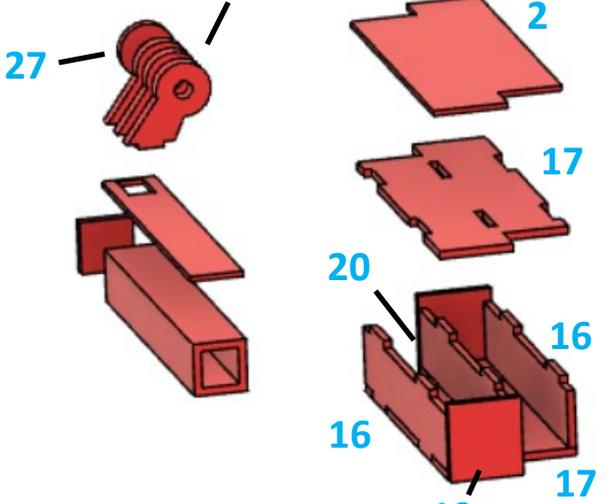
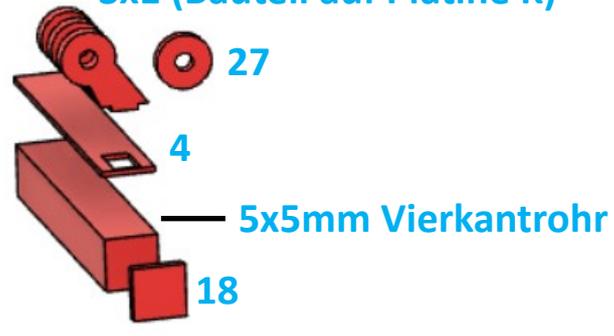


3x1 (Bauteil auf Platine K)

# Verschiebeinheit

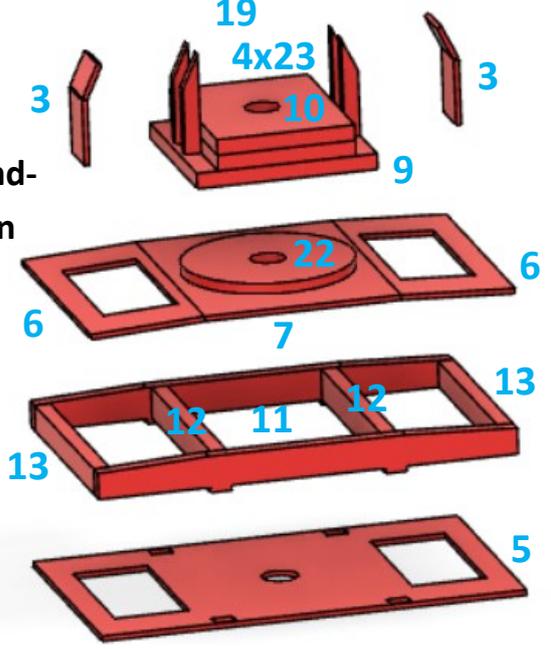


3x1 (Bauteil auf Platine K)

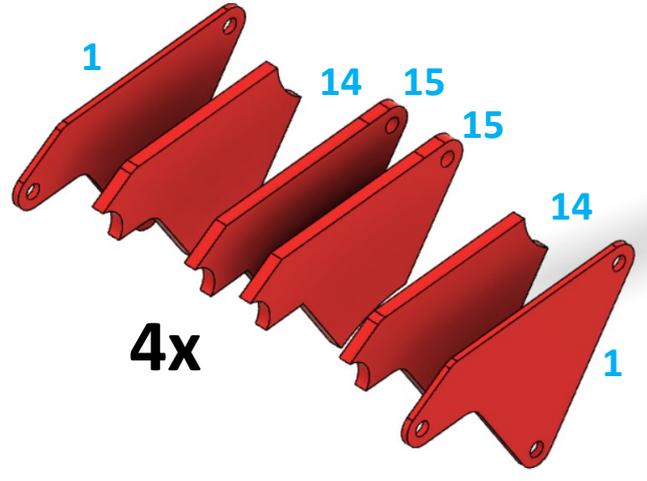


2x

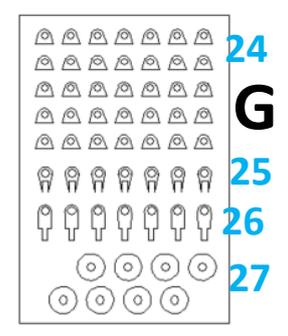
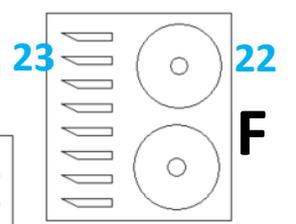
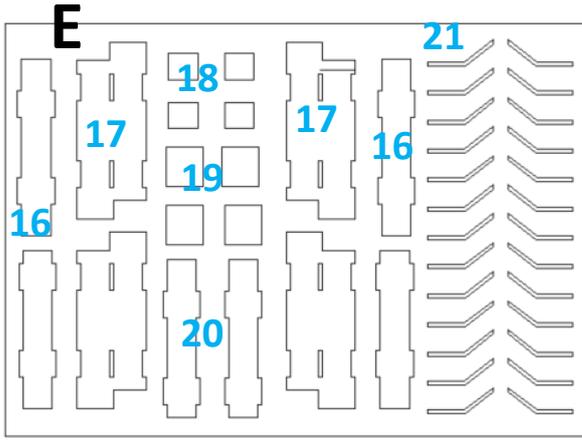
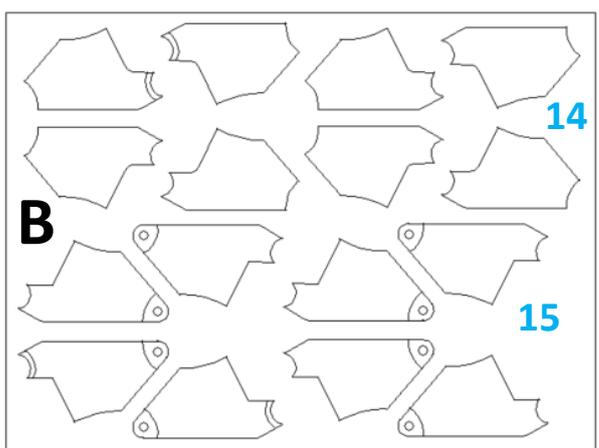
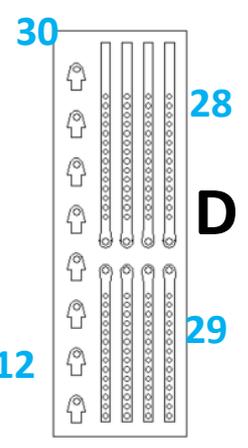
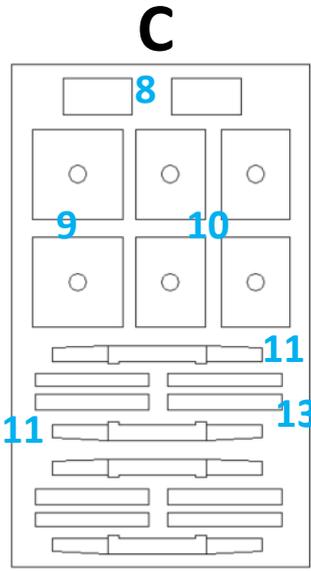
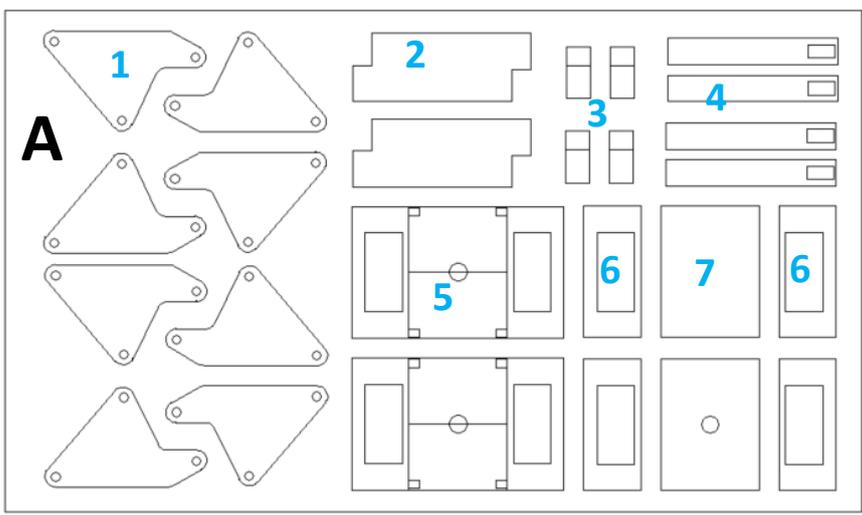
mit 3,2mm Rundprofil verbinden



