









Mapping







AsteRx-i S delivers 3D orientation and coasting functionality for continuous accurate positioning in difficult environments. This multi-frequency GNSS receiver is integrated with an SBG IMU (Internial Measurement Unit).

KEY FEATURES

- Reliable and accurate GNSS/INS positioning down to the cm level
- > 3D attitude heading, pitch and roll
- Ultralight, low power and compact
- AIM+ interference monitoring and mitigation system
- High-update rate, low-latency positioning and attitude
- Robust calibration for wide temperature ranges
- Single antenna for ease of integration and minimal weight
- Dual antenna for fast heading initialization

Reliability, availability and accuracy at their best

Septentrio's multi-constellation, multi-frequency, accurate and reliable RTK is further enhanced by a powerful GNSS/INS integration. Benefiting from a GNSS heading initialization, AsteRx-i S provides 3D attitude and positioning for the POI (point of interest).

The AsteRx-i S includes Septentrio's GNSS+ suite of positioning algorithms to convert difficult environments into good positioning. It also features AIM+ interference mitigation and monitoring system which can suppress the widest variety of interferers, from simple continuous narrowband signals to the most complex wideband and pulsed jammers.

SWaP matters

Designed around demanding requirements for size, weight and power consumption, the AsteRx-i S is ideal for small sized robots working in difficult environments. Consuming typically 1.5 W and having a unique total weight of 38 g the AsteRx-i S will ensure long lasting battery life and increased productivity. The versatility of design and range of connection interfaces extend the AsteRx-i S applicability to automation, logistics and mobile mapping.

Ease of integration

The AsteRx-i S integrates seamlessly into robotic and light UAV platforms. The IMU offers a simple, bolt-on, plug-and-play solution, designed for easy testing and integration. Septentrio's open interfaces and software tools (WebUI, RxTools) make the integration, configuration and control of the AsteRx-i S seem effortless.

FEATURES

GNSS technology

The AsteRx-i S supports tracking of the following signals:

- ▶ GPS: L1, L2
- ► GLONASS: L1, L2
- ► Galileo¹: E1, E5b
- ▶ BeiDou¹: B1, B2
- ► SBAS: EGNOS, WAAS, GAGAN, MSAS, SDCM (L1)
- OZSS: L1, L2

Septentrio's patented GNSS+ technologies

- ► **AIM+** unique anti-iamming and monitoring system against narrow and wideband interference
- ▶ **APME+** a posteriori multipath estimator for code and phase multipath mitigation
- ▶ **LOCK+** superior tracking robustness under heavy mechanical shocks or vibrations
- ▶ IONO+ advanced scintillation mitigation

RAIM (Receiver Autonomous Integrity Monitoring) RTK-INS (rover)1

Formats

Septentrio Binary Format (SBF), fully documented with sample parsing tools

RTCM v2.x and v3.x (MSM included)

CMR and CMR+ (CMR+ input only) NMEA 0183 v2.3, v3.01, v4.0 (output only)

Connectivity AsteRx-i S OEM board

- 4 Hi-speed serial ports (LVTTL)²
- 1 USB device port
- 1 PPS output 2
- 2 Event markers

SDIO interface for logging (covers µSD, SD, eMMC)

Outputs to drive external LEDs General purpose output

SUPPORTING COMPONENTS

Embedded Web UI with full control and monitoring functionality.

RxTools, a complete and intuitive GUI tool set for receiver control, monitoring, data analysis and

GNSS receiver communication SDK. Available for both Windows and Linux.

Integrated position accuracy 3,4

PERFORMANCE

Vertical Horizontal Standalone 1.2 m 1.9 m SRAS $0.6 \,\mathrm{m}$ 0.8 m **DGPS** 0.7 m $0.4 \, \text{m}$

RTK-INS 3,4,5

Horizontal accuracy 0.6 cm + 0.5 ppmVertical accuracy 1 cm + 1 ppm Initialisation 7 s

Integrated attitude accuracy 3,4,5

Non RTK mode RTK mode Heading, dual antenna8 0.3° 0.15° Heading, single antenna8 0.3° 0.2° 0.04° 0.02° Pitch/roll, dual antenna

INS velocity 3,4,5

Non RTK mode RTK mode Velocity 0.05 m/s 0.02 m/s

Position accuracy after outages

Vertical Horizontal Outage duration (s) error (RMS) error (RMS) 0.1 m 0.03 m 10 0.3 m 0.05 m 30 3.0 m 0.24 m

Attitude accuracy after outages

Outage	Heading	Pitch/Roll
duration (s)	error (RMS)	error (RMS)
5	0.23°	0.06°
10	0.25°	0.07°
30	0.3°	0.12°

IMU performance

Gyroscope performance

Input range ± 450°/s Bias in-run instability 7°/hr 0.15°/√hr Random walk / noise density Accelerometer performance

Input range

±16 g Bias in-run instability 0.014 mg 57 μg/√Hz Random walk / noise density

Maximum update rate

Integrated position

Latency <20 ms Post-processing: **GNSS** measurements 2 Hz IMU raw data 200 Hz

Time precision

PPS out 5 ns Event accuracy < 20 ns

Time to first fix

< 45 s Cold start 6 Warm start 7 < 20 s avg 1.2 s Re-acquisition

PHYSICAL AND ENVIRONMENTAL

AsteRx-i S OEM board

47.5 × 70 × 7.6 mm 1.87 × 2.75 × 0.29 in Weight 28 g / 0.987 oz $3.3 \text{ VDC} \pm 5\%$ Input voltage

Connectors

30 pins Hirose DF40 socket

60 pins Hirose DF40 socket for expanded connectivity

Size 26.8 x 18.8 x 9.5 mm 1.05 x 0.74 x 0.37 in Weight 10 g / 0.35 oz 4 -15 VDC Input voltage

Antenna

Antenna connectors $2 \times U.FL$ Antenna supply voltage 3 - 5.5 VDC 200 mA Maximum antenna current Antenna gain range 15-45 dB

System power consumption

AsteRx-i S board + IMU Dual antenna 15W Single antenna 1.3 W

Environment

-40° C to +85° C Operating temperature -40° F to +185° F Storage temperature -40° C to +85° C -40° F to +185° F Humidity 5% to 95% (non-condensing) Vibration MIL-STD-810G

¹ Optional feature

Certification

- ² One port/signal used by the IMU
- ³ Open-sky conditions
- 4 RMS levels
- ⁵ Baseline < 40 Km
- ⁶ No information available (no almanac, no approximate position)
- ⁷ Ephemeris and approximate position known
- 8 1 meter baseline

100 Hz



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