## REXGEAR

Your Power Solution Expert


87330 High Precision Three-Phase Power
Meter User manual (v1.2)

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## Chapter 1: Safety rules

Before using 87330 high precision three-phase power meter or its parting products, please read this user manual carefully, and operate in strict accordance with user manual!


Warning label Warning that the operations, applications, or conditions performed are dangerous, and may result in injury or death. This label is marked where a warning is required in user manual.


Attention label Caution that the operation, application, or condition being performed is dangerous, and may cause damage of analyzer or loss of data stored in instrument. This label is marked where attention is required in user manual.

- The contents of this manual are subject to change with upgrading of performance and functions of instrument a without prior notice.
- The reason for upgrading may cause difference between picture in this manual and the content displayed on instrument screen.

■ We strive to perfect the contents of this manual. If you have any questions or find any error, please contact REXGEAR.

■ It is strictly prohibited to copy or reprint this manual in whole or in part without the permission of REXGEAR Instruments.

- For consultation and taking of latest user manual, please refer to mailbox on home page.

Chapter 2: Technical indexes

## Chapter 2: Technical indexes

## I. Product introduction

87330 series high-precision three-phase power analyzer adopts the latest FPGA+ARM parallel synchronous processing technology, it conforms to IEC standard about 3 U compact case with exquisite appearance. It is widely used in the energy efficiency test for three-phase electric equipment, etc. It is equipped with Ethernet TCP-MODBUS standard protocol in standard configuration, and meets the requirements of engineering integration. Optional motor test module can be used to test the torque and speed of three-phase motor, multiple applications are available with one machine.

## II. Product features

1. High precision, wide frequency band: Basic precision is up to $0.1 \%$, and data can be displayed and updated as fast as 100 ms ; Dual AC and DC signals, power test bandwidth is $\mathrm{DC} 0.5 \mathrm{~Hz} \sim 100 \mathrm{kHz}$, meeting various standard and non-standard sinusoidal waveform load power test.
2. Support the latest motor test module, with the reserved motor sensor test interface, it is suitable for sensor signal test for majority of motors available on market; with single-machine, three-phase motor efficiency test can be made, it can ensure signal synchronization, and thus improve test accuracy.
3. Support RS232/RS485, Ethernet communication interface, standard MODBUS, MODBUS/TCP, and other optional communication protocols;
4. Adopt frequency-mixing sampling technology to measure high-frequency waveform more accurately;
5. Support three-phase interphase angle test.

## III. Technical parameters

| Model | 87330 |
| :---: | :---: |
| Current specification | 20A <br> *1/5/50A optional |
| Wiring method | 1P3W (single-phase 3-wires) <br> 3P3W (three-phases 3-wires, 2 voltages, 2 currents) 3V3A (three-phases 3 -wires, 3 voltages, 3 currents) 3P4W (three-phases 4-wires) |
| Input impedance of each phase | Voltage: About $2 \mathrm{M} \Omega$ <br> Current sensor: About $100 \mathrm{k} \Omega$ <br> Direct input of current(20A): About $10 \mathrm{~m} \Omega$ <br> *50A: $2.5 \mathrm{~m} \Omega ; 5 \mathrm{~A}: 50 \mathrm{~m} \Omega ; 1 \mathrm{~A}: 200 \mathrm{~m} \Omega$ |
| Peak factor of full range | 3 <br> *Highest range: 1.5 |
| Rated range of voltage (Direct input) | 15/30 / $60 / 100 / 150 / 300 / 600 / 1000 *[V]$ |
| Rated range of current (Direct input) | $100 \mathrm{~m} / 200 \mathrm{~m} / 500 \mathrm{~m} / 1 / 2 / 5 / 10 / 20 *[A]$ |
| Rated range of current (Sensor input) | $50 \mathrm{~m} / 100 \mathrm{~m} / 200 \mathrm{~m} / 500 \mathrm{~m} / 1 / 2 / 5 / 10[\mathrm{~V}]$ |
| Voltage/current Precision scope | $\begin{aligned} & (1 \% \sim 110 \%) \times \text { range } \\ & * \text { Voltage } 1000 \mathrm{~V} \text { rage, current } 20 \mathrm{~A} \text { range, precision range is }(1 \% \sim 100 \%) \times \text { range } \end{aligned}$ |
| Range of power factor | $\pm(0.0001 \sim 1.0000)$ |

Chapter 2: Technical indexes


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Chapter 2: Technical indexes

1. [Condition] temperature: $23 \pm 5^{\circ} \mathrm{C}$, humidity: $30 \% \sim 75 \% \mathrm{RH}$, input wave form: Sine wave, common mode voltage: 0 V , line filter: OFF, frequency filter: 440 Hz below ON, power factor $\lambda$ : 1 , Peak factor: 3 . After preheating In the wiring state, after zeroing or changing the range.
2. In the measurement accuracy formula, $f$ is frequency, unit kHz .
3. When the data update rate is 100 ms , all accuracy $+0.05 \%$ of the reading.
4. Influence of temperature change after zeroing or range changing: Voltage DC precision $+0.02 \% /{ }^{\circ} \mathrm{C}$ of range, current DC precision $+500 \mu \mathrm{~A} /{ }^{\circ} \mathrm{C}$, external sensor DC precision $+50 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$, power DC precision + product of voltage and current influence.

## IV. The influence of system setting on measurement accuracy

## 1. Influence of line filter on measurement accuracy

Line filter locates in voltage and current measurement circuit, when turning on line filter, the measured value does not contain high frequency component, which can remove noise from inverter, switching power supply or distortion waveform, so will directly affect the measurement precision of voltage, current and power; therefore, when turning on line filter, the influence on measurement precision is as follows:

| Line filter | Voltage /current | Power |
| :---: | :--- | :--- |
| On | When the cutoff frequency is 500 Hz, | When the cutoff frequency is 500 Hz, |
|  | $45 \mathrm{~Hz} \sim 66 \mathrm{~Hz}:+0.2 \%$ of reading value | $45 \mathrm{~Hz} \sim 66 \mathrm{~Hz}:+0.3 \%$ of reading value |
|  | $<45 \mathrm{~Hz}:+0.5 \%$ of reading value | $<45 \mathrm{~Hz} \quad+1 \%$ of reading value |
|  | When the cutoff frequency is 5.5 kHz | When the cutoff frequency is 5.5 kHz |
|  | $\leq 66 \mathrm{~Hz}:+0.2 \%$ of reading value | $\leq 66 \mathrm{~Hz} \quad+0.4 \%$ of reading value |
|  | $66 \mathrm{~Hz} \sim 500 \mathrm{~Hz}:+0.5 \%$ of reading value | $66 \mathrm{~Hz} \sim 500 \mathrm{~Hz}:+1.2 \%$ of reading value |

## 2. Influence of harmonics on measurement accuracy

When the harmonic measurement is turned on, the measurement accuracy (reading error + range error) is as follows:
(1) When line filtering is on $(5.5 \mathrm{kHz})$

| Frequency | Voltage $/$ current | Power |
| :---: | :--- | :--- |
| $10 \mathrm{~Hz} \leq \mathrm{f}<45 \mathrm{~Hz}$ | $0.4 \%$ of reading value $+0.35 \%$ of range | $0.85 \%$ of reading value $+0.5 \%$ of range |
| $45 \mathrm{~Hz} \leq \mathrm{f}<440 \mathrm{~Hz}$ | $0.75 \%$ of reading value $+0.35 \%$ of <br> range | $1.5 \%$ of reading value $+0.5 \%$ of range |
| $440 \mathrm{~Hz} \leq \mathrm{f}<1 \mathrm{kHz}$ | $1.2 \%$ of reading value $+0.35 \%$ of range | $2.4 \%$ of reading value $+0.5 \%$ of range |

(2) When the line filter is turned off

| Frequency | Voltage $/$ current | Power |
| :---: | :--- | :--- |
| $10 \mathrm{~Hz} \leq \mathrm{f}<45 \mathrm{~Hz}$ | $0.15 \%$ of reading value $+0.35 \%$ of range | $0.35 \%$ of reading value $+0.5 \%$ of range |
| $45 \mathrm{~Hz} \leq \mathrm{f}<440 \mathrm{~Hz}$ | $0.15 \%$ of reading value $+0.35 \%$ of range | $0.25 \%$ of reading value $+0.5 \%$ of range |
| $440 \mathrm{~Hz} \leq \mathrm{f}<1 \mathrm{kHz}$ | $0.2 \%$ of reading value $+0.35 \%$ of range | $0.4 \%$ of reading value $+0.5 \%$ of range |

## 3. Calculation cycle and lower limit of frequency measurement

The measurement range of frequency varies with different data calculation cycles, and the specific relationship is as follows:

| Computation cycle | 0.1 s | 0.25 s | 0.5 s |
| :---: | :--- | :--- | :--- |
| Measurement <br> range of frequency | $25 \mathrm{~Hz} \sim 100 \mathrm{kHz}$ | $10 \mathrm{~Hz} \sim 100 \mathrm{kHz}$ | $5 \mathrm{~Hz} \sim 100 \mathrm{kHz}$ |
|  | 1 s | 2 s | 5 s |
|  | $2.5 \mathrm{~Hz} \sim 100 \mathrm{kHz}$ | $1.5 \mathrm{~Hz} \sim 50 \mathrm{kHz}$ | $0.5 \mathrm{~Hz} \sim 20 \mathrm{kHz}$ |
|  |  |  |  |

## V.Outline dimension



Figure 2-1: Outline dimension drawing

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## Chapter 3: Operation instruction

## I. Introduction of front panel



Figure 3-1: Schematic diagram for front panel of instrument

## 1. Display window:

Four display windows can display following test parameters respectively (see Table 3-1).
Table 3-1: Instrument test parameters description

| Indicator lamp | Parameters | Unit | $\begin{gathered} \mathrm{m}, \mathrm{k}, \mathrm{M} \text { indocator light: } 1 \mathrm{M}- \\ 1000 \mathrm{k} \\ 1 \mathrm{k}-1000 \\ 1 \mathrm{~m}-0.001 \end{gathered}$ |
| :---: | :---: | :---: | :---: |
| V | Voltage | Volt |  |
| A | Current | Ampere |  |
| W | Active power | Watt |  |
| VA | Apparent power | VA |  |
| var | Reactive power | Var |  |
| TIME | Time | Hour: Minute: Second |  |
| PF | Power factor |  |  |
| $\bigcirc$ | Phase angle | Degree |  |
| \% | Harmonic (B\&D zone) |  |  |
| \% | Mechanical power (D zone) |  |  |
| Vpk | Voltage peak | Volt |  |
| Vpk | Current peak | Ampere |  |
| Wh | Electric power | Wh |  |
| Ah | Electric energy | Ah |  |
| Hz | Frequency | Hz |  |
| $\mathrm{N} \cdot \mathrm{m}$ | Torque | Nm |  |
| rpm | Rotation speed | Rotation /min |  |

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## 2. Character comparison table:

The instrument adopts seven-segment LED to display all characters and data, and display comparison for common number and character is shown in the figure below:


Figure 3-2: Display comparison of Arabic numerals

##  <br> A B C D E F G H I J K L M N O P Q R S T U V W X Y Z

Figure 3-3: Display comparison of English letters

## 3. Meaning of special characters:

-     - . - . : Dash The dash is displayed for the time before starting integration and for abnormal harmonic source.
-- OH - -: Beyond range In the measured state, an overrange occurs when the measured voltage or current exceeds $110 \%$ of current range. When automatic range is used, the instrument will automatically shift upward, and overrange occurs when $110 \%$ of the maximum range is exceeded.
-- O L--: Exceed max measurement value. In the measured state, when the measured voltage or current exceeds the maximum limit defined for this meter.
-- H H - -: Beyond upper limit In the measured state, when the measured voltage or current exceeds the upper limit setting of alarm.
-- L L--: Beyond lower limit In the measured state, when the measured voltage or current is below the lower limit setting of alarm.
- ERROR : No signal In the harmonic state, when there is not signal input during interphase angle test.
- ADJXXX: Channel X coefficient is the initial value.
- BNCXXX: Channel X BNC coefficient is the initial value.
- ERROR1 : Abnormal communication between FPGA and STM32
- ERROR2 : Abnormal communication between network port chip and STM32
- HARM ERROR : Harmonic frequency acquisition is abnormal, all parameters are not displayed.

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## 4. State indicator light:

Table 3-2: Status indicator light description

| Indicator lamp | Meaning | Remarks |
| :--- | :--- | :--- |
| UPDATE | Data update indicator light | During normal operation, this indicator light is On with <br> slight flashing |
| SCALE | Transformation <br> indicator light | When transformation ratio function is On, this indicator light <br> is On |
| U-ALM | Voltage alarm indicator light | When voltage exceeds alarm setting value, this indicator <br> light is On |
| I-ALM | Current alarm indicator light | When current exceeds alarm setting value, this indicator <br> light is On |
| P-ALM | Power alarm indicator light | When power exceeds alarm setting value, this indicator light <br> is On |
| RMS | Measurement mode for valid <br> value | Valid value of measured signal |
| DC | Measurement mode for DC <br> component | DC component of measured signal |
| MEAN | Measurement mode for <br> average rectification value | Average rectification value for valid value of measured <br> signal |
| I-AUTO | Auto current range indicator <br> light | When current range is in auto selection mode, this indicator <br> light is On |
| U-AUTO | Auto voltage range indicator <br> light | When voltage range is in auto selection mod, this indicator <br> light is On |
| LINE | Line filter indicator light | When line filter is On, this indicator light is On |
| FREQ | Frequency filter indicator <br> light | When frequency filter is On, this indicator light is On |
| MAXHOLD | Max value holding indicator <br> light | When MAXHOLD function in On, this indicator light is On |
| KEYLOCK | Key locking indicator light | When operation key is locked, this indicator light will flash |
| T | Torque indicator light | When displaying torque test interface, this indicator light is <br> On |
| n | RPM indicator light | When displaying RPM measurement interface, this indicator <br> light is On |
| light |  |  |

## II. Description of rear panel



Figure 3-4: Schematic diagram for rear panel of instrument

1. The rear panel consists of following parts: Power socket, voltage/current terminal, serial port, extended BNC interface, motor card/switch interface, Ethernet port.
2. The power socket is the power input for meter. Fuse locates below the socket, 250 V 3 A
3. The voltage/current terminals are the terminals that can be connected to measurement loop.

4, Serial port is RS232/RS485 optional, standard configuration RS232.
5 , Network port is RJ-45 port.

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## III. Wiring description

## 1. Voltage input terminal

Terminal is safety bananas jack of $\Phi 4 \mathrm{~mm}$.
Please insert the safety connector (conductor not exposed) into voltage input terminal. A voltage test line with safety connector and test clamp is provided with the box.

## 2. Current input terminal

The terminals are M8 stud terminals. It is recommended to use professional OT wire-pressing terminal for pretreatment of test line, fasten the OT terminal to the stud, and then hold the terminal knob and tighten it. No current test line is provided with the box.

## 3. Configuration and wiring

The optional wiring method for analyzer depends on number of measurement channels configured. The wiring methods mainly include $1 \mathrm{P} 3 \mathrm{~W}, 3 \mathrm{P} 3 \mathrm{~W}, 3 \mathrm{~V} 3 \mathrm{~A}, 3 \mathrm{P} 4 \mathrm{~W}$, etc.
3.1 Wiring example of single-phase 3-wires (1P3W)


### 3.2 Wiring example of three-phases 3-wires (3P3W)

3P3W wiring must be in strict accordance with the following diagram, and the channel sequence cannot be changed.

The power value of a single channel measured in 3 P 3 W wiring may be negative, because the power is calculated by the line voltage and the phase current. The power of a single channel is meaningless. And the total three-phase power is meaningful.

