

## 2-CH RS485 HAT

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This is a dual-channel isolated RS485 extension board specially designed for Raspberry Pi, which adopts SC16IS752+SP3485 solution, embed with protection circuits such as power supply isolation, ADI magnetical isolation, and TVS diode, etc. It is easy to control the 2-channel RS485 for auto transceiving via SPI interface. Due to its fast communication, stability, reliability, and safety, it is an ideal choice for fields like industrial automation.

### Feature

- Standard Raspberry Pi 40PIN GPIO extension header, supports Raspberry Pi series boards.
- Adopts SC16IS752 + SP3485 dual-chip combination, converts SPI to RS232, data rate up to 921600bps.
- Supports manual or automatic data sending and receiving, which can be set by a DIP switch.
- Onboard TVS (Transient Voltage Suppressor), effectively suppresses surge voltage and transient spike voltage in the circuit, lightning proof & anti-electrostatic.
- Onboard resettable fuses and protection diodes ensure a stable output of current and voltage, prevent overcurrent and overvoltage, and improve shock resistance.

- Onboard power indicator and serial port transceiver indicator for checking the module power and communication status.
- With SPI control pins, for connecting with host control boards like Arduino.
- Comes with development resources and a manual (examples in C and Python).

### Parameter

- UART expansion chip: SC16IS752
- RS485 transceiver: SP3485
- Communication interface: SPI
- Data rate: 300 ~ 921600 bps
- Operating voltage: 3.3V / 5V
- Dimensions: 65mm × 56.5mm
- Mounting hole size: 3.0mm

### Interfaces

PIN	SYMBOL	Description
1	VCC	3.3V/5V Power
2	GND	Ground

3	SCLK	SPI Clock input
4	MOSI	SPI Data input
5	MISO	SPI Data output
6	CS	SPI Chip Selection
7	IRQ	Interrupt output (Interrupt Request)
8	EN1	Enable Channel 1
9	EN2	Enable Channel 2

## Working principle

- **Introduction**

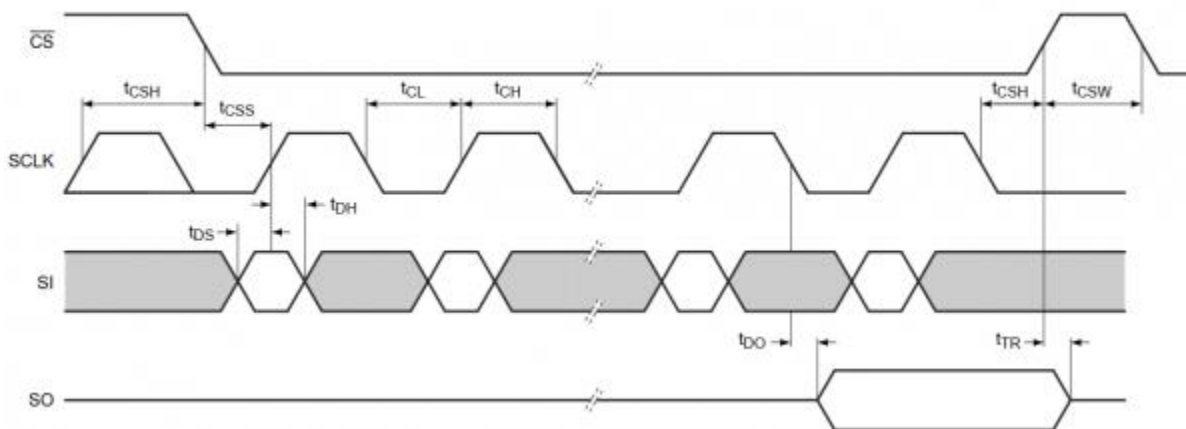
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This product adopts SC16IS752 as a controller. SC16IS752 is a dual-channel high-performance UART expansion chip that supports SPI and I2C. This module adopts the SPI interface, and onboard power isolation, ADI magnetic coupler isolation. It also onboards TVS (transient voltage suppression tube), self-recovery fuses, protection diodes, and an automatic transceiver switching circuit. It can effectively suppress the surge voltage and transient

peak voltage in the circuit, prevent lightning and static electricity, prevent over-voltage, improve the anti-impact ability, and can conduct signal isolation with high dependence, strong anti-interference, and low power consumption advantages, etc.

