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About Tronhelicopters

The company Tronhelicopters was founded 2019 in Switzerland by Dario Neuenschader, Ricky Yin and Joachim Etter. (EMT team)

About us:

Dario Neuenschwander.

Dario has long been known in the RC helicopter scene for many years.

He was heavy involved in the designs of the Protos Helicopters series and the development of the famous MSH Brain FBL unit. Dario also did R@D work for SpinBlades where he is a longtime Factory Pilot.

In 2017 Dario took a break from RC Helicopters to get involved to FPV racing. He did well and took the official FPV-FAI world champion title in 2017.

Joachim Etter

The head behind many projects. He is known for his business ideas and his ability to make products a success with his designs. Before that, he was closely associated with various manufacturers, for whom he did designs and business consultancy. Joachim was also the main founder, designer and builder of the xnovamotors brand.

Ricky Yin

Ricky is deeply involved in the manufacture, development and production of rc model helicopters for a very long time.

That goes back to the beginnings of Synergy Helicopters, which he took over in 2010 after Stephen Fan passed away.



Features.



- 1. WIDE BATTERY COMPARTMENT WITH OUICK LOCK AND RELEASE SYSTEM.
- 2. LIGHT, YET VERY STIFF AND ROBUST.
- 3. INNOVATIVE FBL TRAY. (ADJUSTABLE DAMPENING HARDNESS)
- 4. DRY WEIGHT= (2190) GRAMS WITHOUT BLADES AND ELECTRONICS.
- 5. 12MM HOLLOW MAIN SHAFT.
- 6. 10MM FEATHERING SHAFT.
- 7. MAIN GEAR = 155 T MOD. 1 / TAIL DRIVE FRONT PULLEY = 127 T AND 27 T ON TAIL ASSEMBLY.
- 8. REAL FULL CARBON MAINFRAME.
- 9. MOTOR MOUNTING DESIGN REDUCING OVERALL WEAR ON THE POWER SYSTEM AND DRIVE TRAIN.
- 10. MOTOR SIZES, 4030, 4035, 4525, 4530, 4535 (6MM SHAFT REQUIRED MIN. LENGHT = 20MM) 520 560KV.
- 11. 16 T MOTOR PINION INCLUDED IN KIT. (6MM BORE DIAMETER)
- 12. OCTA BOOM DESIGN WITH OVAL SIDE SHAPES, NO BOOM SUPPORTS NEEDED.
- 13. CAPABLE TO USE A WIDE RANGE OF LIPO BATTERIES. 6S 14S. (12S 5000MAH TO 5500MAH RECOMMENDED).
- 14. PERFECTLY THOUGHT-OUT SERVO LAYOUT IN CONJUNCTION WITH THE FBL SYSTEM AND ESC.
- 15. EASY CABLE ROUTING WITH VARIOUS OPTIONS TO ENSURE A CLEAN SETUP.
- 16. HIGH VISIBILITY CANOPY FOR PERFECT ORIENTATION IN FLIGHT.
- 17. RECOMMENDED MAIN BLADE SIZE 685 720 MM. TAIL BLADE SIZE 95 115 MM
- 18. SUSTAINABLY PRODUCED



safety notice

Operate the helicopter in open areas with no people nearby. Follow your countries air regulation rules.

You may need to join a local club and become a member before you can fly the model.

Do NOT operate the helicopter in the following places and situations (or else you risk severe accidents)

In places where children gather or people pass through in residential areas and parks, indoors and in limited space in windy weather or when there is rain, snow, fog or other precipitation. If you do not observe these instructions you may be held liable for personal injury or property damage!

Always check the R/C system prior to operating your helicopter.

Keep in mind that other people around you might also be operating a R/C model. Never use a frequency which someone else is using at the same time. Radio signals will be mixed and you will lose control of your model. If the model shows irregular behavior, bring the model to a halt immediately and disconnect the batteries. Investigate the reason and fix the problem. Do not operate the model again as long as the problem is not solved, as this may lead to further trouble and unforeseen accidents. In order to prevent accidents and personal injury, be sure to observe the following: Before flying the helicopter, ensure that all screws are tightened. A single loose screw may cause a major accident.

Replace all broken or defective parts with new ones, as damaged parts lead to crashes. Never approach a spinning rotor. Keep at least 5 meters/yards away from a spinning rotor blades. Do not touch the motor immediately after use. It may be hot enough to cause burns. Perform all necessary maintenance.

PRIOR TO ADJUSTING AND OPERATING YOUR MODEL, OBSERVE THE FOLLOWING

Operate the helicopter only outdoors and out of people's reach as the main rotor operates at high rpm!

Note that a badly assembled or improperly adjusted helicopter is a safety hazard! In the beginning, novice R/C helicopter pilots should always be assisted by an experienced pilot.

SAFETY FIRST! ALWAYS.



Safety notice

CAUTION:

This radio controlled helicopter is not a toy.

The product is not suitable for children under 14 years of age.

SAFETY PRECAUTIONS:

This kit includes some preassembled components. Please check for any loose screws and tighten them before you proceed with assembly. Use loctite where required as shown in this manual!

You are responsible for assembly, safe operation, maintenance, inspection and adjustment of the model.

Before beginning assembly, please read these instructions thoroughly.

Check all parts. If you find any defective or missing parts, contact your local dealer.

For the USA market, The Academy of Model Aeronautics (AMA) is a national organization representing modelers in the United States. Please refer to the National Model Aircraft safety code from Academy of Model Aeronautics.



Tools required

UHU Plus Control Binder Plus Control Plus Co	2 component epoxy		
205TTTE. 243 Ø	Loctite 243 / medium strength		
01.04.196.15.15.15.15.15.15.15.15.15.15.15.15.15.	Grease		
TAHLYS	2x 7mm Wrenches for tail shaft nut		
	Hex screwdriver 1.5mm/2mm/2.5mm/4m- m/5mm		
	TR-XXXXX Pair of customized nut wrench for tail shaft assembly. Optionally available at your Dealer.		



