

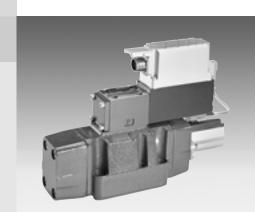
1/16

RE 29089/01.09 Replaces: 01.05

4/3-way servo solenoid directional control valves, pilot operated, with electrical position feedback and on-board electronics

Type 4WRLE 10...35, symbols E./W.

Sizes (NG) 10, 16, 25, 27, 35 Unit series 3X Maximum working pressure P, A, B 350 bar (NG27: 280 bar) Nominal flow rate 50...1100 l/min ($\Delta p = 10$ bar)



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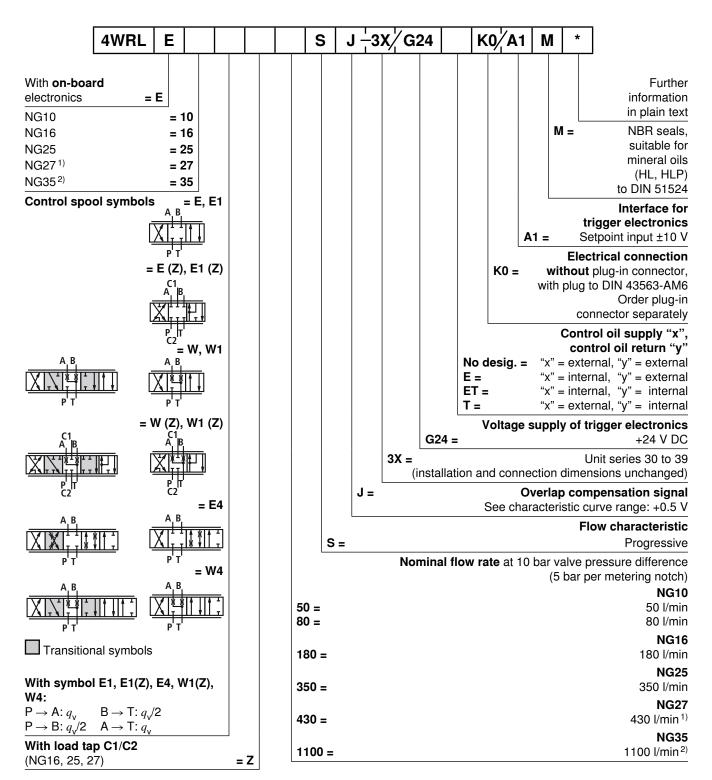
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For information regarding the available spare parts see: www.boschrexroth.com/spc

Features

- Pilot operated 4/3-way servo solenoid directional control valves NG10 to NG35, with approx. 20% overlap
- Pilot valve NG6, with control piston and sleeve in servo quality, actuated on one side, 4/4 fail-safe position when switched off
- Control solenoid with electrical position feedback and on-board electronics (OBE), calibrated at the factory
- Main stage with position feedback
- Electronically calibrated and compensated overlap
- Spool with linear travel, with anti-rotation element
- Flow characteristic
 - S = Progressive
 - NG16, 25 and 27 with load tap C1/C2
- For subplate attachment, mounting hole configuration NG10 to ISO 4401-05-05-0-05, NG16 to ISO 4401-07-07-0-05, NG25/27 to ISO 4401-08-08-0-05 and NG35 to ISO 4401-10-09-0-05
- Subplates as per Technical Data Sheet, NG10 RE 45055, NG16 RE 45057, NG25/27 RE 45059 and NG35 RE 45060 (order separately)
- Plug-in connectors to DIN 43563-AM6,
 see Technical Data Sheet RE 08008 (order separately)

Ordering data



 $^{^{1)}}$ NG27 is a high-flow version of NG25, ports P, A, B and T have Ø 32 mm in the main stage. Contrary to standard ISO 4401-08-08-0-05, ports P, A, B and T may be drilled to max. Ø 30 mm in the control block. These valves therefore offer higher flow rates $Q_{\rm A}$: $Q_{\rm B}$

 $^{^{2)}}$ NG35 is a high-flow version of NG32, ports P, A, B and T have \varnothing 50 mm in the main stage. Contrary to standard ISO 4401-10-09-0-05, ports P, A, B and T may be drilled to max. \varnothing 48 mm in the control block. These valves therefore offer higher flow rates $Q_{\rm A}$: $Q_{\rm B}$