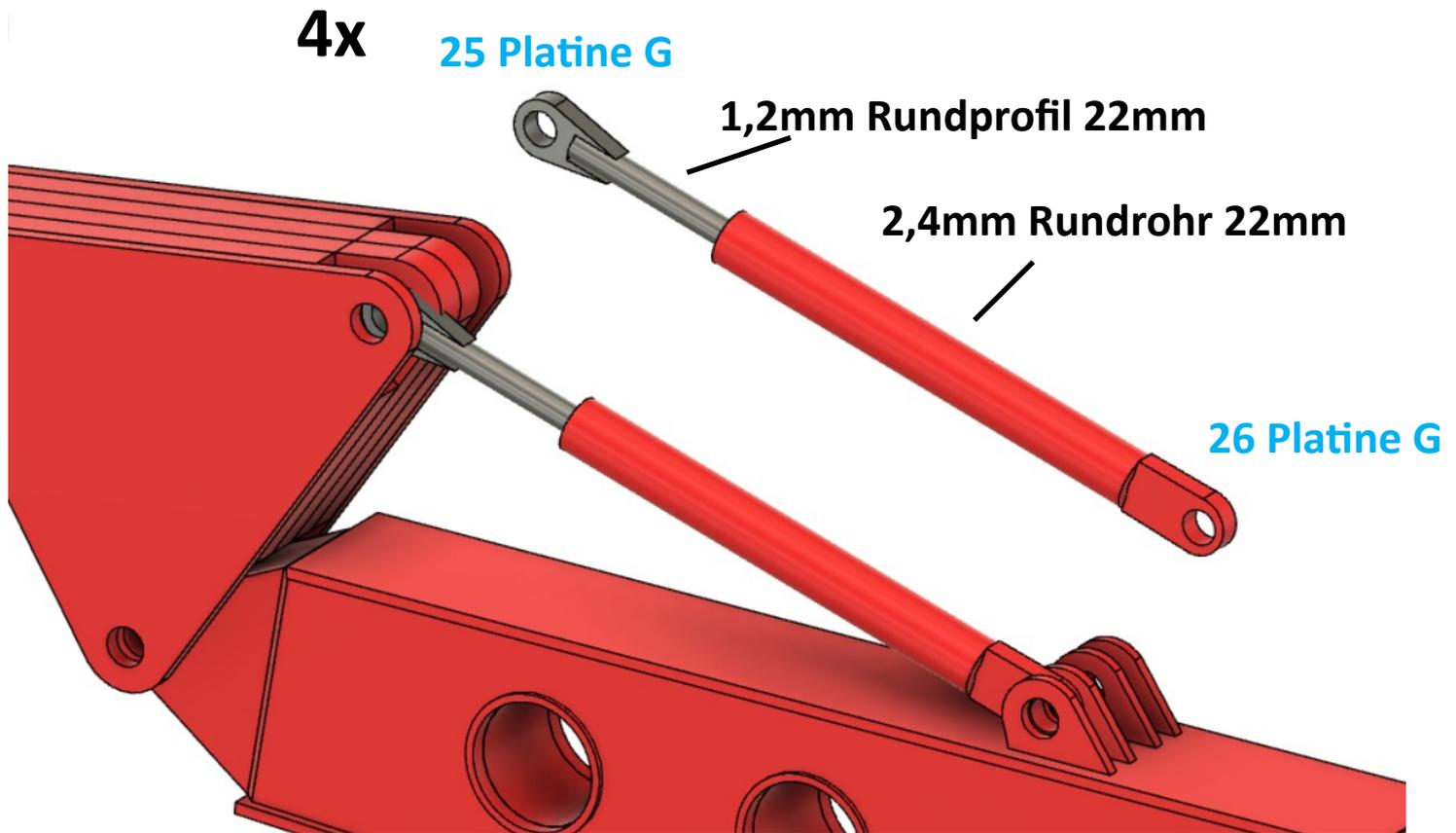
# Hebel



4x

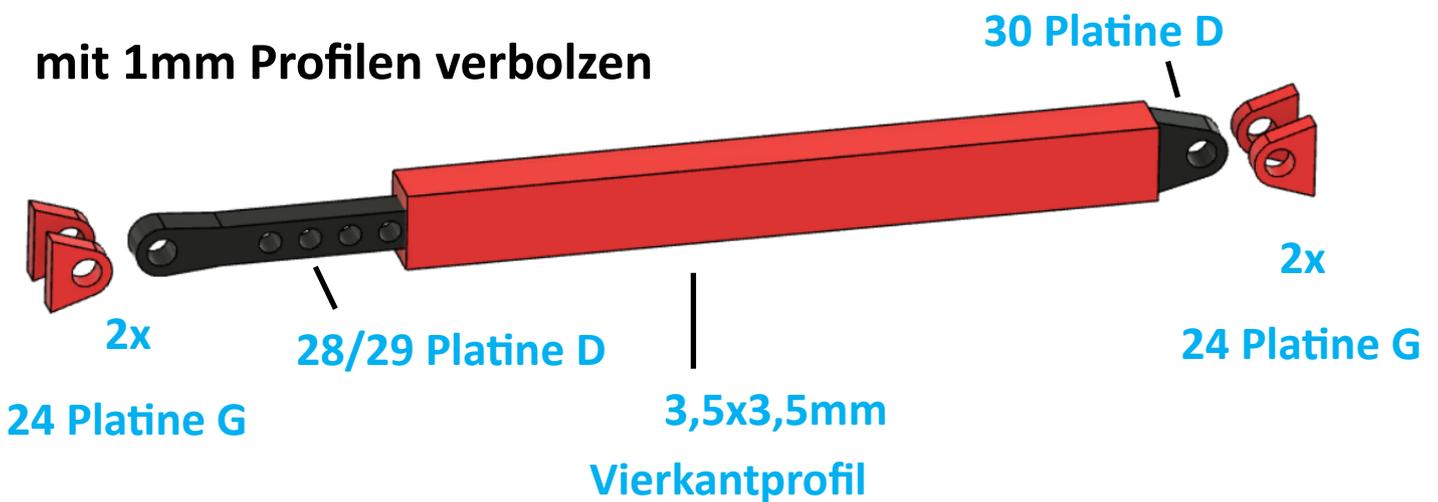


## Hydraulik mit 1,5mm