

TSL25911 Light Sensor

This module is an ambient light sensor with TSL25911 as its core. It can sense the ambient light intensity around and output it through the I2C interface. The output data uses a formula to derive the illuminance in lux (ambient light intensity) to approximate the human eye response.

Specifications

- Light sensor: TSL25911FN
- Communication interface: I2C (constant address: 0x29)
- Effective range: 0~88000Lux
- Operating voltage: 3.3V/5V
- Dimensions: 27mm × 20mm
- Mounting hole size: 2.0mm

Pinouts

Pin	Instruction
VCC	3.3V / 5V
GND	GND
SDA	MCU.I2C data line
SCL	MCU.I2C clock line
INT	interrupt output, optional

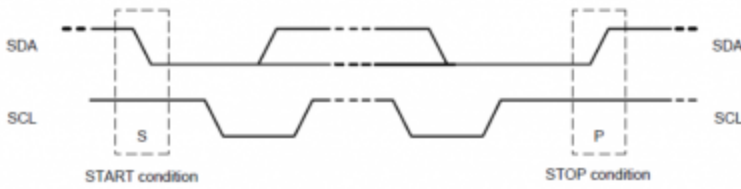
Hardware Description

Chip

This product uses TSL25911FN, which is a light intensity digitizer based on IIC bus communication. The sensor combines a wideband photodiode (visible and infrared) and an infrared response photodiode on a single CMOS integrated circuit that provides near-light adaptive response over an effective 16-bit dynamic range (16-bit resolution). Two integral ADCs convert the photodiode current into a digital output representing the irradiance measured on each channel. The digital output can be inputted to a microprocessor where an empirical formula is used to derive illuminance in lux (ambient light level) to approximate the human eye response.

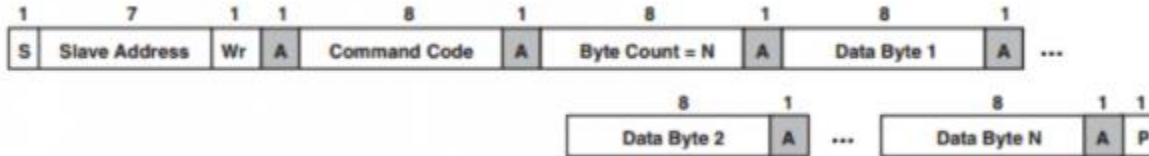
Timing analysis

TSL2591 use I2C interface, has a data line and a clock signal line. There are three types of signals will be used during the I2C bus data transmitting. They are Start signal, Stop signal, and Ack signal.



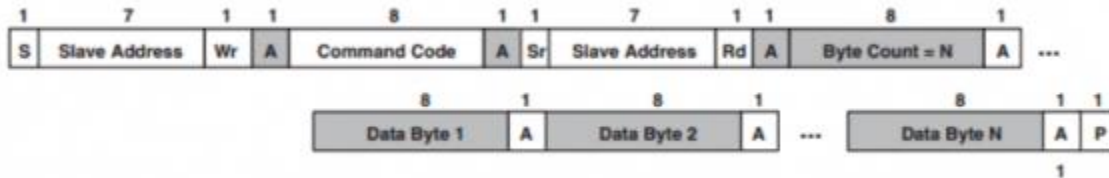
Start signal: When SCL is HIGH and SDA jumps from HIGH to LOW, the data transmission starts. Stop signal: When SCL is HIGH and SDA jumps from LOW to HIGH, the data transmission stops. Ack signal: When the receiver IC have received 8 bit of data, it will send out a special LOW level pulse to the transmitter IC to indicate that the data have been received.

I2C Write



At the beginning, the Host (here is STM32, and we will call it the Host hereafter) sends out a start signal, and combines the 7 bit of I2C slave address with the Write bit, then, sends this 8 bit of data to the Slave (here is TSL2581 sensor, and we will refer it to the Slave hereafter). Then, the Slave sends back an ACK signal when it has received the data. The Host transmits the slave address of the command register to the Slave as soon as it received the ACK signal. And the Slave responds an ACK signal when it has received the slave address. By following, the Host sends the data to the Slave. And the Slave responds an ACK signal once again. The I2C writing operation will be continued till the Host sends out a stop signal.