Accessories, not included in delivery

Fastening bolts	NG10	4 x ISO 4762-M6 x 40-10.9-	N67F82170	2 910 151 209
	NG16	2 x ISO 4762-M6 x 45-10.9-N67F82170		2 910 151 211
		4 x ISO 4762-M10 x 50-10.9	2 910 151 301	
	NG25/27 6 x ISO 4762-M12 x 60-10.9-N67F821 70		-N67F821 70	2 910 151 354
	NG35	6 x ISO 4762-M20 x 90-10.9	-N67F821 70	2 910 151 532
0000	Plug-in connectors 6P+PE, also see RE 08008		KS	1 834 482 022
			KS	1 834 482 026
			MS	1 834 482 023
			MS	1 834 482 024
			KS 90°	1 834 484 252

Testing and service equipment

- Test box type VT-PE-TB3, see RE 30065

- Test adapter 6P+PE type VT-PA-2, see RE 30068

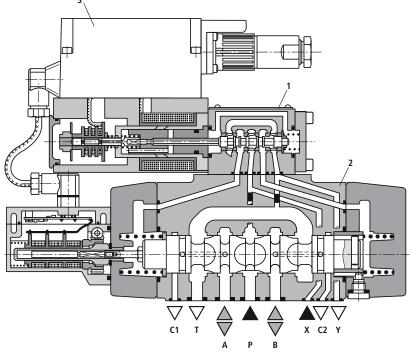
Function, sectional diagram

Construction

The valve consists of three main assemblies:

 Pilot valve (1) with control spool and sleeve, return springs, control solenoid and inductive position transducer

- Main stage (2) with centering springs and position feedback
- On-board trigger electronics (3)



Functional description

When the control solenoid is not actuated, the control spool is held by springs in the fail-safe position, and the main stage spool remains in its spring-centered mid position.

In the on-board electronics, the pre-defined setpoint is compared with the actual value for the position of the main stage control spool. In the event of an error signal, the control solenoid is actuated, and the pilot spool is moved as the magnetic force changes. The flow released through the control cross-sections causes the main control spool to move. The spool stroke is controlled proportionately to the setpoint of 0.5...10 V between 20...100%. If the input setpoint is $<\!\pm0.5$ V, the control spool is held in the spring-centered, overlapped mid position.

The control oil is conveyed to the pilot valve either internally via port P or externally via port X. The oil returns to the tank internally via port T or externally via port Y.

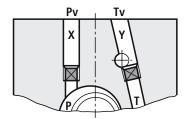
Power failure

In the event of a power failure or an open circuit, the on-board electronics cut off the electricity to the control solenoid and the pilot spool moves to the fail-safe position, relieving the control oil chambers of the main stage. The main stage control spool is held by springs in mid position.

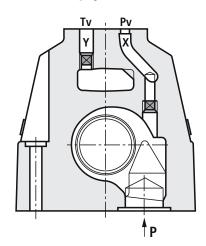
Control oil supply

The pilot valve can be supplied both via ports X and Y (externally) and via the main flow channels P and T.

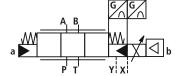
NG10, 25, 27, 35



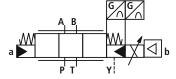
NG16



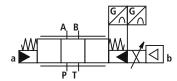
Type...-3X...



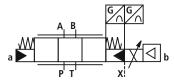
Type...-3X...E...



Type...-3X...ET...



Type...-3X...T...



No designation = E =

ET =

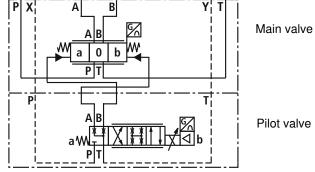
T =

"x" = external
"x" = internal
"x" = internal
"x" = external

"y" = external
"y" = external
"y" = internal
"y" = internal

(external control oil inlet and outlet)