Profilen verbolzen



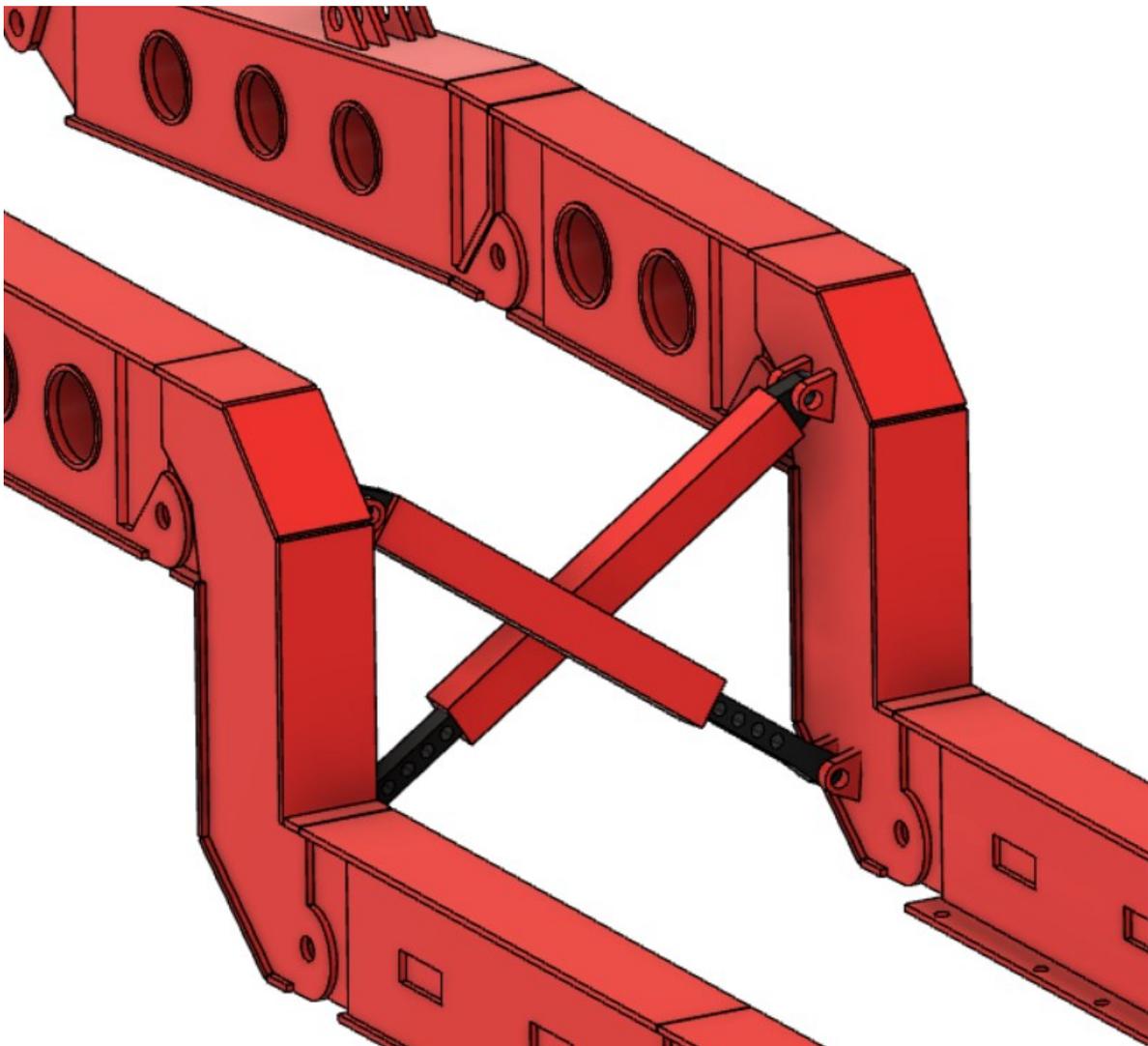
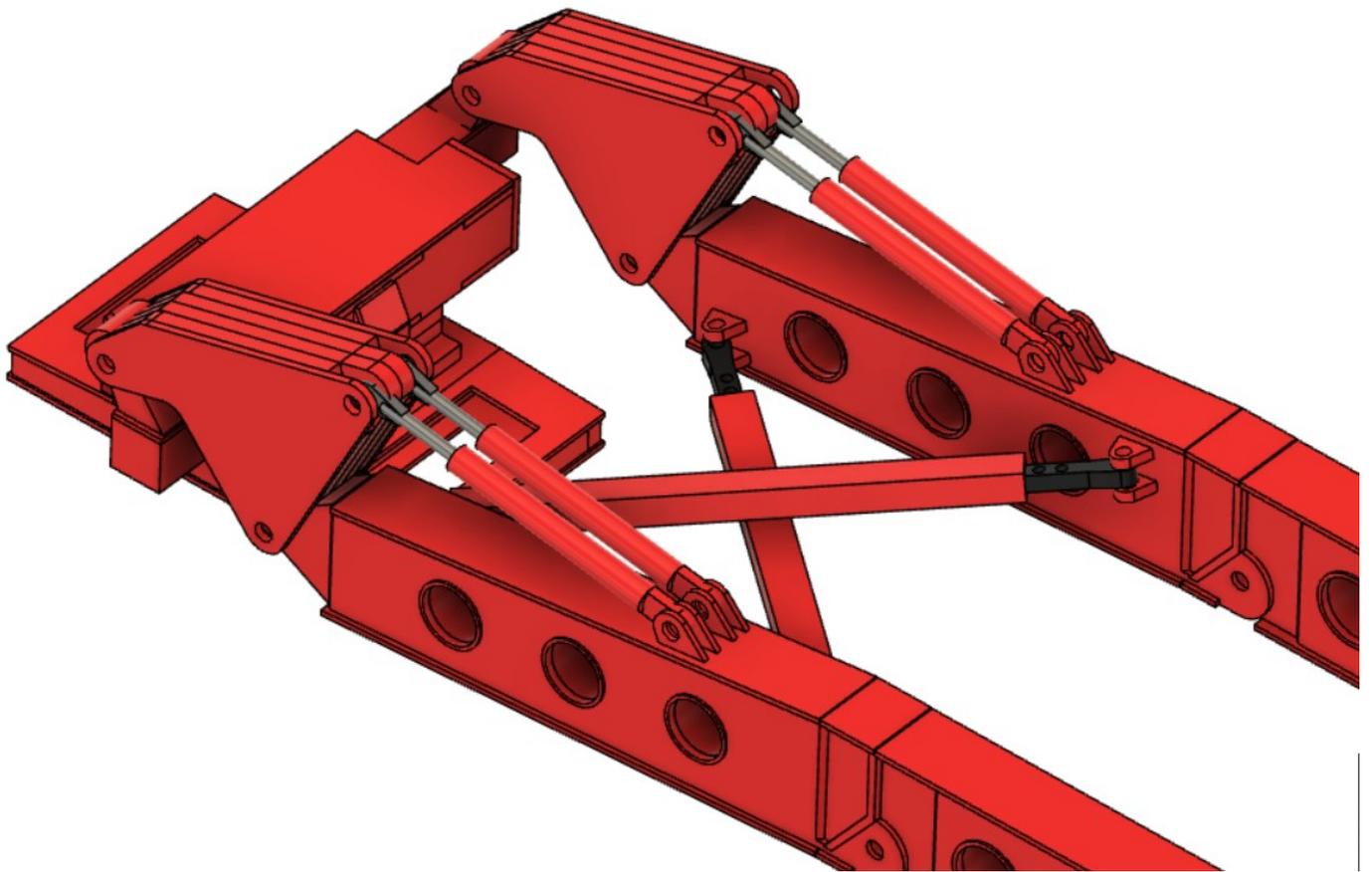
## Querverspannung