## 2-meters wiring (2V2A)




### 3.3 Wiring example of three-phases 4-wires (3P4W)



### 3.4 Wiring example of current sensor (3P4W)


4. Use metrological verification wiring of standard source


Figure 3-5: Schematic diagram for metrological verification wiring of standard source
5. Use metrological verification wiring of standard meter


Figure 3-6: Schematic diagram for metrological verification wiring of standard meter

## WARNING

Notes:
$>$ Press combination key (SHIFT+SET) to restore factory settings (INIT) before metering.
$>$ For current measurement, the input voltage of analyzer shall be greater than 60 V .

## 6. Requirement for wire diameter

The current carrying capacity of copper conductor cables is specified in section 523 - Current carrying capacity, part V Building Installations, IEC, standard no.: IEC 60364-5-523 1983 When the measuring current of analyzer reaches 20 A , it is recommended to use copper wires with a cross-sectional area $\geq 4 \mathrm{~mm} 2$.

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## IV. Keys description

## 1. Functions of keys



Display selection key ( $\mathrm{Fa} \sim \mathrm{Fd}$ ) : 4 in total. They are used to select content of each display window.
Fa: Switch among V, A, W, Va and var.
Fb : Switch among V, A, W and ${ }^{\circ}$. (A\%, V\% optional under harmonic state)
Fc : Switch among V, A, W, Vpk, Apk, Wh, Ah and TIME.
Fd : Switch among V, A, W, PF, Hz and \%. (A\%, V\% optional under harmonic state)
Channel selection key (Ea~Ed) : 4 in total, they are used to select content of each display window respectively.
Display window A~D(Ea~Ed) : Switch among channel 1, channel 2, channel 3 and $\sum$.

## Explain:

(1)When harmonic state is ON :

B zone $\mathrm{A} \%$ and $\mathrm{V} \%$ means the harmonic content of each order. EG: " 01100.0 " means harmonic content $100.0 \%$ in order 1; "03 12.4" means harmonic content $12.4 \%$ in order 3. Press " $\boldsymbol{\nabla}$ " or " $\boldsymbol{\Delta}$ " to switch order.

D zone A\% and V\% means ATHD and VTHD.
(2)When B zone "o" is ON, pressing Eb to switch among:

Phase angle: A-phase, B-phase, C-phase. (unit ${ }^{\circ}$ )
Interface angle: $\mathrm{U} 1-\mathrm{U} 2, \mathrm{U} 2-\mathrm{U} 3, \mathrm{U} 1-\mathrm{U} 3$. (unit $\mathrm{V}^{\circ}$ )
interface angle: I1 - I2, I2 - I3, I1 - I3. (unit $\mathrm{A}^{\circ}$ )
(3)When 'MT SET - MT - DISP' is ON, it is possible to display MT parameter:

A zone can display torque: Press "Fa" until light " T " and " $\mathrm{N} \cdot \mathrm{m}$ " on.
B zone can display RPM: Press "Fb" until light " n " and "rmp" on.
C zone can display mechanical work: Press "Fc" until light "p" and "W" on.
D zone can display mechanical efficiency: Press "Fd" until light " $\eta$ " and "\%" on. The mechanical efficiency is mechanical power divided by electric power. The channel of the electric power is directed by the channel light, and can be switched by key "Ed".
(4)After the parameters of zones $\mathrm{A}, \mathrm{B}, \mathrm{C}$ and D are selected, the instrument will automatically remember the selected parameters, and data will not lose when shutting down.

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Current range key (I-RANGE) : Enter current range selection interface.
Voltage range key (U-RANGE) : Enter voltage range selection interface.
Explain: In range selection interface, It is possible to press " $\boldsymbol{\nabla}$ " and " $\boldsymbol{\Delta}$ " to change range. Press "set" to save range and exit to test interface. Press "I-RANGE" / "U-RANGE" or "ESC" will exit to test state without saving range.

## Direction key:

" $\boldsymbol{\nabla}$ "key: Decrease the setting parameter value at current flashing position or switch to next setting parameter.
" $\boldsymbol{\Delta}$ " key: Increase the setting parameter value at current flashing position or switch to next setting parameter.
" $«$ " key: Combination key (SHIFT+ $\boldsymbol{\nabla}$ ), left shift of circulation, change position of current Nixie tube (flashing position) of setting parameter.
" $\downarrow$ " key: Combination key (SHIFT $+\boldsymbol{\Delta}$ ), right shift of circulation, change position of current Nixie tube (flashing position) of setting parameter.
Set parameter key (SET) : Determine the selected item.
Restore factory setting key (INIT) : Combination key (SHIFT+ SET), restore all parameters to factory setting. Esc key (ESC) : Close setting menu, return to measurement data interface.
Value holding key (HOLD) : The current display data stops updating and holds. Pressing "HOLD" key again can update display again.

Key locking key (KEYLOCK) : Combination key (SHIFT+HOLD), when this key is pressed, the key is locked. Press again to unlock.

Max value holding key (MAXHOLD) : Combination key (SHIFT + I-RANGE), with this feature enabled, if the measured value is larger than the current holding value, the larger value will be remained.
Three-phase parameter alarm setting key(ALM SET) : Combination key (SHIFT+U-RANGE). It is used to set alarm parameters for three-phase voltage, current and power. See page 20 for details.

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Start key (START) : Press in test state, start integral of electric energy. During accumulation of electric energy, the TIME parameter will accumulate every second.
Stop key (STOP) : When electric energy is in state of START, press in test state to stop integral of electric energy.
Reset key (RESET) : Combination key (SHIFT+STOP), when electric energy is in state of STOP, press this key to reset the electric energy record time record.
Zero calculation key (CAL) : Combination key (SHIFT+START), press in test state, calculate zero point of current shift.
Mode key (MODE) : Combination key (SHIFT+ESC), it is used for switching among measurement modes RMS, DC and MEAN.
Shift functional key (SHIFT) : Press SHIFT once, key light will be On, indicating that this key is in switching state, it can be used for reusing corresponding function given by key name below relevant key. Pressing SHIFT key again can release the switching state.
Wiring system switching key (WIRING): Switch among single-phase 3-wires, three-phases 3-wires, threephases 4-wires and 3-voltages 3-currents.
Harmonic key (HARM) : Enable /disable harmonic function
Explain: When harmonic state is ON:
B zone A\% and V\% means the harmonic content of each order. EG: 01100.0 means the harmonic content of the order 1 is $100.0 \%$; 0312.4 means the harmonic content of the order 3 is $12.4 \%$. Press ' $\boldsymbol{\nabla}$ ' or ' $\boldsymbol{\Delta}$ ' to switch order.

D zone A\% and V\% means ATHD and VTHD.
Setup key (SETUP) : Set the ordinary parameters like scale, com, harmonic and source. See page 17 for details.
Network setting key (LAN SET) : Combination key (SHIFT+HARM) Set the TCP parameters like IP address and port. See page 19 for details.

Motor setting key (MT SET) : Combination key (SHIFT+SETUP) : Set the MT parameters. See page 21 for details.

## 2. The operation of the setting interface

Press these four keys can enter different setting interface:
SETUP: Set the ordinary parameters like scale, com, harmonic and source.
LAN SET: Combination key (SHIFT+HARM). Set the TCP parameters like IP address and port.
ALM SET: Combination key (SHIFT+U-RANGE). Set the alarm parameters for three-phase voltage, current and power.
MT SET: Combination key (SHIFT+SETUP). Set the MT parameters.

The operation logics are same in these setting interface. In SETUP case:
Step 1: In the test state, press "SETUP" to enter ordinary parameters setting interface.
Step 2: press " $\boldsymbol{\nabla}$ " or " $\boldsymbol{\Delta}$ " to switch parameter type to be set, character in display window B will flash;
Step 3: press "SET" key to determine the parameter to be set, and characters in display window C will flash;
Step 4: press " $\mathbf{V}$ ", " $\mathbf{\Delta}$ ", " 4 " , key to set parameters;
Step 5: press "SET" key to confirm setting and return to previous menu. Repeat the above steps to continue setting other parameters;
Step 6: press "SETUP" key again to save the instrument settings and exit to the test state.
notes:

1. Some parameters require the energy state to be "RESET".
2. Pressing "ESC" will exit to test state without save.

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## 3. The list of the setting interface

SETUP: Set the ordinary parameters like scale, com, harmonic and source.
Table 3-3: Parameter Settings of the instrument system

| Window A <br> Display <br> character | Window B <br> Display character | Window C <br> Set parameter | Description |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { di } 5 P \\ & \text { D ISP } \end{aligned}$ | uPdREE <br> UPDATE | Display refreshing rate | $0.1 \mathrm{~s}, ~ 0.2 \mathrm{~s}, ~ 0.5 \mathrm{~s}, ~ 1 \mathrm{~s}, ~ 2 \mathrm{~s}, ~ 5 \mathrm{~s}, ~ 10 \mathrm{~s}$ <br> Default value: 0.5 s |
| $\begin{aligned} & \text { UaLE } \\ & \text { VOLT } \end{aligned}$ | 5[ALE SCALE | Voltage transformation ratio | 1.0-5000.0 Default value: 1.0 |
| [utr CURR | 5CALE SCA LE | Current transformation ratio | 1.0-5000.0 Default value: 1.0 |
| bחc <br> BNC | $\begin{aligned} & \text { 5CHLE } \\ & \text { SCALE } \end{aligned}$ | BNC transformation ratio | $0.010-100.000 \mathrm{mV} / \mathrm{A}$ <br> Default value: $1.000 \mathrm{mV} / \mathrm{A}$ |
| $\begin{aligned} & \text { Pat } \\ & \text { POR } \end{aligned}$ | $\begin{aligned} & \text { R } \bar{\sim} P L_{1}, t \\ & \text { AMPLIT } \end{aligned}$ | Threshold current for integral of electric energy | $0.000 \mathrm{~A}-22.000 \mathrm{~A}$ Default value: 0.000 A When the measured current value is greater than this value, the electric energy begins to integrate |
|  | $\begin{aligned} & \boldsymbol{E}_{\prime} \overline{n E} \\ & \text { TIME } \end{aligned}$ | Integral time of electric energy | HH.MM.SS (Hour. Minute. Second) <br> Default 00.00.00 <br> Integral time. Max 48 h . When it set to 00.00.00 means time not limit. |
| $\begin{aligned} & \text { [ם } \\ & \text { COM } \end{aligned}$ | Fddt <br> ADDR | Communication address | 1-255 Default value: 1 |
|  | bAud BAUD | Baud rate of communication | Optional value: 9600, 19200, 38400 <br> Default value: 38400 |
|  | $\begin{aligned} & \bar{n} \quad d E \\ & \text { MODE } \end{aligned}$ | Selection of communication mode | Serial port RS23, network port TCP <br> Default value: RS232 |
|  | Prata <br> PROTO | Communication protocol specification | In serial mode: REXGEAR protocol, MODBUS protocol Default: REXGEAR protocol In network port mode: RTU(MODBUS protocol), TCP(MODBUS-TCP) protocol Default: RTU protocol |

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| ALA <br> ALA | $\begin{aligned} & \text { GEEP } \\ & \text { BEEP } \end{aligned}$ | Buzzer alarm switch | ON/OFF Default value: ON |
| :---: | :---: | :---: | :---: |
|  | thte <br> THRE | Zero threshold switch | ON/OFF Default value: ON ON - no alarm for zero value, OFF- alarm for zero value |
| FL, | $\begin{aligned} & L, ~ \cap E \\ & \text { LINE } \end{aligned}$ | Line filter switch | ON/OFF Default value: OFF OFF - off, $1-500 \mathrm{~Hz}, 2-5.5 \mathrm{kHz}$ |
|  | $\begin{aligned} & \text { FHE } \\ & \text { FRE } \end{aligned}$ | Frequency filter switch | ON/OFF Default value: OFF |
| 54nc SYNC | $\begin{aligned} & \text { Saut[E } \\ & \text { S OUR CE } \end{aligned}$ | Selection of sync source | U1, I1, U2, I2, U3, I3 Default value: U1 |
| [uトト CURR | 5out[E <br> s OUR CE | Selection of current source | Current AMP, BNC input BNC <br> Default value: AMP |
| $\underset{H A R M}{\operatorname{hat}}$ | 5aut[E <br> s OUR CE | Selection of harmonic source | U1, I1, U2, I2, U3, I3 Default value: U1 |
| $, ~ n t E E$ | $\begin{aligned} & \overline{\bmod } \mathrm{d} E \\ & \mathrm{M} \end{aligned}$ | Selection of integral mode | Normal mode NOR, continuous integral mode CONT <br> Default value: NOR |
| $\underset{T}{\text { thd }}$ | nodE | Selection of THD calculation formula | IEC mode CSA mode <br> Default value: IEC |
| $A \bigcup_{A} E$ | $\begin{aligned} & \overline{\operatorname{H}} \boldsymbol{d E} \\ & \mathrm{MO} \mathrm{E} \end{aligned}$ | Selection of mean processing mode | Average mobile LIN, average index EP Default value: LIN |
|  | ${\underset{E}{E}}_{n}$ | Enable/disable average function | ON/OFF Default value: OFF |
|  | Count | Average coefficient | 8/16/32. Default value: 8 |
| 5RUE <br> SAVE | - AnEE <br> R AN GE | Range Save Switch | ON/OFF Default value: OFF <br> When set to ON, the range will saved after shut down. |
| ${ }_{C F}^{C F}$ |  | Selection of peak factor | 3,6 Default value: 3 |

Chapter 3: Operation instruction
LAN SET: Combination key (SHIFT+HARM). Set the TCP parameters like IP address and port.
Note: Mac address is static hardware address that cannot be changed by user.

Table 3-4: Parameter Settings for network port of instrument

| Window A Display character | Window B Display character | Window C Set parameter | Description |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & \mathrm{I} P \\ & \mathrm{IP} \end{aligned}$ | Addrl <br> A DD R1 | IP address 1 | 0-255 Default value: 192 |
|  | $\begin{aligned} & \text { Hddr-2 } \\ & \text { A DDR } 2 \end{aligned}$ | IP address 2 | 0-255 Default value: 168 |
|  | Fdat- <br> A DD R 3 | IP address 3 | 0-255 Default value: 1 |
|  | Addr-4 <br> A DD R 4 | IP address 4 | 0-255 Default value: 10 |
| $\begin{aligned} & \bar{n} \\ & \text { NM } \end{aligned}$ | Addrl <br> A DD R1 | Subnet mask 1 | 0-255 Default value: 255 |
|  | Hddrz $\text { A DD R } 2$ | Subnet mask 2 | 0-255 Default value: 255 |
|  | Addrヨ <br> A DDR3 | Subnet mask 3 | 0-255 Default value: 255 |
|  | Addr4 <br> A DD R 4 | Subnet mask 4 | 0-255 Default value: 0 |
| CREE <br> gate | Addrl <br> A DD R1 | Gateway 1 | 0-255 Default value: 192 |
|  | $\begin{aligned} & \text { Hddtc } \\ & \text { A DD R } 2 \end{aligned}$ | Gateway 2 | 0-255 Default value: 168 |
|  | Fddry <br> A DD R 3 | Gateway 3 | 0-255 Default value: 1 |
|  | Addr- <br> A DD R 4 | Gateway 4 | 0-255 Default value: 1 |
| LaCRL | $\begin{aligned} & \text { Part } \\ & \text { PORT } \end{aligned}$ | Local port | 0-9999 Default value: 502 |
|  | $\underset{\text { тıм }}{\substack{\text { тו } \\ \hline}}$ | TCP connection time | 0-9999 Default value: 0 <br> Short connection, reconnect if timeout; if "0", it is a long connection |

## REXGEAR

Chapter 3: Operation instruction
ALM SET: Combination key (SHIFT+U-RANGE). Set the alarm parameters for three-phase voltage, current and power.

