

Infrared Reflective Sensor

- Reflective Infrared Transceiver
- Features wide-range voltage comparator LM393
- Adjustable sensitivity
- Signal output indicator

Specification

- Power: 3.0V ~ 5.3V
- Dimension: 25mm * 15.9mm
- Mounting holes size: 2.0mm

Pinouts

PIN	Description
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DOUT	Digital data output
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AOUT	Analog data output
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GND	Ground
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VCC	Power input (3.3V~5.3V)
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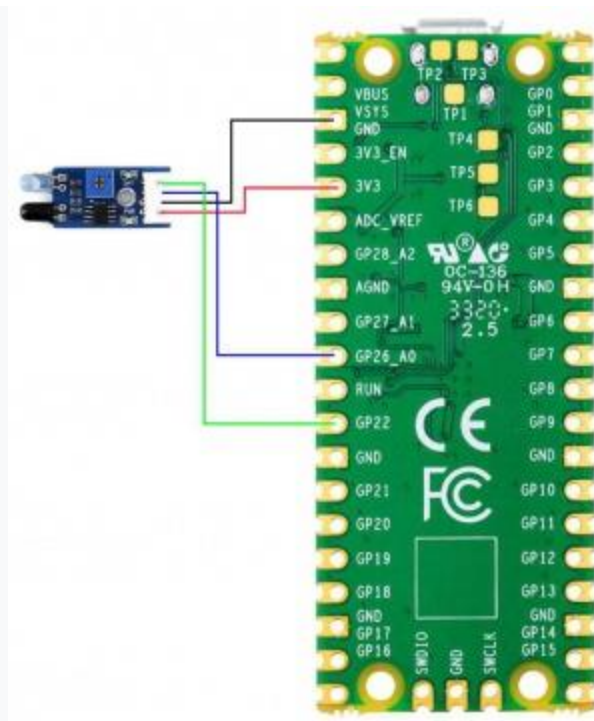
Configure Pico

MicroPython and C examples are provided for this sensor, to use it with Pico, you need to first flash firmware to the Pico according to the example.

Please refer to the guides of Raspberry Pi about how to flash the firmware. We recommend you use the firmware from the Demo codes archive.

- [C/C++ guide of Pico](#)
- [Micropython guide of Pico](#)

Hardware connection



Hardware Connection-Pico

Hall	Pico	Description
VCC	3.3V	Power input
GND	GND	Ground
AOUT	GP26	Analog data output
DOUT	GP22	Digital data output

Examples

Download the example

Open the terminal of Raspberry Pi and run the following command to download the example:

```
sudo apt-get install p7zip-full
cd ~
sudo wget https://www.waveshare.com/w/upload/0/05/Infrared_Proximity_Sensor_Demo.7z
7z x Infrared_Proximity_Sensor_Demo.7z -o./Infrared_Proximity_Sensor_Demo
```

```
cd ~/Infrared_Proximity_Sensor_Demo
cd Pico/c/build/
```

C

Here we use the Raspberry Pi board to flashing the Pico.

- Compile the c examples
 - Go into the directory of C examples

```
cd ~/Infrared_Proximity_Sensor_Demo/Pico/c/
```

- Go into the build folder and add the sdk; ../../pico-sdk is the path of the SDK, if may be different if you have saved the SDK in other path.

```
cd build
export PICO_SDK_PATH=../../pico-sdk
```

- Generate Makefile by cmake command

```
cmake ..
```

- Compile the codes by command make

```
make -j9
```

Note: If you use Pi zero, please run **make** only.