mit 1mm Profilen verbolzen



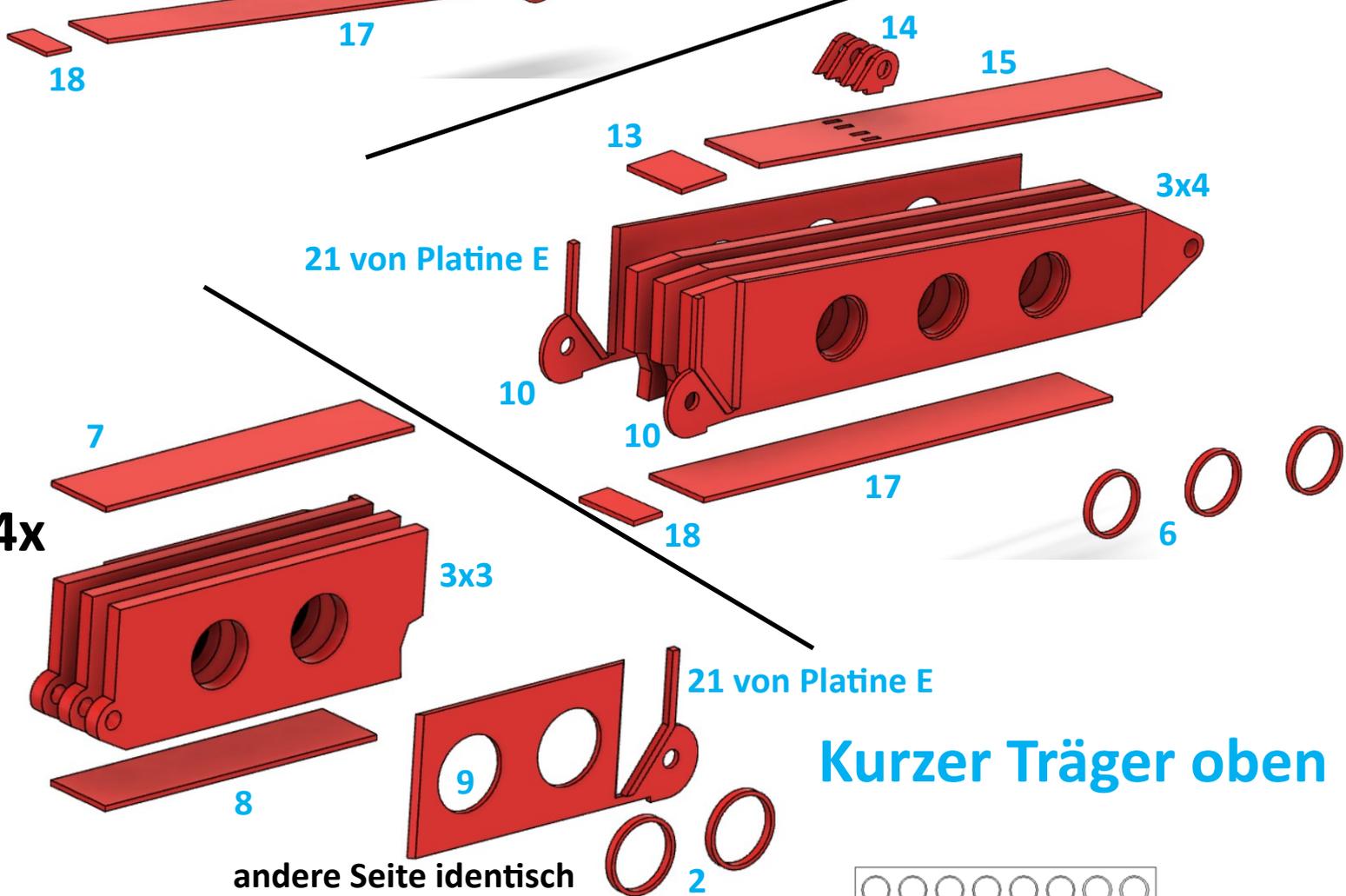
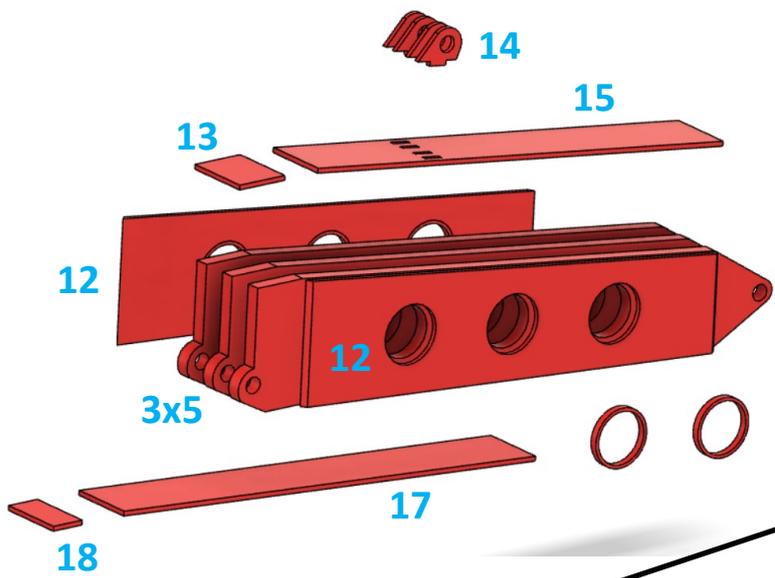
Die Querverspannung wird für EM165 4x und für EM166 8x benötigt (siehe nächste Seite)

Die Länge und Position lässt sich am besten anpassen, nachdem alle Träger montiert sind.