Symbol in detail



Technical data

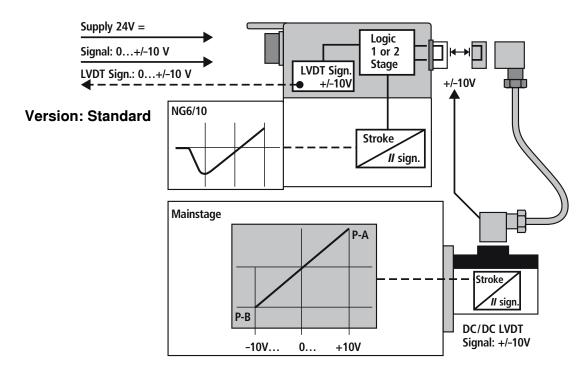
General							
Construction			e, pilot operated				
Actuation		Servo solenoid directional control valve NG6, with position controller for pilot valve and main stage					
Type of mounting		Subplate, mounting hole configuration NG1035 to ISO 4401					
Installation position		Optional					
Ambient temperature range	°C	-20+50					
Weight	kg	NG10 8.7	NG16 10.6	NG25 18.4	NG27 18.4	NG35 81	
Vibration resistance, test con-					NG21 10.4	11033 01	
VIDIALION TESISLANCE, LEST CON	uition	iviax. 20g, Silar	ken in 3 dimensio	JIIS (24 II)			
Hydraulic (measured w	ith HLP 46						
Pressure fluid		Hydraulic oil to DIN 51524535, other fluids after prior consultation					
Viscosity range recommended mm ² /s		20100					
max. permitted mm ² /s		10800					
Pressure fluid temperature ra	nge °C	− 20+70					
Maximum permissible degree)						
of contamination of pressure	fluid						
Purity class to ISO 4406 (c)		Class 18/16/13 ¹⁾					
Flow direction		See symbol					
Nominal flow at		NG10	NG16	NG25	NG27	NG35	
$\Delta p = 5$ bar per notch ²⁾	l/min	50, 80	180	350	430	1100	
Max. Ports P, A, B							
working (external control oil	inlet) bar	350	350	350	280	350	
pressure Ports P, A, B, X	bar	280					
Ports T, Y	bar	250					
Min. control oil pressure							
in "pilot stage"	bar			8			
$Q_{\sf max}$	I/min	170	450	900	1000	3500	
$Q_{\rm N}$ pilot valve (inlet)							
$\Delta p = 35 \text{ bar}$	l/min	2	4	12	12	40	
Leakage of pilot valve							
at X = 100 bar	cm³/min	<150	<180	<350	<500	<1100	
Leakage of main stage							
control spool symbols "E"							
at P = 100 bar	l/min	<0.25	<0.4	<0.6	<0.6	<1.1	
Static/Dynamic							
		10 000/ 1				\ _ \ /	
Overlap in mid position			oool stroke, elec		1		
Spool stroke, main stage	± mm	4	7	10	10	12,5	
Control oil volume	•						
of main stage 100%	cm ³	1.1	4.3	11.3	11.3	41.5	
Control oil requirement 010							
(at X = 100 bar)	I/min	2.2	4.7	11.7	11.7	15.6	
Hysteresis	%	<0.1, scarcely i	neasurable				
Manufacturing tolerance	%	$<\pm 5 (Q_{\rm max})$	I	I			
Response time for 0100%,							
(at X = 100 bar)	ms	<40	<80	<80	<80	<130	
Response time for 0100%,		450	050	050	050		
(at X = 10 bar)	ms	<150	<250	<250	<250	<500	
Switch-off behavior			switch-off (pilot v	,			
The			ves to spring-cer	ntered overlappe	ea mia position		
Thermal drift		$<1\%$ at $\Delta T = 40$ °C					
Calibration			1%, see flow cu	rve			
Electromagnetic compatibility		EN 61000-6-2:					
		EN 61000-6-3:	2002-08				

¹⁾ The purity classes stated for the components must be complied with in hydraulic systems. Effective filtration prevents problems and also extends the service life of components. For a selection of filters, see Technical Data Sheets RE 50070, RE 50076 and RE 50081.

 $^{^{2)}}$ Flow rate at a different Δp $~Q_{\rm x}$ = $Q_{\rm nom} \cdot \sqrt{\frac{\Delta p_{\rm x}}{5}}$

