



Model LMA-1800

Operating Instructions

Plug-in Vehicle Loop Detector

Single Channel – Dual Solid State Outputs

General/Overview:

The EDI Model LMA-1800 operates on 12 VDC, 24 VDC, and 24 VAC. The detector is designed to handle gate, parking, drive-through, and all access control applications where **solid-state** outputs are required for both the “detect and “fail” outputs. From a diagnostic standpoint, the LMA-1800 automatically and continuously senses three (3) types of possible loop fault conditions: Open Loop(s), Shorted Loop(s), sudden changes in inductance exceeding 25% of the nominal inductance. The LMA-1800 also displays the frequency of the loop upon power up. Immediately after applying power, the unit displays 2 or 3 numbers quickly flashing (values between 13 and 150 kilohertz) before the DEFLECTOMETER resets to zero. This allows you to measure and separate the frequency of each detector loop. The detector frequency should be adjusted so that there is a minimum of 5 kilohertz of separation between all adjacent loops.

The LMA-1800 is compatible with the following gate / parking operators:

- All Linear Operators with APeX controller
- Advanced Access Automation/FAAC CSL2000, CSW2000, RSW1000
- All-O-Matic SL100-DC
- Chamberlain/Elite SL3000, CSW200
- Intelligate Systems IQ500, IQ5000
- SECOM Late model operators with 10-pin Molex connectors
- Rotary Gate Systems SL1000R, SL1000C, SL1000I
- TyMetal TYM 1000 , TYM 2000
- Viking Access Models L-3, F-1, T-21, H-10, B-12, Q-4

Setting Sensitivity:



The **DEFLECTOMETER** (front panel 7-segment LED) aids in setting the detector to the most optimum sensitivity level to help ensure the detection of all vehicles, including motorcycles and high bed vehicles.

For typical vehicles (mid-size vehicle / small pick up) utilizing properly installed roadway loops, when the number 4, 5, or 6 (**5 being optimum**) is displayed on the DEFLECTOMETER during the DETECT output period then the sensitivity is set correctly. For high profile vehicles (commercial trucks, 4x4's, etc...), DEFLECTOMETER reading 3 or 4 will be best. For low profile vehicles (sports cars, etc...), DEFLECTOMETER reading 6 or 7 will be best.

Adjusting sensitivity utilizing the DEFLECTOMETER (Recommended):

The DEFLECTOMETER should read zero (0) with no vehicle over the roadway loop.

If a mid-size vehicle, located over the roadway loop causes the number “7” to be displayed on the DEFLECTOMETER, you need to lower the sensitivity two levels (7 – 2 = DEFLECTOMETER reading 5). This can be done by pressing the front panel SENS ▼ (down) push button twice.

If a mid-size vehicle, located over the roadway loop causes the number “2” to be displayed on the DEFLECTOMETER, you need to add three sensitivity levels (2 + 3 = DEFLECTOMETER reading “5”. This can be done by pressing the front panel SENS ▲ (up) push button 3 times.

Another great feature to note is that the sensitivity dynamically updates after each push button position change, allowing you to change sensitivity settings while a vehicle is over the loop zone.

Adjusting sensitivity without using the DEFLECTOMETER (Manually set Sensitivity):

The Model LMA-1800 offers 9 levels of sensitivity (1 to 9). This can be manually set to any desired level by pressing the SENS ▲ or SENS ▼ front panel push buttons when a vehicle is NOT over the roadway loop. The sensitivity level will be displayed on the 7-segment LED. The factory default is level 4. Pressing the SENS ▲ or SENS ▼ switch once will display the sensitivity without changing the setting. After pressing the SENS ▲ or SENS ▼ switches to display the sensitivity, the sensitivity can be changed by pressing the SENS ▲ or SENS ▼ switches again. The display will automatically return to the normal display after several seconds.

Dip Switch Functions:

Dip Switch 1 & 2 – Frequency: The operating frequency is controlled by the setting of switches 1 & 2 of the 8 position DIP Switch. Occasionally when loops are in close proximity to each other, it may be necessary to select different frequencies for each loop detector to avoid loop interference (crosstalk). The actual loop frequency is a function of the size of the loop, number of turns of loop wire in the loop, length of the lead-in cable, and the setting of the frequency switches. When power is applied to the detector, the operating frequency (between 13 and 150 kilohertz) is displayed on the front panel 7-segment LED (2 or 3 numbers will quickly flash before the DEFLECTOMETER goes to zero) allowing you to measure the frequency of each detector/loop. The detector frequency should be adjusted so that there is a minimum of 5 kilohertz of separation between all adjacent loops.