Table 3-5: Setting of instrument alarm parameters

| Window A <br> Display character | Window B <br> Display character | Window C <br> Set parameter | Description |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { UaLE } \\ & \text { VOLT } \end{aligned}$ | $\begin{aligned} & \text { uPLI } t \\ & \text { UPLI T } \end{aligned}$ | Upper limit of voltage alarm | $0.00 \mathrm{~V}-1000.00 \mathrm{~V}$ Default value: 1000.00 V , when the measured voltage is larger than this value, upper alarm will be triggered |
|  | $\begin{aligned} & \text { LaLı } t \\ & \text { LOLI } \end{aligned}$ | Lower limit of voltage alarm | $0.00 \mathrm{~V}-1000.00 \mathrm{~V}$ Default value: 0.00 V , when the measured voltage is less than this value, lower alarm will be triggered |
|  | $\begin{aligned} & \text { EhtE } \\ & \text { THRE } \end{aligned}$ | Threshold value of voltage alarm | $0.00 \mathrm{~V}-1000.00 \mathrm{~V}$ Default value: 0.00 V , only when the measured voltage is larger than this value, the alarm function will be valid |
| [uトト CURR | $\mathrm{uPL},$ <br> UPLIT | Upper limit of current alarm | $0.000 \mathrm{~A}-22.000 \mathrm{~A}$ Default value: 22.000 A , when the measured current is larger than this value, upper alarm will be triggered |
|  | $\begin{aligned} & \text { LaLit } \\ & \text { LOLIT } \end{aligned}$ | Lower limit of current alarm | $0.000 \mathrm{~A}-22.000 \mathrm{~A}$ Default value: 0.000 A , when the measured current is less than this value, lower alarm will be triggered |
|  | $\begin{aligned} & \text { EHtE } \\ & \text { THRF } \end{aligned}$ | Threshold value of current alarm | $0.000 \mathrm{~A}-22.000 \mathrm{~A}$ Default value: 0.000 A , only when the measured current is larger than this value, the alarm function will be valid |
| Pot <br> POR | uPLIt UPLIT | Upper limit of power alarm | $0.00 \mathrm{~W}-66.000 \mathrm{~kW}$ Default value: 22.000 kW , when the measured power is larger than this value, upper alarm will be triggered |
|  | $\begin{aligned} & \text { LaLit } \\ & \text { LOLIT } \end{aligned}$ | Lower limit of power alarm | $0.00 \mathrm{~W}-66.000 \mathrm{~kW}$ Default value: 0.00 W , when the measured power is less than this value, lower alarm will be triggered |
|  | $\begin{aligned} & \text { thte } \\ & \text { THRE } \end{aligned}$ | Threshold value of power alarm | $0.00 \mathrm{~W}-66.000 \mathrm{~kW}$ Default value: 0.00 W , only when the measured power is larger than this value, the alarm function will be valid |
| FLA <br> AL A | $\begin{aligned} & \boldsymbol{E}_{\prime} \overline{n E} \\ & \text { TIME } \end{aligned}$ | Alarm delay time | $0.0-20.0$ s Default value: 0.0 , when the alarm occurs, the timing will start. If the parameters are still over the limit at the end of timing, the alarm will start |

Chapter 3: Operation instruction
MT SET: Combination key (SHIFT+SETUP). Set the MT parameters.
Table 3-6: Parameter settings of instrument motor

| Window A Display character | Window B Display character | Window C <br> Set parameter | Description |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & \bar{n} t \\ & M T \end{aligned}$ | $\begin{aligned} & d, 5 P \\ & \text { DI SP } \end{aligned}$ | MT display switch | ON/OFF Default value: OFF |
| $\begin{aligned} & \pi \\ & \text { NM } \end{aligned}$ | - $\operatorname{An} \mathrm{BE}$ <br> R AN GE | Full torque range (Nm) | 0-1000.0 <br> Represent 0-1000.0Nm <br> Default value: 10 |
|  | FHEh, <br> FRE H I | Forward full range output frequency $\mathrm{f}_{\mathrm{p}}(\mathrm{kHz})$ | 0.001-99.999 <br> Represent 0-99.999kHZ <br> Default value: 15 |
|  | $\begin{aligned} & \text { FFELa } \\ & \text { FRE LO } \end{aligned}$ | Negative full range output frequency f (kHz) | 0.001-99.999 <br> Represent 0-99.999kHZ <br> Default value: 5 |
|  | FFEZI, <br> FREMI | Output frequency at zero point of torque $\mathrm{f}_{0}(\mathrm{kHz})$ | 0.001-99.999 <br> Represent 0-99.999kHZ <br> Default value: 10 |
| $\begin{aligned} & \text { FP̄} \\ & R P M \end{aligned}$ | $\begin{gathered} \text { חū } \\ \text { NUM } \end{gathered}$ | Output frequency pulse count of torque | 1-1000 represent 1-1000 pieces <br> Default value: 60 |

## ATTENTION

Notes: Hold down (SHIFT+INIT) in the regular setting interface to set parameter to default value, and hold down (SHIFT+STOP) in "MT SET" setting interface to collect zero point data, ensuring that the collection can be completed only when frequency at this time is between the preset forward full range output frequency and reverse full range output frequency.

Chapter 3: Operation instruction

## Chapter 4: Description of the main functions

## I. Measure and calculate

The principle of power analyzer calculation is to sample voltage and current for 200000 times per second. Then power analyzer calculates all electrical parameters according to the sampling data. The following is the calculation formula of some electrical parameters. (Analog)

## 1. Current and Voltage

Take the voltage $u(t)$ in $T$ period as an example. The calculation formula of each mode:
RMS

$$
U_{r m s}=\sqrt{\frac{1}{T} \int_{0}^{T} u^{2}(t) d t}
$$

DC

$$
U_{d c}=\frac{\int_{0}^{T} u(t) d t}{T}
$$

MEAN

$$
U_{\text {mean }}=\frac{\int_{0}^{T}|u(t)| d t}{T}
$$

## 2. Power

Power calculation does not distinguish among modes:

$$
\begin{gathered}
P=\frac{\int_{0}^{T} u(t) i(t) d t}{T} \\
\mathrm{~S}=U_{r m s} \times I_{r m s} \\
\mathrm{Q}=\sqrt{S^{2}-P^{2}}
\end{gathered}
$$

## 3. Three-phase parameter calculation

Press "WIRING" to Switch among wirings.
1P3W:

$$
\begin{aligned}
P_{\Sigma} & =P_{1}+P_{3} \\
U_{\Sigma} & =\frac{U_{1}+U_{3}}{2} \\
I_{\Sigma} & =\frac{I_{1}+I_{3}}{2}
\end{aligned}
$$

3P3W:
2V2A

$$
\begin{aligned}
P_{\Sigma} & =P_{1}+P_{3} \\
U_{\Sigma} & =\frac{U_{1}+U_{3}}{2} \\
I_{\Sigma} & =\frac{I_{1}+I_{3}}{2}
\end{aligned}
$$

3V3A

$$
\begin{gathered}
P_{\Sigma}=P_{1}+P_{3} \\
U_{\Sigma}=\frac{U_{1}+U_{2}+U_{3}}{3} \\
I_{\Sigma}=\frac{I_{1}+I_{2}+I_{3}}{3}
\end{gathered}
$$

3P4W:

$$
\begin{gathered}
P_{\Sigma}=P_{1}+P_{2}+P_{3} \\
U_{\Sigma}=\frac{U_{1}+U_{2}+U_{3}}{3} \\
I_{\Sigma}=\frac{I_{1}+I_{2}+I_{3}}{3}
\end{gathered}
$$

## II. Range select

## 1. Manual

The power analyzer voltage and current have eight range respectively. Press "I-RANGE/U-RANGE" to enter range selection interface.

In range selection interface, press " $\boldsymbol{\nabla}$ " and " $\boldsymbol{\Delta}$ " to change range. Press "set" to save range and exit to test interface. Press "I-RANGE/U-RANGE" or "ESC" will exit to test state without saving range.

## 2. Automatic

In automatic mode, light "U-AUTO/I-AUTO" on. If RMS Value is Lower than $30 \%$ of range or higher than $110 \%$, the range will shift automatically.

## 3. Settings

Range Save Switch (SETUP - RANGE -SAVE): When set to ON, the range will saved after shut down.

## 4. Note

The value cannot be measured normally when range is shifting. So please do not read the value immediately when range is changing. Wait at least 0.5 s plus two refresh periods.

## REXGEAR

## III. Harmonic

## 1. Function description

Press "HARM" to enable harmonic function.
B zone and D zone on screen is able to display harmonic parameters.
B zone A\% and V\% means the harmonic content of each order. EG: 01100.0 means harmonic content $100.0 \%$ in order 1; 0312.4 means harmonic content $12.4 \%$ in order 3. Press ' $\boldsymbol{\nabla}$ ' or ' $\boldsymbol{\Delta}$ ' to switch order.

D zone A\% and V\% means ATHD and VTHD.

## 2. Settings

Ensure that the harmonic source has stable $10-600 \mathrm{~Hz}$ signal when the harmonic is turned on. Otherwise, "HARM ERROR" will be displayed on the screen.

Harmonic source can be change in SETUP - HARM - SOURCE. Default harmonic source is U1.

## 3. Harmonic mode (SETUP - THD - MODE) description

The calculation formula of IEC mode:

$\sqrt{ } \sum\left(\mathrm{C}_{\mathrm{k}}\right)^{2} \quad / \mathrm{C}_{1}$

$$
\text { 「 } \mathrm{k}=2
$$

The calculation formula of CSA mode:
n
$\sqrt{\sum\left(\mathrm{C}_{\mathrm{k}}\right)^{2}}$

$$
\mathrm{k}=2
$$

[
n
$\sqrt{ } \sum\left(\mathrm{C}_{\mathrm{k}}\right)^{2}$
k=1

## IV.Communication

The power analyzer is equipped with network port and serial port. The relevant communication settings are as follows. See Chapter 6 for the communication protocol

## 1. Serial mode

The communication mode (SETUP - COM - MODE) needs to be set to RS232; The baud rate of communication (SETUP - COM - BAUD) needs to be set to be same as the computer. The Communication protocol (SETUP - COM - PROTO) needs to match the computer.

Default serial type is RS232, RS485 optional. The interface of computer, power analyzer and communication line shall be of the same type.

The COM port of the upper computer software should select the COM port witch actually connected to the power analyzer.
2. Network port mode

SETUP: Communication mode needs to be set to TCP. The Communication protocol (SETUP - COM PROTO) needs to match the upper computer.

LAN SET (SHIFT + HARM) : The IP address and Local port is set correctly on the upper computer and the power analyzer.

## V.Integral

## 1. Function description

Press "START" to start integral. In START state, Press "STOP" to stop integral. In STOP mode, Press "RESET" (SHIFT + STOP) to clear all the integral date.

Screen C zone is possible to display integral data: TIME - Integral time. Wh - Electric power. Ah - Electric energy.

## 2. Settings

Threshold current for integral of electric energy (SETUP - POR - AMPLIT): When the measured current value is greater than this value, the electric energy begins to integrate.

Integral time of electric energy (SETUP - POR - TIME) : The integration will automatically stop when reaches this time.

## 3. Notes

Range changing will affect the integration accuracy. It is recommended to reduce the shift action during integration.

After pressing "STOP", the integration will not stop immediately, but will stop in an integer second. The calculation of the average power of the short-term integration needs to wait until the integration stops.

## VI. Current sensor

The current sensor directly outputs the current signal. The power analyzer can directly measure the current signal. It can also be connected to the output voltage signal of the sampling resistance by BNC port.

## 1. Current sensor for output current

Connection: Take a typical sensor as an example. The sensor has four interfaces: $+15 \mathrm{~V},-15 \mathrm{~V}, \mathrm{M}, \mathrm{GND}$. Connect the sensor $\pm 15 \mathrm{~V}$ and GND to the external power supply. Connect sensor M to the positive (red) current input of the power analyzer and GND to the negative (black) current input of the power analyzer.

Settings: Current source (SETUP - CURR - SOURCE) needs to be AMP. Current transformation ratio (SETUP - CURR - SCALE) needs to be set as the ratio of the current sensor.

Circuit diagram: See Page 11.

## 2. Current sensor for output voltage

Connection: The sensor has four interfaces: $+15 \mathrm{~V},-15 \mathrm{~V}$, EXT port, GND. Connect the sensor $\pm 15 \mathrm{~V}$ and GND to the external power supply. Connect sensor EXT port and the BNC port of power analyzer.

Settings: Current source (SETUP - CURR - SOURCE) needs to be BNC. BNC transformation ratio (SETUP - BNC - SCALE) needs to be set as appropriate value. For example, the ratio of the current sensor is 2000: 1 and the sampling resistance is $5 \Omega$. According to the calculation, the output voltage is 2.5 mV when the actual current is 1 A , so the BNC transformation ratio should be set to $2.5 \mathrm{mV} / \mathrm{A}$.

Circuit diagram: Similar as Page 11.

Chapter 3: Operation instruction

## VII. Average function

When the power supply, load or low frequency signal input changes abruptly, the data may fluctuate greatly, and the average function can be used to stabilize the display value.

## 1. Settings

"SETUP - AVE - EN" : Enable/disable average function;
" SETUP - AVE - COUNT" : Set average coefficient;
"SETUP - AVE - MODE" : Selection of mean processing mode.

## 2. calculation formula

If $D_{n}$ is the current display value, $S_{n}$ is the current measure value, and K is the average coefficient.
LIN:

$$
D_{n}=\frac{S_{n}+S_{n-1} \ldots S_{(n-K+1)}}{\mathrm{K}}
$$

EP:

$$
D_{n}=\frac{1}{K} S_{n}+\frac{K-1}{K} D_{n-1}
$$

3. Notes

When the average function is on, the following values will be averaged: $\mathrm{P}, U_{r m s}, U_{d c}, I_{r m s}, I_{d c}$, other value will not be averaged.

The power analyzer will automatically shift range according to the averaged value, but if the peak value of the measurement overflows, it will shift immediately.

After shifting, the average value in the cache will be discarded.

## VII. Alarm function

The instrument has the functions of over-limit alarm.

## 1. Function description

When the measured value is greater than the threshold value, make alarm judgment. If it is higher than the upper limit or lower than the lower limit, delay for a period of time to trigger the alarm action:

The alarm lights U-ALM, I-ALM, P-ALM are on.
Display interface displays alarm characters. " - HH - " means higher than the upper limit. "- LL - - " means lower than the lower limit.

## 2. Settings

Press "ALM SET" (SHIFT+U-RANGE) to enter the alarm parameters setting interface: Set upper limit, lower limit and threshold value of U, I, P.

Press "SETUP" to enter the ordinary parameters setting interface: The buzzer alarm switch (SETUP - ALA BEEP) can set whether the buzzer sounds when alarming. Zero value threshold switch (SETUP - ALA - THRE) can set whether to alarm when there is no input signal.

## Chapter 5: Description of external interfaces

There is a 9-pin D-type communication port (male port) on rear panel of analyzer, which can provide RS232 or RS-485 communication data transmission function, and a LAN interface which can be used for network port communication.

## I. RS-232/485 communication port

The analyzer provides two serial ports for users to select, RS-232 and RS-485. For 87330, it is RS-232 by default, and the product is equipped with a standard RS-232 communication line. RS-485 communication shall be explained at the time of ordering (special RS-485 communication cable is equipped for product delivered).