Technical data

Electric pilot valve NG6, trigger electronics integrated in the valve				
Cyclic duration factor %	100 ED			
Degree of protection	IP 65 to DIN 40050 and IEC 14434/5			
Connection	Plug-in connector 6P+PE, DIN 43563			
Power supply Terminal A: Terminal B: 0 V	24 V DC _{nom} min. 21 V DC/max. 40 V DC Ripple max. 2 V DC			
Power consumption	Solenoid 45 mm = 40 VA max.			
External fuse	2,5 A _F			
Input, "Standard" version Terminal D: $U_{\rm E}$ Terminal E:	Differential amplifier, $R_{\rm i}$ = 100 k Ω 0±10 V 0 V			
Max. differential input voltage at 0 V	$ \begin{bmatrix} D \to B \\ E \to B \end{bmatrix} $ max. 18 V DC			
Test signal, "Standard" version Terminal F: $U_{\rm Test}$ Terminal C:	LVDT 0±10 V Reference 0 V			
Protective conductor and screen	See pin assignment			
Recommended cable	See pin assignment up to 20 m 7 x 0.75 mm ² up to 40 m 7 x 1 mm ²			
Calibration	Overlap and P-A at +8 V, calibrated at the factory, see valve characteristic curve			



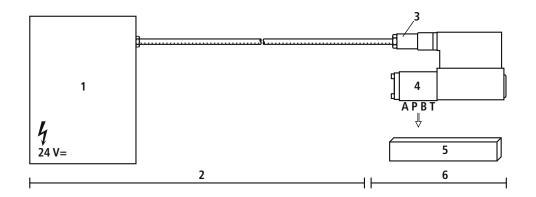
Important

Pilot operated 4/3-way servo solenoid directional control valves with positive overlap perform their function in open or closed-loop-controlled axes and have approx. 20 % overlap when switched off.

This condition does not constitute an active fail-safe position. For this reason, many applications require the use of "external check valves" or certain sandwich-mounted valves, which must be taken into account during the On/Off switching sequence.

Connection

For electrical data, see page 6



- 1 Control
- 2 Provided by customer
- 3 Plug-in connector
- 4 Valve
- 5 Connecting surface
- 6 Provided by Rexroth

Technical notes on the cable

Version: - Multi-wire cable

> - Extra-finely stranded wire to VDE 0295, Class 6

- Protective conductor, green/yellow

- Cu braided screen

Types: - e.g. Ölflex-FD 855 CP

(from Lappkabel company)

No. of wires: – Determined by type of valve,

plug type and signal assignment

- 0.75 mm² to 20 m length Cable Ø:

- 1.0 mm² to 40 m length

- 9.4...11.8 mm - Pg11 Outside Ø:

- 12.7...13.5 mm - Pg16

Important

Voltage supply 24 V $\mathrm{DC}_{\mathrm{nom.}}$, if voltage drops below 18 V DC, rapid shutdown resembling

"Enable OFF" takes place internally.

In addition, with the "mA signal" version:

 $I_{D-E} \ge 3 \,\text{mA} - \text{valve is active}$

 $I_{D-E} \le 2 \text{ mA} - \text{valve is deactivated.}$

Electrical signals emitted via the trigger electronics (e.g. actual values) must not be used to shut down safety-

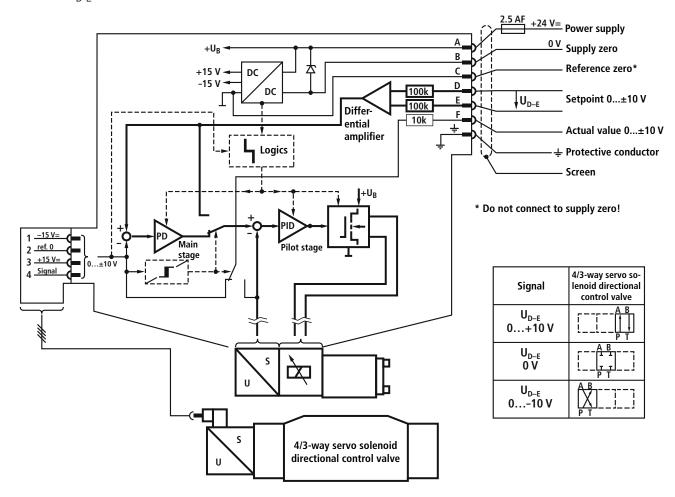
relevant machine functions! (See European Standard, "Technical Safety Requirements for Fluid-Powered Systems

and Components - Hydraulics", EN 982.)