Electronics required

	3x full size servo for swashplate	
Primary Primary	1 full size servo for tail	
	BL motor. 4030-4535 /500-560KV	
They HOBBYWING ***	ESC 6S-12S 112A-205A	
CH3	FBL device and receiver with 6 channel transmitter.	

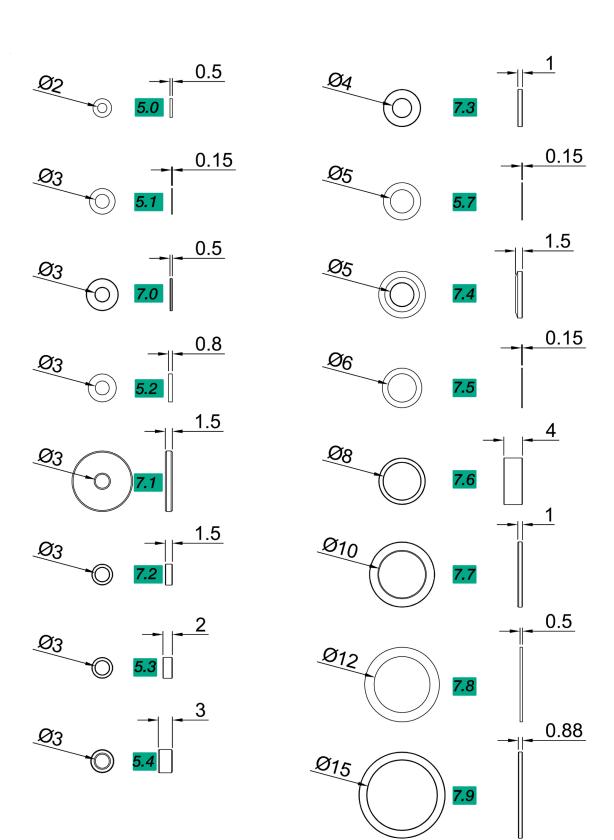


Screws and nuts

1.0	M2*4mm		2.5 M3*18mm
1.1	M2*6mm		2.6 M3*25mm
1.2	M2*16mm		2.7 M3*40mm
1.3	M2.5*6mm		2.8 M4*10mm
1.4	M2.5*6mm		2.9 M4*26.5mm
1.5	M2.5*8mm		3.0 M4*40mm
1.6	M2.5*10mm		3.1 M7*15mm
1.7	M3*6mm		IVI7 ISIIIII
1.8	M3*8mm	0	3.2 M3*12mm
1.9	M3*6mm		3.3 M4*5mm
2.0	M3*8mm		3.4 M4*6mm
2.1	M3*10mm	0	3.5 M2 Nut
2.2	M3*12mm		3.6 M3 Nylon Nut
2.3	M3*16mm		3.7 M4 Nylon Nut
2.4	M3*17.8n	nm 🔘	3.8 M5 Nylon Nut



Shims and washers.