1. Definition of RS-232 communication port


Figure 4-1: Definition of RS-232 cable port (same definition for microcomputer and instrument)

| Microcomputer (9-pins female) | Instrument (9-pins female) |
| :---: | :---: |
| 1 | 1 |
| 2 | 3 |
| 3 | 2 |
| 4 | 6 |
| 5 | 5 |
| 6 | 4 |
| 7 | 8 |
| 8 | 7 |
| 9 | Metal housing (connection with metal |
| shielding layer) |  |
| Metal housing |  |

## 2. Defination of RS-485 communication port




Figure 4-2: Definition of RS-485 cable port

| Microcomputer (9-pins female) | Instrument (9-pins female) |
| :---: | :---: |
| 1 | 2 |
| 2 | 3 |
| Metal housing | Metal housing (connection with metal |
| shielding layer) |  |

II. Ethernet communication port

| Interface | RJ-45 |
| :---: | :---: |
| Standard | IEEE802.3 |
| Protocol | UTP |
| Transmission rate | $10 / 100 \mathrm{Mbps}$ |

Notes: The communication address and baud rate of instrument shall be same as that of upper computer. The analyzer supports REXGEAR internal protocol, Modbus general protocol and Modbus/TCP protocol.

## Chapter 6: Communication protocol appendix

## I. Modbusrtu communication protocol

## 1. Query category

Note: (In the specification, X stands for channel no. 1-3 of power analyzer. It reads no more than 100 bytes each time, and can only be read continuously within range of each parameter. The harmonic content shall be read separately. The reading test parameters include voltage, current and BNC transformation ratio)

### 1.1 Frame format

1.1.1 Read contents of meter register (function code 03 H ) as shown in table 1:

| Sequence | Code | Example | Description |
| :---: | :--- | :--- | :--- |
| 1 | Instrument address | 01 H | nstrument communicationaddress (01H-FFH, <br> representing 1-255) |
| 2 | 03 H | 03 H | Function code (query) |
| 3 | High byte of starting register <br> address | 11 H |  |
| 4 | Low byte of starting register <br> address | 00 H | Starting address of register 1100H |
| 5 | High byte of number of registers | 00 H | Number of registers 02H |
| 6 | Low byte of number of registers | 02 H |  |
| 7 | Low byte of CRC16 check | C1H | CRC check data |
| 8 | High byte of CRC16 check | 37 H |  |

Table 1
1.1.2 The frame format (correct instruction) of instrument echo is shown in table 2:

| Sequence | Code | Description |
| :---: | :--- | :--- |
| 1 | Instrument address | nstrument communicationaddress (01H-FFH, <br> representing 1-255) |
| 2 | 03 H | Function code (query) |
| 3 | Echo data domain byte (M) |  |
| $\ldots-\cdot$ | First register data |  |
|  | Nth register data |  |
| $\mathrm{M}+4$ | Low byte of CRC16 check |  |
| $\mathrm{M}+5$ | High byte of CRC16 check |  |

Table 2
1.1.3 The query instruction is wrong, and the meter echo content is shown in table 3:

| Sequence | Code | Example | Description |
| :---: | :---: | :---: | :---: | :---: |
| 1 | Instrument address | 01 H | nstrument communicationaddress (01H-FFH, |

Chapter 5: Communication protocol appendix

|  |  |  | representing 1-255) |
| :--- | :--- | :--- | :--- |
| 2 | 83 H | 83 H | Function code (query instruction error) |
| 3 | 02 H | 02 H | Error code |
| 4 | Low byte of CRC check | C0H |  |
| 5 | High byte of CRC check | F1H |  |

Table 3
Error code:
01 H - Function code error
02 H ——Instruction length error
03 H ——eading register error

### 1.2 Description about register address

| Serial <br> numbe <br> r | Register <br> address <br> Hexadecimal | Data name | Data <br> Format | Register <br> Number | Number of bytes | Remarks | Descriptio <br> n |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 1 X 00 H | Valid value of voltage (V) | Float32 | 2 | 4 | Read-only | Normal parameter |
| 2 | 1 X 02 H | Valid value of current (mA) | Float32 | 2 | 4 | Read-only |  |
| 3 | 1X04H | Power (W) | Float32 | 2 | 4 | Read-only |  |
| 4 | 1X06H | Power factor | Float32 | 2 | 4 | Read-only |  |
| 5 | 1 X 08 H | Apparent power (Va) | Float32 | 2 | 4 | Read-only |  |
| 6 | $1 \mathrm{X0AH}$ | Reactive power (Var) | Float32 | 2 | 4 | Read-only |  |
| 7 | 1 X 0 CH | Voltage frequency (HZ) | Float32 | 2 | 4 | Read-only |  |
| 8 | $1 \mathrm{X0EH}$ | Current frequency (HZ) | Float32 | 2 | 4 | Read-only |  |
| 9 | 1 X 10 H | Phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |
| 10 | 1X12H | Rectified mean value of voltage (V) | Float32 | 2 | 4 | Read-only |  |
| 11 | 1X14H | Simple mean value of voltage (V) | Float32 | 2 | 4 | Read-only |  |
| 12 | 1X16H | High point of voltage peak (V) | Float32 | 2 | 4 | Read-only |  |
| 13 | 1X18H | Low point of voltage peak (V) | Float32 | 2 | 4 | Read-only |  |
| 14 | 1X1AH | Voltage peak (V) | Float32 | 2 | 4 | Read-only |  |
| 15 | $1 \mathrm{X1CH}$ | Rectified mean value of current (mA) | Float32 | 2 | 4 | Read-only |  |
| 16 | 1X1EH | Simple mean value of current (mA) | Float32 | 2 | 4 | Read-only |  |
| 17 | 1X20H | High point of current peak $(\mathrm{mA})$ | Float32 | 2 | 4 | Read-only |  |
| 18 | 1X22H | Low point of current peak $(\mathrm{mA})$ | Float32 | 2 | 4 | Read-only |  |
| 19 | 1X24H | Current peak (mA) | Float32 | 2 | 4 | Read-only |  |

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| 20 | 1X26H | Running time of electric energy - h | Float32 | 2 | 4 | Read-only | Electric <br> energy <br> parameter |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 21 | 1X28H | Running time of electric energy - min | Float32 | 2 | 4 | Read-only |  |
| 22 | 1X2AH | Running time of electric energy - s | Float32 | 2 | 4 | Read-only |  |
| 23 | 1 X 2 CH | Energy value of positive voltage (Wh) | Float32 | 2 | 4 | Read-only |  |
| 24 | 1X2EH | Energy value of negative voltage (Wh) | Float32 | 2 | 4 | Read-only |  |
| 25 | 1 X 30 H | Electric energy value (Wh) | Float32 | 2 | 4 | Read-only |  |
| 26 | 1X32H | Energy value of positive voltage (mAh) | Float32 | 2 | 4 | Read-only |  |
| 27 | 1 X 34 H | Energy value of negative voltage (mAh) | Float32 | 2 | 4 | Read-only |  |
| 28 | 1 X 36 H | Electric energy (mAh) | Float32 | 2 | 4 | Read-only |  |
| 29 | 1 X 38 H | RPM | Float32 | 2 | 4 | Read-only | Motor parameter |
| 30 | 1 X 3 AH | Torque ( Nm ) | Float32 | 2 | 4 | Read-only |  |
| 31 | $1 \mathrm{X3CH}$ | Mechanical work (W) | Float32 | 2 | 4 | Read-only |  |
| 32 | 1X3EH | Mechanical efficiency of each channel (\%) | Float32 | 2 | 4 | Read-only |  |
| 33 | 1X40H | Total mechanical efficiency of three phases (\%) | Float32 | 2 | 4 | Read-only |  |
| 34 | 2 X 00 H | Valid value of current base wave (mA) | Float32 | 2 | 4 | Read-only | Harmonic parameter |
| 35 | 2X02H | Valid value of voltage base wave (V) | Float32 | 2 | 4 | Read-only |  |
| 36 | 2X04H | Valid value of power base wave (W) | Float32 | 2 | 4 | Read-only |  |
| 37 | 2X06H | Total distortion of current harmonics (\%) | Float32 | 2 | 4 | Read-only |  |
| 38 | 2X08H | Total distortion voltage harmonics (\%) | Float32 | 2 | 4 | Read-only |  |
| 39 | 2X0AH | Total distortion power harmonics (\%) | Float32 | 2 | 4 | Read-only |  |
| 40 | $2 \mathrm{X0CH}$ | Apparent power of base wave (VA) | Float32 | 2 | 4 | Read-only |  |
| 41 | 2X0EH | Reactive power of base wave (var) | Float32 | 2 | 4 | Read-only |  |
| 42 | 2X10H | Power factor of base wave | Float32 | 2 | 4 | Read-only |  |
| 43 | 2X12H | U1-U2 phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |
| 44 | 2X14H | U2-U3 phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |
| 45 | 2X16H | U1-U3 phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |

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| 46 | 2X18H | I1-I2 phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 47 | $2 \mathrm{X1} 1 \mathrm{AH}$ | I2-I3 phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |
| 48 | 2X1CH | I1-I3 phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |
| 49 | 2X1E~4FH | Content of current harmonics *100(\%)(1~50, hexadecimal, back haul 0 BH , correspond to 12 , represent $0.12 \%$ ) | int | 50 | 100 | Read-only |  |
| 50 | 2X50~81H | Content of voltage harmonics *100(\%)(1~50, hexadecimal, back haul 0BH, correspond to 12 , represent $0.12 \%$ ) | int | 50 | 100 | Read-only |  |
| 51 | 3000H | Total voltage of three phases (V) | Float32 | 2 | 4 | Read-only |  |
| 52 | 3002H | Total current of three phases (mA) | Float32 | 2 | 4 | Read-only |  |
| 53 | 3004H | Total power of three phases (W) | Float32 | 2 | 4 | Read-only |  |
| 54 | 3006H | Power factor of three phases | Float32 | 2 | 4 | Read-only |  |
| 55 | 3008H | Apparent power of three phases (VA) | Float32 | 2 | 4 | Read-only |  |
| 56 | 300AH | Reactive power of three phases (var) | Float32 | 2 | 4 | Read-only | Threephase |
| 57 | 301 CH | Total Energy value of positive voltage (Wh) | Float32 | 2 | 4 | Read-only |  |
| 58 | 301EH | Total Energy value of negative voltage (Wh) | Float32 | 2 | 4 | Read-only |  |
| 59 | 3020H | Total Electric energy value (Wh) | Float32 | 2 | 4 | Read-only |  |
| 60 | 3022H | Total Energy value of positive voltage (mAh) | Float32 | 2 | 4 | Read-only |  |
| 61 | 3024H | Total Energy value of negative voltage (mAh) | Float32 | 2 | 4 | Read-only |  |
| 62 | 3026H | Total Electric energy (mAh) | Float32 | 2 | 4 | Read-only |  |

## Setting category (read-only)

| Serial | Register <br> address <br> number | Hexadeci <br> mal | Data name | Data |
| :---: | :---: | :--- | :---: | :---: | :---: | :---: | :---: |
| Format |  |  |  |  | | Register |
| :---: |
| Number | | Number |
| :---: |
| of bytes | | Remar |
| :---: |
| ks | | Descri |
| :---: |
| ption |

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| 3 | 5004H | Load type of 123 channel (range: 0-3, $0-$ 1P3W, 1-3P3W, 2-3P4W, 3-3V3A) | Float32 | 2 | 4 | Readonly | eter |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 4 | 5006H | $\begin{aligned} & \text { Calculation cycle (range } 0-6,0-0.1 \mathrm{~s}, 1-0.2 \mathrm{~s} \text {, } \\ & 2-0.5 \mathrm{~s}, 3-1 \mathrm{~s}, 4-2 \mathrm{~s}, 5-5 \mathrm{~s}, 6-10 \mathrm{~s} \text { ) } \end{aligned}$ | Float32 | 2 | 4 | Readonly |  |
| 5 | 5X08H | Voltage range of each channel. Range 0-7 representing 8 ranges of voltage, 8 for auto range. $\begin{aligned} & (0-15 \mathrm{~V}, 1-30 \mathrm{~V}, 2-60 \mathrm{~V}, 3-100 \mathrm{~V} \\ & 4-150 \mathrm{~V}, 5-300 \mathrm{~V}, 6-600 \mathrm{~V}, 7-1000 \\ & \mathrm{~V}) \end{aligned}$ | Float32 | 2 | 4 | Readonly |  |
| 6 | 5X0AH | Current range of each channel. Range 0-7 representing 8 ranges of current, 8 for auto range. $\begin{aligned} & (0-100 \mathrm{~mA}, 1-200 \mathrm{~mA}, 2-500 \mathrm{~mA}, 3-1 \mathrm{~A}, 4- \\ & 2 \mathrm{~A}, 5-5 \mathrm{~A}, 6-10 \mathrm{~A}, 7-20 \mathrm{~A}) \end{aligned}$ | Float32 | 2 | 4 | Readonly |  |
| 7 | 5X0CH | Current source of each channel (range 2-3, 2 BNC input, 3 - direct input) | Float32 | 2 | 4 | Readonly |  |
| 8 | 5X0EH | Sync source of each channel (range 0-5, $0-\mathrm{U} 1$, $1-\mathrm{A} 1,2-\mathrm{U} 2,3-\mathrm{A} 2,4-\mathrm{U} 3,5-\mathrm{A} 3)$ | Float32 | 2 | 4 | Readonly |  |
| 9 | 5010H | Harmonic source of each channel (range 0-5, 0 $\text { - U1, } 1 \text { - A1, } 2 \text { - U2, 3-A2, } 4 \text { - U3, } 5 \text { - A3) }$ | Float32 | 2 | 4 | Read- <br> only |  |
| 10 | 5012H | Harmonic switch (range 0-1, 0 - off (normal measurement), 1 - On (harmonic measurement) ) | Float32 | 2 | 4 | Readonly |  |
| 11 | 5014H | Line filter (range 0-2, 0-off, 1-500Hz, 2 - $5.5 \mathrm{kHz})$ | Float32 | 2 | 4 | Read- <br> only |  |
| 12 | 5016H | Frequency filter (range 0-1, 0 - off, 1-on) | Float32 | 2 | 4 | Readonly |  |
| 13 | 5018H | Max range of torque (range 0-10000, representing $0-1000.0 \mathrm{Nm}$ ) | Float32 | 2 | 4 | Readonly |  |
| 14 | 501AH | Max output frequency of torque (range 0-9999, representing $0-99.99 \mathrm{kHz}$ ) | Float32 | 2 | 4 | Readonly | Motor |
| 15 | 501CH | Max output frequency of torque (range 0-9999, representing $0-99.99 \mathrm{kHz}$ ) | Float32 | 2 | 4 | Read- <br> only | param |
| 16 | 501EH | Zero point of output frequency of torque (range $0-9999$, representing $0-99.99 \mathrm{kHz}$ ) | Float32 | 2 | 4 | Readonly | eter |
| 17 | 5020H | Number of pulses per turn of motor (range 01000 , representing $0-1000$ ) | Float32 | 2 | 4 | Read- <br> only |  |
| 18 | 5022H | Voltage transformation ratio (range 10-50000, representing 1.0-5000.0) | Float32 | 2 | 4 | Readonly | Transf |
| 19 | 5024H | Current transformation ratio (range 10-50000, representing 1.0-5000.0) | Float32 | 2 | 4 | Readonly |  |

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| 20 | 5026H | BNC transformation ratio (range 10-100000, representing $0.010-100.000 \mathrm{mV} / \mathrm{A}$ ) | Float32 | 2 | 4 | Read- <br> only | on <br> ratio <br> param <br> eter |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

### 1.3 Example of instrument communication data (all data below will be in hexadecimal)

(1) Read instrument voltage (channel 1):