I2C Read



At the beginning, the Host sends out a start signal, and combines the 7 bit of I2C slave address with the Write bit, then, sends this 8 bit of data to the Slave. Then, the Slave sends back an ACK signal when it has received the data. The Host transmits the slave address of the command register to the Slave as soon as it received the ACK signal. And the Slave responds an ACK signal when it has received the slave address. At this moment, the Host sends out a start signal once again, and combines its 7 bit of slave address with Read bit, then, sends this 8 bit data to the Slave. And then, the Slave responds an ACK signal to the Host when it has received the data, and sends out the data stored in the Slave register to the Host. The Host sends back an ACK signal as soon as it received the value. The I2C communication will be continued, till the Host sends out a stop signal.

I2C address

The I2C address of the TSL25911 is as follows:0x29

Ordering Code	Address	Interface	Delivery Form
TSL25911FN	0x29	I ² C V _{bus} = V _{DD} Interface	ODFN-6
TSL25913FN	0x29	I ² C V _{bus} = 1.8V	ODFN-6

Note: The device address of 0x29 is 7 bits, and the 8-bits device address required to be shifted to 0x52 by moving 1 bit to high position.

Raspberry Pi application

Open the I2C

- Open the terminal and execute the code as follow :

```
sudo raspi-config
```

Select Interfacing Options -> i2c-> yes to start the I2C driver

```
Raspberry Pi Software Configuration Tool (raspi-config)

1 Change User Password Change password for the current user
2 Network Options      Configure network settings
3 Boot Options         Configure options for start-up
4 Localisation Options Set up language and regional settings to match your location
5 Interfacing Options  Configure connections to peripherals
6 Overclock           Configure overclocking for your Pi
7 Advanced Options    Configure advanced settings
8 Update              Update this tool to the latest version
9 About raspi-config  Information about this configuration tool

<Select>                                <Finish>
```

```
Raspberry Pi Software Configuration Tool (raspi-config)

P1 Camera      Enable/Disable connection to the Raspberry Pi Camera
P2 SSH         Enable/Disable remote command line access to your Pi using SSH
P3 VNC         Enable/Disable graphical remote access to your Pi using RealVNC
P4 SPI         Enable/Disable automatic loading of SPI kernel module
P5 I2C        Enable/Disable automatic loading of I2C kernel module
P6 Serial      Enable/Disable shell and kernel messages on the serial connection
P7 1-Wire      Enable/Disable one-wire interface
P8 Remote GPIO Enable/Disable remote access to GPIO pins

<Select>                                <Back>
```

```
Would you like the ARM I2C interface to be enabled?

<Yes>                                <No>
```

</br>

- Then restart Raspberry Pi:

sudo reboot

Install libraries

- Install BCM2835 libraries

```
wget http://www.airspayce.com/mikem/bcm2835/bcm2835-1.60.tar.gz
```

```
tar zxvf bcm2835-1.60.tar.gz
```

```
cd bcm2835-1.60/
```

```
sudo ./configure
```

```
sudo make
```

```
sudo make check
```

```
sudo make install
```

```
# For more code, please refer to our official website http://www.airspayce.com/mikem/bcm2835/
```

- Install wiringPi libraries

```
sudo apt-get install wiringpi
```

```
#For Raspberry Pi 4B, an upgrade may be required:
```

```
cd /tmp
```

```
wget https://project-downloads.drogon.net/wiringpi-latest.deb
```