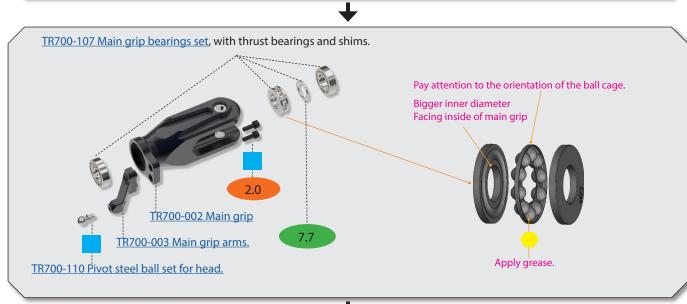


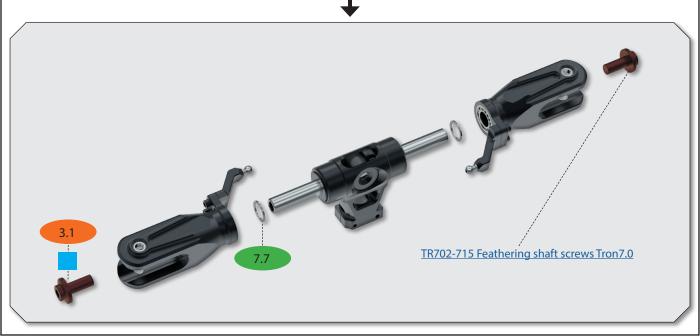


You will need: Loctite 243 = blue Grease = yellow

Head assembly

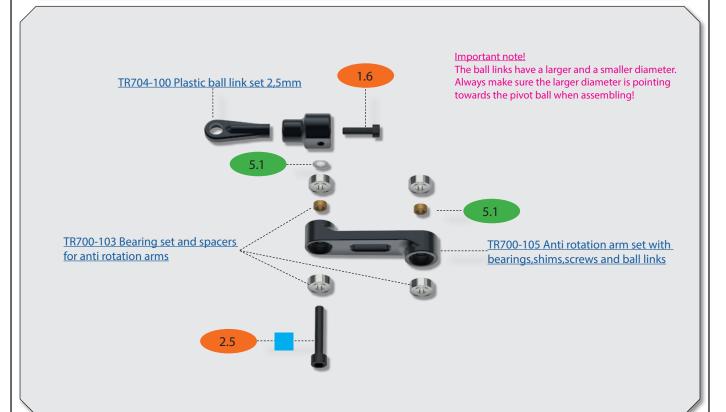






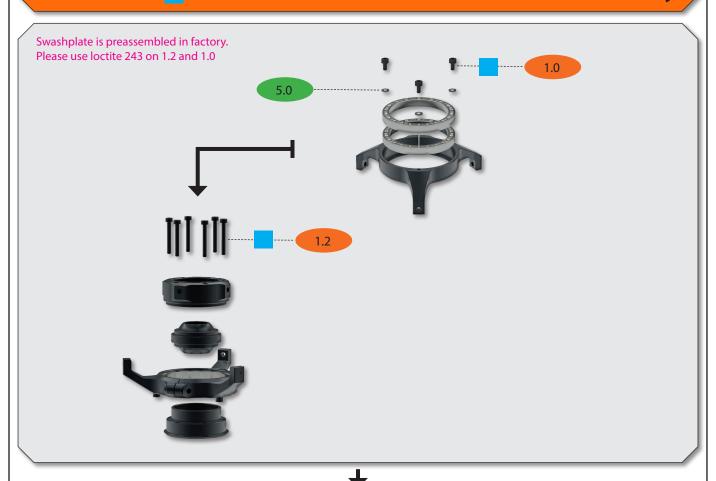


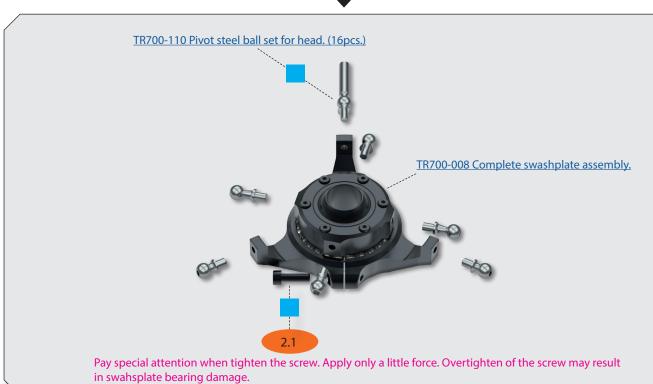
Head assembly





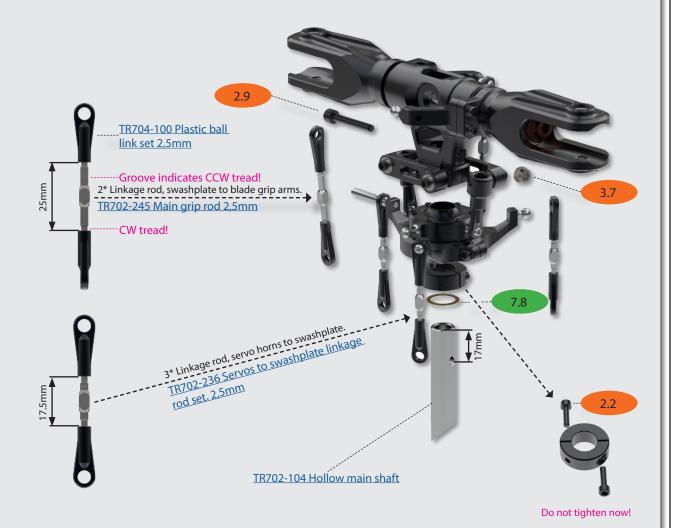
Head assembly





Head assembly

- 1. Insert main shaft into center hub first.
- 2. Tighten screw 2.9
- 3. Tighten screw 2.6 left and right step by step (use loctite 248). Make sure the shim 5.2 do not fall off. (page 12)

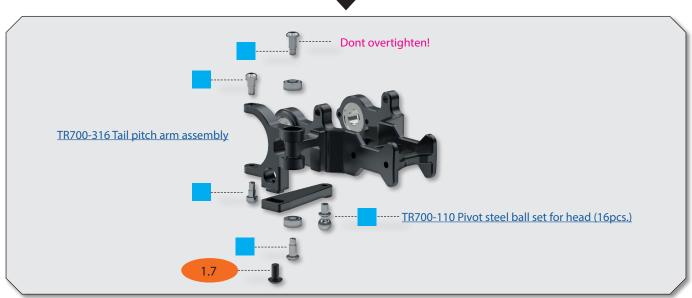


<u>Important note!</u>

The ball links have a larger and a smaller diameter. Always make sure the larger diameter is pointing towards the pivot ball when assembling!