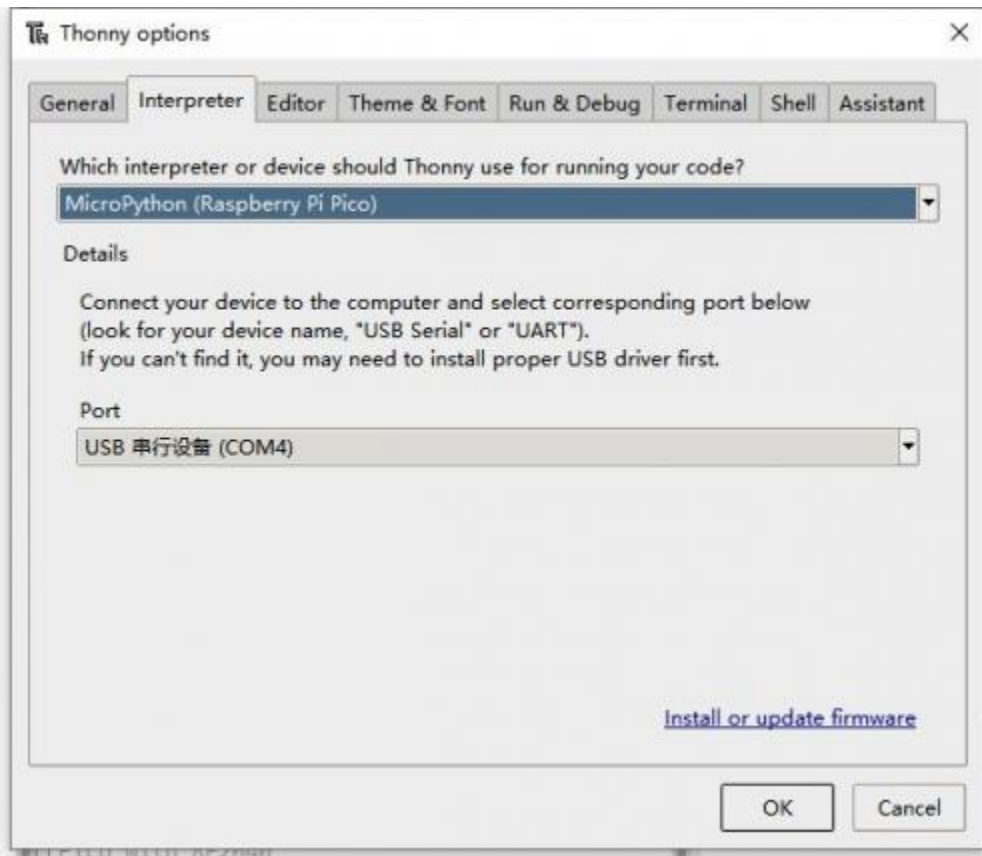
- After compiling, a uf2 file is generated.
 - Hold the button of Pico board, connect the Pico board to Raspberry Pi by USB cable
 - After connecting, release the button and a portable disk (RPI-RP2) is recognized.
 - Copy the main.uf2 file generated which locates in build folder to the portable disk (RPI-RP2)

```
cp main.uf2 /media/pi/RPI-RP2/
```

Python examples

In windows PC

- Hold the BOOTSET button of the PICO board, connect the Pico board to Raspberry Pi by USB cable
 - After connecting, release the button and a portable disk (RPI-RP2) is recognized.
- Copy the [rp2-pico-20210418-v1.15.uf2](#) file to the portable disk (RPI-RP2).
- Open the Thonny IDE (Please install the newest version which supports Pico board or update).
- Choose Tools -> Options -> Interpreter, choose the Pico and the port