- **Communication protocol**

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- CS: Slave chip selection, when CS is low, the slave chip is enabled.
- SCLK: SPI communication clock
- MOSI/SI: SPI Communication master sends, slave receives
- MOSI/SI: SPI Communication master receives, slave sends
- Timing Sequence: CPHL=0, CPOL=0 (SPI0)

## Working with RPI

### How to use

We provide C and Python demo codes for Raspberry Pi. A quick testing example is provided in python.

- **Hardware Connection**

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232 PIN	Raspberry Pi(BCM)	Description
VCC	5V	3.3/5V Power Input
GND	GND	Ground
SCLK	P21 (SPI1 SCLK)	SPI Clock Signal Input
MOSI	P20 (SPI1 MOSI)	SPI Data Input
MISO	P19 (SPI1 MISO)	SPI Data Output
CS	P18 (SPI1 CS)	SPI Chip Select
IRQ	P24	Interrupt Output
EN1	P27	Channel 1 transceiver enable: high level transmit enable, low level receive enable
EN2	P22	Channel 2 transceiver enable: high level transmit enable, low level receive enable

- **Software setup**

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- Open the terminal and modify config.txt file by commands:

```
sudo nano /boot/config.txt
```

- Add the line below to the file, the int\_pin should be set according to the actual welding:

```
dtoverlay=sc16is752-spi1,int_pin=24
```

- Then restart Raspberry Pi

```
sudo reboot
```

- After rebooting, the driver of SC16IS752 will be loaded into the system kernel. You can run command **ls /dev** to check the following devices:

```
pi@raspberrypi:~$ ls /dev/
autofs          gpiochip3      wdog          ram11          i2c          tty19          tty34          tty5            tty8            vcs5
block          gpiomem        mem           ram12          i2c-1        tty2           tty35          tty50          tty9            vcs6
btrfs-control  hwrng          memory_bandwidth ram13          i2c-dev      tty20          tty36          tty51          ttyAMA0        vcs7
bus            i2c-1         mmcblk0       ram14          i2c-gpio     tty21          tty37          tty52          ttyprintk      vcsa
cachefiles     initctl        mmcblk0p1     ram15          i2c-rtc      tty22          tty38          tty53          ttySC0         vcsa1
char           input          mmcblk0p2     ram2           i2c-serial   tty23          tty39          tty54          ttySC1         vcsa2
console        kmsg           queue         ram3           i2c-smbus    tty24          tty4           tty55          urandom        vcsa3
cpu_dma_latency log            net           ram4           i2c-tpm      tty25          tty40          tty56          uinput        vcsa4
cuse           loop0          network_latency ram5           i2c-usb      tty26          tty41          tty57          urandom        vcsa5
disk          loop1          network_throughput ram6           i2c-usb      tty27          tty42          tty58          vchiq          vcsa6
fb0           loop2          null          ram7           i2c-usb      tty28          tty43          tty59          vcio           vcsa7
fd            loop3          ppp           ram8           i2c-usb      tty29          tty44          tty6           vc-mem        vcsm
full         loop4          ptmx          ram9           i2c-usb      tty3           tty45          tty60          vcs            vhci
fuse          loop5          ptp           random         i2c-usb      tty15          tty30          tty46          tty61          vcs1         watchdog
gpiochip0     loop6          ram0          ram            i2c-usb      tty16          tty31          tty47          tty62          vcs2         watchdog0
gpiochip1     loop7          ram1          rfskill        i2c-usb      tty17          tty32          tty48          tty63          vcs3         zero
gpiochip2     loop-control  ram10         serial1        i2c-usb      tty18          tty33          tty49          tty7           vcs4
```