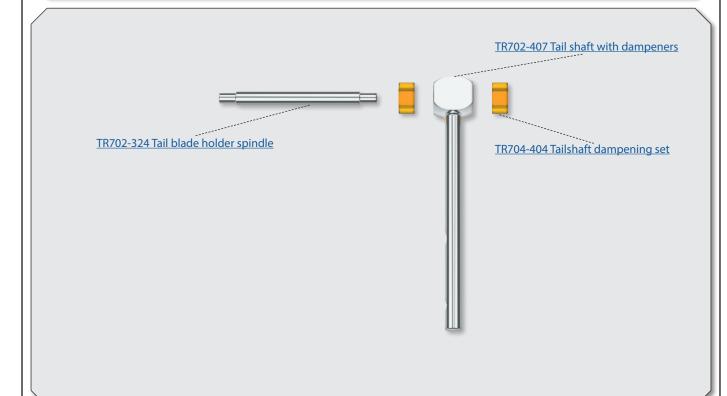


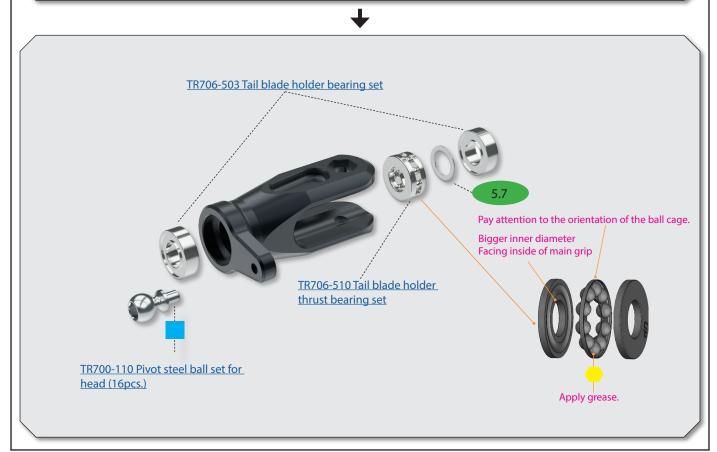






You will need: Loctite 243 = blue Grease = yellow

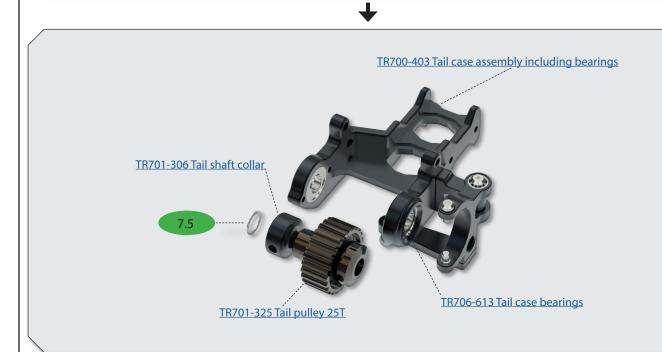




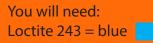


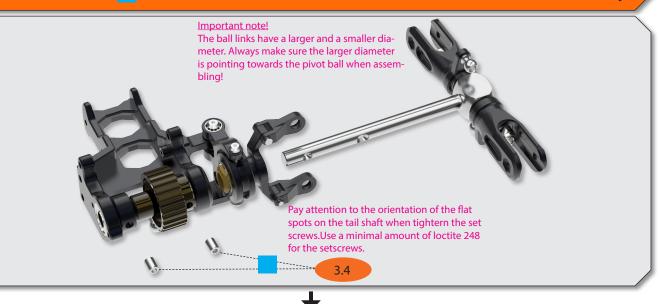




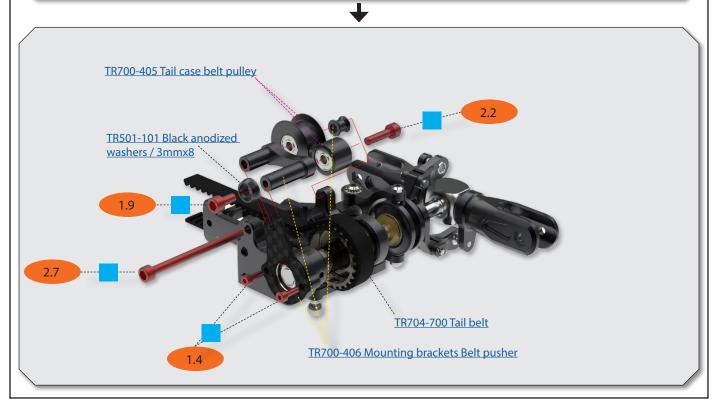








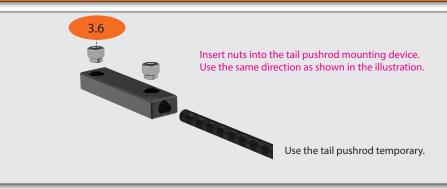


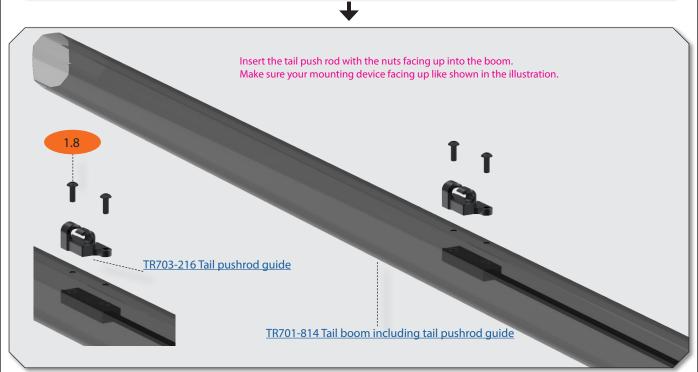


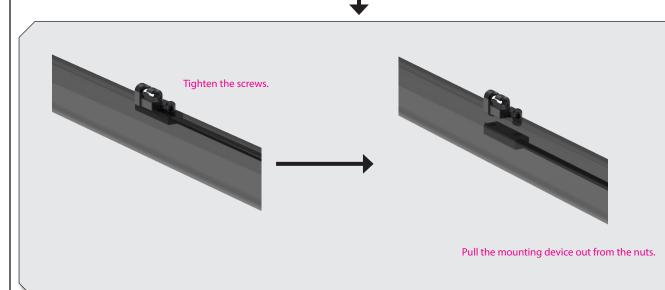


You will need:

A little bit of patience when assembling it for the first time









You will need: 2 component epoxy

Tail assembly

- -Pre assemble the threaded rod and the shell.

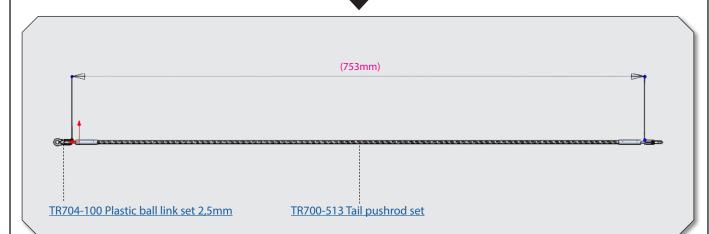
 Adjust the threaded rod to a length of 15mm (same as shown in
- -Adjust the threaded rod to a length of 15mm. (same as shown in the illustration below
- -Glue the tread into the tail push rod and the shell on the outside of the rod. Use 2 component epoxy!

please let it dry overnight to achieve 100% strength

Apply 2 component epoxy on the outside of the carbon rod.