A, Send from upper machine

| 01H | 03H | 11H | 00H | 00H | 02H | C1H | 37H |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Instrument <br> address | Command | Starting register address, high, low bytes |  | Number of register, high, low bytes |  | CRC check, low, high bytes |  |

B, Data returned from instrument: Voltage $=238.97 \mathrm{~V}$

| 01 H | 03 H | 04 H | 43 H | 6 EH | F 8 H | A 0 H | CDH | D 2 H |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Instrument <br> address | Command | Number of <br> bytes | Float32 data, high byte in front |  |  |  | CRC check code |  |

(2) Read instrument voltage, current and power:

A, Send from upper machine
$\left.\begin{array}{c|c|c|c|c|c|c}\hline 01 \mathrm{H} & 03 \mathrm{H} & 11 \mathrm{H} & 00 \mathrm{H} & 00 \mathrm{H} & 06 \mathrm{H} & \mathrm{C} 0 \mathrm{H}\end{array}\right) \mathrm{F4H}$

B, Data returned from instrument: Voltage $=230.8 \mathrm{~V}$, current $=4.089 \mathrm{~A}$, power $=943.88 \mathrm{~W}$

| 01 H | 03 H | 0 CH | $43,66, \mathrm{CD}, \mathrm{C} 8-40,82, \mathrm{DD}, 6 \mathrm{E}-44,6 \mathrm{~B}, \mathrm{~F} 8,45$ | 6 FH | A 2 H |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Instrument | Command | Number | Float32 data, high byte in front | CRC check code |  |
| address |  | of bytes |  |  |  |

## 2. Setting category

## 2.1 frame format

2.1.1 Set contents of meter register (function code 06 H ) as shown in table 4:

| Sequence | Code | Example | Description |
| :---: | :--- | :--- | :--- | :--- |
| 1 | Instrument address | 01 H | nstrument <br> remmunicationaddress $\quad(01 H-F F H$ <br> $~ r e p r e s e n t i n g ~ 1-255) ~$ |

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|  |  |  |  |
| :--- | :--- | :--- | :--- |
| 2 | 06 H | 06 H | Function code (setting) |
| 3 | High byte of starting register address | 20 H | Register address 2000H |
| 4 | Low byte of starting register address | 00 H |  |
| 5 | Write high byte of data | 00 H | Write data 01H Write data of BNC transformation |
| 6 | Write low byte of data | 01 H |  |
| 7 | Low byte of CRC16 check | 43 H | CRC check data |
| 8 | High byte of CRC16 check | CAH |  |

Table 4
2.1.2 Frame format of instrument echo: If written correctly, the meter will echo with same frame format as given in table 4.
2.1.3 The setting instruction is wrong, and the instrument echo is shown in table 5:

| Sequence | Code | Example | Description |
| :---: | :--- | :--- | :--- |
| 1 | Instrument address | 01 H | nstrument communicationaddress (01H- |
| 2 | 86 H | FFH, representing 1-255) |  |
| 3 | 03 H | 03 H | Error code |
| 4 | High byte of CRC check | 02 H |  |
| 5 | Low byte of CRC check | 61 H |  |

Table 5
Error code:
01 H —— Function code error
02 H - Instruction length error
$03 \mathrm{H} —$ Reading register error
04 H —— Error of setting beyond range

### 2.2 Register address description

| Serial number | Register <br> address <br> Hexadeci <br> mal | Data name | Data <br> Forma <br> t | Register <br> Number | Number <br> of bytes | Remar <br> ks | Descri ption |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 4000H | Integral time (range in minutes: 0-2880, 48h) | int32 | 1 | 2 | Write only |  |
| 2 | 4001H | Integral state <br> (Range 0-2, 0 - zeroing, 1 - starting, 2 - stopping) | int32 | 1 | 2 | Write only |  |
| 3 | 4002H | Load type of 123 channel (range: 0-3, 0-1P3W $, 1-3 \mathrm{P} 3 \mathrm{~W}, 2-3 \mathrm{P} 4 \mathrm{~W}, 3-3 \mathrm{~V} 3 \mathrm{~A})$ | int32 | 1 | 2 | Write only |  |

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| 4 | 4003H | Calculation cycle (range 0-6, 0-0.1s, $1-0.2 \mathrm{~s}, 2$ - $0.5 \mathrm{~s}, 3-1 \mathrm{~s}, 4-2 \mathrm{~s}, 5-5 \mathrm{~s}, 6-10 \mathrm{~s})$ | int32 | 1 | 2 | Write only |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 5 | 4004H | Voltage range of each channel. Range 0-7 representing 8 ranges of voltage, 8 for auto range. $\begin{aligned} & (0-15 \mathrm{~V}, ~ 1-30 \mathrm{~V}, 2-60 \mathrm{~V}, 3-100 \mathrm{~V}, 4- \\ & 150 \mathrm{~V}, 5-300 \mathrm{~V}, 6-600 \mathrm{~V}, 7-1000 \mathrm{~V}) \end{aligned}$ | int32 | 1 | 2 | Write only |  |
| 6 | 4005H | Current range of each channel. Range 0-7 representing 8 ranges of current, 8 for auto range. $(0-100 \mathrm{~mA}, 1-200 \mathrm{~mA}, 2-500 \mathrm{~mA}, 3-1 \mathrm{~A}, 4-$ <br> 2A, $5-5 \mathrm{~A}, 6-10 \mathrm{~A}, 7-20 \mathrm{~A}$ ) | int32 | 1 | 2 | Write only |  |
| 7 | 4006H | Current source of each channel (range 2-3, 2 BNC input, 3 - direct input) | int32 | 1 | 2 | Write only |  |
| 8 | 4007H | Sync source of each channel (range 0-5, 0-U1, 1 $-\mathrm{A} 1,2-\mathrm{U} 2,3-\mathrm{A} 2,4-\mathrm{U} 3,5-\mathrm{A} 3)$ | int32 | 1 | 2 | Write only |  |
| 9 | 4008H | Harmonic source of each channel (range 0-5, 0 - $\mathrm{U} 1,1-\mathrm{A} 1,2-\mathrm{U} 2,3-\mathrm{A} 2,4-\mathrm{U} 3,5-\mathrm{A} 3)$ | int32 | 1 | 2 | Write only |  |
| 10 | 4009H | Harmonic siwtch (range 0-1, 0 - off (normal measurement), 1 - On (harmonic measurement) ) | int32 | 1 | 2 | Write only | Contr <br> ol |
| 11 | 400AH | Frequency filter for channel 1 (range $0-1,0$ - off, $1 \text { - on) }$ | int32 | 1 | 2 | Write <br> only | specifi <br> c |
| 12 | 400BH | Line filter for channel 1 (range 0-2, 0 - off, 1 $500 \mathrm{~Hz}, 2-5.5 \mathrm{kHz}$ ) | int32 | 1 | 2 | Write <br> only | param eter |
| 13 | 400 CH | Max range of torque (range $0-10000$, representing $0-1000.0 \mathrm{Nm})$ | int32 | 1 | 2 | Write <br> only | Motor |
| 14 | 400DH | Max output frequency of torque (range 0-9999, representing $0-99.99 \mathrm{kHz}$ ) | int32 | 1 | 2 | Write <br> only | setting param |
| 15 | 400EH | Max output frequency of torque (range 0-9999, representing $0-99.99 \mathrm{kHz}$ ) | int32 | 1 | 2 | Write only | eter |
| 16 | 400FH | Zero point of output frequency of torque (range <br> $0-9999$, representing $0-99.99 \mathrm{kHz}$ ) | int32 | 1 | 2 | Write only |  |
| 17 | 4010H | Number of pulses per turn of motor (range 0- <br> 1000 , representing $0-1000$ ) | int32 | 1 | 2 | Write <br> only |  |
| 18 | 4011H | Voltage transformation ratio (range 10-50000, representing 1.0-5000.0) | int32 | 1 | 2 | Write only | Transf ormati |
| 19 | 4012H | Current transformation ratio (range 10-50000, representing 1.0-5000.0) | int32 | 1 | 2 | Write only | $\begin{gathered} \text { on } \\ \text { ratio } \end{gathered}$ |

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| 20 | 4013 H | BNC transformation ratio (range 10-100000, <br> representing 0.010-100.000) | int32 | 2 | 4 | Write |
| :--- | :---: | :--- | :--- | :--- | :--- | :---: |
| only |  |  |  |  |  |  | | param |
| :---: |
| eter |

### 2.3 Example of instrument communication data (all data below will be in hexadecimal)

(1) Set load type for channel 1, 2, 3:

Send from upper machine: Set to 1P3W
$\left.\begin{array}{c|c|c|c|c|c|c}\hline 01 \mathrm{H} & 06 \mathrm{H} & 40 \mathrm{H} & 02 \mathrm{H} & 00 \mathrm{H} & 01 \mathrm{H} & \mathrm{FCH}\end{array}\right) 0 \mathrm{AH}$
(2) Set voltage range:

Send from upper machine: Set to 30 V

| 01H | 06H | 40H | 04H | 00H | 01H | 1 CH | 0BH |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Instrument address | Command | Starting register address, high, low bytes |  | 2-bytes data bit |  | CRC check, low, high bytes |  |

## II. ModbusTCP communication specification

## 1. Query category

Note: (In the specification, X stands for channel no. 1-3 of power analyzer. It reads no more than 100 bytes each time, and can only be read continuously within range of each parameter. The harmonic content shall be read separately. The reading test parameters include voltage, current and BNC transformation ratio)

### 1.1 Frame format

1.1.1 Read contents of meter register (function code 03 H ) as shown in table 1:

| Sequence (byte) | Code | Example | Description |
| :---: | :---: | :---: | :---: |
| 1 | High byte of transaction processing identifier | 00H | Identification for Modbus request response/response transaction processing (client generation, service machine returns original value) |
| 2 | Low byte of transaction processing identifier | 01H |  |
| 3 | High byte of protocol identifier | 00H | $0000 \mathrm{H}=$ Modbus protocol |
| 4 | Low byte of protocol identifier | 00H |  |
| 5 | High byte of frame data length | 00H | Start calculating length from $7^{\text {th }}$ byte |
| 6 | Low byte of frame data length | 06H |  |
| 7 | Instrument address | 01H | Nstrument communicationaddress ( $01 \mathrm{H}-\mathrm{FFH}$, representing 1-255) |
| 8 | Function code | 03H | Function code (query) |
| 9 | High byte of starting register | 11H | Starting address of register 1100 H |

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| Chapter 5: Communication protocol appendix |  |  |  |
| :---: | :--- | :---: | :---: |
|  | address |  |  |
| 10 | Low byte of starting register <br> address | 00 H |  |
| 11 | High byte of number of registers | 00 H | Number of registers 02 H |
| 12 | Low byte of number of registers | 02 H |  |

Table 1
1.1.2 The frame format (correct instruction) of instrument echo is shown in table 2:

| Sequence (byte) | Code | Description |  |
| :---: | :--- | :--- | :--- |
| 1 | High byte of transaction processing identifier | Identification for Modbus request response/response |  |
| transactionprocessing (client <br> generation, service |  |  |  |
| 2 | Low byte of transaction processing identifier | machine returns original value) |  |

Table 2
1.1.3 The query instruction is wrong, and the meter echo content is shown in table 3:

| Sequence | Code | Example | Description |  |
| :---: | :--- | :---: | :--- | :---: |
| 1 | High byte of transaction <br> processing identifier | 00 H | Identification for Modbus request response/response <br> transaction processing (client generation, service <br> machine returns original value) |  |
| 2 | Low byte of transaction <br> processing identifier | 01 H |  |  |
| 3 | High byte of protocol identifier | 00 H | $0000 \mathrm{H}=$ Modbus protocol |  |

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| 8 | 83 H | 83 H | Function code (query instruction error) |
| :---: | :--- | :---: | :--- |
| 9 | 02 H | 02 H | Error code |

Table 3
Error code:
01 H —— Function code error
02 H - Instruction length error
$03 \mathrm{H}-$ Reading register error

### 1.2 Description about register address

| Serial numbe <br> r | Register <br> address <br> Hexadecimal | Data name | Data <br> Format | Register <br> Number | Number <br> of bytes | Remarks | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 1X00H | Valid value of voltage (V) | Float32 | 2 | 4 | Read-only | Normal parameter |
| 2 | 1X02H | Valid value of current (mA) | Float32 | 2 | 4 | Read-only |  |
| 3 | 1X04H | Power (W) | Float32 | 2 | 4 | Read-only |  |
| 4 | 1X06H | Power factor | Float32 | 2 | 4 | Read-only |  |
| 5 | 1X08H | Apparent power (Va) | Float32 | 2 | 4 | Read-only |  |
| 6 | $1 \mathrm{X0AH}$ | Reactive power (Var) | Float32 | 2 | 4 | Read-only |  |
| 7 | 1X0CH | Voltage frequency (HZ) | Float32 | 2 | 4 | Read-only |  |
| 8 | 1X0EH | Current frequency (HZ) | Float32 | 2 | 4 | Read-only |  |
| 9 | 1X10H | Phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |
| 10 | 1X12H | Rectified mean value of voltage <br> (V) | Float32 | 2 | 4 | Read-only |  |
| 11 | 1X14H | Simple mean value of voltage (V) | Float32 | 2 | 4 | Read-only |  |
| 12 | 1X16H | High point of voltage peak (V) | Float32 | 2 | 4 | Read-only |  |
| 13 | 1X18H | Low point of voltage peak (V) | Float32 | 2 | 4 | Read-only |  |
| 14 | 1 X 1 AH | Voltage peak (V) | Float32 | 2 | 4 | Read-only |  |
| 15 | $1 \mathrm{X1CH}$ | Rectified mean value of current $(\mathrm{mA})$ | Float32 | 2 | 4 | Read-only |  |
| 16 | 1X1EH | Simple mean value of current $(\mathrm{mA})$ | Float32 | 2 | 4 | Read-only |  |
| 17 | 1X20H | High point of current peak (mA) | Float32 | 2 | 4 | Read-only |  |
| 18 | 1X22H | Low point of current peak (mA) | Float32 | 2 | 4 | Read-only |  |
| 19 | 1X24H | Current peak (mA) | Float32 | 2 | 4 | Read-only |  |
| 20 | 1X26H | Running time of electric energy $-\mathrm{h}$ | Float32 | 2 | 4 | Read-only | Electric energy |
| 21 | 1X28H | Running time of electric energy $-\min$ | Float32 | 2 | 4 | Read-only | parameter |

