

LF24-MFT-S US Technical Data Sheet

Modulating, Spring Return, 24 V, Multi-Function Technology®



Technical Data	
Power Supply	24 VAC, ±20%, 50/60 Hz, 24 VDC, ±10%
Power consumption in operation	2.5 W
Power consumption in rest position	1 W
Transformer sizing	5 VA (class 2 power source)
Shaft Diameter	3/8...1/2" round, centers on 1/2"
Electrical Connection	(2) 18 GA appliance cables with 1/2" conduit connectors, 3 ft [1 m],
Overload Protection	electronic throughout 0...95° rotation
Electrical Protection	actuators are double insulated
Operating Range	2...10 V (default), 4...20 mA w/ ZG-R01 (500 Ω, 1/4 W resistor), variable (VDC, PWM, on/off, floating point)
Operating range Y variable	Start point 0.5...30 V End point 2.5...32 V
Input Impedance	100 kΩ for 2...10 V (0.1 mA), 500 Ω for 4...20 mA, 1500 Ω for PWM, On/Off and Floating point
Position Feedback	2...10 V, Max. 0.5 mA, VDC variable
Angle of rotation	Max. 95°, adjustable with mechanical stop
Torque motor	35 in-lb [4 Nm]
Direction of motion motor	selectable with switch 0/1
Direction of motion fail-safe	reversible with cw/ccw mounting
Position indication	Mechanical
Running Time (Motor)	default 150 s, variable 75...300 s
Running time fail-safe	<25 s @ -4...122°F [-20...50°C], <60 s @ -22°F [-30°C]
Angle of rotation adaptation	off (default)
override control	min. position = 0% , mid. Position = 50% , max. position = 100% (Default)
Ambient humidity	max. 95% r.H., non-condensing
Ambient temperature	-22...122°F [-30...50°C]
Storage temperature	-40...176°F [-40...80°C]
Degree of Protection	IP54, NEMA 2
Housing material	galvanized steel
Agency Listing	cULus acc. To UL 873 and CAN/CSA C22.2 No. 24-93
Noise level, motor	30 dB(A)
Noise level, fail-safe	62 dB(A)
Servicing	maintenance-free
Quality Standard	ISO 9001
Weight	3.3 lb [1.5 kg]
Auxiliary switch	1 x SPDT, 3 A resistive (0.5 A inductive) @ AC 250 V, adjustable 0...95°

*Variable when configured with MFT options.

†Rated Impulse Voltage 800V, Type of Action 1.AA.B, Control Pollution Degree 3.

Torque min. 35 in-lb, Control DC 2...10 V (DEFAULT), Feedback DC 2...10 V (DEFAULT)

Application

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. A feedback signal is provided for position indication.

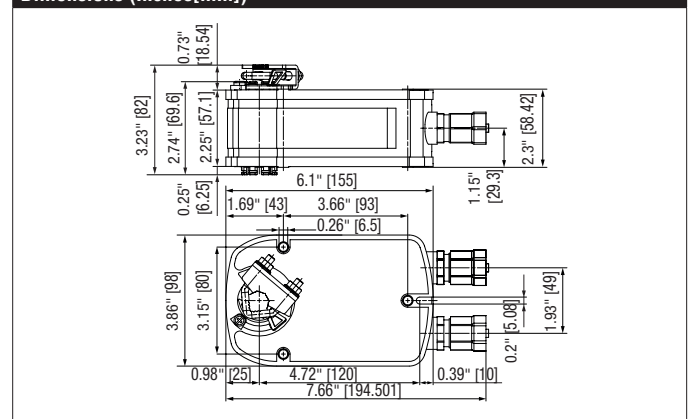
Default/Configuration

Default parameters for 2 to 10 VDC applications of the LF.-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

Operation

The LF24-MFT US actuator provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The actuator will synchronize the 0° mechanical stop or the damper or valves mechanical stop and use this point for its zero position during normal control operations. The actuator uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact position. The ASIC monitors and controls the brushless DC motor's rotation and provides a Digital Rotation Sensing (DRS) function to prevent damage to the actuator in a stall condition. The position feedback signal is generated without the need for mechanical feedback potentiometers using DRS. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The LF24-MFT US is mounted directly to control shafts up to 3/4" diameter (K6-1 clamp) and anti-rotation bracket. A crank arm and several mounting brackets are available for damper applications where the actuator cannot be direct coupled to the damper shaft. The spring return system provides minimum specified torque to the application during a power interruption. The LF24-MFT US actuator is shipped in the zero position, compression against seats or gaskets for tight shut-off is accomplished manually.

Dimensions (Inches[mm])