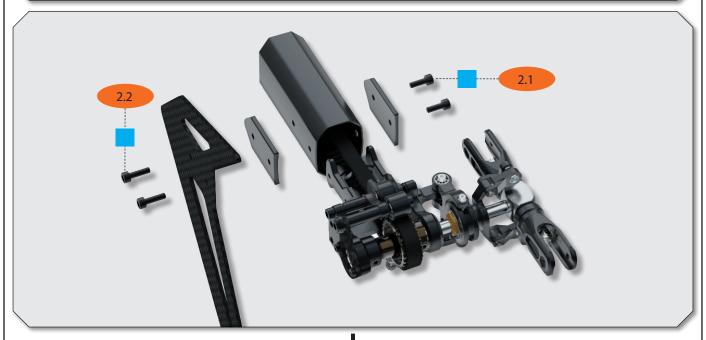
Apply 2 component epoxy inside the hole of the carbon rod to glue the treaded rod versus the carbon rod.

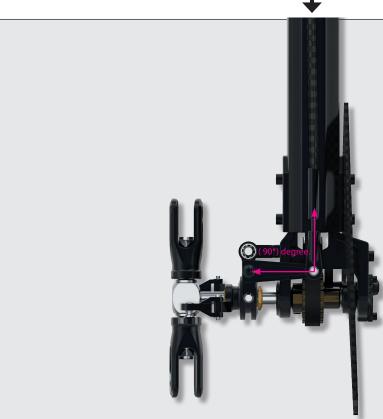
15mm on both sides.
Use 2 component epoxy!





Tail assembly





For best tail authority performance adjust center position of your FBL controller (tail servo) same as shown in the illustration (90*) degree.