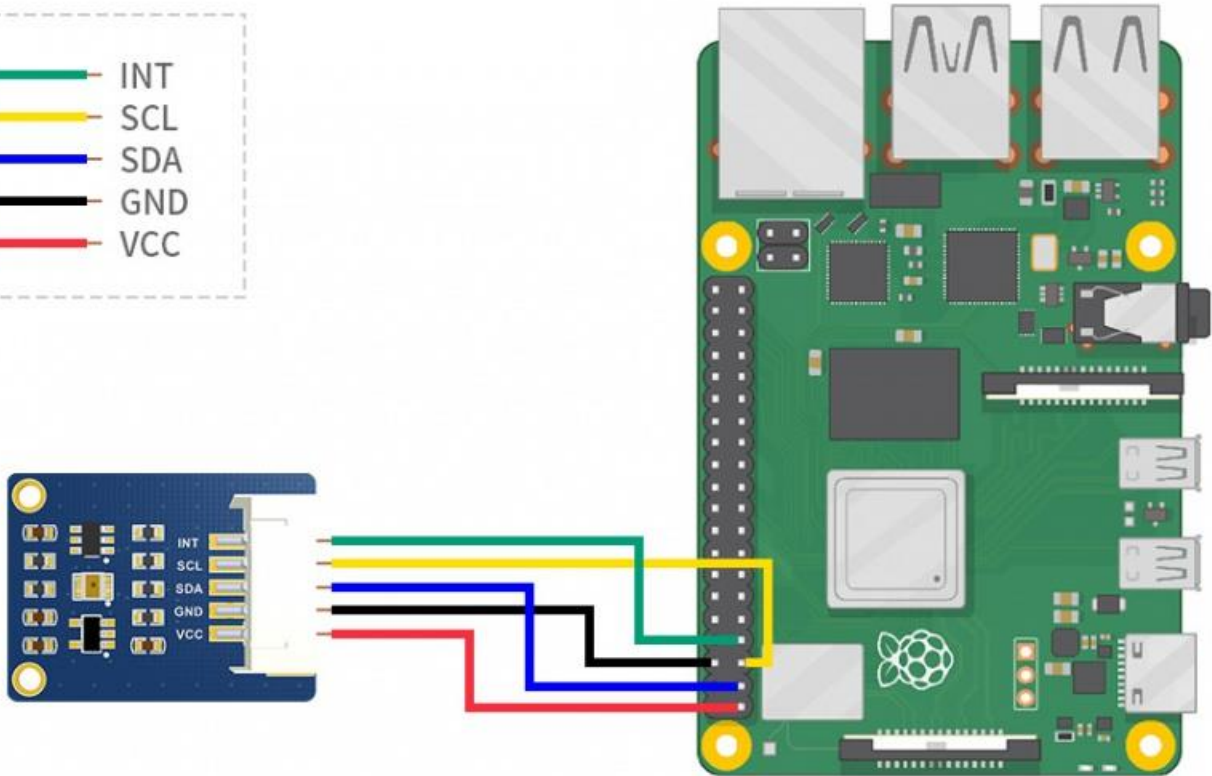
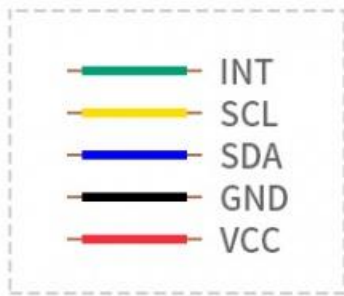
```
sudo dpkg -i wiringpi-latest.deb
```

```
gpio -v
```

```
#Running gpio -v will appear version 2.52. If not, the installation is wrong.
```

Hardware connection

TCS34725 Color Sensor	Raspberry Pi (BCM)
VCC	3.3V
GND	GND
SDA	SDA(2)
SCL	SCL(3)
INT	4



Download and run the test examples

```
sudo apt-get install p7zip-full
```

```
wget http://www.waveshare.net/w/upload/b/bc/TSL2591X_Light_Sensor_code.7z
```

```
7z x TSL2591X_Light_Sensor_code.7z -r -o./TSL2591X_Light_Sensor_code
```

```
sudo chmod 777 -R TSL2591X_Light_Sensor_code
```

You can clone the project on our Github:

```
sudo git clone https://github.com/waveshare/TSL2591X-Light-Sensor
```

- C code

```
cd c
```

```
make clean
```

```
make
```

```
sudo ./main
```

Expected result

```
pi@raspberrypi:~/TSL2591X_Light_Sensor_code/TSL2591x_Light_Sensor_code/Raspberry
Pi/c$ sudo ./main
bcm2835 init success !!!
Current environment: Raspbian
BCM2835 I2C Device
BCM2835 I2C Device
ID = 0xB2
INT 0
Lux = 65508
Infrared light: 180
Visible light: 11927550
Full spectrum (IR + visible) light: 11927732
```

- Python code

cd python

sudo python main.py

Expected result

```
pi@raspberrypi:~/TSL2591X_Light_Sensor_code/TSL2591x_Light_Sensor_code/Raspberry
Pi/python/examples$ sudo python main.py
INT 0
Lux: 11
Infrared light: 63
Visible light: 786483
Full spectrum (IR + visible) light: 786495
```

STM32 application

Download the example from Waveshare Wiki and unzip it. The STM32 projects are located at the path ~/STM32/... Open \XNUCLEO-F103RB\MDK-ARM\demo.uvprojx project with Keil uVision5.