## • Install Libraries

- Install wiringpi

```
sudo apt-get install wiringpi
```

```
# An upgrade may be required for raspberry PI 4B:
```

```
cd /tmp
```

```
wget https://project-downloads.drogon.net/wiringpi-latest.deb
sudo dpkg -i wiringpi-latest.deb
gpio -v
# Running gpio-v to check if the version is 2.52, If
it is not, you need to check the installation again.
```

- **Install the python2 library**

```
sudo apt-get update
sudo apt-get install python-pip
sudo pip install RPi.GPIO
sudo apt-get install python-serial
```

- **Install the python3 library**

```
sudo apt-get update
sudo apt-get install python3-pip
sudo pip3 install RPi.GPIO
sudo apt-get install python3-serial
```

- **Test**

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- **Download and run the examples:**

```
sudo apt-get install p7zip-full
wget https://www.waveshare.com/w/upload/4/44/2-CH_RS4
85_HAT_code.7z
```

```
7z x 2-CH_RS485_HAT_code.7z
sudo chmod 777 -R 2-CH_RS485_HAT
cd 2-CH_RS485_HAT/
```

- You can also clone the project from our Github:

```
sudo git clone https://github.com/waveshare/2-CH-RS485-HAT
cd 2-CH-RS485-HAT/
```

- C program

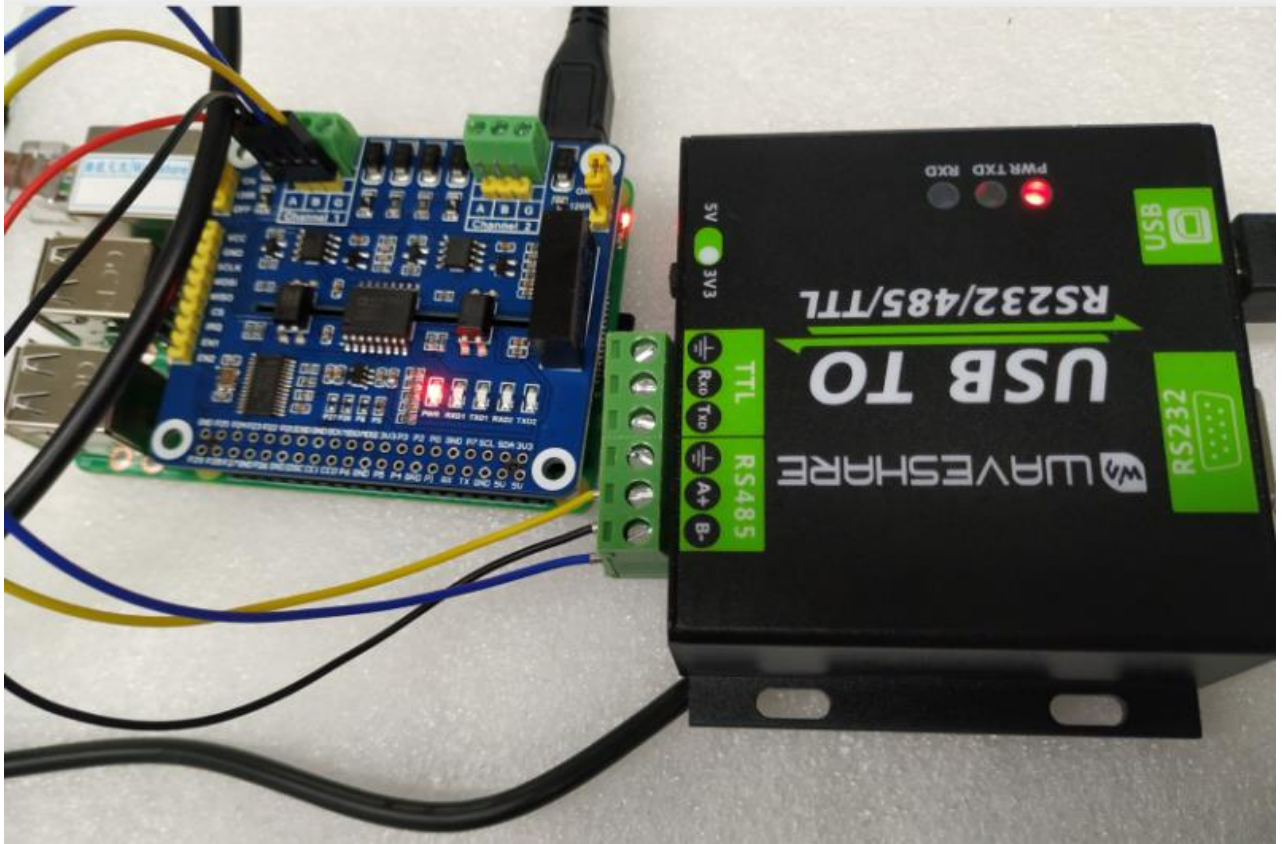
```
cd c
make clean
make
sudo ./main
```