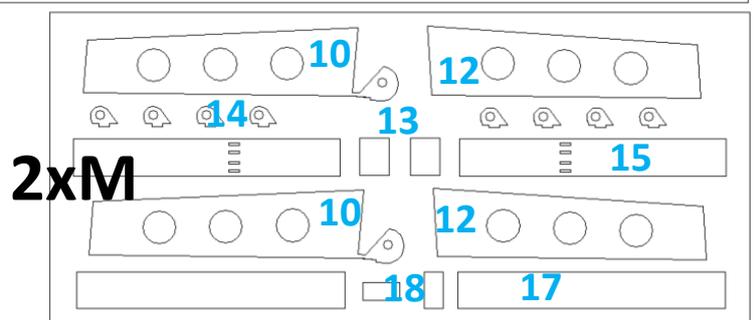
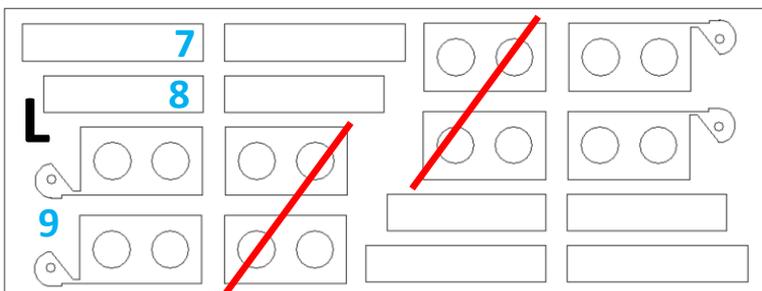
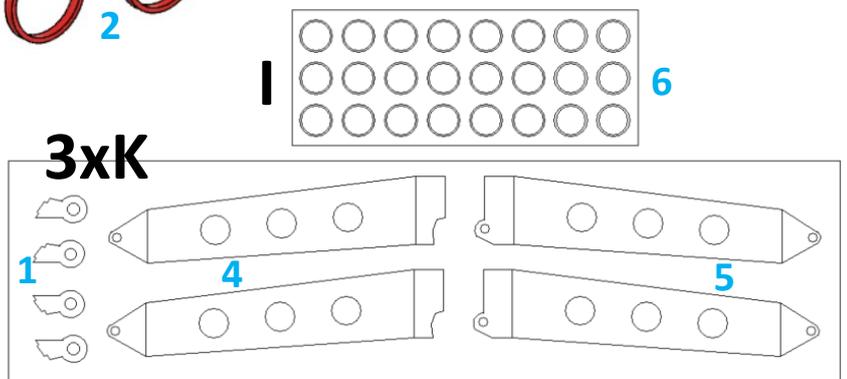
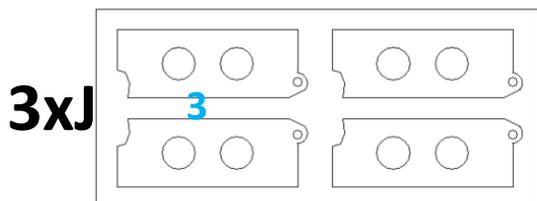


