





TITAN GER - 1000

5 Systems in 1 Device



LONG RANGE SYSTEM

> **IONIC SEARCH SYSTEM**

3D IMAGING SYSTEM



Downlo







Critical Warning

Please be sure that all precautions taken against risks

Do not use your device while it is raining or on extremely wet floor

Turn on your device after you make sure that all parts are in place

Make sure that the device battery is fully charged before searching

If the battery start to give a peep sound, close the device and recharge the battery

Do not start the pulse induction system without connecting the coil cable to the device, other ways the device will stop in the middle of opening

It is recommended to read the user manual before start working on the device to understand everything and to avoid mistakes doing the search

After the device start make sound and turn off automatically put the battery on charge and do not try to start the device without charging the battery



Dear customer, thank you for choosing the TITAN GER – 1000 This device enables you to detect underground gold &Treasures TITAN GER – 1000 designed to reach 45 meters under the ground and 2500 meters front range In addition, it contain five systems to confirm your target and identify the target underground and its depth

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Be aware of high voltage resources, and do not use any charger other than the original charger that come with the device

Main unit of the device is under warranty against all electronic breakdowns for two (2) years

Any damages caused by user errors (laying open the main unit, hits, harms etc.) are not within this warranty

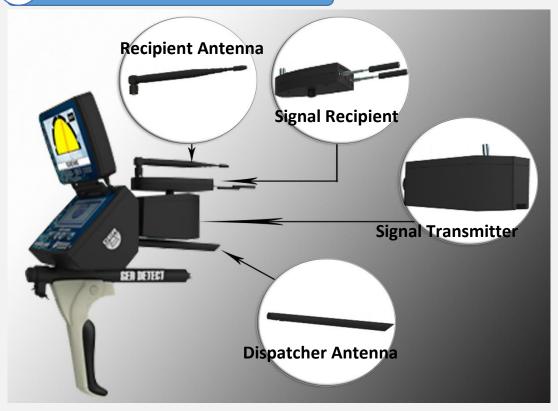
Battery , antenna and tablet are also not within this warranty

You should follow the instructions in this user manual strictly to minimize the faults and to use your device correctly

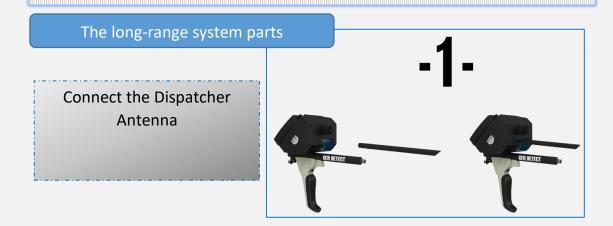




1 The Long Range System



This system specializes to cover vast areas and locate the target with in 1 meter Square up to depths of 45 meters below the surface of the ground and Front Range up to 2,500 meters.



Downlo







Connect the Signal Transmitter



Connect the Signal Recipient



Connect the Recipient
Antenna









- Connect the Battery to the Device
- Open the Device
 Screen and Start The

Device Through

ON / OFF switch



CLICK ON THE SCREEN OF THE DEVICE TO DISPLAY THE LANGUAGES LIST THE DEVICE WORKS ON FOUR LANGUAGES:

(DUTCH-ENGLISH-FRENCH-ARABIC)





Press on setting icon to enter to setting screen



Press on information icon to enter to information

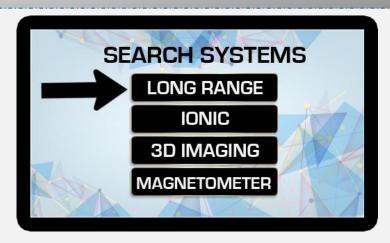
www.gerdetect.de





After selecting the language, you want to work in (English for example)

The search systems menu will appear (Select long-range search system)



After selecting the long-range system, the metals that this system can detect will appear :

Choose the metal to be search for from a list of metals through pressure on the metal name, (BURIED GOLD FOR EXAMPLE)



After selecting, the metal to be searched for, the Front Range Options will appear

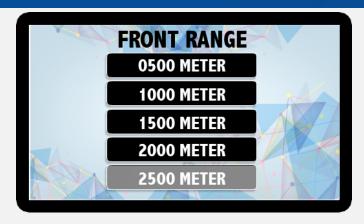
Choose the Front Range according to the area you want to reach

You can select between (0500 M - 1000 M - 1500 M - 2000 M - 2500 M)

Choose 2500 M for example.