Dip Switch 3 – Fail-Safe / Fail-Secure Operation: Either Fail-Safe or Fail-Secure Operation is controlled by the setting of switch 3 of the 8 position DIP Switch. The default position is Fail-Safe (switch 3 in the OFF position). If a loop fault occurs while in the Fail-Safe mode, Output A activates. If a loop fault occurs in the Fail-Secure mode (switch 3 is in the ON position) Output A will not activate.

Dip Switch 4 & 5 – Output “B” Modes (pin 6): Output B has 4 selectable output modes: Loop Fault, B same as A, Pulse on Exit, Pulse on Entry. For Loop Fault Mode, if the loop fails the Output B will conduct indicating the failure. For either Pulse on Entry or Pulse on Exit a 250 millisecond pulse is generated on Output B. The default position is set to Loop Fault (switch 4 = OFF & switch 5 = OFF).

SWITCH	Loop Fault	B same as A	Pulse On Exit	Pulse On Entry
4	OFF	ON	OFF	ON
5	OFF	OFF	ON	ON

Dip Switch 6 – Delay Timing: The default position is set to OFF. When switch 6 is in the ON position, a 2-second “detect” delay feature will delay outputs A & B for a period of 2 seconds after a vehicle has entered the detection zone. Note that the DEFLECTOMETER will display the letter “d” for “Delay Time”. If the vehicle does not remain in the loop zone for the full 2 seconds the delay will terminate and no DETECT output will be produced.

Dip Switch 7 – Output “A” Modes: Output A has 2 selectable output modes: Infinite Presence and Normal Presence. The default position is Infinite Presence (switch 7 = OFF). In the Infinite Presence mode, a presence output will always be maintained as long as a vehicle is over the loop and power is not removed for more than approximately 3 seconds. In the Normal Presence mode (switch 7 = ON), the output hold time is between 5 minutes minimum and 3 hours maximum. Hold time depends on loop geometry; number of wire turns in the loop, vehicle size, and position of the vehicle relative to the loop.

Dip Switch 8 – Sensitivity Boost: The default position is set to OFF. When switch 8 is in the ON position and when a vehicle enters the loop zone, the detector sensitivity is boosted to a higher level than the vacant loop setting. The boosted sensitivity remains throughout the DETECT period. When the vehicle leaves the loop zone, the sensitivity returns to the vacant loop setting. This feature is designed to automatically increase sensitivity only during the DETECT output period. This feature aids in preventing dropouts during the passage of high bed vehicles and is particularly useful in sliding gate situations.

Detector Diagnostics: The detector continuously checks the integrity of the loop. The system is able to detect open or shorted circuit loops, or sudden changes in inductance exceeding 25% of the nominal inductance. If a fault is detected, the POWER and DETECT LED both continuously emit a sequence of flashes. Additionally, the 7-Segment DEFLECTOMETER displays F1, F2, or F3 indicating a current loop fault. Each type of fault is identified by a different flash sequence:

Flash Sequence	Deflectometer Display	Fault Condition
1 flash	F 1	Open Circuit Loop
2 flashes	F 2	Shorted Circuit Loop
3 flashes	F 3	25% excessive change in inductance

If the Open or Shorted fault condition self heals, the DETECT LED and 7-Segment DEFLECTOMETER will return to normal operation. Only the POWER LED will continue to flash with the sequence signifying the type of fault that was last detected. In the case of the excessive inductance change (F3) fault, the unit will retune to the new inductance after a period of two seconds and continue operation. The previous fault condition will be indicated by the flash sequence of the only POWER LED. Pressing the “Reset” button will reset the detector and clear the flash sequence from the POWER LED. If you want to review the last loop fault condition, simply press and hold the “Reset” button for 2 seconds and the DETECT LED will display the previous loop fault condition.

Pin Assignments:

Pin	Function	Pin	Function
1	Loop	6	Output B
2	Loop	7	Output B Inverted
3	Power (12-24VDC, 24Vac)	8	Output A (Presence Output)
4	No Connection	9	Power (12-24VDC, 24Vac)
5	No Connection	10	Common

Note: Power may be applied on either pin 3 or 9, or both