On-board electronics

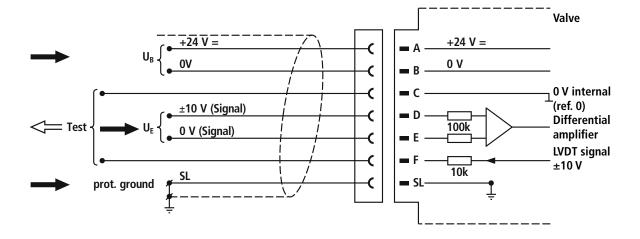
Block diagram/pin assignment

Version A1: $U_{\mathrm{D-E}}$ ±10 V



Pin assignment 6P+PE

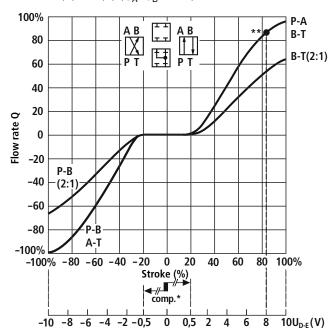
Version A1: $U_{\rm D-E}$ ±10 V ($R_{\rm i}$ = 100 k Ω)



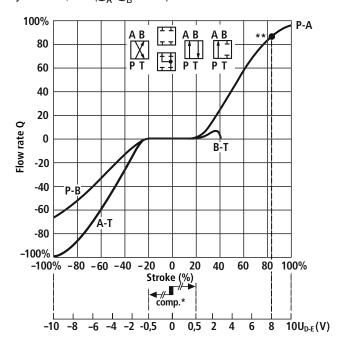
Characteristic curves (measured with HLP 46, $\vartheta_{oil} = 40 \, ^{\circ}\text{C} \pm 5 \, ^{\circ}\text{C}$)

Flow rate - signal function $Q = f(U_{\mathsf{D-E}})$

$$\begin{aligned} \text{Symbol E(Z), W(Z) } (Q_{\text{A}} \colon & Q_{\text{B}} = 1 \colon 1) \\ & \text{E1(Z), W1(Z) } (Q_{\text{A}} \colon & Q_{\text{B}} = 2 \colon 1) \end{aligned}$$

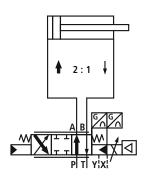


Symbol E4, W4 $(Q_A: Q_B = 2:1)$



Control spool with asymmetric metering notches

Control spools with asymmetric metering notches are available in a ratio of 2:1 for the purpose of adaptation to differential cylinders.



Flow in mid position, "leakage oil pressure relief"

With symbol "E", leakage oil in the two work chambers A and B of the control piston gives rise to a build-up of pressure in A or B, which then causes a connecting cylinder to drift out of position.

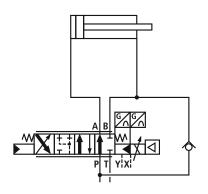
In many cases, the "W" symbol is a better solution. With a setpoint of "0", the control piston moves into the overlapped mid position. In this mid position, pressure is then relieved from ports A and B with 1 % \pm 0.5% Q_N to T. This also supports the function of external check valves.

Control spools in a differential circuit

In order to produce differential circuits, valve spools with a 4th position are available.

It is sufficient to install a check valve in the consumer lines.

In addition, a control spool (symbol) with internal B-P connection is employed for certain branch-oriented solutions. However, we recommend that you consult the BRH Application Center with regard to these special symbols, as a simulation or knowledge of this type of system is usually required.



^{*} Comp. $U_{\rm D-E}$ ±0.5 V factory setting ±1% ** $Q_{\rm P-A}$ at +8 V $[U_{\rm D-E}]$ manufacturing tolerance $Q_{\rm max}$ \leq ±5%

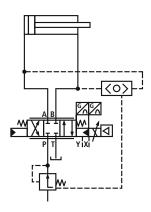
Characteristic curves (measured with HLP 46, $\vartheta_{oil} = 40 \degree C \pm 5 \degree C$)

Load tap C1/C2

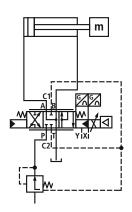
To compensate for fluctuations in the load or supply pressure, 4/3-way servo solenoid directional control valves are combined with pressure compensators. The load is tapped via a shuttle valve for the NG10 and 35, and via two additional ports C1 and C2 for the NG16, 25 and 27.

The pressure compensator therefore always receives the correct pressure signal even in the event of negative load. When using pressure compensators, an external control oil supply should always be selected.