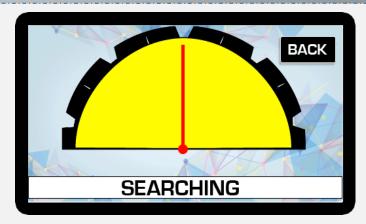






After selecting the Front Range, the search screen will appear which contain an indicator, which will guide you directly to the target. Make sure that the antenna is pointing ahead

Adjust the antenna with the indicator on the screen to receive accurate signal



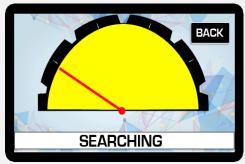
Increase the length of the antennas receiving a signal

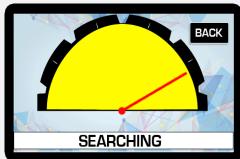
To able the device to detects targets even to 2500 meters



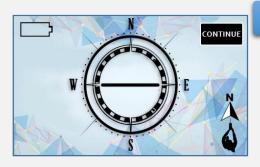








After detecting the target, confirm the target from four direction





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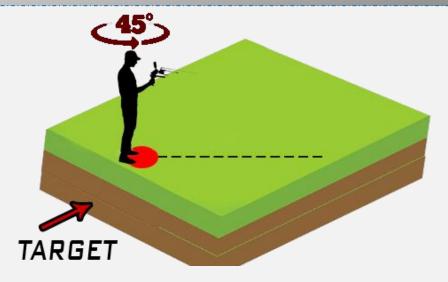






To determine the depth of the discovered target Stand above target and turn 45 degrees

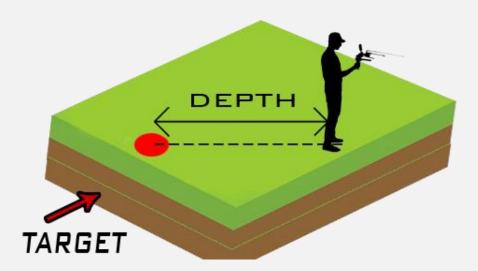
Walk straight ahead until the antenna reverse to the back



Measure the distance between the antennas reversing back and the target center point.

The distance between the antennas reversing back and the center point is equal the target depth

For example, if the distance is 10 m the depth of the target is 10.







The Ionic Search System



This system specializes to cover vast areas and locate the target with In 1 meter Square up to a depths of 45 meters below the surface of The ground and Front Range up to 2500 meters vertical

Connect component

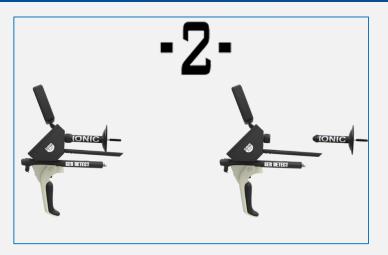
Connect the Dispatcher Antenna







Connect the Ionic
Sensor



- Connect the Battery to the Device
 - Open the Device Screen and Start the Device through ON / OFF switch



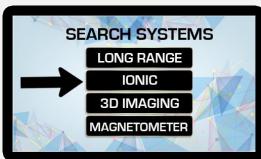
Click on the screen of the device to display the languages list the device works on four languages:

(DUTCH-ENGLISH-FRENCH-ARABIC)





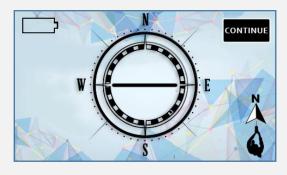


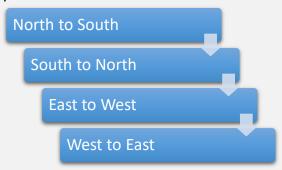


After selecting the language, you want to work in (English for example)

The search systems menu will appear, Select IONIC search system

After selecting the ionic system you have to determine the direction from north / south





After selecting the ionic system, the search screen will appear.