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| 22 | 1X2AH | Running time of electric energy -s | Float32 | 2 | 4 | Read-only |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 23 | 1X2CH | Energy value of positive voltage (Wh) | Float32 | 2 | 4 | Read-only |  |
| 24 | 1X2EH | Energy value of negative voltage (Wh) | Float32 | 2 | 4 | Read-only |  |
| 25 | 1 X 30 H | Electric energy value (Wh) | Float32 | 2 | 4 | Read-only |  |
| 26 | 1X32H | Energy value of positive voltage $(\mathrm{mAh})$ | Float32 | 2 | 4 | Read-only |  |
| 27 | 1X34H | Energy value of negative voltage (mAh) | Float32 | 2 | 4 | Read-only |  |
| 28 | 1 X 36 H | Electric energy (mAh) | Float32 | 2 | 4 | Read-only |  |
| 29 | 1 X 38 H | RPM | Float32 | 2 | 4 | Read-only |  |
| 30 | 1 X 3 AH | Torque (Nm) | Float32 | 2 | 4 | Read-only |  |
| 31 | 1 X 3 CH | Mechanical work (W) | Float32 | 2 | 4 | Read-only |  |
| 32 | 1X3EH | Mechanical efficiency of each channel (\%) | Float32 | 2 | 4 | Read-only | Motor parameter |
| 33 | 1X40H | Total mechanical efficiency of three phases (\%) | Float32 | 2 | 4 | Read-only |  |
| 34 | 2X00H | Valid value of current base wave (mA) | Float32 | 2 | 4 | Read-only |  |
| 35 | 2X02H | Valid value of voltage base wave (V) | Float32 | 2 | 4 | Read-only |  |
| 36 | 2X04H | Valid value of power base wave (W) | Float32 | 2 | 4 | Read-only |  |
| 37 | 2X06H | Total distortion of current harmonics (\%) | Float32 | 2 | 4 | Read-only |  |
| 38 | 2X08H | Total distortion voltage harmonics (\%) | Float32 | 2 | 4 | Read-only | Harmonic parameters |
| 39 | 2X0AH | Total distortion power harmonics (\%) | Float32 | 2 | 4 | Read-only |  |
| 40 | $2 \mathrm{X0CH}$ | Apparent power of base wave (VA) | Float32 | 2 | 4 | Read-only |  |
| 41 | 2X0EH | Reactive power of base wave (var) | Float32 | 2 | 4 | Read-only |  |
| 42 | $2 \mathrm{X10H}$ | Power factor of base wave | Float32 | 2 | 4 | Read-only |  |
| 43 | 2X12H | U1-U2 phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |
| 44 | 2X14H | U2-U3 phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |

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| 45 | 2X16H | U1-U3 phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 46 | 2 X 18 H | I1-I2 phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |
| 47 | 2X1AH | I2-I3 phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |
| 48 | $2 \mathrm{X1CH}$ | I1-I3 phase angle ( ${ }^{\circ}$ ) | Float32 | 2 | 4 | Read-only |  |
| 49 | 2X1E~4FH | Content of current harmonics *100(\%) (1~50, hexadecimal, back haul 0 BH , correspond to 12 , represent $0.12 \%$ ) | int | 50 | 100 | Read-only |  |
| 50 | 2X50~81H | Content of voltage harmonics *100(\%) (1~50, hexadecimal, back haul 0 BH , correspond to 12 , represent $0.12 \%$ ) | int | 50 | 100 | Read-only |  |
| 51 | 3000H | Total voltage of three phases (V) | Float32 | 2 | 4 | Read-only |  |
| 52 | 3002H | Total current of three phases $(\mathrm{mA})$ | Float32 | 2 | 4 | Read-only |  |
| 53 | 3004H | Total power of three phases (W) | Float32 | 2 | 4 | Read-only |  |
| 54 | 3006H | Power factor of three phases | Float32 | 2 | 4 | Read-only |  |
| 55 | 3008H | Apparent power of three phases (VA) | Float32 | 2 | 4 | Read-only |  |
| 56 | 300AH | Reactive power of three phases (var) | Float32 | 2 | 4 | Read-only | Three-phase |
| 57 | 301 CH | Total Energy value of positive voltage (Wh) | Float32 | 2 | 4 | Read-only | parameter |
| 58 | 301EH | Total Energy value of negative voltage (Wh) | Float32 | 2 | 4 | Read-only |  |
| 59 | 3020H | Total Electric energy value $(\mathrm{Wh})$ | Float32 | 2 | 4 | Read-only |  |
| 60 | 3022H | Total Energy value of positive voltage (mAh) | Float32 | 2 | 4 | Read-only |  |
| 61 | 3024H | Total Energy value of negative voltage (mAh) | Float32 | 2 | 4 | Read-only |  |
| 62 | 3026H | Total Electric energy (mAh) | Float32 | 2 | 4 | Read-only |  |

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## Setting category (read-only)

| Rerial | Register <br> address <br> nember <br> Hexadeci <br> mal |  | Data name | Data <br> Register <br> Number | Number <br> of bytes | Remar <br> ks |
| :---: | :---: | :--- | :--- | :--- | :--- | :--- |
| 12 | 5000 H | Integral time (range in minutes: 0-5000) | Fescri |  |  |  |
| ption |  |  |  |  |  |  |

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| 15 | 501CH | Max output frequency of torque (range 0-9999, representing $0-99.99 \mathrm{kHz}$ ) | Float32 | 2 | 4 | Readonly | Motor <br> param <br> eter |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 16 | 501EH | Zero point of output frequency of torque (range $0-9999$, representing $0-99.99 \mathrm{kHz}$ ) | Float32 | 2 | 4 | Read- <br> only |  |
| 17 | 5020H | Number of pulses per turn of motor (range 01000 , representing $0-1000$ ) | Float32 | 2 | 4 | Read- <br> only |  |
| 18 | 5022H | Voltage transformation ratio (range 10-50000, representing 1.0-5000.0) | Float32 | 2 | 4 | Read- <br> only | Transf |
| 19 | 5024H | Current transformation ratio (range 10-50000, representing 1.0-5000.0) | Float32 | 2 | 4 | Readonly | ormati <br> on |
| 20 | 5026H | BNC transformation ratio (range 10-100000, representing $0.010-100.000 \mathrm{mV} / \mathrm{A}$ ) | Float32 | 2 | 4 | Read- <br> only | ratio <br> param <br> eter |

### 1.3 Example of instrument communication data (all data below will be in hexidecimal)

(1) Read instrument voltage (channel 1):

A, Send from upper machine

| 0001 H | 0000 H | 0006 H | 01 H | 03 H | 11 H | 00 H | 00 H | 02 H |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Transaction | Modbus | Frame data |  |  |  |  |  |  |
| processing | protocol | length | Instrument |  | Starting register address, | Number of register, high, low |  |  |
| identifier |  |  | hadress |  | high, low bytes | bytes |  |  |

B, Data returned from instrument: Voltage=238.97V

| 0001H | 0000H | 0007H | 01H | 03H | 04H | 43H | 6EH | F8H | A0H |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Transaction | Modbus | Frame data |  |  |  | Float32 data, high byte in front |  |  |  |
| processing <br> identifier | protocol | length | address | Command | bytes |  |  |  |  |

(2) Read instrument voltage, current and power:

A, Send from upper machine

| 0001 H | 0000 H | 0006 H | 01 H | 03 H | 11 H | 00 H | 00 H | 06 H |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Transaction | Modbus | Frame data | Instrument |  | Comand |  |  |  |
| processing |  |  |  |  |  |  |  |  |
| identifier | protocol | length | Starting register address, <br> high, low bytes | Number of register, high, low <br> bytes |  |  |  |  |

B, Data returned from instrument: Voltage $=230.8 \mathrm{~V}$, current $=4.089 \mathrm{~A}$, power $=943.88 \mathrm{~W}$

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| 0001 H | 0000 H | 000 FH | 01 H | 03 H | 0 CH | $43,66, \mathrm{CD}, \mathrm{C} 8-40,82, \mathrm{DD}, 6 \mathrm{E}-44,6 \mathrm{~B}, \mathrm{~F} 8,45$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Transaction | Modbus | Frame data | Instrument | Command | Number of | Float32 data, high byte in front |
| processing | protocol | length | address |  | bytes |  |
| identifier |  |  |  |  |  |  |

## 2. Setting category

## 2.1 frame format

2.1.1 Set contents of meter register (function code 06 H ) as shown in table 4:


Table 4
2.1.2 Frame format of instrument echo: If written correctly, the meter will echo with same frame format as given in table 4.
2.1.3 The setting instruction is wrong, and the instrument echo is shown in table 5:


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| 2 | Low byte of transaction processing | 01 H | (client generation, service machine returns |
| :---: | :--- | :---: | :---: |
| identifier | High byte of protocol identifier | 00 H | $0000 \mathrm{H}=$ Modbus protocol |
| 3 | Low byte of protocol identifier | 00 H |  |
| 4 | High byte of frame data length | 00 H | Start calculating length from 7 byte |
| 5 | Low byte of frame data length | 03 H |  |
| 7 | Instrument address | 01 H | nstrument communicationaddress (01H-FFH, |
| 8 | 86 H | representing 1-255) |  |
| 9 | 03 H | 03 H | Error code |

Table 5
Error code:
01 H —Function code error
02 H - Instruction length error
$03 \mathrm{H}-$ Reading register error
04 H _Error of setting beyond range

### 2.2 Register address description

| Serial <br> number | Register <br> address <br> Hexadeci <br> mal | Data name | Data <br> Forma <br> t | Register <br> Number | Number of bytes | Remar <br> ks |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 4000H | Integral time (range in minutes: 0-2880, 48h) | int32 | 1 | 2 | Write only |  |
| 2 | 4001H | Integral state (Range 0-2, 0 - zeroing, 1 - starting, 2 - stopping) | int32 | 1 | 2 | Write only |  |
| 3 | 4002H | $\begin{aligned} & \text { Load type of } 123 \text { channel (range: } 0-3, ~ 0-1 \mathrm{P} 3 \mathrm{~W} \\ & , 1-3 \mathrm{P} 3 \mathrm{~W}, ~ 2-3 \mathrm{P} 4 \mathrm{~W}, ~ 3-3 \mathrm{~V} 3 \mathrm{~A} \text { ) } \end{aligned}$ | int32 | 1 | 2 | Write only |  |
| 4 | 4003H | Calculation cycle (range 0-6, 0-0.1s, 1-0.2s, 2 - $0.5 \mathrm{~s}, 3-1 \mathrm{~s}, 4-2 \mathrm{~s}, 5-5 \mathrm{~s}, 6-10 \mathrm{~s})$ | int32 | 1 | 2 | Write only |  |
| 5 | 4004H | Voltage range of each channel. Range 0-7 representing 8 ranges of voltage, 8 for auto range. $\begin{aligned} & (0-15 \mathrm{~V}, 1-30 \mathrm{~V}, 2-60 \mathrm{~V}, 3-100 \mathrm{~V}, 4- \\ & 150 \mathrm{~V}, 5-300 \mathrm{~V}, 6-600 \mathrm{~V}, 7-1000 \mathrm{~V}) \\ & \hline \end{aligned}$ | int32 | 1 | 2 | Write only |  |
| 6 | 4005H | Current range of each channel. Range 0-7 representing 8 ranges of current, 8 for auto range. | int32 | 1 | 2 | Write only |  |

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|  |  | $\begin{aligned} & (0-100 \mathrm{~mA}, 1-200 \mathrm{~mA}, 2-500 \mathrm{~mA}, 3-1 \mathrm{~A}, 4- \\ & 2 \mathrm{~A}, 5-5 \mathrm{~A}, 6-10 \mathrm{~A}, 7-20 \mathrm{~A}) \end{aligned}$ |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | 4006H | Current source of each channel (range 2-3, 2 BNC input, 3 - direct input) | int32 | 1 | 2 | Write only |  |
| 8 | 4007H | Sync source of each channel (range 0-5, 0-U1, 1 $\text { - A1, } 2 \text { - U2, } 3 \text { - A2, } 4 \text { - U3, } 5 \text { - A3) }$ | int32 | 1 | 2 | Write only |  |
| 9 | 4008H | Harmonic source of each channel (range 0-5, 0 - $\text { U1, } 1 \text { - A1, } 2 \text { - U2, } 3 \text { - A2, } 4-\mathrm{U} 3,5-\mathrm{A} 3)$ | int32 | 1 | 2 | Write only |  |
| 10 | 4009H | Harmonic siwtch (range 0-1, 0 - off (normal measurement), 1 - On (harmonic measurement) | int32 | 1 | 2 | Write <br> only | Contr <br> ol |
| 11 | 400AH | Line filter for channel 1 (range 0-2, 0-off, 1 $500 \mathrm{~Hz}, 2-5.5 \mathrm{kHz})$ | int32 | 1 | 2 | Write <br> only | specifi <br> c |
| 12 | 400BH | Frequency filter for channel 1 (range $0-1,0$ - off, $1 \text { - on) }$ | int32 | 1 | 2 | Write only | param eter |
| 13 | 400 CH | Max range of torque (range $0-10000$, representing $0-1000.0 \mathrm{Nm})$ | int32 | 1 | 2 | Write <br> only |  |
| 14 | 400DH | Max output frequency of torque (range 0-9999, representing $0-99.99 \mathrm{kHz}$ ) | int32 | 1 | 2 | Write only |  |
| 15 | 400EH | Max output frequency of torque (range 0-9999, representing $0-99.99 \mathrm{kHz}$ ) | int32 | 1 | 2 | Write <br> only | setting |
| 16 | 400FH | Zero point of output frequency of torque (range <br> $0-9999$, representing $0-99.99 \mathrm{kHz}$ ) | int32 | 1 | 2 | Write only | eter |
| 17 | 4010H | Number of pulses per turn of motor (range 0 1000 , representing $0-1000$ ) | int32 | 1 | 2 | Write <br> only |  |
| 18 | 4011H | Voltage transformation ratio (range 10-50000, representing 1.0-5000.0) | int32 | 1 | 2 | Write only | Transf ormati |
| 19 | 4012H | Current transformation ratio (range 10-50000, representing 1.0-5000.0) | int32 | 1 | 2 | Write <br> only | on ratio |
| 20 | 4013H | BNC transformation ratio (range 10-100000, representing $0.010-100.000$ ) | int32 | 2 | 4 | Write only | param eter |

### 2.3 Example of instrument communication data (all data below will be in hexidecimal)

(1) Set load type for channel 1, 2, 3:

Send from upper machine: Set to 1P3W

| 0001 H | 0000 H | 0006 H | 01 H | 06 H | 40 H | 01 H | 00 H | 00 H |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Transaction | Modbus | Frame data | Instrument | Comm | Starting register address, |  |  |  |
| processing | protocol | length | address | and | high, low bytes | 2-bytes data bit |  |  |


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| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| identifier |  |  |  |  |  |  |

(2) Set voltage range (channel 1):

Send from upper machine: Set to 30V


## III. REXGEAR communication protocol

## 1. Protocol description

### 1.1 Communication function test

Connect the measuring instrument with upper computer, and open software of upper computer. Before starting communication function test, please set the measuring instrument as required: In "SETUP", communication address (Addr) is set to 1, Baud rate is set to 38400 (or consistent with ones in software of upper computer). After successful setting, return to standby mode.

Note: For other commands and detailed format, see contents below.

### 1.2 Communication handshake protocol

In the measurement and control network consisting of upper computer (PC) and lower computer (87330 measuring instrument), each communication is initiated by upper computer first, and ended with response of lower computer. One-way handshake protocol is adopted.


Figure A-1: Handshake protocol

### 1.3 Communication data format

1, Communication baud rate can be set to $9600,19200,38400$ manually, default setting is 38400 .
2, Address of this mache can be set at will, the range is $1 \sim 255$.
3, Data frame format is: One starting bit, seven data bits, one stop bit, total 10 bits.
4, Communication can be divided into two types: receiving information and transmitting information. The unified information format is as follows:

| Frame head | Total number of bytes | Slave address | Command |  |  | Check sum | Frame end |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Class | Comman d word | Parameters |  |  |
| 0x7B | 0xXXXX | 0xXX | 0xXX | 0xXX | $\begin{gathered} 0 \mathrm{xXXXXX} \\ \mathrm{X} \end{gathered}$ | 0xXX | 0x7D |

Frame head: 1 byte, fixed at $0 \times 7 \mathrm{~B}$, the ASCII code of ' $\{$ '.
Total number of bytes: 2 bytes, the value is the sum of "frame head + Total number of bytes + slave

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address + command Class + command word + command parameter + check sum+ frame end" bytes. The high bytes first, and the low bytes last.

Address: 1 byte, communication address of measurement apparatus.
Command <parameter> string: Different byte length, the length of each command is shown in "Communication Command Description".