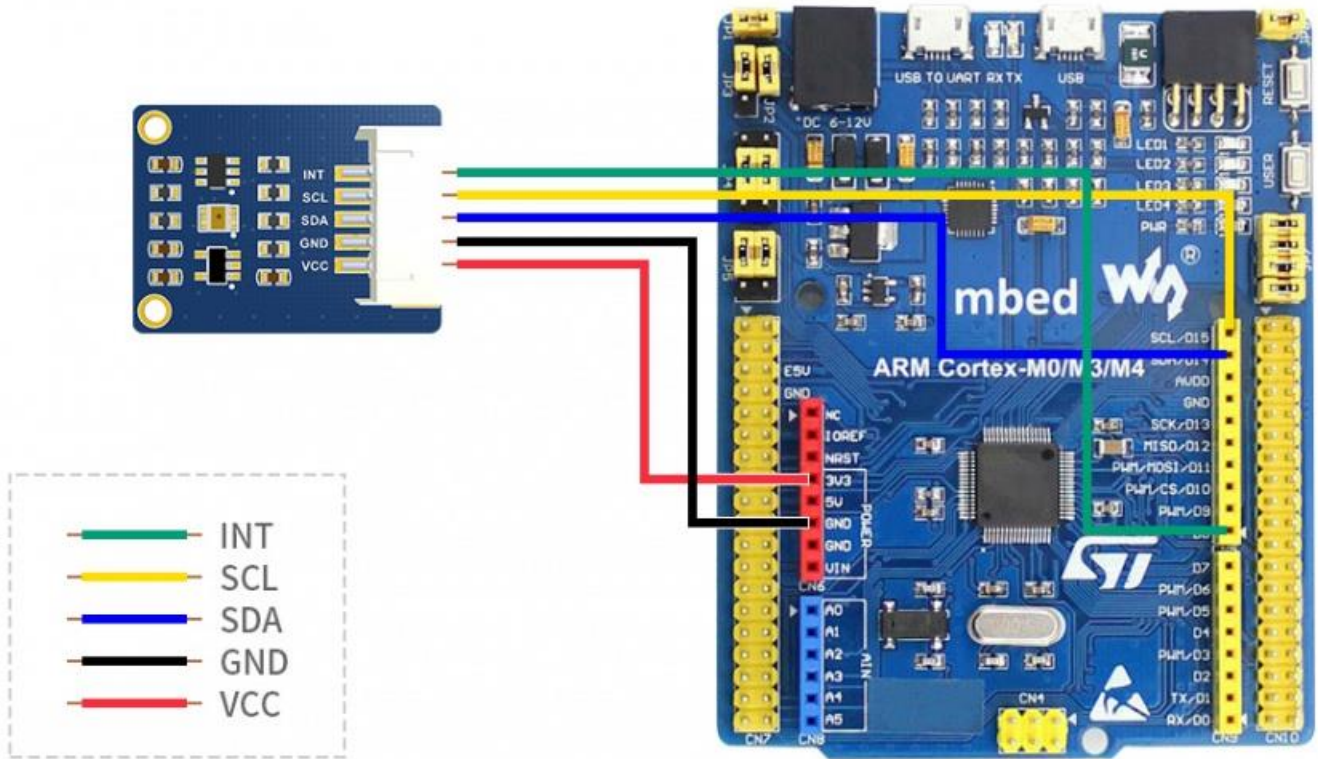
The example is based on HAL library. The development board used for the test is XNUCLEO-F103RB of Waveshare, wich chip is STM32F103RBT6.

