

Programmable DC Power Supply

PFR-100 Series

PROGRAMMING MANUAL



ISO-9001 CERTIFIED MANUFACTURER

GW INSTEK

This manual contains proprietary information, which is protected by copyright. All rights are reserved. No part of this manual may be photocopied, reproduced or translated to another language without prior written consent of Good Will company.

The information in this manual was correct at the time of printing. However, Good Will continues to improve products and reserves the rights to change specification, equipment, and maintenance procedures at any time without notice.

Good Will Instrument Co., Ltd.
No. 7-1, Jhongsing Rd., Tucheng Dist., New Taipei City 236, Taiwan.

Table of Contents

SAFETY INSTRUCTIONS	4
GETTING STARTED	8
PFR-100 Series Overview	9
Appearance	12
Configuration Settings	19
REMOTE CONTROL	26
Interface Configuration	28
Socket Server Examples	59
Command Syntax	63
Command List	67
Status Register Overview	119
Error List	133
APPENDIX	142
PFR-100 Default Settings	142
Error Messages & Messages	144
LED ASCII Table Character Set	145
INDEX.....	146

S SAFETY INSTRUCTIONS

This chapter contains important safety instructions that you must follow during operation and storage. Read the following before any operation to insure your safety and to keep the instrument in the best possible condition.

Safety Symbols

These safety symbols may appear in this manual or on the instrument.



Warning: Identifies conditions or practices that could result in injury or loss of life.



Caution: Identifies conditions or practices that could result in damage to the PFR-100 or to other properties.



DANGER High Voltage



Attention Refer to the Manual



Protective Conductor Terminal



Earth (ground) Terminal



Do not dispose electronic equipment as unsorted municipal waste. Please use a separate collection facility or contact the supplier from which this instrument was purchased.

Safety Guidelines

General Guideline



CAUTION

- Do not place any heavy object on the PFR-100.
- Avoid severe impact or rough handling that leads to damaging the PFR-100.
- Do not discharge static electricity to the PFR-100.
- Use only mating connectors, not bare wires, for the terminals.
- Do not disassemble the PFR-100 unless you are qualified.

(Measurement categories) EN61010-1:2010 and EN61010-2-030 specifies the measurement categories and their requirements as follows. The PFR-100 falls under category II.

- Measurement category IV is for measurement performed at the source of low-voltage installation.
- Measurement category III is for measurement performed in the building installation.
- Measurement category II is for measurement performed on the circuits directly connected to the low voltage installation.
- 0 is for measurements performed on circuits not directly connected to Mains.

Power Supply



WARNING

- AC Input Voltage: 100Vac-240Vac
 - Frequency: 47Hz to 63Hz
 - To avoid electrical shock connect the protective grounding conductor of the AC power cord to an earth ground.
-

- Cleaning the PFR-100
- Disconnect the power cord before cleaning.
 - Use a soft cloth dampened in a solution of mild detergent and water. Do not spray any liquid.
 - Do not use chemicals containing harsh material such as benzene, toluene, xylene, and acetone.

Operation Environment

- Location: Indoor, no direct sunlight, dust free, almost non-conductive pollution (Note below)
- Relative Humidity: 20%~ 80% (no condensation)
- Altitude: < 2000m
- Temperature: 0°C to 40°C

(Pollution Degree) EN61010-1:2010 and EN61010-2-030 specifies the pollution degrees and their requirements as follows. The PFR-100 falls under degree 2.

Pollution refers to “addition of foreign matter, solid, liquid, or gaseous (ionized gases), that may produce a reduction of dielectric strength or surface resistivity”.

- Pollution degree 1: No pollution or only dry, non-conductive pollution occurs. The pollution has no influence.
- Pollution degree 2: Normally only non-conductive pollution occurs. Occasionally, however, a temporary conductivity caused by condensation must be expected.
- Pollution degree 3: Conductive pollution occurs, or dry, non-conductive pollution occurs which becomes conductive due to condensation which is expected. In such conditions, equipment is normally protected against exposure to direct sunlight, precipitation, and full wind pressure, but neither temperature nor humidity is controlled.

Storage environment

- Location: Indoor
- Temperature: -20°C to 70°C
- Relative Humidity: 20 to 85%(no condensation)

Disposal



Do not dispose this instrument as unsorted municipal waste. Please use a separate collection facility or contact the supplier from which this instrument was purchased. Please make sure discarded electrical waste is properly recycled to reduce environmental impact.

Power cord for the United Kingdom

When using the power supply in the United Kingdom, make sure the power cord meets the following safety instructions.

NOTE: This lead/appliance must only be wired by competent persons




WARNING: THIS APPLIANCE MUST BE EARTHED

IMPORTANT: The wires in this lead are coloured in accordance with the following code:

Green/ Yellow:	Earth
Blue:	Neutral
Brown:	Live (Phase)



As the colours of the wires in main leads may not correspond with the coloured marking identified in your plug/appliance, proceed as follows:

The wire which is coloured Green & Yellow must be connected to the Earth terminal marked with either the letter E, the earth symbol  or coloured Green/Green & Yellow.

The wire which is coloured Blue must be connected to the terminal which is marked with the letter N or coloured Blue or Black.