Servos preparation

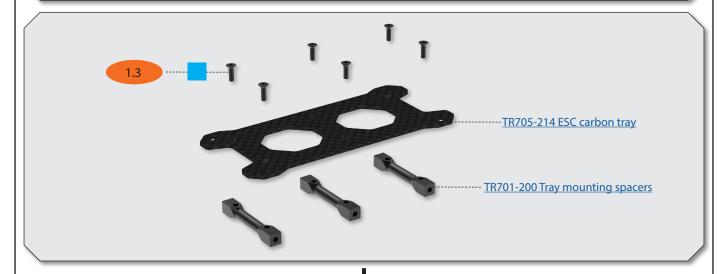




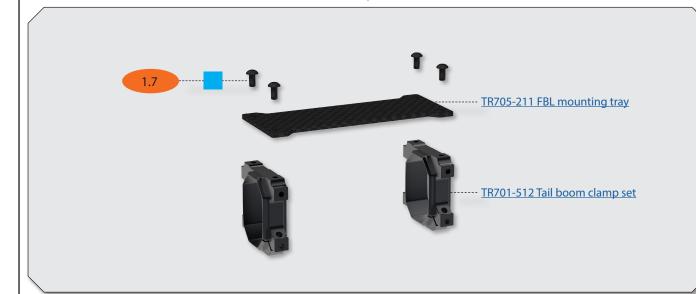


You will need: Battery tray Loctite 243 = blue TR700-711 Battery tray assembly

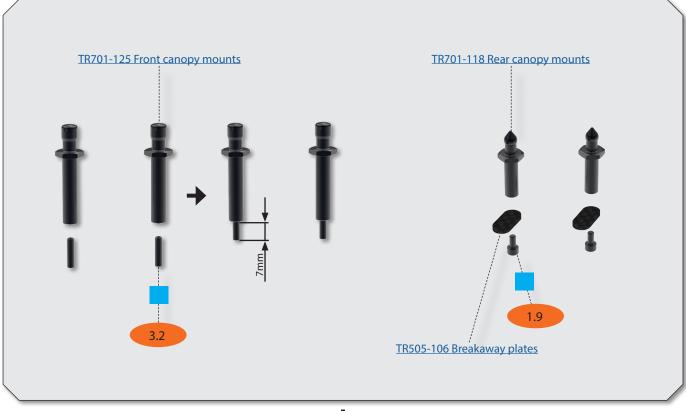


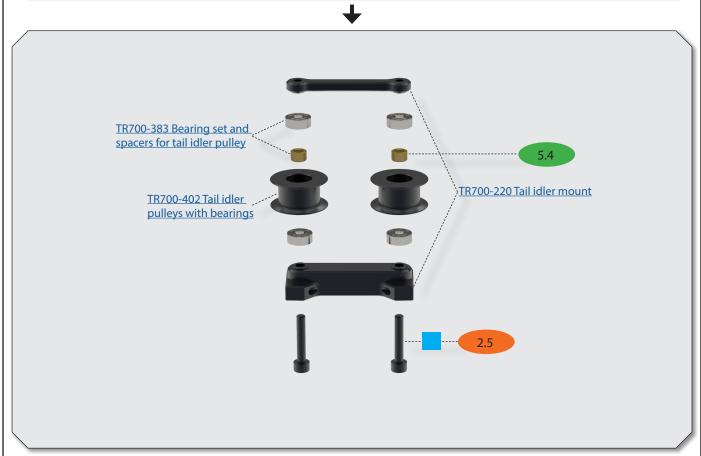




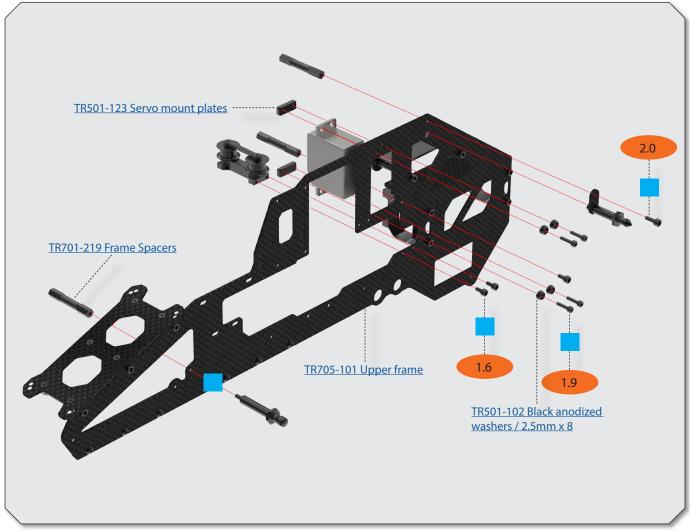


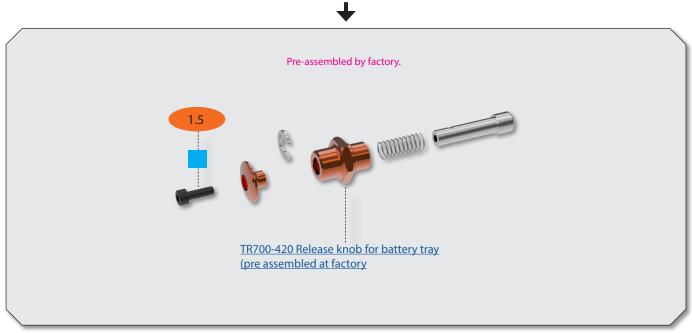




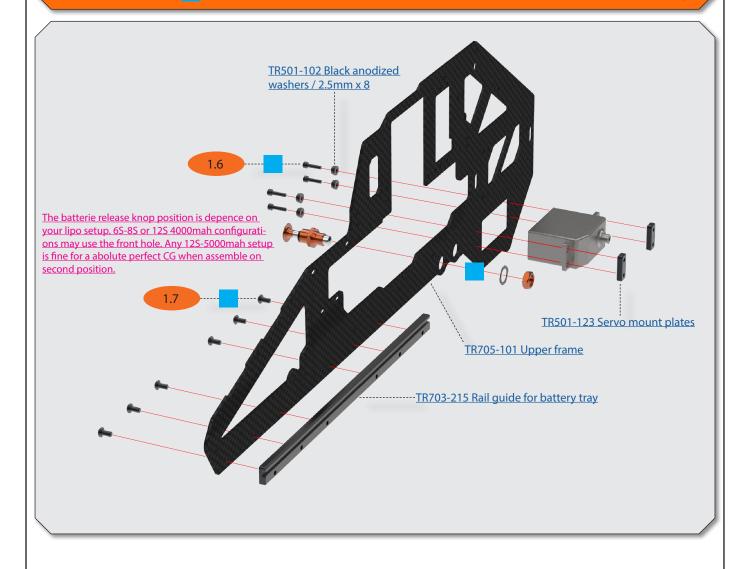












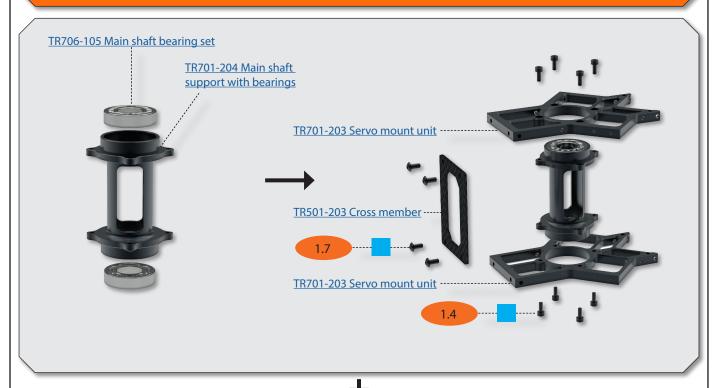


Motor mount and pinion





Servo frame and motor support

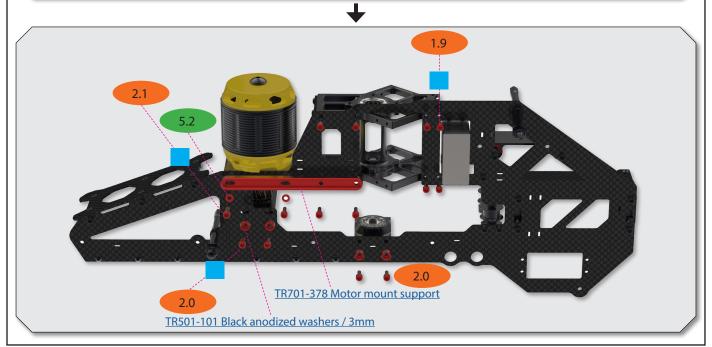


TR506-105 Main shaft bearing set-

When final assembling of the main gear, press shaft suport up versus the main gear assembling to remove up and down play. (page 37)