- Python program

```
cd python
cd examples
sudo python main.py
```

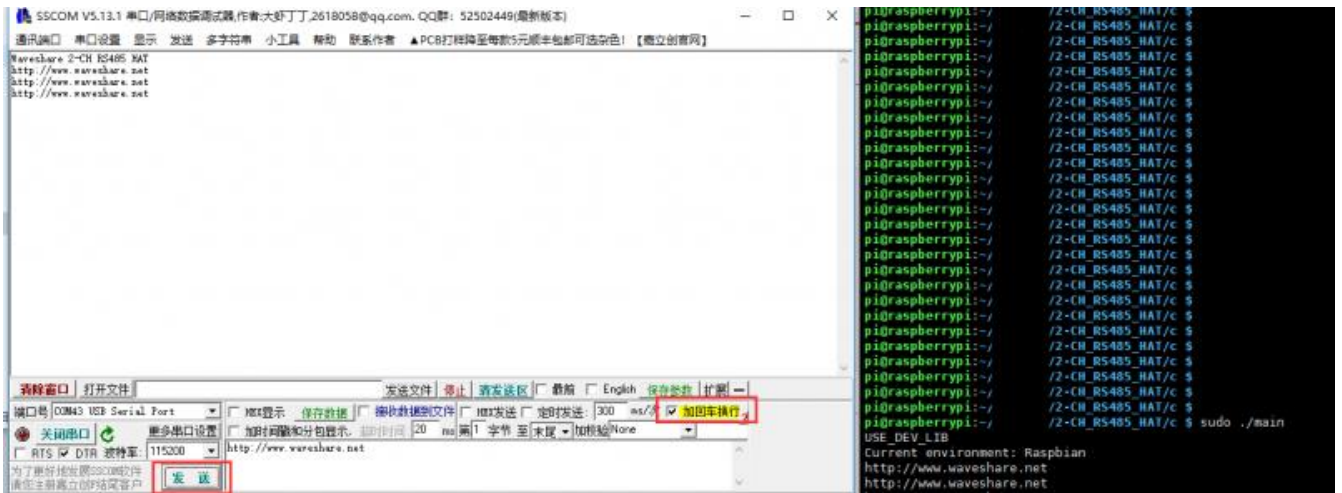


Hardware connection: Channel 1 of the 2-CH RS485 HAT is connected to [USB TO RS232/485/TTL](#):