Point the device to the ground if the device start to make a sound you must calibrate

The device with the ground by pressing on the calibration button as follow:









After you finish the calibration, start the search by moving the device 180 degrees right and left.

When the device detect a target, it will start to make a sound.

In addition, the indicter will start to move to alert you about the target discovered.

The sound will start Accelerating when you will be close to the target.



YOU CAN ALSO USE THE IONIC SEARCH SYSTEM DURING THE DRIVING IN A MOVING VEHICLE... AS FOLLOW:

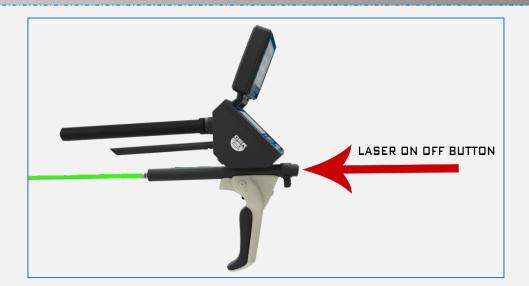






In the event of lack of vision, you can operate the laser to locate the target place.

Through the laser ON OFF, button



Note:

When you use the Ionic Search System the researcher should avoid directing device northward never, because the device will make a sound (This is because the device in this case will be Reverse of magnetic fields, which is directing from north to south)





3 3D Imaging System



This system specializes to show you the area scanned on the tablet screen in three-dimensional photo and through which you can specify the target size, shape and depth of the target underground up to 45 meters.









Connect the 3D Imaging Sensor

TITAN SENSOR

TITAN SENSOR

GERRIER

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Install the Tablet Holder To The Device



Fix the tablet that supplied with the device on the tablet holder which

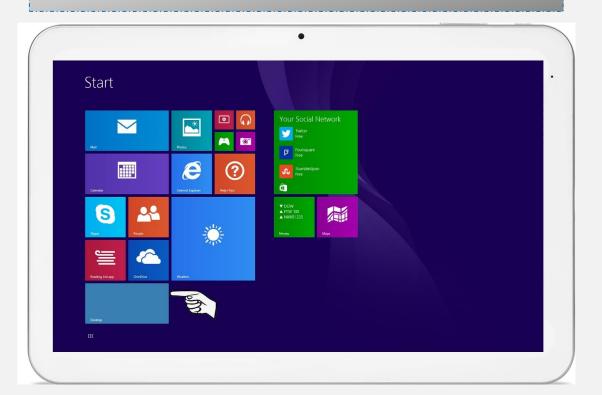
Contains analysis program to display the photo







- Turning to the tablet to make a Bluetooth connection between the device and the analysis program.
- Click on the Desktop option

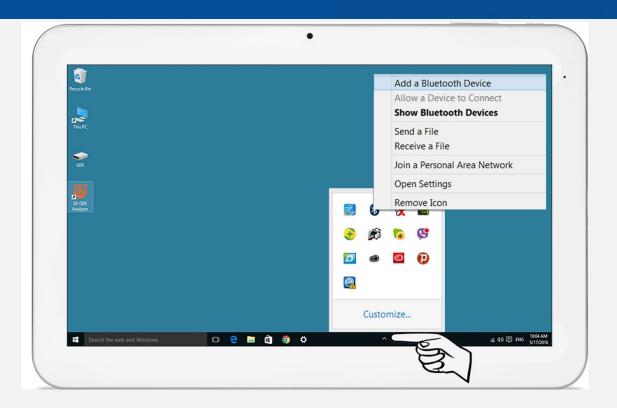


The desktop screen will appear.