If you want to port the examples for other STM32 chip, or change to standard libraries, you can only modify the DEV_Config.c and .h files to implement the functions and acro definitions. You can also use STM32CubeMX to port example. The example uses UART3 (PA3, PA3) to output debug information. It is set to 115200, 8N1.

Hardware connection

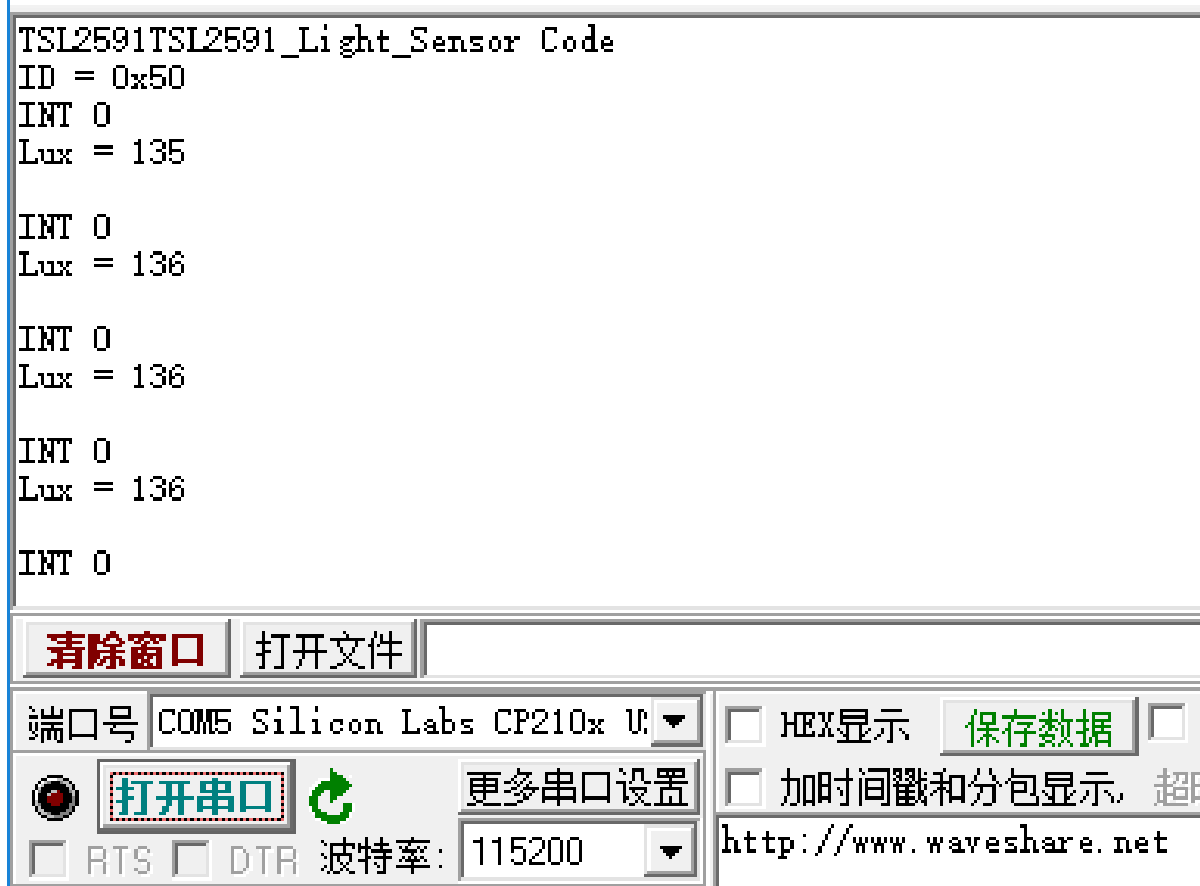
The connection is shown in the following table:

TCS34725 Color Sensor	STM32
VCC	3.3V
GND	GND
SDA	SDA/D14/PB9
SCL	SCL/D15/PB8
INT	D8/PA9



Expected Result

Open the serial port assistant software on the computer and select the corresponding port to check the output data:



Arduino

Download the example from Waveshare Wiki and unzip it. The Arduino projects are located at the path ~/Arduino/...