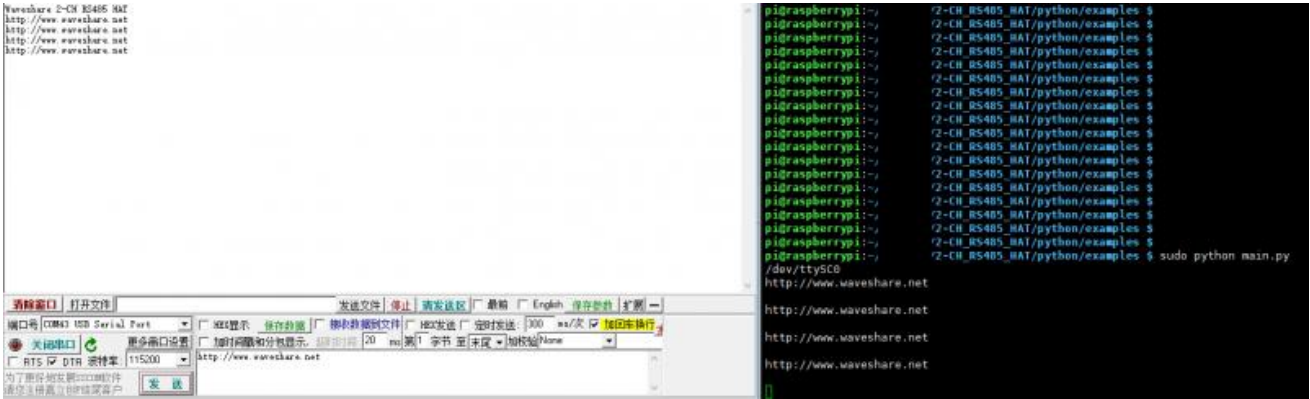
Connect [USB TO RS232/485/TTL](#) to the computer, open the serial port assistant software, select the corresponding serial port, and set the baud rate to 115200.

- Run the C program, the data sent by computer will all be received by Raspberry Pi, as below:



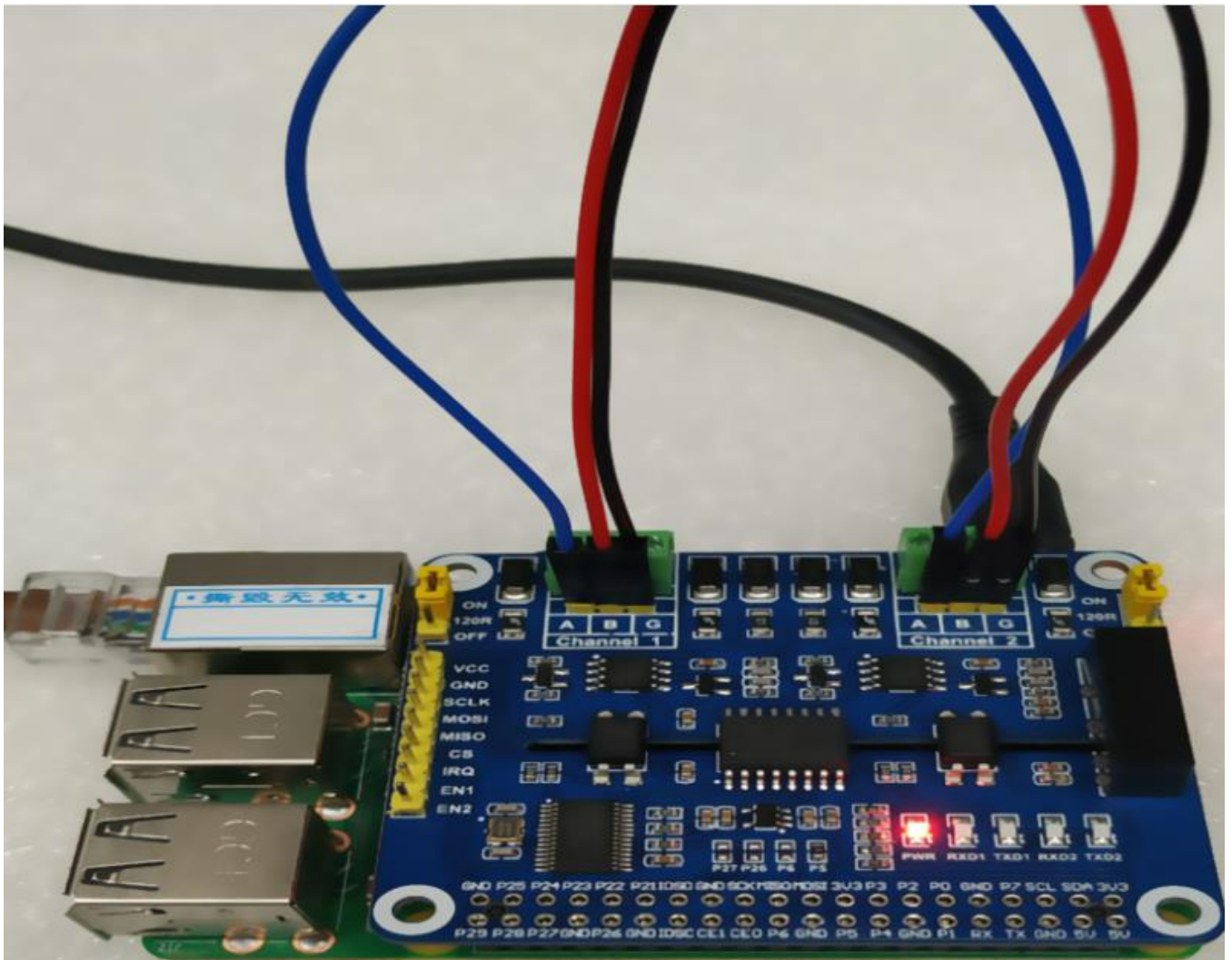
Note: You need to press Enter for a line feed, otherwise the data will not be returned; the program directory of the example is based on the actual.