- 1- Touch the arrow to revel the hidden icons.
- 2- Click on the Bluetooth icon.
- 3- Chose add a Bluetooth device

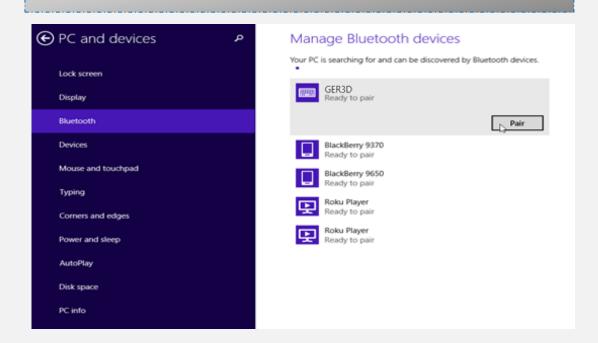






The tablet will start to search for any devices with Bluetooth in the area.

When the device Bluetooth appear click on pair.



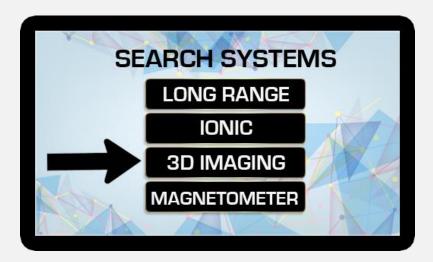




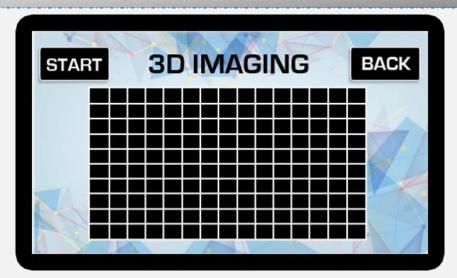


NOTE: The Bluetooth password is 1000

Now select the 3D IMAGING system from the systems menu in the device.



After selecting the 3D imaging system, the search screen will appear.



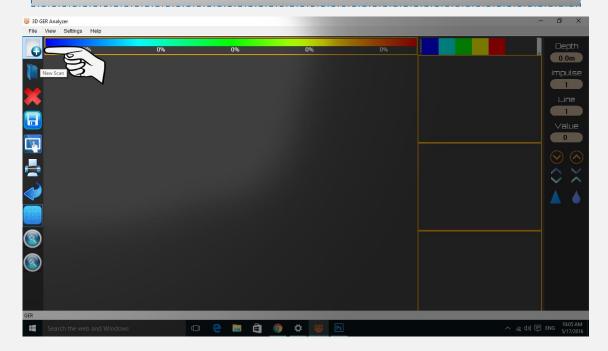




Open the 3D GER Analyzer that installed on the tablet



Start a new project to scan the ground by clicking on new scan

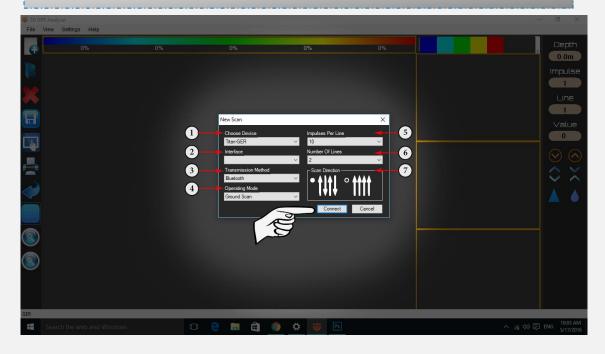








The connection settings window will appear on the screen.



Enter the settings as follow

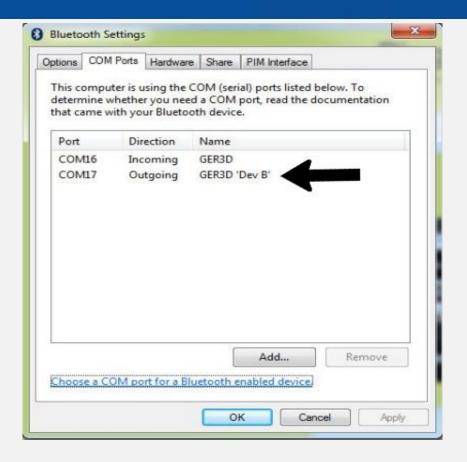
1- CHOSE DEVICE: TITAN GER

2-INTER FACE: OPEN THE BLUETOOTH SETTINGS AND ENTER THE

COM NUMBER (OUT GOING) FOR EXAMBLE COM 17







3-TRANSMISSION METHOD: BLUETOOTH

4- OPERATING MODE: GROUND SCAN

5-IMPULSES PER LINE : 10 TO 50 (EACH IMPULSE = 30 CM)