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Accessories	
AV6-20	Shaft extension
K6 US	Standard LF clamp (3/8" to 1/2").
K6-1	Shaft clamp reversible
KG10A	Ball joint
KG8	Ball joint
KH8	Damper crank arm
KH-LF	Actuator arm
KH-LFV	V-bolt Kit for KH-LF.
LF-P	Anti-rotation bracket LF.
SH10	Push rod for KG10A ball joint (36" L, 3/8" diameter).
SH8	Push rod for KG6 & KG8 ball joints (36" L, 5/16" diameter).
TOOL-06	8 mm and 10 mm wrench.
ZDB-LF	Angle of rotation limiter
ZF8-LF	Form fit adapter
ZG-109	Right angle bracket for ZS-260.
ZG-110	Stand-off bracket for ZS-260.
ZG-112	LF right angle bracket 4-1/2x5-1/2x2-1/2" (HxWxD).
ZG-DC1	Damper clip for damper blade, 3.5" width.
ZG-DC2	Damper clip for damper blade, 6" width.
ZG-LF112	LF crankarm adaptor kit (includes ZG-112).
ZG-LF2	LF crankarm adaptor kit (T bracket included).
ZG-LMSA-1	Shaft extension for 3/8" diameter shafts (4" L).
ZG-LMSA-1/2-5	Shaft extension for 1/2" diameter shafts (5" L).
ZS-100	Weather shield - galvanneal 13x8x6" (LxWxD).
ZS-101	Base plate for ZS-100.
ZS-150	Weather shield - PC w/ foam seal 16x8-3/8x4" (LxWxD).
ZS-260	Explosion proof housing.
ZS-300	NEMA 4X, 304 stainless steel enclosure.
ZS-300-5	NEMA 4X, 316L stainless steel enclosure.
ZS-300-C1	1/2" shaft adaptor, standard with ZS-300(-5).
ZS-300-C2	3/4" shaft adaptor for ZS-300(-5).
ZS-300-C3	1" shaft adaptor for ZS-300(-5).
IRM-100	Input rescaling module for modulating actuators.
MFT-P	Belimo PC-Tool
P475	Shaft mount, non-Mercury aux. switch for 1/2" dia. shafts.
P475-1	Shaft mount, non-Mercury aux. switch for 1" dia. shafts.
PS-100	Low voltage and control signal simulator.
PTA-250	Pulse width modulation interface for modulating actuators.
SGA24	Positioners suitable for use with the modulating damper actuators LM..A-SR, NM..A-SR, SM..A-SR and GM..A-SR
SGF24	Positioners suitable for use with the modulating damper actuators LM..A-SR, NM..A-SR, SM..A-SR and GM..A-SR
UK24BAC	Gateway MP to BACnet MS/TP
UK24LON	Gateway MP to LonWorks
UK24MOD	Gateway MP to Modbus RTU
ZG-CBLS	Electrical junction box for LF.
ZG-R01	4 to 20 mA adaptor, 500Ω, 1/4 W resistor w 6" pigtail wires.
ZG-R02	50% voltage divider kit (resistors with wires).
ZG-SGF	Mounting plate for SGF.
ZG-X40	120 to 24 VAC, 40 VA transformer.
ZK2-GEN	Connection cable
ZTH US	Handheld programming tool w/ ZK1-GEN, ZK2-GEN, ZK6-GEN.

24 VAC Transformer

Blk (1)	Common
Red (2)	+ Hot
Wht (3)	Y Input
Wht (5)	U Output

On/Off

24 VAC Transformer (AC Only)

Blk (1)	Common
Red (2)	+ Hot
Wht (3)	Y Input
Wht (5)	U Output

Floating Point

24 VAC Transformer

Blk (1)	Common
Red (2)	+ Hot
Wht (3)	Y Input
Wht (5)	U Output

VDC/mA Control

24 VAC Transformer (AC Only)

Blk (1)	Common
Red (2)	+ Hot
Wht (3)	Y Input
Wht (5)	U Output

PWM Control

24 VAC Transformer (AC Only)

Blk (1)	Common
Red (2)	+ Hot
Wht (3)	Y Input
Wht (5)	U Output

Functions	a	b	c
Min	0% ←	↘	↘
Mid	50% ←	↘	↘
Max	100% ←	↘	↘
Normal	Control mode acc. to Y	↘	↘

Override Control

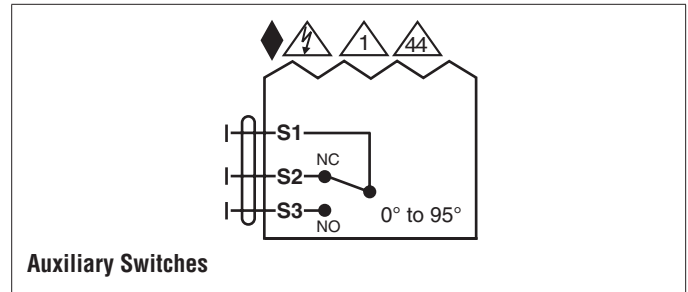
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Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a shaft up to a 3/4" diameter and center on a 1/2" shaft (default). Actuator shall deliver a minimum output torque of 35 in-lbs. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.



Wiring Diagrams

- WARNING! LIVE ELECTRICAL COMPONENTS!**
During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.
- Meets cULus requirements without the need of an electrical ground connection.
- Apply only AC line voltage or only UL-Class 2 voltage to the terminals of auxiliary switches. Mixed or combined operation of line voltage/safety extra low voltage is not allowed.
- Actuators with appliance cables are numbered.
- Provide overload protection and disconnect as required.
- Actuators may also be powered by 24 VDC.
- Only connect common to negative (-) leg of control circuits.
- A 500 Ω resistor (ZG-R01) converts the 4 to 20 mA control signal to 2 to 10 VDC.
- Control signal may be pulsed from either the Hot (Source) or Common (Sink) 24 VAC line.
- For triac sink the Common connection from the actuator must be connected to the Hot connection of the controller. Position feedback cannot be used with a triac sink controller; the actuator internal common reference is not compatible.
- Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.
- IN4004 or IN4007 diode. (IN4007 supplied, Belimo part number 40155).
- One built-in auxiliary switch (1x SPDT), for end position indication, interlock control, fan startup, etc.

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