress
- •If you need to leave for any reason, click yellow pause button, turn router off
- If shapes appear off, click red stop button and troubleshoot
- •If you began the cut, then stopped because it was off, when you start again you can move your sled to a new area of your plywood, then re-define HOME



STEP 5 ASSEMBLE FINAL SLED

- •Once pieces are cut, turn router off
- •Hang temporary sled on bolt in top beam
- •Remove chains from carriage mounts
- •Remove sled from bolt, set on workbench
- •Remove bolts holding bricks, router, and ring kit to temporary sled
- •Transfer everything to final sled, referencing instructions in Temporary Sled section if needed
- •Sled will slide across the work area more smoothly with a rounded edge
- •Use sandpaper to round the edge

STEP 6 ATTACH FINAL SLED TO FRAME

- •Hang final sled on bolt in top beam
- Attach chains to sled, referencing instructions in Temporary Sled section if needed
- •Remove sled from bolt and gently lay against work surface
- •You're now ready to begin making amazing projects!!

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FINAL SLED ASSEMBLY PG. 4