6- NUMBER OF LINES: 1 TO 15 (EACH IMPULSE = 30 CM)

7- SCAN DIRECTION: OPTIONAL



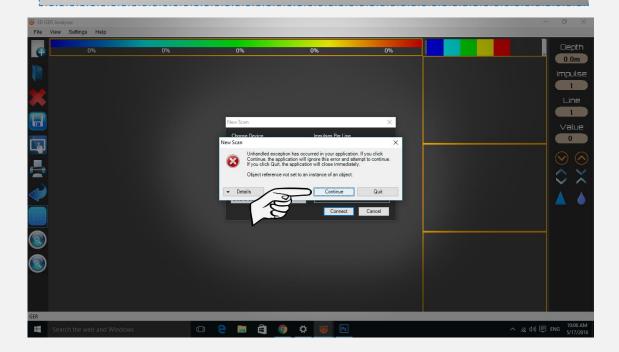






After you enter the sittings, click on connect and shift to the device.

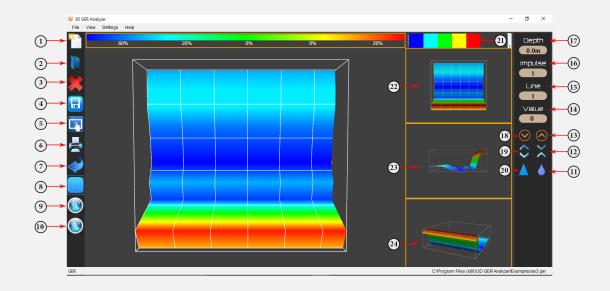
Therefore, the device will start taking pictures as follow:









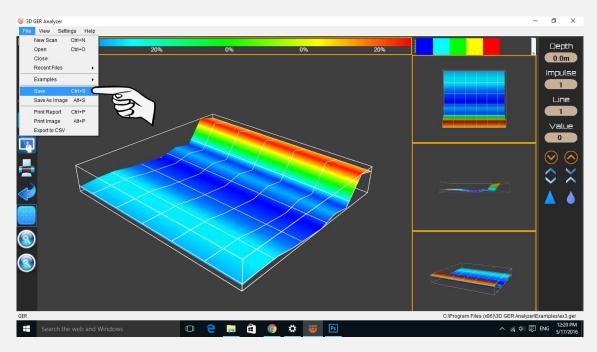


NO	Explaining		
1	Start new scan and disconnect after scanning finish		
2	Open file from your tablet already existing in your tablet		
3	Cancel the scanning or delete the photo		
4	Save the photo as a .GER file to re-open it any time you want		
5	Save as a photo with no option to change anything in the photo shape		
6	Print report allowed you to see the where about of the metal and the other elements		
7	To return the photo as it is was before you start analyzing		
8	To hide and appear the grid which Represent the number of photo in the scan		
9	zoom to make the picture bigger		





10	Miniature to make the picture smaller			
11	A Tool you use it in case of not clear target to see the correct shape (-)			
12	A Tool you use it in case of not clear target to see the correct shape (+)			
13	to make the target in high size			
14	to make the target in low size			
15	move between the grid squares to pin point the area that you want to know its depth			
16	move between the grid squares to pin point the area that you want to know its depth			
17	The value which will deferent between the metals and the cavity and the ground			
18	when you pin point the target will allowed you to now in which line is your target exactly			
19	when you pin point the target will allowed you to now in which line is your target exactly			
20	Depth when you can see the target exact depth			
21	This options allowed you to see the target in 2D & 3D shape and you can hide the soil for			
	example or the metals and keep the cavity			
22	Another way to see the target from down			
23	Another way to see the target from the side			
24	Another way to see the target from the angle			