NG10, 35

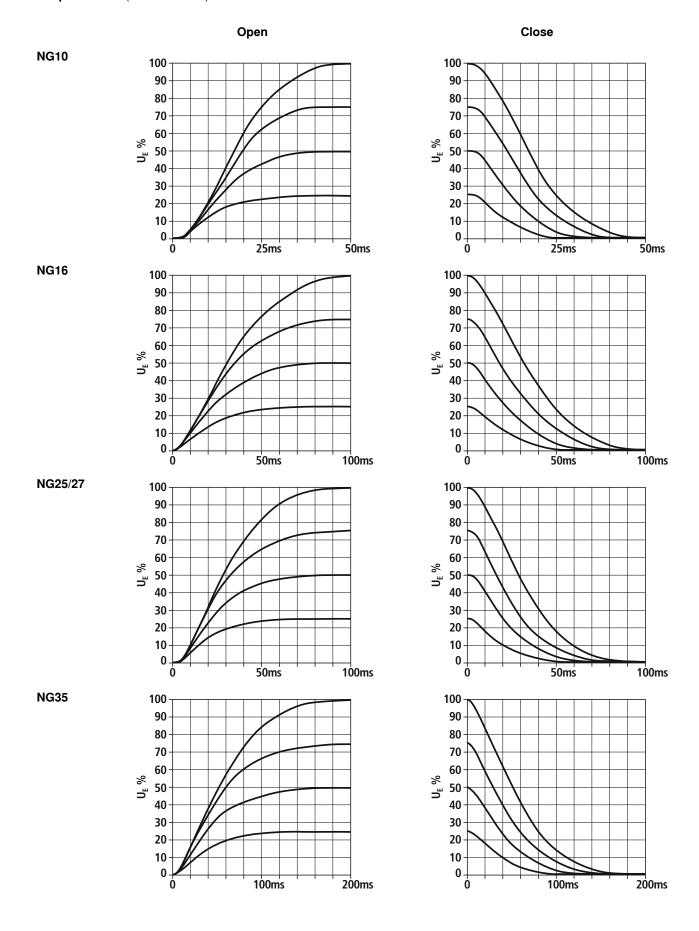


NG16, 25, 27

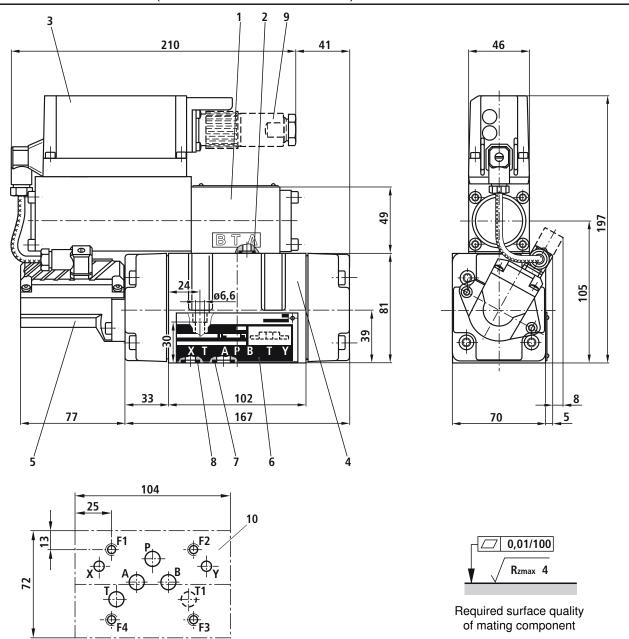


Characteristic curves (measured with HLP 46, $\vartheta_{oil} = 40 \, ^{\circ}\text{C} \pm 5 \, ^{\circ}\text{C}$)

Response time (at X = 100 bar)



Unit dimensions NG10 (nominal dimensions in mm)



- 1 Pilot valve
- 2 O-ring 9.25 x 1.78 (ports P, A, B, T)
- 3 On-board electronics
- 4 Main valve
- 5 Inductive position transducer (main valve)
- 6 Nameplate
- **7** O-ring 12 x 2 (ports P, A, B, T, T1)
- **8** O-ring 10 x 2 (ports X, Y)
- **9** Plug-in connector not included in delivery (order separately)

10 Machined valve contact surface, mounting hole configuration according to ISO 4401-05-05-0-05

Deviates from standard:

Ports P, A, B, T, T1 Ø 10,5 mm

Minimum thread depth: Ferrous metal 1.5 x Ø

Non-ferrous 2 x Ø

Subplates, see Technical Data Sheet RE 45055

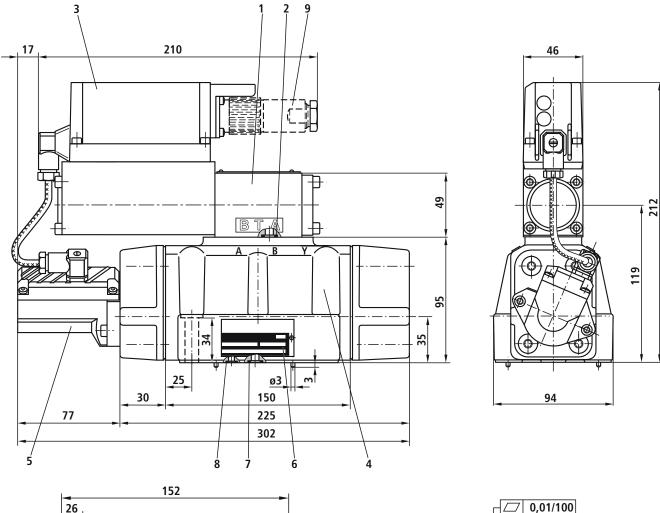
Valve fastening bolts (order separately)

The following valve fastening bolts are recommended:

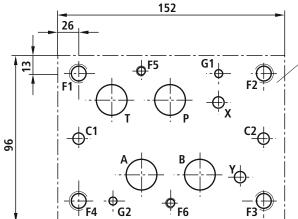
4 cheese-head bolts ISO 4762-M6x40-10.9-N67F82170 (galvanized in accordance with Bosch standard N67F82170) Tightening torque $M_{\rm A}$ = 11+3 Nm

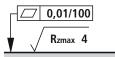
Material no. 2910151209

Unit dimensions NG16 (nominal dimensions in mm)



10





Required surface quality of mating component

10 Machined valve contact surface, mounting hole configuration according to ISO 4401-07-07-0-05 Deviates from standard:

Ports P, A, B, T Ø 20 mm

Minimum thread depth: Ferrous metal 1.5 x Ø Non-ferrous 2 x Ø

Subplates, see Technical Data Sheet RE 45057

Valve fastening bolts (order separately)

The following valve fastening bolts are recommended:

2 cheese-head bolts ISO 4762-M6x45-10.9-N67F82170 (galvanized in accordance with Bosch standard N67F82170) Tightening torque $M_A = 11+3 \text{ Nm}$

Material no. 2910151211

4 cheese-head bolts ISO 4762-M10x50-10.9-N67F82170 (galvanized in accordance with Bosch standard N67F82170) Tightening torque $M_A = 50+10 \text{ Nm}$

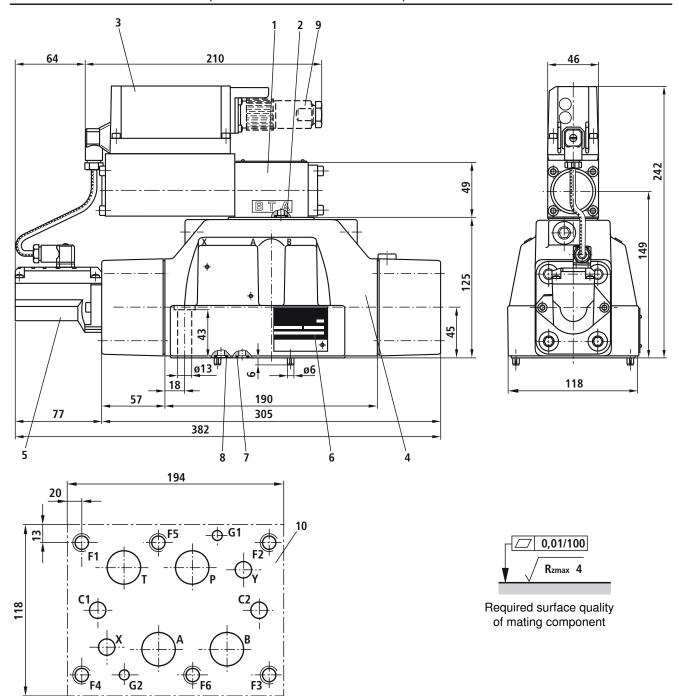
Material no. 2910151301

1 Pilot valve

2 O-ring 9.25 x 1.78 (ports P, A, B, T)

- 3 On-board electronics
- 4 Main valve
- **5** Inductive position transducer (main valve)
- 6 Nameplate
- **7** O-ring 23 x 2.5 (ports P, A, B, T)
- 8 O-ring 9 x 2 (ports X, Y, C1, C2)
- 9 Plug-in connector not included in delivery (order separately)