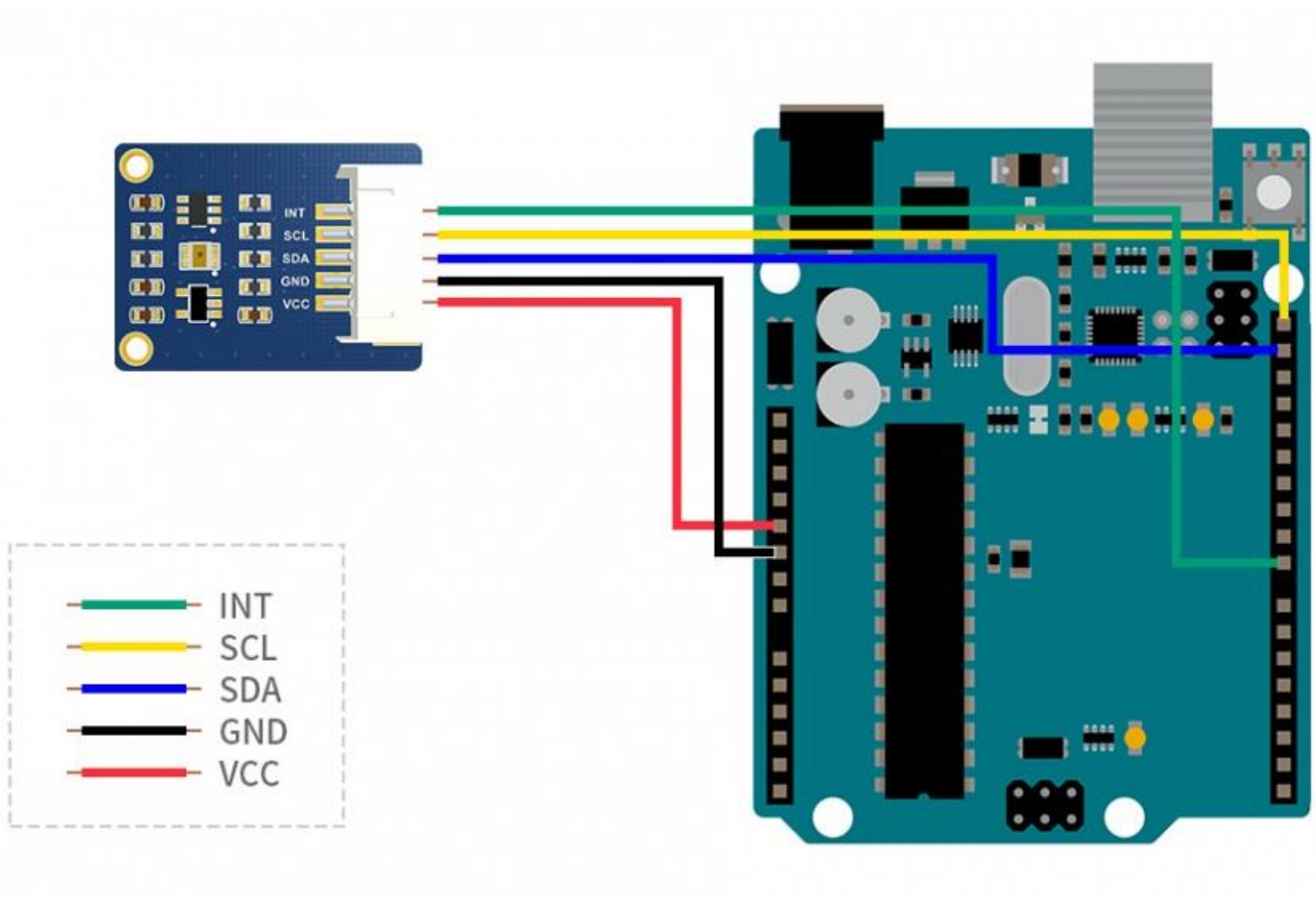
Copy the folder in the Arduino directory to the library in the Arduino installation directory.

Open the Arduino IDE: Click File-> Example to see if there is a TSL25911 option.

If so, the library is imported successfully, open TSL25911-demo, select the corresponding COM port, download it to UNO, open the serial monitor, and check the data outputted.

