SPEC SHEET

Trimble R780 GNSS System



Highly accurate GNSS receiver built to handle the toughest construction environments.

Key Features

- Configurable receiver, scalable for future requirements.
- Available in base & rover, rover only, or base only configurations.
- Trimble[®] Inertial Platform[™] technology for magnetically immune IMU-based tilt compensation.
- Trimble ProPoint[™] GNSS positioning engine for improved accuracy and productivity in challenging GNSS conditions.
- Trimble Maxwell[™] 7 GNSS ASIC.
- 9 GB internal memory.
- Trimble xFill[®] correction outage technology.
- Supports Trimble CenterPoint[®] RTX corrections for RTK level accuracy worldwide via satellite/IP.
- Military-grade ultra-rugged design, IP68 rating.
- Optimized for Trimble FieldLink[™] field software.





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PERFORMANCE SPECIFICATIONS				
GNSS TECHNOLOGY				
	Constellation agnostic, flexible signal tracking, improved positioning in challenging environments1 and inertial measurement integration with Trimble ProPoint GNSS technology			
	Increased measurement and stakeout productivity and traceability with Trimble TIP™ technology IMU-based tilt compensation			
	Trimble RTX worldwide corrections			
	Advanced Trimble Maxwell 7 technology			
	Trimble EVEREST Plus™ multipath signal rejection			
	Spectrum Analyzer to troubleshoot GNSS jamming			
	Japanese LTE Filtering below 1510 MHz allows antennas to be used 100 m away from Japanese LTE cell tower			
	Iridium Filtering above 1616 MHz allows the antenna to be used 20 m away from Iridium transfer			
SATELLITE TRACKING				
	GPS: L1C, L1 C/A, L2E (L2P), L2C, L5			
	GLONASS: L1C/A, L1P. L2C/A, L2P, L3			
	Galileo: E1, E5A, E5B and E5AltBOC, E6 ²			
	BeiDou: B1, B2, B3, B1C, B2A			
	QZSS: L1 C/A, L1C, L1S, L2C, L5, LEX/L6			
	IRNSS: L5			
	SBAS: L1 C/A (EGNOS/MSAS GAGAN/SDC	M), L1 C/A and L5 (WAAS)		
	L-Band: Trimble RTX			
POSITIONING PERFORMANC	E3			
STATIC GNSS SURVEYING				
High-Precision Static				
	Horizontal	3 mm + 0.1 ppm RMS		
	Vertical	3.5 mm + 0.4 ppm RMS		
Static and Fast Static				
	Horizontal	3 mm + 0.5 ppm RMS		
	Vertical	5 mm + 0.5 ppm RMS		
REAL TIME KINEMATIC SUR	VEYING			
Single Baseline < 30 km				
	Horizontal	8 mm + 1 ppm RMS		
	Vertical	15 mm + 1 ppm RMS		
Network RTK⁴				
	Horizontal	8 mm + 0.5 ppm RMS		
	Vertical	15 mm + 0.5 ppm RMS		
	RTK start-up time for specified precisions⁵	2 to 8 seconds		
TRIMBLE INERTIAL PLATFOR	RM (TIP) TECHNOLOGY			
TIP Compensated Surveying	6			
	Horizontal	RTK + 8 mm + 0.5 mm/° tilt (up to 30°) RMS		
	Horizontal	RTX + 8 mm + 0.5 mm/° tilt (up to 30°) RMS		
IMU Integrity Monitor	Bias monitoring	Temperature, age and shock		

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POSITIONING PERFORMANCE³ Cont.