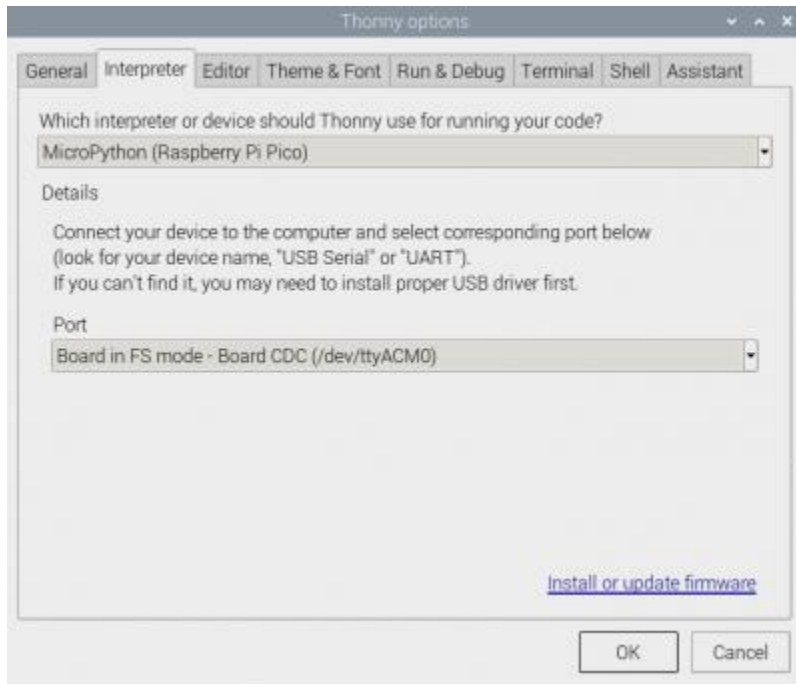


- Download the demo codes, unzip and find the MicroPython example
- Choose File -> Open -> Infrared_Proximity_Sensor.py and run it.

```
Shell X
MicroPython v1.13-290-g556ae7914 on 2021-01-21; Raspberry Pi Pico with RP2040
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT
```

In Raspberry Pi

- Flash the uf2 file to the Pico board just like in the Windows PC
- Open the Thonny IDE of Pi, make sure that it is the newest version, or update it.
- Choose Tools -> Options... -> Interpreter
 - Choose Pico and the Port



- If your Thonny IDE cannot support the Pico board, you can update it and try again.

```
sudo apt upgrade thonny
```

- Choose File -> Open... -> python/Infrared_Proximity_Sensor.py and run it.

Expected result

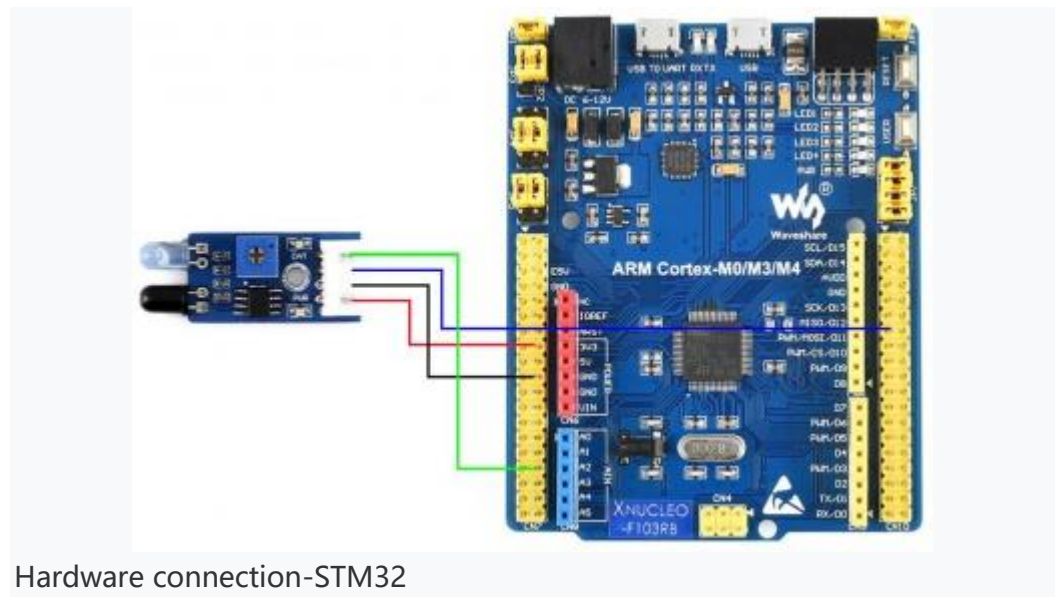
- The indicator of the sensor lights up when the sensor is close to the obstacle and goes off when it is away from the obstacle.