TR701-205 3rd bearing block



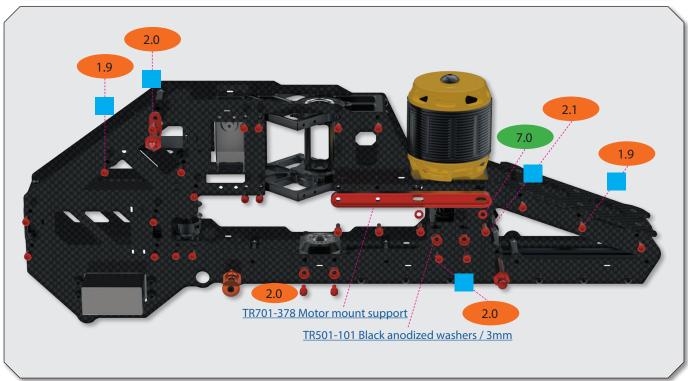


Upper and lower main frame assembly





Upper and lower main frame assembly

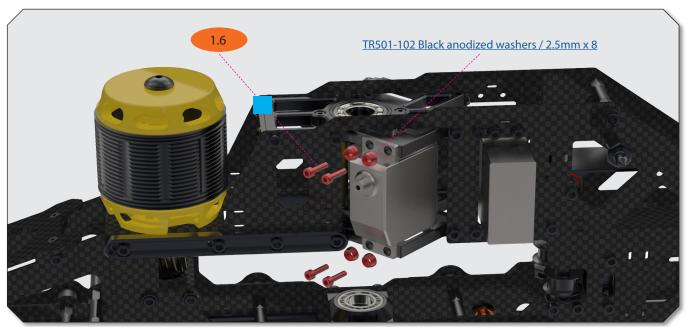






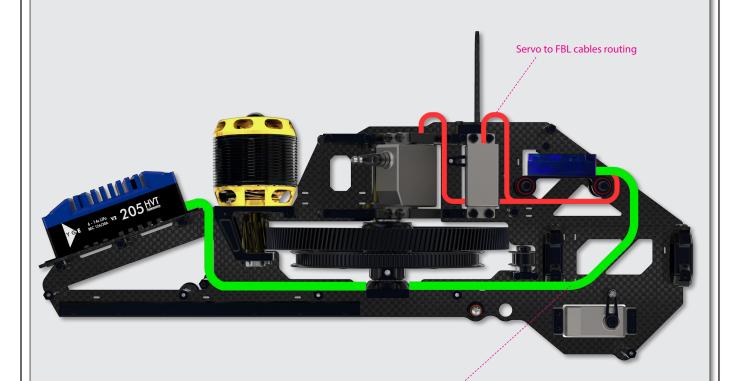
Landing gear and cyclic servos





Tips Wiring

Additionally, you may want to use servo wire protection shrink tube to avoid cuffing or cutting on servo wires. Please make sure all edges on the frames which are in contact with wires are eased with sandpaper.