Check sum: 1 byte (hexadecimal), the check result for the sent data. Horizontal check is adopted, that is, the sum of total bytes + address + command $<$ parameter $>$ string, and low byte is taken as the check sum.

Frame end: 1 byte, fixed to $0 x 7 \mathrm{D}$, the ASCII code of ' $\{$ '.
Table A-1: Communication command description

| Command |  |  | Functions |
| :---: | :---: | :---: | :---: |
| Class | Command word | Parameters |  |
| Query category (0xF1) | 0x00 | 1 byte (channel no.) | Query normal measurement parameter (including transformation ratio ) |
|  | 0x01 | 1 byte (channel no.) | Query relevant parameters of electric energy |
|  | $0 \times 02$ | 1 byte (channel no.) | Query parameters in three-phases (including transformation ratio ) |
|  | 0x03 | 1 byte (channel no.) | Query relevant parameters of motor |
|  | 0x04 | 1 byte (channel no.) | Query harmonic parameter |
|  | 0x05 | - | Query phase angle |
|  | 0x06 | - | Query overview test data (including transformation ratio ) |
| Setting category (0x5A) | 0x00 | 2 bytes (setting data) | Setting specific command set |
|  | $0 \times 01$ | 50 bytes (setting data) | Setting alarm specific parameters |

## ATTENTION

When accumulation of electric energy is not started or reset, it is not allowed to set transformation ratio, calculation mode, calculation cycle, current threshold for accumulation of electric energy, and timing for electric energy.

## A.4.1 Query specific commands (0xF1)

(1) Query normal measurement parameter (including transformation ratio)

Command character: $0 \times 00$
Function: Query all normal measurement parameters
Query valid voltage value ( 6 bytes) for current channel, valid current value ( 6 bytes), active power ( 8 bytes), power factor ( 2 bytes), apparent power ( 8 bytes), reactive power ( 6 bytes), phase angle ( 2 bytes), voltage frequency ( 4 bytes), current frequency ( 4 bytes), rectified mean value of voltage ( 6 bytes), DC component of voltage ( 6 bytes), positive voltage peak ( 6 bytes),,negative voltage peak ( 6 bytes), voltage peak ( 6 bytes), rectified mean value of current ( 6 bytes), DC component of current ( 6 bytes), positive current peak ( 6 bytes), negative current peak ( 6 bytes), current peak ( 6 bytes) in turn.

Sample: Receive by this machine-_7B 00
Transmit from this machine_-7B 007301 F1 000100000000 E6 $61000000039 B$
34000000000002 1F 3526 F8 000000000002207 A 0000000025280027
0000 C 7 3A $0000 \mathrm{C7} 3 \mathrm{~A} 000000000000000000000000000000014620 \mathrm{FF}$
FF FF FE B9 E7 00000001462000000000 2C DB 00000000 2C DB 00000005
B8 71 FF FF FF FB 1C B6 00000005 B8 71 XX 7D
Instructions for receiving: Underline byte $\underline{01}$ represents channel to be queried, range is $01-03$, representing CH1CH3.
Instructions for transmitting:

1) Byte $00 \underline{000000 \mathrm{E} 661}$ corresponds to 58977 , representing valid voltage value
58.977 V ;
2) Byte $00 \underline{0000039 B 34}$ corresponds to 236340, representing valid current value 236.340 mA ;
3) Byte $00 \underline{00000000021 F 35}$ corresponds to 139061, representing active power 13.9061W;
4) Byte 26 F8 corresponds to 9976 , representing power factor 0.9976 ;
5) Byte $00 \underline{0000000002207 \mathrm{~A}}$ corresponds to 139386, representing apparent power 13.9386;
6) Byte $00 \underline{0000002528}$ corresponds to 9512 , representing reactive power 0.9512 ;
7) Byte $00 \underline{27}$ corresponds to 39 , representing phase angle $3.9^{\circ}$;
8) Byte 0000 C 73 A corresponds to 51002 , representing voltage frequency 51.002 Hz ;
9) Byte 0000 C 73 A corresponds to 51002 , representing current frequency 51.002 Hz ;
10) Byte 000000000000 corresponds to 0 , representing rectified mean value of voltage 0.000 V ;
11) Byte 000000000000 corresponds to 0 , representing DC component of voltage 0.000 V ;
12) Byte $00 \underline{0000014620}$ corresponds to 83488 , representing positive voltage peak 83.488 V ;
13) Byte FF FF FF FE B9 E7 corresponds to -83481, representing negative voltage peak -83.481V;
14) Byte $00 \underline{0000014620}$ corresponds to 83488 , representing voltage peak 83.488 V ;
15) Byte 000000002 C DB corresponds to 11483 , representing rectified mean value of current 11.483 mA .
16) Byte 000000002 CDB corresponds to 11483 , representing DC component of current 11.483 mA .
17) Byte $00 \underline{000005 \mathrm{~B} 871}$ corresponds to 374897 , representing positive current peak 374.897 mA ;
18) Byte FF FF FF FB 1C B6 corresponds to -320330, representing negative current peak -320.330 mA ;
19) Byte 00000005 B 871 corresponds to 374897 , representing current peak 374.897 mA ;
(2) Query relevant parameters of electric energy

Command character: 0x01
Function: Query relevant parameters of electric energy
Query running time of electric energy -hour ( 1 byte) for current channel, running time of electric energy $-\min (1$ byte), running time of electric energy - second ( 1 byte), positive electric energy ( 8 bytes), negative electric energy ( 8 bytes), electric energy value ( 8 bytes), positive electric energy value ( 8 bytes), negative electric energy value ( 8 bytes), electric energy value ( 8 bytes) in turn.
Sample: Receive by this machine-7B $\quad 00 \quad 09 \quad 01 \quad$ F1 $\quad 01 \quad \underline{01}$ FD 7 D

|  | mit | m |  |  | 7 B | 00 | 3C | 01 | F1 | 01 | 01 | 00 | 00 | 0A | $\underline{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00 | 00 | 00 | 00 | 00 | 00 | 11 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | $\underline{00}$ |
| 00 | 00 | 00 | 00 | 0 | 00 | 11 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 39 | $\underline{00}$ |
| 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 39 | CF |

Instructions for receiving: Underline byte $\underline{01}$ represents channel to be queried, range is $01-03$, representing CH1CH3.
Instructions for transmitting:

1) Byte 00 corresponds to 0 , representing running time of electric energy -h 0 ;
2) Byte 00 corresponds to 0 , representing running time of electric energy -m 0 ;
3) Byte 0 A corresponds to 10 , representing running time of electric energy -s 10 s ;
4) Byte $00 \underline{00000000000011}$ corresponds to 17 , representing positive electric

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energy 0.017 mWh ;
5) Byte $00 \underline{00000000000000}$ corresponds to 0 , representing negative electric energy 0 ;
6) Byte 0000000000000011 corresponds to 17 , representing electric energy value 0.017 mWh ;
7) Byte $00 \underline{00000000000039}$ corresponds to 57, representing positive electric energy value 0.057 mAh ;
8) Byte $00 \underline{00000000000039}$ corresponds to 0 , representing negative electric energy value 0 ;
9) Byte 0000000000000039 corresponds to 57 , representing electric energy value 0.057 mAh .
(3) Query measurement parameter in three-phases mode

Command character: 0x02
Function: Query parameters in three-phases (including transformation ratio)
Total voltage of three-phases ( 6 bytes), total current ( 6 bytes), total power ( 6 bytes), power factor ( 2 bytes), total apparent power ( 6 bytes), total reactive power ( 6 bytes), positive electric energy of three-phases ( 8 bytes), negative electric energy of three-phases ( 8 bytes), electric energy value of three-phases ( 8 bytes), positive electric energy value of three-phases ( 8 bytes), negative electric energy value of three-phases ( 8 bytes), electric energy value of three-phases ( 8 bytes) in turn.
Sample: Receive by this machine- 7 - $\begin{array}{lllllllll}00 & 09 & 01 & \text { F1 } & 02 & \underline{00} & \text { FD } & \text { 7D }\end{array}$

| Transmit | $m$ t |  |  | -7B | 00 | 59 | 01 | F1 | 2 | 00 | 00 | 00 | 00 | 00 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| EA 1C | 00 | 00 | 00 | 03 | 36 | 3 E | 00 | 00 | 00 | 03 | D8 | 0A | 27 | 00 |
| 00 | 00 | 03 | D9 | 91 | 00 | 00 | 00 | 00 | 36 | D4 | 00 | 00 | 00 | 0 |
| 00 | 00 | 11 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 |
| 00 | 00 | 11 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 39 | 00 | 00 | 00 | 00 |
| 0 | 00 | 00 | 00 | 00 | 00 | 00 |  | 00 |  |  |  |  |  |  |

Instructions for receiving: $\underline{00}$ is a fixed byte, three-phases query function, do not differentiate channel; when making three-phases data query, analyzer must be operated in three-phases state (three-phases 3wires or three-phases 4 -wires).
Instructions for transmitting:

1) Byte 00000000 EA 1 C corresponds to 59932 , representing total voltage of threephases 59.932 V ;
2) Byte 00000003363 E corresponds to 210494 , representing total current of threephases 210.494 mA ;
3) Byte 00000003 D 80 A corresponds to 251914 , representing total power of threephases 25.1914 W ;
4) Byte 2700 corresponds to 9984 , representing three-phases power factor 0.9984 ;
5) Byte 00000003 D 991 corresponds to 252305 , representing total apparent power of three-phases 25.2305 W ;
6) Byte 0000000036 D 4 corresponds to 14036 , representing total reactive power of three-phases 1.4036 W ;
7) Byte $00 \underline{00000000000011}$ corresponds to 17, representing positive electric energy of three-phases 0.017 mWh ;
8) Byte $00 \underline{00000000000000}$ corresponds to 0 , representing negative electric energy of three-phases 0 ;
9) Byte 0000000000000011 corresponds to 17 , representing electric energy value of three-phases 0.017 mWh ;
10) Byte 0000000000000039 corresponds to 57 , representing positive electric energy value of three-phases 0.057 mAh ;
11) Byte 0000000000000000 corresponds to 0 , representing negative electric energy value of three-phases 0 ;
12) Byte 0000000000000039 corresponds to 57 , representing electric energy value of three-phases 0.057 mAh .
(4) Query relevant parameters of motor

Command character: 0x03
Function: Query relevant parameters of motor
Query torque (4 bytes), RPM (4 bytes), mechanical work (4 bytes), mechanical efficiency of channel 1 (2 bytes), mechanical efficiency of channel 2 (2 bytes), mechanical efficiency of channel 3 (2 bytes), total mechanical efficiency of three-phases (2 bytes) in turn.

Transmit from this machine- $-7 \mathrm{BB} \quad 00 \quad$ 1D $\quad 01$

| 00 | 03 | $9 B$ | 34 | 00 | 02 | 1 | F | 35 | 26 | F 8 | 26 | F 8 | 26 | F 8 | 26 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| O |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | CC 7D

Instructions for receiving: Underline byte $\underline{00}$ is a fixed value, not differentiate channel for motor functions
Instructions for transmitting:

1) Byte 0000 E 661 corresponds to 5.8977 , representing torque $5.8977 \mathrm{~N} . \mathrm{m}$;
2) Byte 00039 B 34 corresponds to 236340 , representing RPM 236.340 RPM ;
3) Byte $00 \underline{02} 1 \mathrm{~F} 35$ corresponds to 139061 , representing mechanical work 13.9061 W ;
4) Byte 26 F8 corresponds to 9976 , representing mechanical efficiency of phase-1
99.76\%;
5) Byte 26 F8 corresponds to 9976 , representing mechanical efficiency of phase-2 99.76\%;
6) Byte 26 F8 corresponds to 9976 , representing mechanical efficiency of phase- 3
99.76\%;
7) Byte 26 F8 corresponds to 9976 , representing total mechanical efficiency of threephases $99.76 \%$;
(5) Query harmonic parameters

Command character: 0x04
Function: Query harmonic parameter
Query valid value of voltage base wave (4 bytes) for current channel, valid value of current base wave ( 4 bytes), valid value of power base wave (4 bytes), total distortion of voltage harmonics (4 bytes), total distortion of current harmonics (4 bytes), total distortion of power harmonics (4 bytes) in turn.

Sample: Receive by this machine-——B $00 \begin{array}{lllllllll} & 09 & 01 & \text { F1 } & 04 & \underline{01} & 00 & 7 D\end{array}$ | Transmit from this machine | $-7 B$ | 00 | 21 | 01 | F 1 | 04 | 01 | $\underline{00}$ | 01 | 61 | 1 B |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 00 | 01 | 61 | 1 B | 00 | 01 | 61 | 1 B | 00 | 00 | 00 | 3 C | $\underline{00}$ | 00 | 00 | 3 C | $\underline{00}$ |
| 00 | 00 | 3 C | 43 | 7 D |  |  |  |  |  |  |  |  |  |  |  |  |

Instructions for receiving: Underline byte $\underline{01}$ represents channel to be queried, range $01-03$, representing $\mathrm{CH} 1-$ CH3
Instructions for transmitting:

1) Byte $00 \underline{01611 \mathrm{~B}}$ corresponds to 90395 , representing voltage base wave 90.395 V ;
2) Byte $000161 \mathrm{1B}$ corresponds to 90395 , representing current base wave 90.395 mA ;
3) Byte 0001611 B corresponds to 90395 , representing power base wave 9.0395 W ;
4) Byte 0000003 C corresponds to 60 , representing total distortion of voltage harmonics $0.60 \%$;
5) Byte 0000003 C corresponds to 60 , representing total distortion of current harmonics $0.60 \%$;
6) Byte 0000003 C corresponds to 60 , representing total distortion of power harmonics $0.60 \%$;
(5) Query phase angle

Command character: 0x05
Function: Query phase angle
Phase angle of phase-A ( 2 bytes), phase angle of phase-B ( 2 bytes), phase angle of phase-C ( 2 bytes), U1-U2 phase angle ( 2 bytes), U2-U3 phase angle ( 2 bytes), U1-U3 phase angle ( 2 bytes), I1-I2 phase angle ( 2 bytes), I2-I3( 2 bytes), I1-I3( 2 bytes).
Sample: Receive by this machine - - 7B 000801 F1 05 FF 7D
Transmit from this machine - - 7B 00 1B 01 F1 05 FF 0299000000000194019400000 B 53

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0B 530000927 D ,
Instructions for receiving: Phase angle query function, not differentiate channel Instructions for transmitting:

1) Byte 0299 corresponds to 665 , representing phase angle of phase-A $66.5^{\circ}$;
2) Byte 0000 corresponds to 0 , representing phase angle of phase-B $0^{\circ}$;
3) Byte 0000 corresponds to 0 , representing phase angle of phase- $C 0^{\circ}$;
4) Byte 0194 corresponds to 404, representing phase angle of phase U1-U2 $40.4^{\circ}$;
5) Byte 0194 corresponds to 404, representing phase angle of phase U2-U3 $40.4^{\circ}$;
6) Byte 0000 corresponds to 0 , representing phase angle of phase U1-U3 $0^{\circ}$;
7) Byte 0B 53 corresponds to 2899 , representing phase angle of phase I1-I2 $289.9^{\circ}$;
8) Byte 0B 53 corresponds to 2899 , representing phase angle of phase I2-I3 $289.9^{\circ}$;
9) Byte 0000 corresponds to 0 , representing phase angle of phase I1-I3 $0^{\circ}$;
(6) Query overview test data