- As the distance between the sensor and the obstacle changes, the output data of the serial port changes accordingly

The examples provided are based on the STM32F103RBT6 and the STM32H743, the connection provided is based on the STM32F103RB.

If you want to use other STM32 boards, please change the connection and you may need to port the codes yourself.

Hardware connection



Hardware connection-STM32

Connect to STM32F103RBT6

Hall	STM32	Description
VCC	3.3V	Power input
GND	GND	Ground
AOUT	PA6	Analog data output
DOUT	PA4	Digital data output

Examples

The examples are based on the HAL library. Please download the demo codes, unzip them and find the STM32 examples.

- Open the project from Infrared_Proximity_Sensor_Demo\STM32\STM32F103RB\MDK-ARM by Keil.
- Build the project and program it to the STM32 board.
- connect the UART1 of the STM32 board to the PC and check the serial data by SCCOM software.

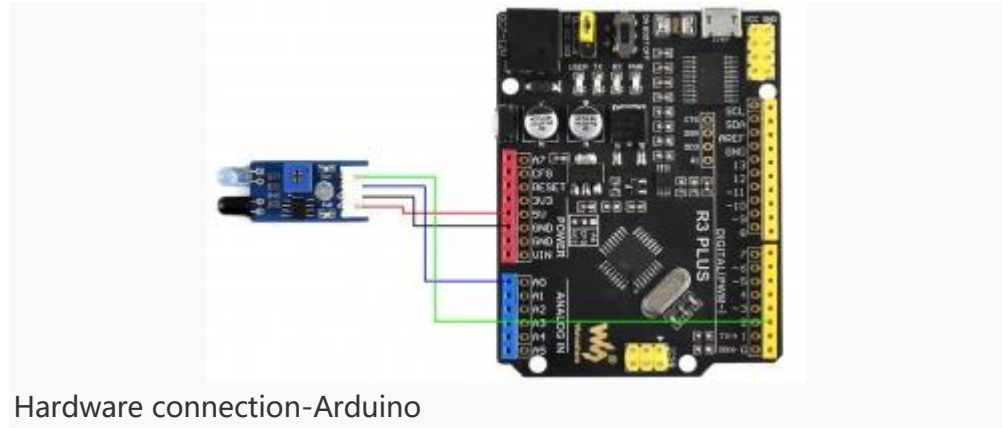


Expected result

- The indicator of the sensor lights up when the sensor is close to the obstacle and goes off when it is away from the obstacle.
- As the distance between the sensor and the obstacle changes, the output data of the serial port changes accordingly

The examples provided are based on the Arduino UNO, if you need to use other Arduino boards, please check if the board is compatible with the UNO.

Hardware connection



Hardware connection-Arduino

Connect to Arduino UNO

Hall	Arduino	Description
VCC	5V	Power input
GND	GND	Ground
AOUT	A0	Analog data output
DOUT	D2	Digital data output

Examples

- Please download and install Arduino IDE to your PC.
 - [Arduino Website](#)
- Download the demo codes, unzip and find the Arduino examples

- Open the Infrared_Proximity_Sensor.ino file by the Arduino IDE



- Build and upload the codes to the UNO board
- After uploading, you can open the Serial Monitor of IDE and check the data

Expected result

- The indicator of the sensor lights up when the sensor is close to the obstacle and goes off when it is away from the obstacle.
- As the distance between the sensor and the obstacle changes, the output data of the serial port changes accordingly.

Resources

- [User Manual](#)
- [Schematic](#)
- [Demo Code](#)
- [Software](#)