- Run the main.py, the data sent by computer will all be received by Raspberry Pi, as below:



Note: You need to press Enter for a line feed, otherwise the data will not be returned; the program directory of the example is based on the actual.

If you don't have other RS485 devices, you can choose the test method as follow by connecting channel 1 with channel 2:



- Running result of test.py :

```
pi@raspberrypi:~ $ cd ~/waveshare_2-CH_RS485_HAT/python/examples $ sudo python test.py
/dev/ttySC0
/dev/ttySC1
Channel 1 send channel 2 received successfully
waveshare_2-CH_RS485_HAT

Channel 2 send channel 1 received successfully
waveshare_2-CH_RS485_HAT

Channel 1 send channel 2 received successfully
waveshare_2-CH_RS485_HAT

Channel 2 send channel 1 received successfully
waveshare_2-CH_RS485_HAT

Channel 1 send channel 2 received successfully
waveshare_2-CH_RS485_HAT

Channel 2 send channel 1 received successfully
waveshare_2-CH_RS485_HAT
```

## Resources

- [Documentation](#)

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- [Schematic](#)
- [3D Drawings](#)

- [Demo code](#)

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- [Demo code](#)
- [Github](#)

- [Datasheets](#)

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- [SP3481\\_SP3485.pdf](#)
- [SC16IS752\\_datasheet.pdf](#)

## FAQ

**Question:**485 speed is too high to communicate?

**Answer:**

If the automatic transceiver is used, you will find that it can only reach 921600 bps at most, and the manual transceiver can reach 2M when testing.

**Question:**In the semi-automatic mode (manual mode), the green RXD light or the green TXD light is always on?

**Answer:**

In the semi-automatic mode, the voltage on the EN pin determines whether RS485 is transmitted or received. In the transmit mode, the RXD green light may be always on. In the receive mode, the TXD green light may be always on, which is normal.

**Question:**485 communication is abnormal, what should I do?

**Answer:**

1. Check whether A and B of 485 correspond to the controlled devices.
2. You can use the USB to 485 device to communicate with the module first to ensure that there is no problem with the settings of the Raspberry Pi;

3. Check the setting of odd and even bit parity of serial communication parameters.

[Question:Can the Ubuntu system be installed on the Raspberry Pi? Why can't I find the config.txt file in the boot folder?](#)

**Answer:**

1. The Raspberry Pi is installed with the mainstream ubuntu system and can be used.

2. Ubuntu's config.txt file is usually in the /boot/firmware folder.

3. You also can use the SD card of the Raspberry Pi to read and change the config.txt file under the computer (or other hosts that can recognize the SD card) through a card reader.