TRIMBLE RTX CORRECTION SERVICES

I RIMBLE RTX CORRECT	HON SERVICES			
CenterPoint RTX ⁷				
	Horizontal	2 cm RMS		
	Vertical	5 cm RMS		
	RTX convergence time for specified precisions in Trimble RTX Fast regions	<1min		
	RTX convergence time for specified precisions in non RTX Fast regions	< 3 min		
	RTX QuickStart convergence time for specified precisions	< 5 min		
TRIMBLE xFILL ⁸				
	Horizontal	RTK ⁹ + 10 mm/minute RMS		
	Vertical	RTK ⁹ + 20 mm/minute RMS		
TRIMBLE xPREMIUM ⁸				
	Horizontal	3 cm RMS		
	Vertical	7 cm RMS		
CODE DIFFERENTIAL GN	ISS POSITIONING			
	Horizontal	0.25 m + 1 ppm RMS		
	Vertical	0.50 m + 1 ppm RMS		
	SBAS ¹⁰	Typically < 5 m 3DRMS		
HARDWARE				
PHYSICAL				
Dimensions (W×H)	13.9 cm x 13 cm (5.5 in x 5.1 in) including c	13.9 cm x 13 cm (5.5 in x 5.1 in) including connectors		
Weight	1.55 kg (3.42 lb) receiver only including radio and battery			
Temperature ¹¹				
	Operating	-40 °C to +65 °C (-40 °F to +149 °F)		
	Storage	-40 °C to +75 °C (-40 °F to +167 °F)		
Humidity		100%, condensing		
Ingress protection		IP68 Certified per IEC-60529: waterproof/dustproof (1 m submersion for 1 hour)		
Shock and Vibration				
	Pole drop	Designed to survive a 2 m (6.6 ft) pole drop onto concrete		
	Shock	Non-operating: 75 Gs at 6msec		
	Shock	Operating: 40 Gs at 10msec		
	Vibration	Mil-Std-810G, FIG 514.6E-1 Cat 24, Mil-Std-202G, FIG 214-1, Condition D		

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ELECTRICAL						
	Internal	Rechargeable, removeable Lithium-ion battery in internal battery compartment				
		Internal battery operates as a UPS during an ext power source failure				
		Internal battery will charge from external source as long as source can support the power drain and is more than 11.8 VDC				
		Integrated charging circuitry				
	External	External power input with over-voltage protection on Port 1 (7-pin Lemo 2-key) Minimum 10.8 V, Maximum 28 VDC, shutdown optimized for 12 V lead acid battery operation				
		Power source supply (Internal/External) is hot-swap capable in the event of power source removal or cut off				
		DC external power input with over-voltage protection on Port 1 (Lemo)				
		Receiver automatically turns on when connected to external power				
	Devention	3.2 W in rover mode with internal receive radio ¹²				
	Power consumption	5.2 W in base mode with internal 0.5 W transmit radio				
Operating Times On Internal Batte	ry ¹³					
	Rover	5.5 hours; varies with temperature				
	Base station	5.5 hours; varies with temperature				
	450 MHz systems	Approximately 4 hours; varies with temperature				
	900 MHz systems	Approximately 4 hours; varies with temperature				
COMMUNICATIONS AND DATA STORAGE						
Lemo (Serial 1)	7-pin Lemo 2-key, Power Input, USB. Optional USB to RS232 serial cable. Receiver supports RNDIS communications over USB					
Wi-Fi	Client or Access Point. Receive or transmit corrections. Wi-Fi b/g/n					
Bluetooth® wireless technology	Fully-integrated sealed 2.4 GHz Bluetooth module					

Fully-integrated, fully-sealed internal 403-473 MHz; Internal 900 MHz; Rx/Tx

CMR+, CMRx, RTCM 2.1, RTCM 2.3, RTCM 3.0, RTCM 3.1, RTCM 3.2 input and output

12.5 kHz or 25 kHz spacing available

1 Hz, 2 Hz, 5 Hz, 10 Hz, and 20 Hz

0.5 W, 2.0 W, depending on the local required licensing.

Worldwide, depending on the local required licensing.

9 GB internal data logging. Moving base and heading

24 NMEA outputs, GSOF, RT17, and RT27 outputs

-114 dBm (12 dB SINAD)

Integrated radios (optional)

Channel spacing (450 MHz)

Frequency approvals (403–473

Sensitivity (450 MHz)

450 MHz output power

Positioning rates Data storage

Data format

MHz)

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CERTIFICATIONS		
	FCC Part 15 Subpart B (Class B Device), Part 15.247, Part 90	
	Canadian ICES-003 (Class B), RSS-GEN, RS-102, RSS-247	
	IEC62368-1 2nd Edition	
	CISPR 32, EN 55032, EN 55035	
	RCM mark, AS/CISPR 32, AS/NZS 4768	
	Japan MIC	
	CE mark, Radio Equipment Directive (RED 2014/53/EU)	
	RoHS compliance	
	WEEE compliance	
TRIMBLE PROTECTED PROTECTION PLANS		
	Add a Trimble Protected protection plan for worry-free ownership over and above the standard Trimble product warranty.	