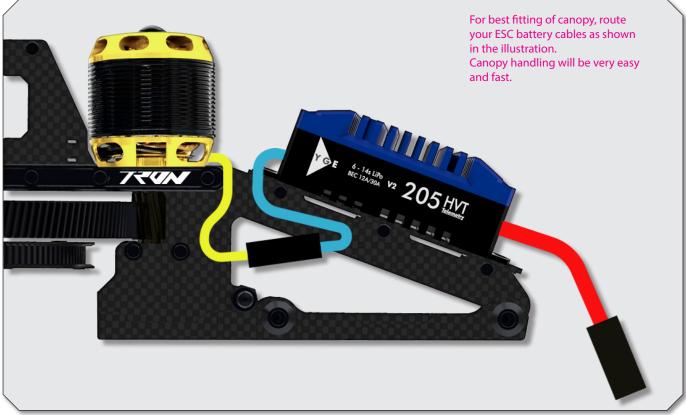


ESC to FBL cables routing



Tips Wiring

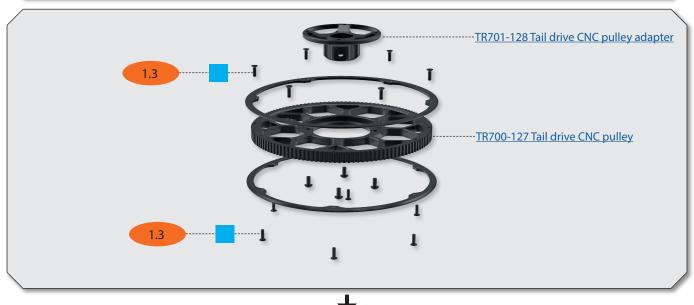


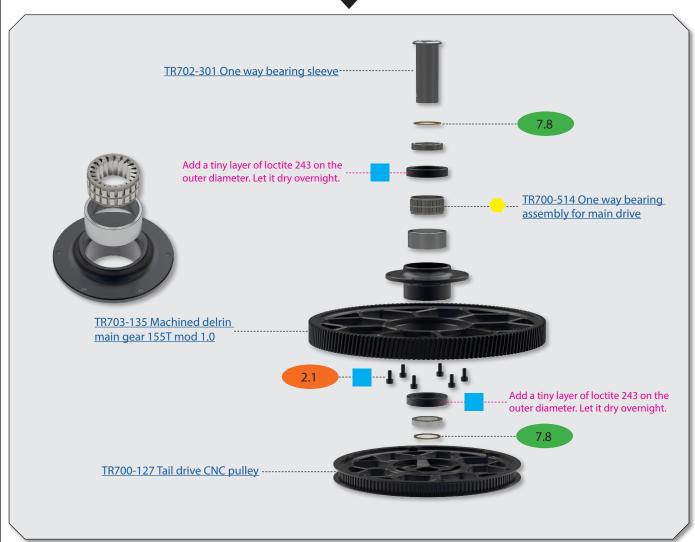




You will need: Loctite 243 = blue Grease = yellow

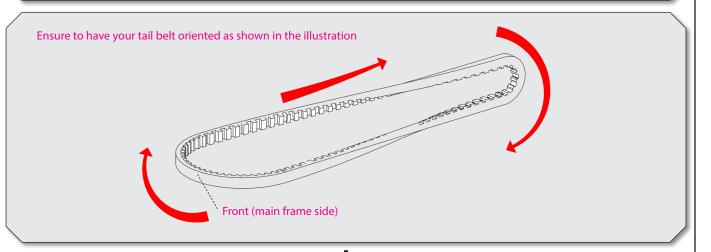
Main drive preparation

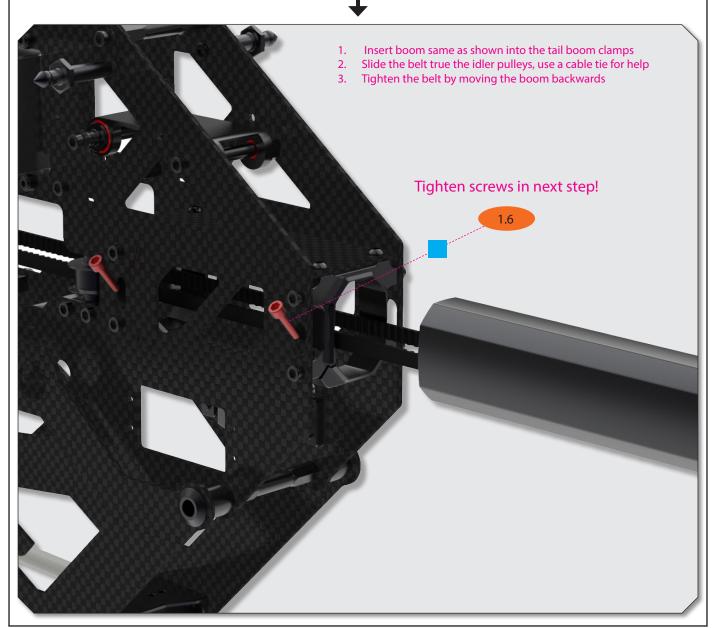






Tail boom to main frame assembly







Head and main drive

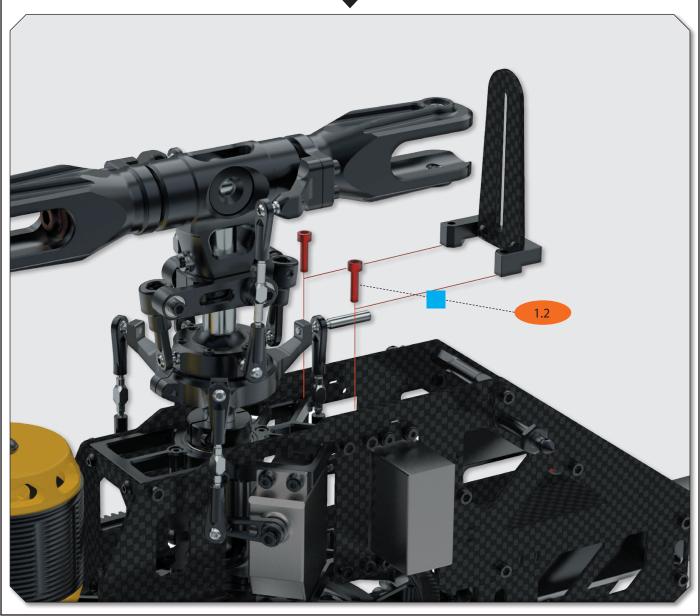
- 1. Insert main gear assembly into frame while pulling tail belt over drive pulley
- 2. Insert rotor head assembly
- 3. Make sure your main shaft glide true the one way bearing sleeve and line up with the jesus bolt screw X.X
- 4. Move down the main shaft collar to have zero up and down play on the rotor head assembly, then tighten screws X.X step by step.
- 5. Make sure to have an equal gap on the collar to achieve best holding results for the main shaft.





Anti rotation guide







Tips

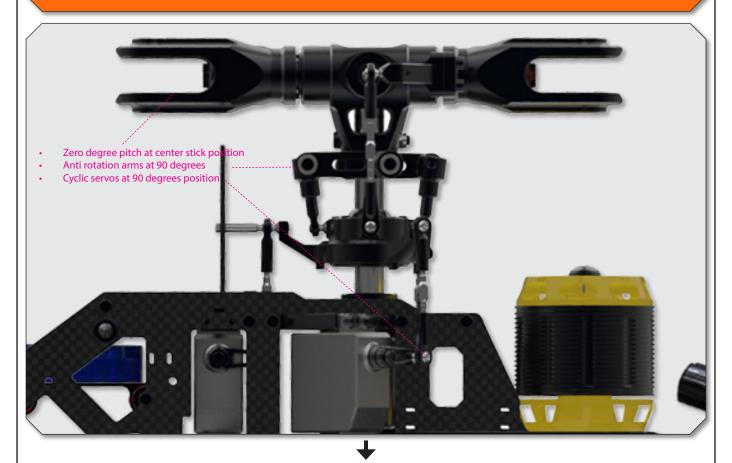
Tail rotation and canopy







Final setup and pre-flight check



- 1. <u>Disconnect your Motor wires</u> from the ESC!
- 2. FBL controller should be to set to the mode where you can level your servo center position and, or swashplate level mode.
- 3. Fine tune your servo center position as precise as you can by the position of the servo horns. For finetuning use Sub trims in the FBL software.
- 4. Adjust your linkage from the servos to the swashplate as shown in the illustration. (90 degree)
- Adjust your swashplate to Blade grip linkage to achieve 0 pitch at center stick position.
- 6. Continue setup as required in your FBL controller software.





Pre-flight check and gear ratios

1. Make sure your battery tray is securely locked. Use 4 battery straps.

Inspect your blades for possible damage and if they are slightly tighten.

3. Inspect your linkages if they all in place and not have been popt off turing transport of your model.

4. Confirm that the FBL unit is correctly initialized.

5. Make sure your canopy is secured safely. (2 pins on backside are fine)

 If you are a beginner, always seek advice by a expirianced pilot, specially for your first flight.



Recommended head speed.

Flying styles	Head speed	
Beginner and sport flying.	1500-1900rpm.	
Advanced sport, 3D flying.	1900-2200rpm.	
Hardcore 3D flying.	2200-2400rpm.	

Main and tail rotor gear ratios.

Main gear	Pinion	Ratio	Tail drive	Tail	Ratio
155/mod 1.0	14T	11.07	127T	25T	5.08
155/mod 1.0	15T	10.33			
155/mod 1.0	16T	9.69			
155/mod 1.0	17T	9.12			
155/mod 1.0	18T	8.61			

Make sure to check your model on regular basis, do a preflight check every time you plan to fly your model. <u>Max.</u> <u>head speed for main rotor head must not exceed 2600 RPM!</u>

Fly safe!

Contact:

For sales: sales@tronhelicopters.com / for support: support@tronhelicopters.com tronhelicopters.com