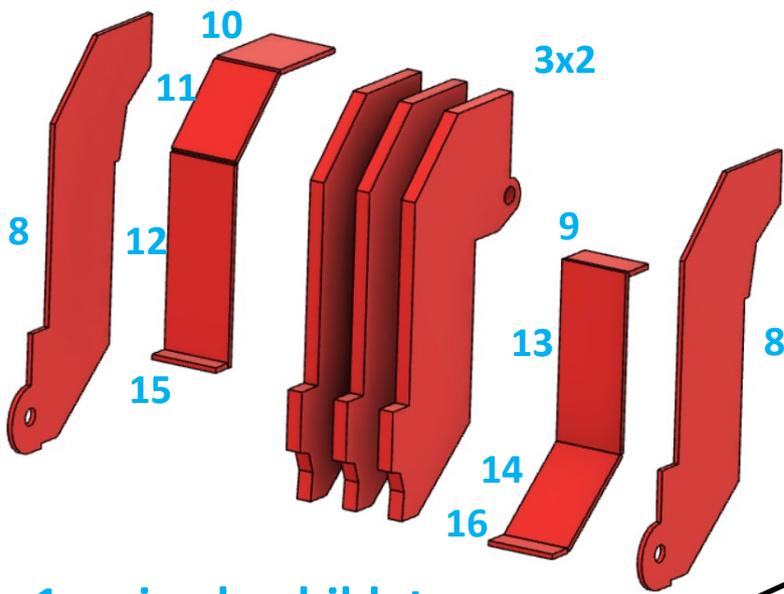
# 1. Träger

alle Träger mit 1,5mm  
Rundprofilen verbinden



## Kurzer Träger oben





# S Stücke

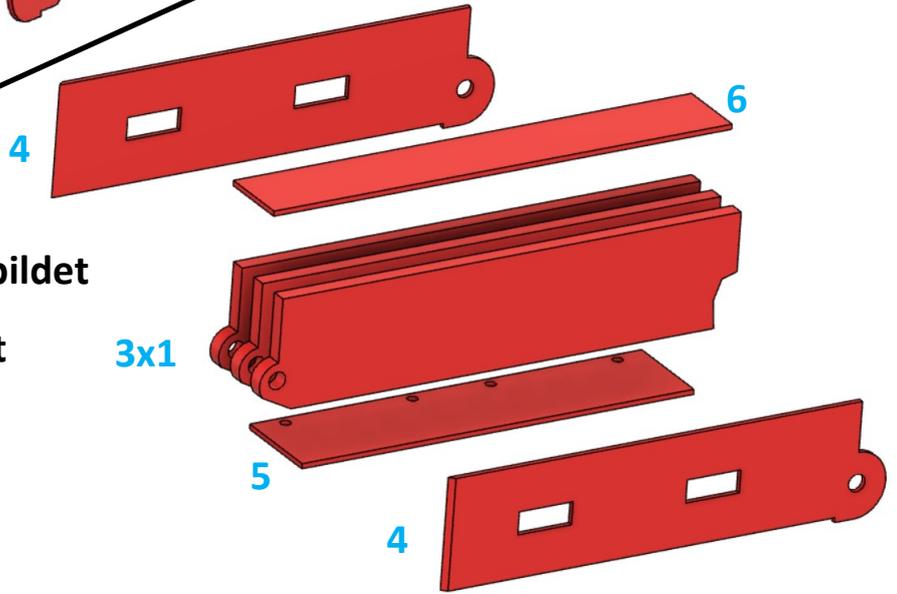
1x wie abgebildet

1x als Gegenstück

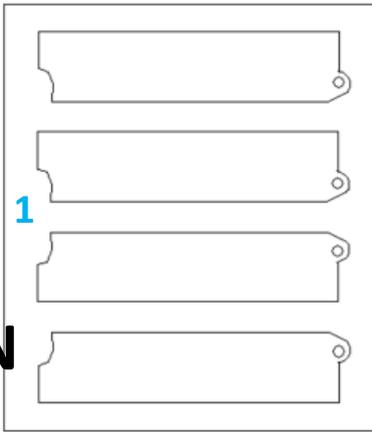
2x wie abgebildet

2x gespiegelt

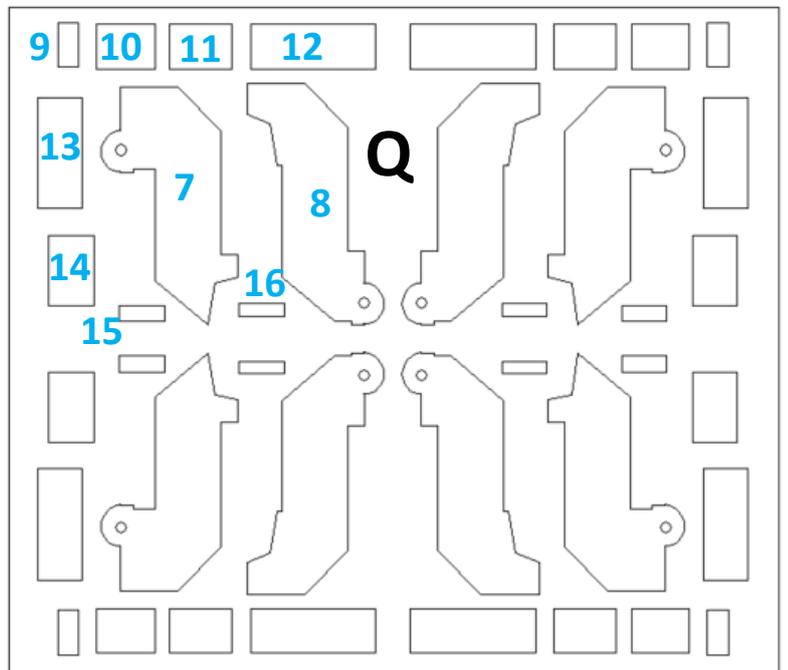
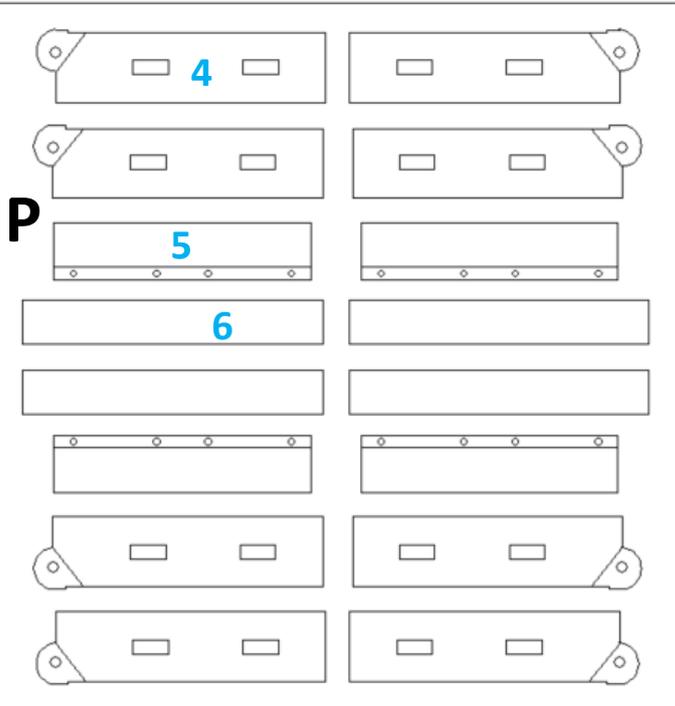
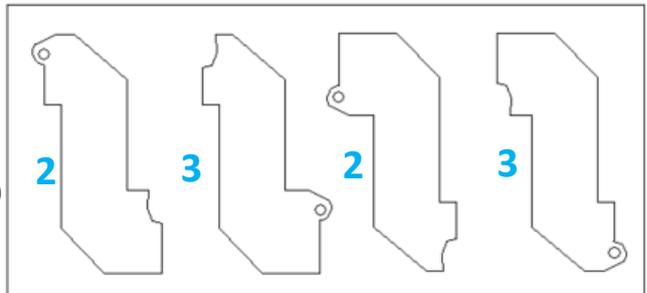
# Träger unten



