FT232 USB UART Board (type A)

Introduction

Industrial USB TO TTL Converter, Original FT232RL Onboard, Multi-Protection Circuits, Multi-Systems Support

Resources

- Schematic
- Datasheets
- Software

FAQ

Question:IN7 driver installation failed?

Answer:

Please install this driver:

FT232-WIN7-Driver

Question: Does this module support win8.1, win10 and other operating systems?

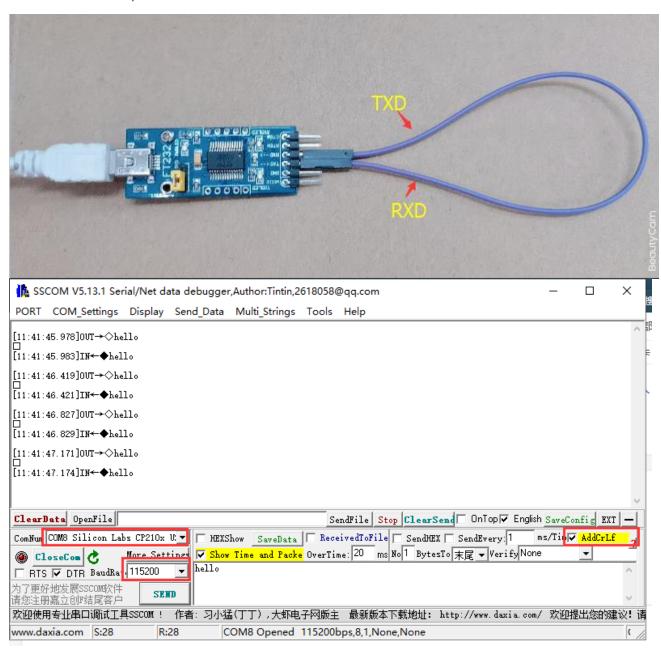
Answer:

The FT232 USB UART Board adopts the official FT232 original chip from FTDI, which can support a variety of operating systems. The drivers for different systems can be downloaded from the official website: www.ftdichip.com/FTDrivers.htm

Question: Is there any way to judge whether the FT232 function is normal?

Answer:

You can short-circuit TXD and RXD, and then send data in the serial debugging assistant Windows to see if there is corresponding data returned, if there is, the function is normal; as shown below:



Question:Two rows of pins, which row is VCC GND TXD RXD; which row is 5V GND CTS RTS?

Answer:

The label faces up, the upper row is VCC GND TXD RXD; the lower row is 5V GND CTS RTS, as shown in the figure:



FAQ

Question: Why did WIN7 driver installation fail?

Answer:

Install this driver.

Question: Does this module support win8.1, win10 and other operating systems?

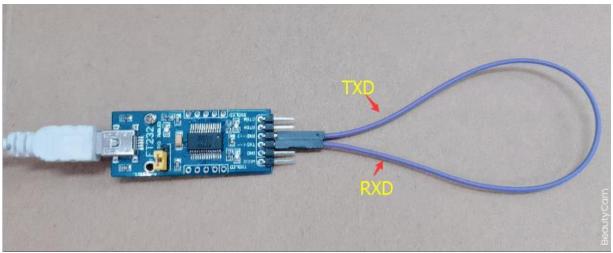
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Maybe we only want to run the robot for a set period of time. For that, we can use the Python time package.

[5]: import time

This package defines the sleep function, which causes the code execution to block for the specified number of seconds before running the next command. Try the following to make the robot turn left only for half a second.

[6]: robot.left(0.3)
time.sleep(0.5)
robot.stop()



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