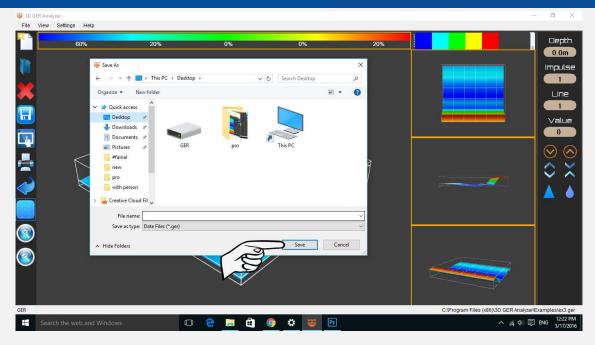
After you finish the scanning you can save the scan on the tablet as a project to be able to analyze again also you can save it as a photo

Note: Here is the color system

Red	Metal	Green	Ground
Yellow	Minerals	Blue	Cavity

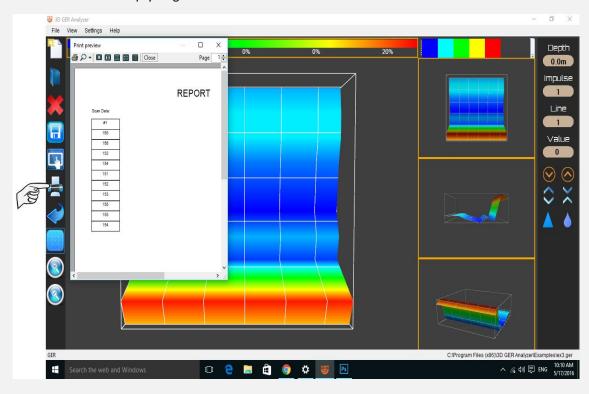






If you want to have printed report you can press on the print icon, the report will appear, and you can print it (the number in the report it is the value of the ground – metals – cavities)

Note: if the deference between tow picture (tow square) is big that mean good target and if is it small that is mean empty target







4

The Magnetometer System



Connect component

Connect the Sensor to the Device









Click on the screen of the device to display the languages list

The device works on four languages:

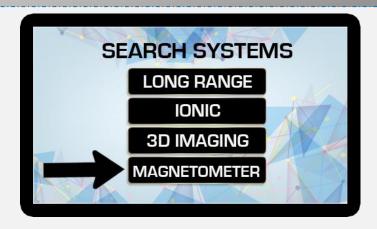
(DUTCH-ENGLISH-FRENCH-ARABIC)



After selecting the language, you want to work in (English for example)

The search systems menu will appear

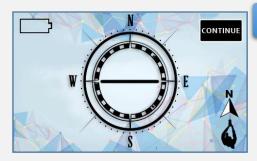
Select **MAGNETOMETER** search system







After selecting the magnetometer system you have to determine the direction from north / south











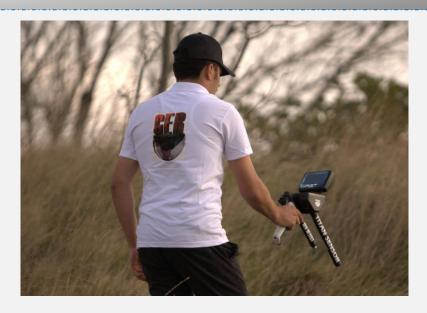
After selecting the magnetometer system, the search screen will appear.

Point the device to the ground if the device start to make a sound you must calibrate

The device with the ground by pressing on the **calibration button** as follow:



After you finish the calibration, start the search by moving the device forward and back agents the ground

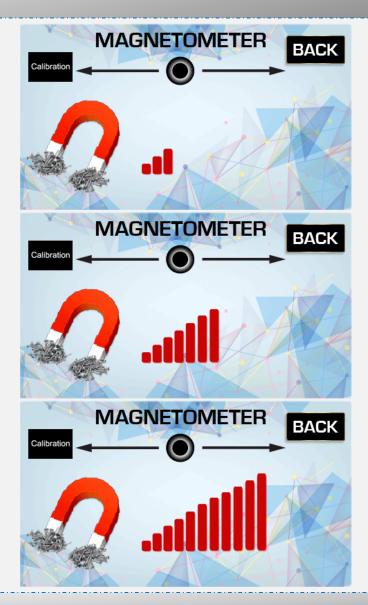






When the device detect a target, it will start to make a sound.