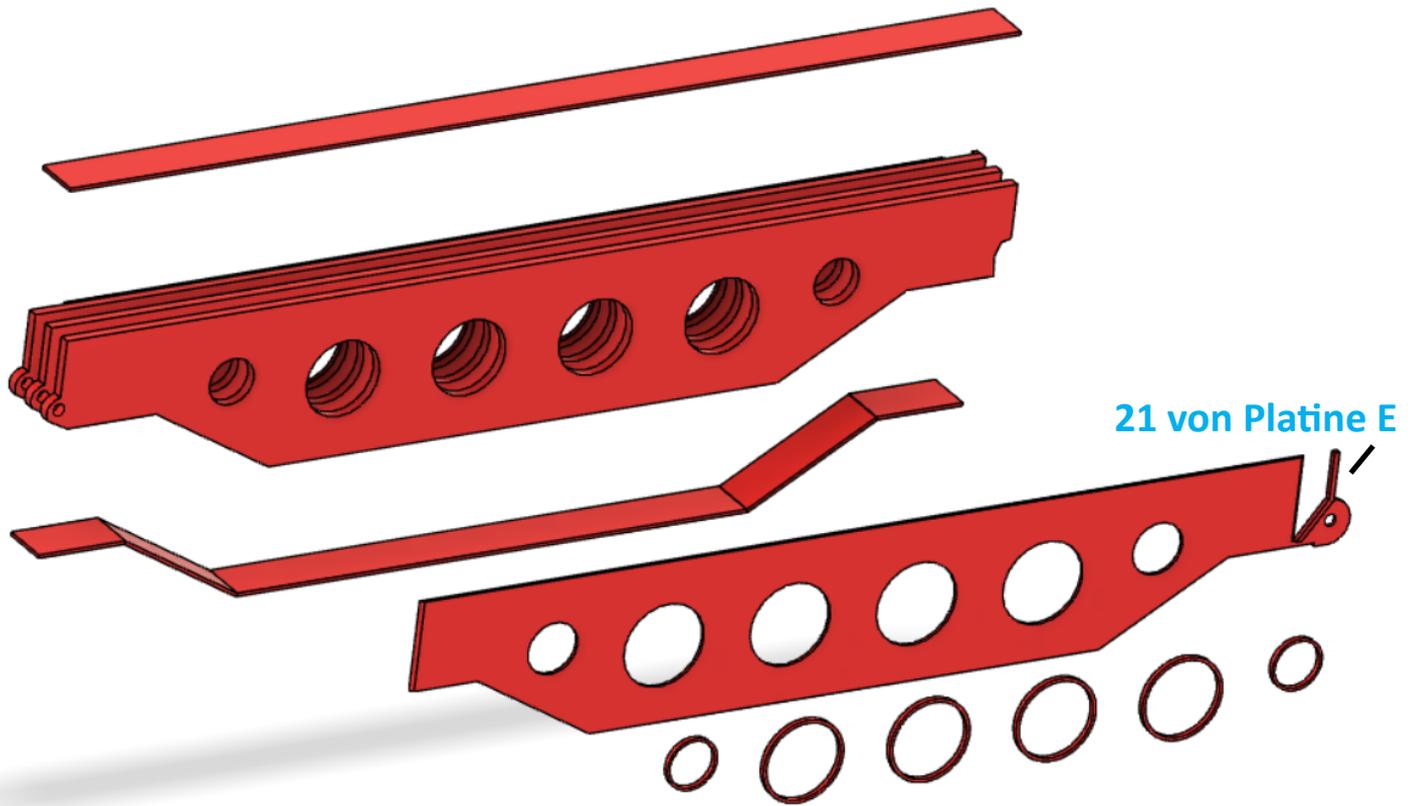
3xN



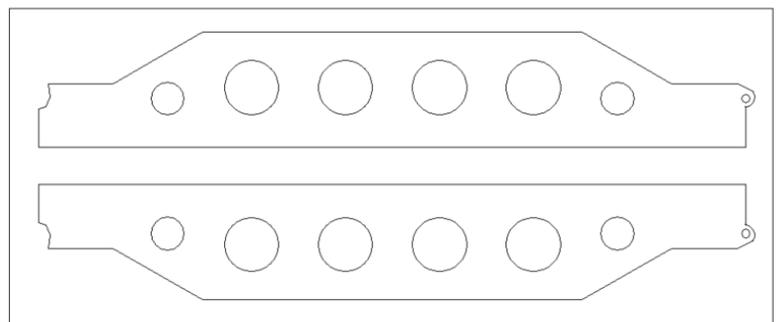
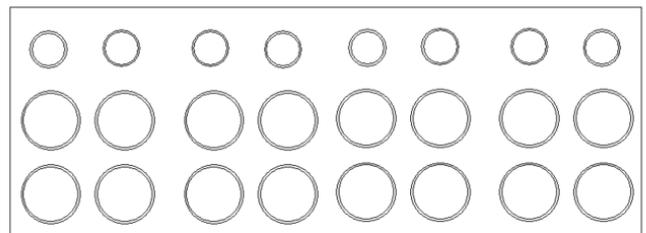
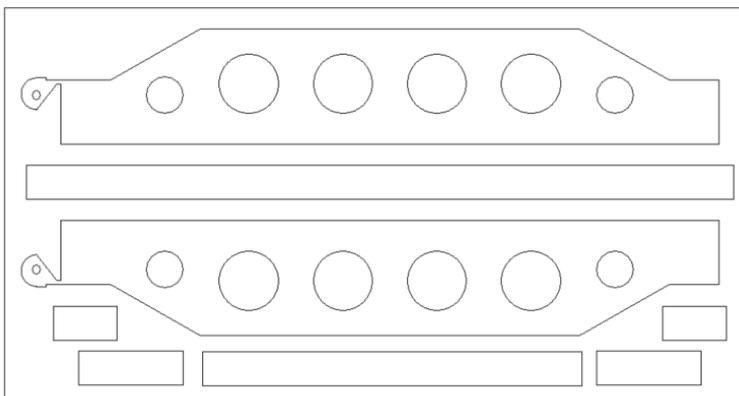
3xO