Unit dimensions NG25/27 (nominal dimensions in mm)



- 1 Pilot valve
- 2 O-ring 9.25 x 1.78 (ports P, A, B, T)
- 3 On-board electronics
- 4 Main valve
- 5 Inductive position transducer (main valve)
- 6 Nameplate
- 7 O-ring (ports P, A, B, T)

NG25: 28 x 3 NG27: 34.6 x 2.62

- 8 O-ring 15 x 2.5 (ports X, Y, C1, C2)
- 9 Plug-in connector not included in delivery (order separately)

10 Machined valve contact surface, mounting hole configuration according to ISO 4401-08-08-0-05

Deviates from standard:

NG25: Ports P, A, B, T \varnothing 25 mm

NG27: Ports P, A, B, T Ø 32 mm

Minimum thread depth: Ferrous metal 1.5 x Ø

Non-ferrous 2 x Ø

Subplates, see Technical Data Sheet RE 45059

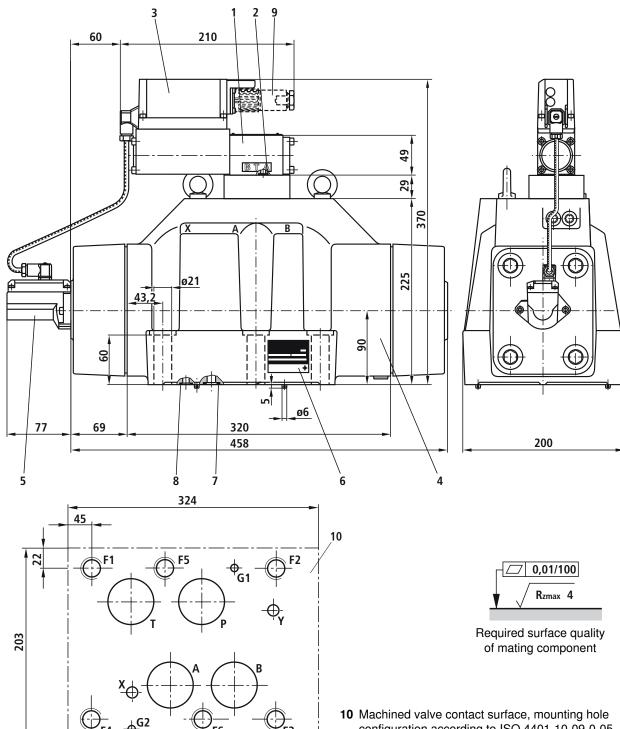
Valve fastening bolts (order separately)

The following valve fastening bolts are recommended:

6 cheese-head bolts ISO 4762-M12x60-10.9-N67F82170 (galvanized in accordance with Bosch standard N67F821 70) Tightening torque NG25 $M_{\rm A}$ = 90+30 Nm, NG27 $M_{\rm A}$ = 90±15 Nm

Material no. 2910151354

Unit dimensions NG35 (nominal dimensions in mm)



- 1 Pilot valve
- 2 O-ring 9.25 x 1.78 (ports P, A, B, T)
- 3 On-board electronics
- 4 Main valve
- **5** Inductive position transducer (main valve)
- 6 Nameplate
- **7** O-ring 53.57 x 3.53 (ports P, A, B, T)
- **8** O-ring 15 x 2.5 (ports X, Y)
- 9 Plug-in connector not included in delivery (order separately)

configuration according to ISO 4401-10-09-0-05

Deviates from standard:

Ports P, A, B, T Ø 48 mm

Minimum thread depth: Ferrous metal 1.5 x Ø Non-ferrous 2 x Ø

Subplates, see Technical Data Sheet RE 45060

Valve fastening bolts (order separately)

The following valve fastening bolts are recommended:

6 cheese-head bolts ISO 4762-M20x90-10.9-N67F82170 (galvanized in accordance with Bosch standard N67F82170) Tightening torque $M_A = 450+110 \text{ Nm}$

Material no. 2910151532

Notes

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