Added enhancements include coverage for wear & tear, environmental damage, and more. Accidental damage is covered with Premium plans, available only at point-of-sale in selected regions. For details, visit trimbleprotected.com or contact a local Trimble distributor.

- Challenging GNSS environments are locations where the receiver has sufficient satellite availability to achieve minimum accuracy requirements, but where the signal may be partly obstructed by and/or reflected off of trees, buildings, and other objects. Actual results may vary based on user's geographic location and atmospheric activity, scintillation levels, GNSS constellation health and availability, and level of multipath and signal occlusion. 1
- 2
- atmospheric activity, scintiliation levels, GNSS constellation health and availability, and level of multipath and signal occlusion. The current capability in the receivers is based on publicly available information. As such, Trimble cannot guarantee that these receivers will be fully compatible with a future generation of Galileo satellites or signals. Precision and reliability may be subject to anomalies due to multipath, obstructions, satellite geometry, and atmospheric conditions. The specifications stated recommend the use of stable mounts in an open sky view, EMI and multipath clean environment, optimal GNSS constellation configurations, along with the use of survey practices that are generally accepted for performing the highest-order surveys for the applicable application including occupation times appropriate for baseline length. Baselines longer than 30 km require precise ephemeris and occupations up to 24 hours may be required to achieve the high precision static constructions that are generally accepted for performing the highest-order surveys for the applicable applicable application including occupation times appropriate for baseline length. Baselines longer than 30 km require precise ephemeris and occupations up to 24 hours may be required to achieve the high precision static 3 specification
- Network RTK PPM values are referenced to the closest physical base station.
- 5 May be affected by atmospheric conditions, signal multipath, obstructions and satellite geometry. Initialization reliability is continuously monitored to ensure 6
- May be affected by atmospheric conditions, signal multipath, ous fuctions and satellite genreu y, intranzetion renzions is continuously in control or size 2 TIP references the overall positioning error estimate at the tip of the surveying pole throughout the tilt compensation range. RTK refers to the estimated horizontal precision of the underlying GNSS position, which is dependent on factors that affect GNSS solution quality. The 8 mm constant error component accounts for residual misalignment between the vertical axes of the receiver and the built-in Interial Measurement Unit (IMU) after factory calibration, assuming the receiver is mounted on a standard 2 m carbon fiber range pole which is properly calibrated and free from physical defects. The tilt-dependent error component is a function of the quality of the computed tilt azimuth, which is assumed here to be aligned using optimal GNSS conditions. For best IMU tilt compensated results, perform a pole bias adjustment
- RMS performance based on repeatable in field measurements. Achievable accuracy and initialization time may vary based on type and capability of receiver and antenna, user's geographic location and atmospheric activity, scintillation levels, GNSS constellation health and availability and level of multipath including
- obstructions such as large trees and buildings. Accuracies are dependent on GNSS satellite availability. xFill positioning without an xFill Premium subscription ends after 5 minutes of radio downtime. xFill Premium will continue beyond 5 minutes providing the solution has converged, with typical precisions not exceeding 3 cm horizontal, 7 cm vertical. xFill is not available in all regions, check with your local sales representative for more information. 8
- RTK refers to the last reported precision before the correction source was lost and xFill started.
- Depends on SBAS system performance. Receiver will operate normally to -40 °C, internal batteries are rated from -20 °C to +60 °C (ambient +50 °C). Tracking GPS, GLONASS and SBAS satellites. 10 11
- Varies with temperature and wireless data rate. When using a receiver and internal radio in the transmit mode, it is recommended that an external 6 Ah or higher battery is used.

Specifications subject to change without notice

Contact your local dealer today	,	

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