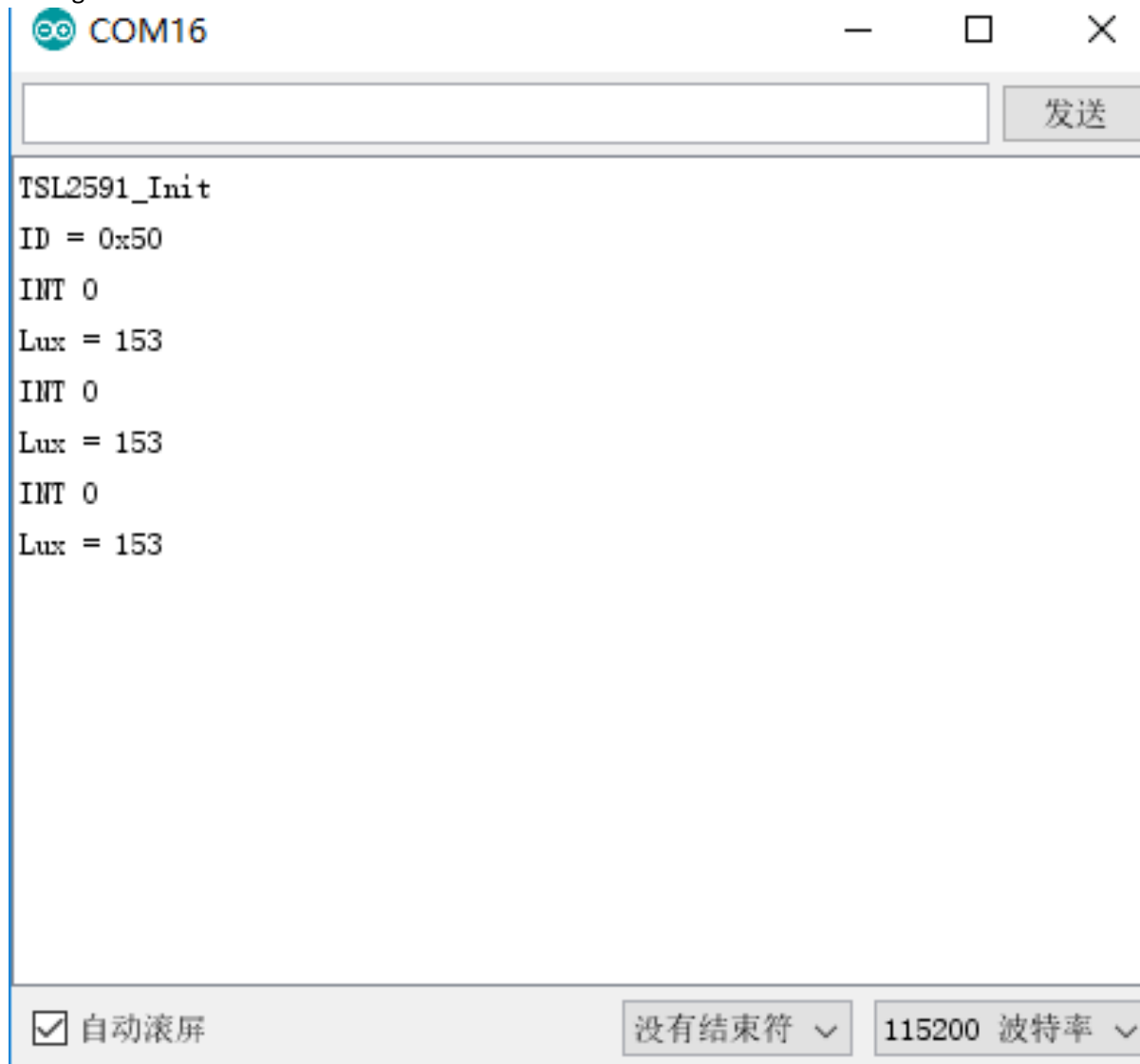
Hardware connection

TCS34725 Color Sensor	Arduino
VCC	3.3V/5V
GND	GND
SDA	SDA
SCL	SCL



Expected result

The figure below shows the data of the test:



Resources

- [Schematic](#)
- [Demo Code](#)
- [Github](#)
- [TSL2591 Datasheet](#)