

# ADVANCED BIONIC & INDUSTRIAL APPLICATIONS EDUCATIONAL ROBOTICS CAMP

Technical sheet

# **Krypton 5 Robotics kit – SOLD SEPARATELY**

What's in the box?



## **Programmable Logic Controller:**

User friendly main control board. This is the brain for every project in this course. The controller manages the program signals from and to each sensor and actuator. It offers a simple UI through an LCD screen.



#### Main characteristics:

- RJ15 connector pins for 7 sensors, 4 motors, and 1 camera module
- Multicore Cortex-A7 processor @1.3GHz
- 1.6Gb storage
- 64KB RAM
- Wi-Fi & Bluetooth modules
- 2.3" single touch LCD screen
- Embedded sensors: Gyroscope, Compass, Microphone.
- 1500mAh rechargeable battery



# Structural parts:

A total of **762** plastic parts are included in this kit. These structural components are meant to be assembled without the need of special tools.

Part list				
Porous beam Black 30mm x20	Porous beam Red 30mm x6	Porous beam Green 30mm x6	Porous beam Yellow 30mm x6	Porous beam Blue 30mm x6
	Se Contraction		SE LEVE	No.
Porous beam 20mm x20	Porous beam Gray 30mm x20	Porous beam gray 70mm x25	Porous beam White 110mm x25	Axle(20mm) x10
		THE PROPERTY OF THE PARTY OF TH	September 1	
Axle (30mm) x10	Axle (40mm) x10	Axle(50mm) x10	Axle (60mm) x10	Axle(80mm) x10
30	40	50	[0]	
Coupling (90°) x6	Mecanum Wheel x 1	Guide Wheel x4	Coupling(20mm) x8	Marble x1
			9-0	
Bolt(20mm) x120	Bolt(30mm) x60	Bolt(15mm) x20	Axle sleeve x30	Beam U shape x2
				Q.s.
Middle A connector x4	Slide bearing x8	Short bolt(2mm) x10	Middle L connector x10	Middle H connector x2
Porous beam 90° x10	Porous beam 126.87° x20	Porous beam 90° x10	Porous beam 126.87° x20	Gray gear #1 x4
Section 1975				



Black gear #1 x4	Yellow gear #1 x4	Gray gear #1 x4	Black gear #2 x4	Yellow gear #2 x4
Cube x30	Half cube x20	Cube connector x20	Slope cube x10	60° cube x5
Non-slip rubber x44	Rail x66	Rail rim x4	Tire x2	Rim x2
Square beam x6	Small slab x1	1# Slab x3	2# Slab x2	3# Slab x1
			19 19 19 19 19 19 19 19 19 19 19 19 19 1	
4# Slab x1	8# Slab x1	Cable para motor x12		
		3 pin		

### Sensors

These components are used to collect data from the environment. Each sensor must be connected to the PLC board and be programmed individually.

Sensor list			
Picture	Name	Quantity	Function
-	Compass (embedded)	1	Using the earth's magnetic field, determines the position in which the PLC is facing.
-	Gyroscope (embedded)	1	Determines the acceleration force magnitude in X, Y and Z axis.
-	Microphone (embedded)	1	Records any environmental audio when active.



-	Position (embedded in motor)	3	Determines motor's axis actual position and RPM
	Touch	1	Recalls the current state of the button, either pressed or not.
	Grayscale	5	Analyses the color of an object (how light or dark) to determine its shade of gray.
	Color	1	Determines the color of an object in front of it (red, green, blue, yellow, or white) or the intensity of a light shining upon the sensor. Best reads at 0.5in.
	Ultrasonic	1	Using an ultrasonic soundwave calculates the distance between the sensor and an object in front of it. Best reads from 1 to 25in.

## Actuators

These components are used to create motion within an assembly. Each actuator must be connected to the PLC board and be programmed individually.

Actuator list				
Picture	Name	Quantity	Function	
-	RGB LED (embedded)	1	Individually controllable RGB LED light.	
-	Speaker (embedded)	2	Play any sound coming from the PLC board.	
	Small motor	1	Creates rotational motion at low torque and high speeds.	



	Big motor	2	Creates rotational motion at high torque and low speeds.
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## Minimum Hardware Requirements

Mobile Device: with Operating Systems iOS 9.3 or later or Android Oreo 8.0 or later. Memory: 8GB Minimum and RAM: 2GB Minimum.

#### **Applications:**

Download the following Apps in your device:

Abilix Krypton Mobile App

This application encloses every functionality the Krypton robotics family has. The app contains introductory activities, a project gallery, interactive 3D assembly manuals, and three different block-based programming environments.



The app is available for iOS and Android users:

Apple AppStore: <a href="https://apps.apple.com/mx/app/abilix-krypton-todays-future/id1140118489">https://apps.apple.com/mx/app/abilix-krypton-todays-future/id1140118489</a> Google PlayStore: <a href="https://play.google.com/store/apps/details?id=com.partnerx.CRobotgplay">https://play.google.com/store/apps/details?id=com.partnerx.CRobotgplay</a>

The App Includes 3 programming modules:

Block-based Programming (Krypton Project Programming)

This programming tool is the easiest way to start programming robotics. The user works in an environment in which there are pre-programmed blocks; each block contains a predefined sequence which makes the robot move in a certain way. In this tool, there is no chance for failure since every block has been previously proven to work. This programming method is recommended for absolute beginners.



Krypton Scratch Programming

This programming tool uses natural language blocks to program the robot; works just as any other Scratch programming environment. If you are already familiar using Scratch, this tool will fit you best.





• Krypton Chart Programming

This tool follows a flowchart programming scheme. Just as a regular flowchart program in any environment, the program will play from top to bottom following each block's configuration. This is the ideal tool for a more complete and complex project development.