In addition, the indicter will start to move to alert you about the target discovered.



The sound will start Accelerating when you will be close to the target.

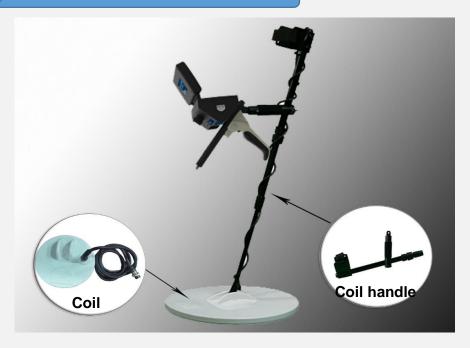
Note:

When you use the magnetic system the researcher should avoid directing device northward never, because the device will make a sound (This is because the device in this case will be Reverse of magnetic fields, which is directing from north to south)





5 • The Pulse induction System



This system specializes to cover vast areas and locate the target with in 1 meter Square up to depths of 12 meters below the surface of the ground.

Connect component

Connect the coil cable to the device

Start the device by pressing on the power switch (on off)







After pressing the on off button

Make sure that there is no metal on the person he will hold the device or electronic devices or mobile phones or high voltage electricity wires in the area you want to use the device in

open the device by the start button



Select the device language from the list of languages

Move between languages through the navigation keys (up and down)





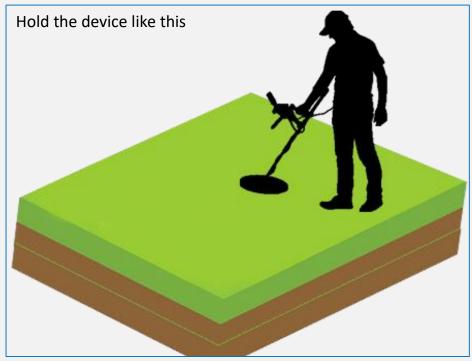




After selecting the language the device will open to the discrimination search mode

First, you have to calibrate the device with the ground when you start searching (during the search if you hear noise you have to make calibration again











The device work on two modes

- 1- Discrimination search mode : This mode can discriminate between ferrous metal and non-ferrous
- 2- Cavity search mode

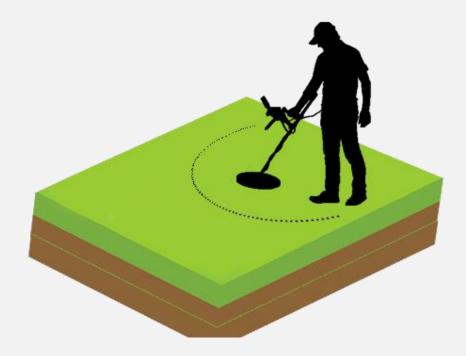
 This mode can detect all cavities under the ground

 (Natural cavities made by human cavities)

 In addition, it can show you the shape and the size

Start the search by moving the device right and left in stable movement and close to the ground.

The coil should be above the ground between 5 TO 10 CM









Start with the normal search mode

In case the device detect any metal an indicator will appear on the screen and you will start to hear sound conforming the target present:



Adjust the sensitivity by the navigation buttons UP & DOWN.

Switch between the options by start button.

The descremination mode it can Separate between metals

Ferrous : for iron and the invaluable metals like copper & steel & aluminum

Non- Ferrous: for Gold and silver and bronze.





In the cavity search mode start your scan in stable way to determine the shape of the cavity.











Warning

If you want the device work well without errors you have to follow next steps

When using the device please do not wear the watch



When using the device please do not wear the jewelry



When using the device please get away from metal, lighter and mobile phone



Please take off the belt



The shoes shoud not contain any metal



Stay away from the car

Only you can use the ionic system, while you are driving the car



Stay away from electrical ground power lines or any surfacing electric



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