Command character: 0x06
Function: Query overview test data (including transformation ratio)
Channel-1 voltage ( 6 bytes), channel- 1 current ( 6 bytes), channel- 1 power ( 8 bytes), channel- 1 power factor ( 2 bytes), channel-1 voltage frequency ( 4 bytes), channel- 1 current frequency ( 4 bytes), channel-1 DC component of voltage ( 6 bytes), channel- 1 DC component of current ( 6 bytes), channel-2 voltage ( 6 bytes), channel-2 current ( 6 bytes), channel-2 power ( 8 bytes), channel-2 power factor ( 2 bytes), channel-2 voltage frequency ( 4 bytes), channel- 2 current frequency ( 4 bytes), channel-2 DC component of voltage ( 6 bytes), channel- 2 DC component of current ( 6 bytes), Channel- 3 voltage ( 6 bytes), channel- 3 current ( 6 bytes), channel- 3 power ( 8 bytes), channel- 3 power factor ( 2 bytes), channel- 3 voltage frequency ( 4 bytes), channel- 3 current frequency ( 4 bytes), channel-3 DC component of voltage ( 6 bytes), channel- 3 DC component of current ( 6 bytes), Total three-phases voltage ( 6 bytes), total three-phases current ( 6 bytes), total three-phases power ( 6 bytes), three-phases power factor ( 2 bytes).
Sample: Receive by this machine- $-7 B \begin{array}{lllllll} & 00 & 08 & 01 & \text { F1 } & 06 & 00 \\ \text { 7D }\end{array}$
Transmit from this machine--7B $\quad 00$

| 00 | 00 | 00 | 03 | 9 B | 34 | 00 | 00 | 00 | 00 | 00 | 02 | 1 F | 35 | 26 | F8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00 | 00 | C7 | 3A | 00 | 00 | C7 | 3A | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 |
| 00 | 00 | 01 | 72 | 00 | 00 | 00 | 00 | E6 | 61 | 00 | 00 | 00 | 03 | 9B | 34 |
| 00 | 00 | 00 | 00 | 00 | 02 | 1 F | 35 | 26 | F8 | 00 | 00 | C7 | 3A | 00 | 00 |
| C7 | 3A | $\underline{00}$ | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 00 | 01 | 72 | 00 | 00 |
| 00 | 00 | E6 | 61 | 00 | 00 | 00 | 03 | 9B | 34 | 00 | 00 | 00 | 00 | 00 | 02 |
| 1 F | 35 | 26 | F8 | 00 | 00 | C7 | 3 A | $\underline{00}$ | 00 | C7 | 3A | 00 | 00 | 00 | 00 |
| 00 | 00 | 00 | 00 | 00 | 00 | 01 | 72 | 00 | 00 | 00 | 00 | EA |  |  |  |
| 00 | 03 | 36 | 3E | 00 | 00 | 00 | 03 | D8 | 0 A | $\underline{27}$ | 00 | 22 | 7 D |  |  |

Instructions for transmitting:

1) Byte 00000000 E 661 corresponds to 58977 , representing channel-1 voltage 58.977 V ;
2) Byte 000000039 B 34 corresponds to 236340 , representing channel-1 current 236.340 mA ;
3) Byte 0000000000021 F 35 corresponds to 139061 , representing channel-1 active power 13.9061W;
4) Byte 26 F8 corresponds to 9976 , representing channel-1 power factor 0.9976 ;
5) Byte 0000 C 73 A corresponds to 51002 , representing channel-1 voltage frequency 51.002 Hz ;
6) Byte 0000 C 73 A corresponds to 51002 , representing channel-1 current frequency 51.002 Hz ;
7) Byte 000000000000 corresponds to 0 , representing channel-1 DC component of voltage 0.000 V ;
8) Byte 000000000172 corresponds to 370 , representing channel-1 DC component of current 0.370 mA ;
9) Byte 00000000 E 661 corresponds to 58977 , representing channel-1 voltage 58.977 V ;
10) Byte 000000039 B 34 corresponds to 236340 , representing channel-1 current 236.340 mA ;
11) Byte 000000000002 1F 35 corresponds to 139061, representing channel-1 active power 13.9061W;
12) Byte 26 F 8 corresponds to 9976 , representing channel-1 power factor 0.9976 ;
13) Byte 0000 C 73 A corresponds to 51002 , representing channel-1 voltage frequency 51.002 Hz ;
14) Byte 0000 C 73 A corresponds to 51002 , representing channel-1 current frequency 51.002 Hz ;
15) Byte 000000000000 corresponds to 0 , representing channel-1 DC component of voltage 0.000 V ;

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16) Byte 000000000172 corresponds to 370 , representing channel-1 DC component of current 0.370 mA ;
17) Byte 00000000 E 661 corresponds to 58977 , representing channel-1 voltage 58.977 V ;
18) Byte 000000039 B 34 corresponds to 236340 , representing channel-1 current 236.340 mA ;
19) Byte 000000000002 1F 35 corresponds to 139061, representing channel-1 active power
13.9061 W ;
20) Byte 26 F 8 corresponds to 9976 , representing channel-1 power factor 0.9976 ;
21) Byte 0000 C 73 A corresponds to 51002 , representing channel-1 voltage frequency 51.002 Hz ;
22) Byte 0000 C 73 A corresponds to 51002 , representing channel- 1 current frequency 51.002 Hz ;
23) Byte 000000000000 corresponds to 0 , representing channel-1 DC component of voltage 0.000 V ;
24) Byte 000000000172 corresponds to 370 , representing channel-1 DC component of current 0.370 mA ;
25) Byte 00000000 EA 1C corresponds to 59932, representing total three-phases voltage 59.932 V ;
26) Byte 00000003363 E corresponds to 210494, representing total three-phases current 210.494mA;
27) Byte 00000003 D 80 A corresponds to 251914 , representing total three-phases power 25.1914 W;
28) Byte 2700 corresponds to 9984 , representing three-phases power factor 0.9984 ;

## A.4.2Setting specific commands ( $0 \times 5 \mathrm{~A}$ )

(5) Set of setting specific commands

Command character: 0x00
Function: Set control specific parameters, parameters to be set (1 byte, see table below for details), and setting value (1 byte) in turn.
$\begin{array}{rcccccccccc}\text { Sample: Receive by this machine }--7 \mathrm{~B} & 00 & 0 \mathrm{~A} & 01 & 5 \mathrm{~A} & 00 & 01 & 00 & 66 & 7 \mathrm{D} \\ \text { Transmit from this machine -7B } & 00 & 09 & 01 & 5 \mathrm{~A} & 00 & \underline{00} & 64 & 7 \mathrm{D}\end{array}$

| $7^{\text {th }}$ byte | $8^{\text {th }}$ byte |
| :---: | :---: |
| 00- integral state | Range 0-2, 0-zeroing, 1 - start, 2 - stop |
| 01- voltage range | Voltage range of each channel. Range $0-7$ representing 8 ranges of voltage, 8 for auto range. $\begin{aligned} & (0-15 \mathrm{~V}, 1-30 \mathrm{~V}, 2-60 \mathrm{~V}, 3-100 \mathrm{~V}, 4-150 \mathrm{~V}, 5-300 \mathrm{~V}, 6-600 \mathrm{~V}, \\ & 7-1000 \mathrm{~V}) \end{aligned}$ |
| 02- current range | Current range of each channel. Range 0-7 representing 8 ranges of current, 8 for auto range. $(0-100 \mathrm{~mA}, 1-200 \mathrm{~mA}, 2-500 \mathrm{~mA}, 3-1 \mathrm{~A}, 4-2 \mathrm{~A}, 5-5 \mathrm{~A}, 6-10 \mathrm{~A}, 7-20 \mathrm{~A})$ |
| 03-current source | Range 2-3, 2 - BNC input, 3 - direct input |
| 04- calculation cycle | Calculation cycle (range $0-6,0-0.1 \mathrm{~s}, 1-0.2 \mathrm{~s}, 2-0.5 \mathrm{~s}, 3-1 \mathrm{~s}, 4-2 \mathrm{~s}, 5-5 \mathrm{~s}, 6-$ 10s) |
| 05-sync source | Sync source of each channel (range 0-5, $0-\mathrm{U} 1,1-\mathrm{A} 1,2-\mathrm{U} 2,3-\mathrm{A} 2,4-\mathrm{U} 3,5$ - A3) |
| 06- harmonic source | Harmonic source of each channel (range 0-5, 0-U1, 1 - A1, 2 - U2, 3-A2, 4 U3, 5 - A3) |
| 07- harmonic switch | Range 0-1, 0 - off (normal measurement), 1 - on (harmonic measurement) |
| 08- line filter | Range 0-2, $0-$ off, $1-500 \mathrm{~Hz}, 2-5.5 \mathrm{kHz}$ |
| 09- frequency filter | Range 0-1, 0 - off, $1-$ on |
| 0A- load type | Range: 0-3, 0-1P3W, 1-3P3W, 2-3P4W, 3-3V3A |

(6) Set alarm specific parameters

Command character: 0x01
Function: Set alarm specific parameters: upper limit of voltage alarm (4 bytes), lower limit (4 bytes), threshold (4 bytes), upper limit of current (4 bytes), lower limit (4 bytes), threshold (4 bytes), upper limit of power (4 bytes), lower limit (4 bytes), threshold (4 bytes), alarm delay time ( 2 bytes), voltage transformation ratio (4 bytes), current transformation ratio (4 bytes), BNC transformation ratio (4 bytes) in turn.

Sample: Receive by this machine- $-7 B \begin{array}{llllllll} & 00 & 3 A & 01 & 5 A & 01 & 00 & 00 \\ 00\end{array}$

| 01 | 00 | 00 | 00 | 02 | 00 | 00 | 00 | 03 | 00 | 00 | 00 | 04 | 00 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |


| 00 | 00 | 05 | 00 | 00 | 00 | 06 | 00 | 00 | 00 | 07 | 00 | 00 | 00 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 08 | 00 | 00 | 00 | 09 | 00 | 0 A | 00 | 00 | 00 | C 8 | 00 | 00 | 00 |

$\begin{array}{lllllll}\mathrm{C} 8 & 00 & 00 & 00 & \mathrm{C} 8 & 25 & 7 \mathrm{D}\end{array}$
Transmit from this machine-—7B $00 \begin{array}{llllllll} & 09 & 01 & 5 A & 01 & \underline{00} & 65 & \text { 7D }\end{array}$
Instructions for receiving:

1) Upper limit of voltage alarm , range $0-100000$, representing $0-1000.00 \mathrm{~V}$ (max range)
2) Lower limit of voltage alarm , range $0-100000$, representing $0-1000.00 \mathrm{~V}$
3) Threshold of voltage alarm , range $0-100000$, representing $0-1000.00 \mathrm{~V}$
4) upper limit of current alarm, range $0-22000$, representing $0-22.000 \mathrm{~A}$ (max range, similar for other current specifications)
5) Lower limit of current alarm, range $0-22000$, representing $0-22.000 \mathrm{~A}$
6) Threshold of current alarm, range $0-22000$, representing $0-22.000 \mathrm{~A}$
7) Upper limit of power alarm, range $0-6600000$, representing $0-66000.00 \mathrm{~W}$ (max range of corresponding voltage and current)
8) Lower limit of power alarm, range $0-6600000$, representing $0-66000.00 \mathrm{~W}$
9) Threshold of power alarm, range $0-6600000$, representing $0-66000.00 \mathrm{~W}$
10) Alarm delay time, range $1-200$, representing $1-20.0 \mathrm{~s}$
11) Voltage transformation ratio, range $10-50000$, representing $1.0-5000.0$
12) Current transformation ratio, range $10-50000$, representing $1.0-5000.0$
13) BNCtransformation ratio, range $10-100000$, representing $0.010-100.000$

Instructions for transmitting: If the command (not including the query specific command) is received and executed correctly, the corresponding execution command will be returned with $0 x 00$ for parameter. If parameter setting is beyond range, the command type returned will be $0 x 99$, as well as the received command word and error code 04. Receiving by this machine: 7B 00 0A 015 A 00 0A 0473 7D (set load type to 4, exceeding range of 0-3)
Transmitting from this machine: 7B $000901 \underline{99} 00 \underline{04}$ A7 7D

## Chapter 7: Motor card function

## I. Motor data calculation

87330 can be equipped with an optional motor card. At present, the motor card can realize signal sampling for frequency type torque and RPM sensor. In other words, with frequency sampling, corresponding torque and RPM can be gotten via calculation, and the calculation formula is given below;

## 1. Torque test

$\mathrm{M}_{\mathrm{P}}=\mathrm{N} *\left(\mathrm{f}-\mathrm{f}_{0}\right) /\left(\mathrm{f}_{\mathrm{p}}-\mathrm{f}_{0}\right)$
$\mathrm{M}_{\mathrm{r}}=\mathrm{N} *\left(\mathrm{f}_{0}-\mathrm{f}\right) /\left(\mathrm{f}_{0}-\mathrm{f}_{\mathrm{r}}\right)$
Note:
Mp: Forward torque
Mr : Backward torque
N : Full range of torque

$\xrightarrow{\text { Negative }}$
$\mathrm{f}_{0}$ : Output frequency at zero point of torque $(\mathrm{kHz})$
$\mathrm{fr}_{\mathrm{r}}$ : Output frequency for full range of backward torque $(\mathrm{kHz})$
$\mathrm{f}_{\mathrm{p}}$ : Output frequency for full range of forward torque $(\mathrm{kHz})$
f : Actual measured output frequency of torque ( kHz )
2. RPM test
$\mathrm{n}=\frac{60 * \mathrm{f}}{\mathrm{Z}}$
Note:
n : RPM ( $\mathrm{r} / \mathrm{min}$ )
$f$ : Actual measured output frequency of RPM (Hz)
$Z$ : Number of teeth on tachometer disc of sensor

## 3. Mechanical work

$\mathrm{P}=\frac{\mathrm{T} * \mathrm{n}}{9550}$
Note:
P: Mechanical work (kW)
T: Torque (Nm)
n : $\quad \operatorname{RPM}(\mathrm{r} / \mathrm{min})$

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## Chapter 8: Maintenance guide

## I. Maintenance and care

## 1. Periodic maintenance

- For analyzer, input power cable, communication cable and other related accessories, they shall be checked and verified at least once a year to ensure safety of user and accuracy of machine. If the analyzer is used in production sites or under other adverse conditions, it must be checked and calibrated every six months.
- If analyzer is not used for a long time, it shall be powered on regularly. Power-on shall be made usually each month, and the power-on time shall be at least 30 minutes.
- In order to ensure accuracy and reliability of analyzer, it is required to calibrate instrument at least once a year.

2. Daily maintenance

- Do not let analyzer operating over the range for a long time. The amplitude of the shock signal allowed by analyzer shall not exceed 1.6 times of normal signal. When analyzer is not in use, unplug the power cable of meter.
- When analyzer is not in use for a long time, please pack it, and keep it in dry environment without dust or strong vibration.
$\bullet$ If analyzer is operated after long time storage, it shall be turned on for 30 min before operation and measurement.


## II. Troubleshooting for simple faults

WARNING
Warning: The analyzer must be repaired and maintained by experienced engineer or technician; if this series analyzer is maintained or repaired by person not passing qualified training, physical injury or death may occur.

| Failure | Solution |
| :--- | :--- |
| No display after turning on analyzer. | 1) Check whether power supply of instrument is properly <br> connected; <br> 2) Check whether the fuse tube of instrument is broken. If so, <br> please replace the fuse tube with same model. <br> 3) Turn on machine again. |
| When measuring correctly, the <br> current and power values are zero | 1) Check whether the load under test is normal; <br> 2) Check whether the load wiring is correct. |
| The measured value differs too | 1) Check whether the load under test is normal; <br> 2) Check whether the setting of voltage transformation ratio and <br> current transformation ratio is normal; <br> much from the actual value |

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[^0]:    - 30 -

[^1]:    - 40 -

[^2]:    - 44 -