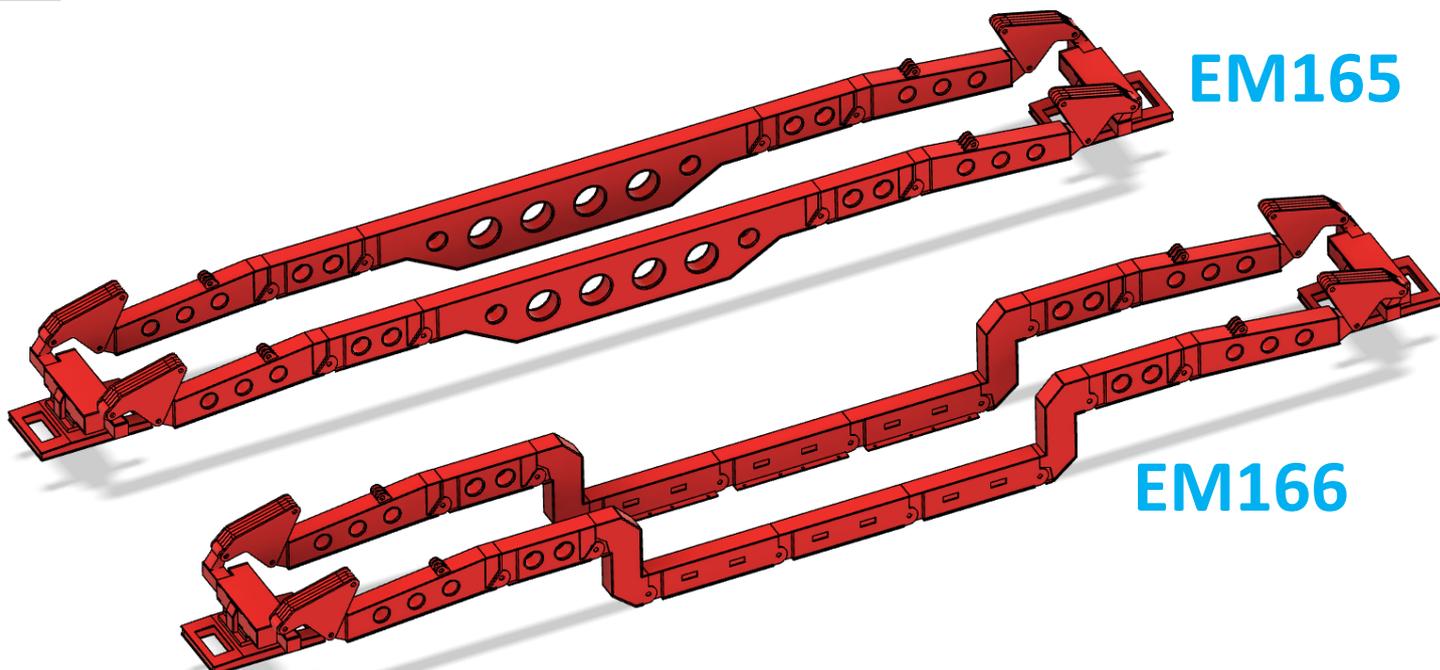
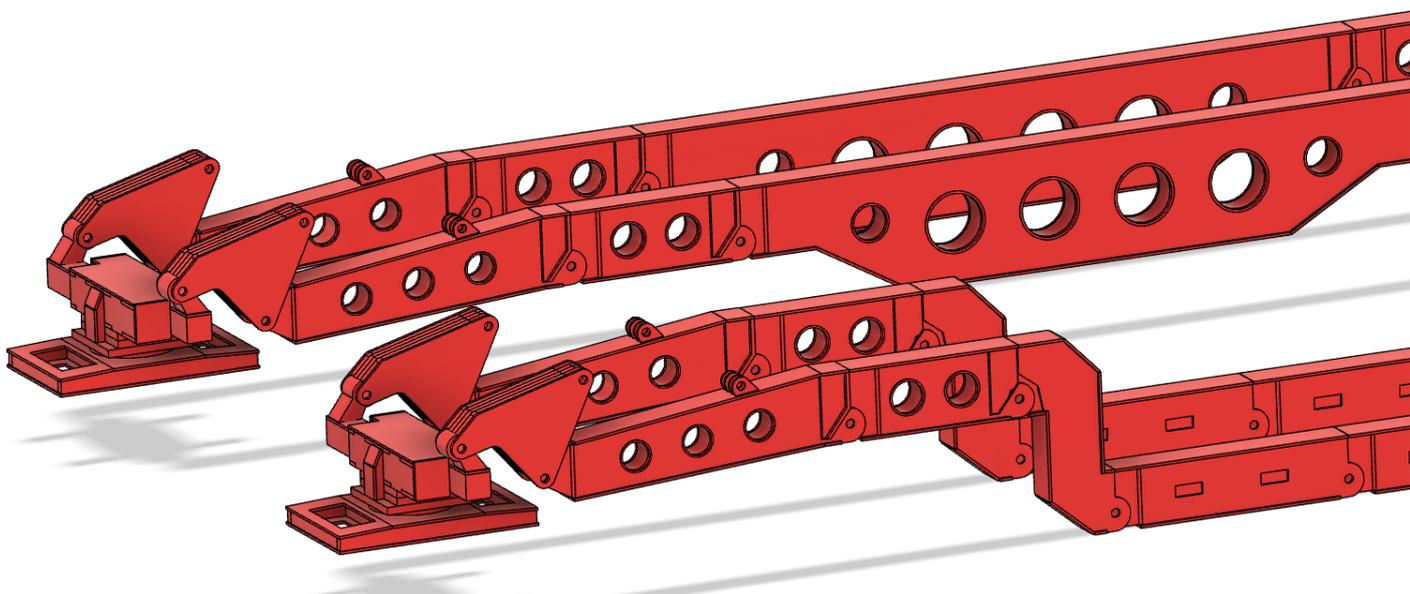
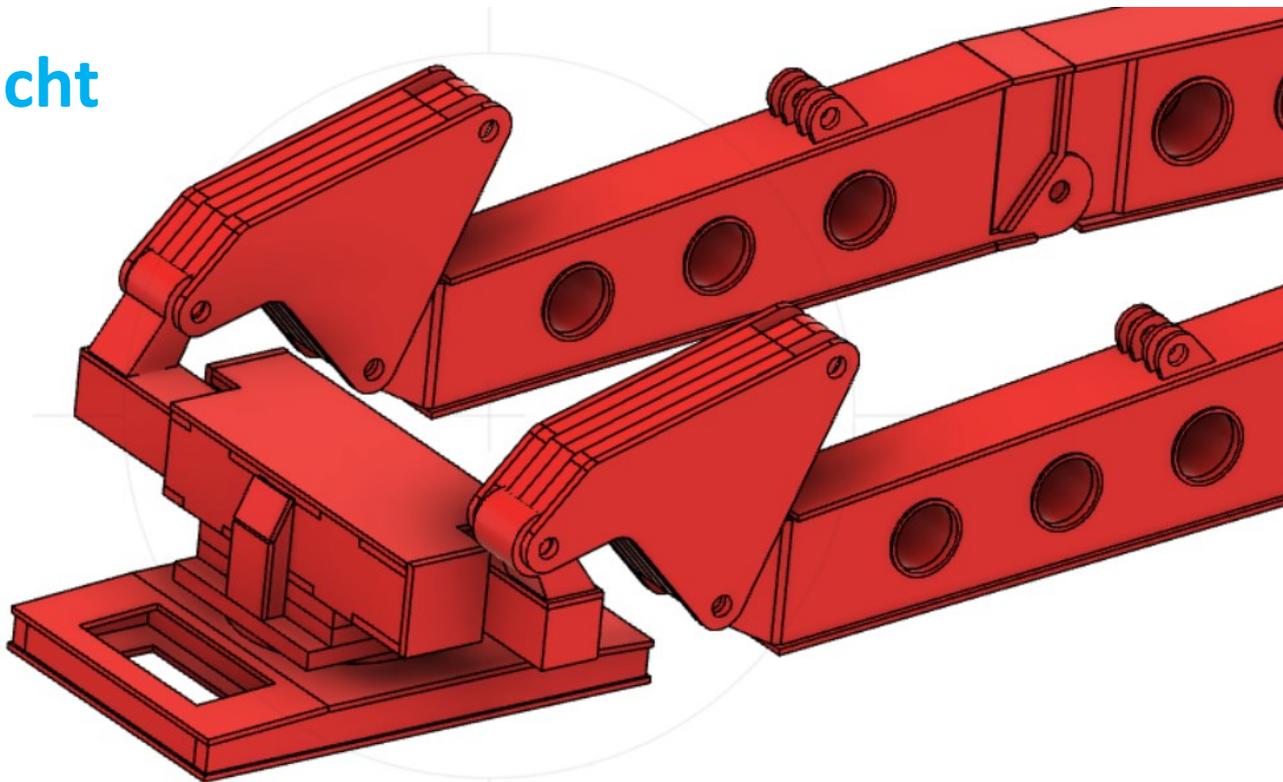
# Seitenträger



21 von Platine E



# Übersicht



EM165

EM166