The wire which is coloured Brown must be connected to the terminal marked with the letter L or P or coloured Brown or Red.

If in doubt, consult the instructions provided with the equipment or contact the supplier.

This cable/appliance should be protected by a suitably rated and approved HBC mains fuse: refer to the rating information on the equipment and/or user instructions for details. As a guide, a cable of 0.75mm² should be protected by a 3A or 5A fuse. Larger conductors would normally require 13A types, depending on the connection method used.

Any exposed wiring from a cable, plug or connection that is engaged in a live socket is extremely hazardous. If a cable or plug is deemed hazardous, turn off the mains power and remove the cable, any fuses and fuse assemblies. All hazardous wiring must be immediately destroyed and replaced in accordance to the above standard.

G E T T I N G S T A R T E D

This chapter describes the power supply in a nutshell, including its main features and front / rear panel introduction. After going through the overview, please read the theory of operation to become familiar with the operating modes, protection modes and other safety considerations.

PFR-100 Series Overview	9
Series lineup	9
Main Features	9
Accessories	10
Appearance	12
Front Panel	12
Display Area	15
Rear Panel	17
Configuration Settings	19
Setting Normal Function Settings	19
Setting Power On Configuration Settings	21
Configuration Table	22

PFR-100 Series Overview

Series lineup

The PFR-100 series consists of 2 models, covering a number of different current, voltage and power capacities:

Model name	Operation Voltage	Operation Current	Rated Power
PFR-100L	0-50V	0-10A	100W
PFR-100M	0-250V	0-2A	100W

Main Features

- Performance
- Variable voltage and current combinations with 5 times.
 - Natural convection cooling.
 - Supporting universal input voltage.
-

- Features
- Preset memory function.
 - Output ON/OFF delay function.
 - CV, CC priority start function. (prevents overshoot with output ON)
 - Adjustable voltage and current slew rates.
 - Bleeder circuit ON/OFF setting. (to prevent over-discharging of batteries)
 - OVP, OCP, AC FAIL and OTP protection.
 - Supports test scripts.
 - Web server monitoring and control.
 - Analog monitor output.
 - Remote sensing function.
-

- Interface
- Built-in USB and RS-232/485 interface.
 - External analog control function.
 - Optional LAN and GPIB interface.

Accessories

Before using the PFR-100 power supply unit, check the package contents to make sure all the standard accessories are included.

Standard Accessories	Part number	Description	Qty.
	CD-ROM	User manual, Programming manual	1
		Power Cord	1
	GTL-134	Test leads for rear panel, 1.2m, 10A, 16AWG	1
	PFR-001	Binding Posts Terminal Accessory Kit (Output terminal cover × 1, Socket × 1, Protection Cover × 2, Short Bar × 1)	1
	GTL-104A	Test leads for PFR-100L (Binding Posts Terminal), 1m, 10A	1
	PFR-002	European Type Jack Terminal Accessory Kit (Output terminal cover × 1, Socket × 1, Protection Cover × 2, Short Wire × 1)	1
	GTL-105A	Test leads for PFR-100M, 1m, 3A	1
	GTL-204A	Test leads for PFR-100L (European Type Jack Terminal), 1m, 10A	1

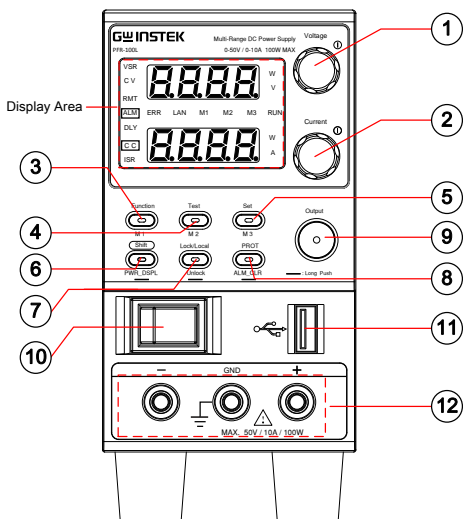
Optional Accessories	Part number	Description
	GRA-431-J-100	Rack mount adapter (JIS) with AC 100V
	GRA-431-J-200	Rack mount adapter (JIS) with AC 200V
	GRA-431-E-100	Rack mount adapter (EIA) with AC 100V
	GRA-431-E-200	Rack mount adapter (EIA) with AC 200V
	GTL-258	GPIB Cable, 2000mm

PSU-232	RS-232 Cable with DB9 Connector Kit. It includes RS-232 cable with DB9 connector, RS-485 used master cable (gray plug), slave cable (black plug) and end plug terminal.
PSU-485	RS-485 Cable with DB9 Connector Kit. It includes RS-485 cable with DB9 connector, RS-485 used master cable (gray plug), slave cable (black plug) and end plug terminal.
GTL-246	USB Cable (USB 2.0 Type A- Type B Cable, 4P)

Factory Installed Options	Part number	Description
	PFR-GL	LAN + GPIB interface

Appearance

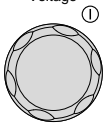
Front Panel



Display Area The display area shows setting values, output values and parameter settings. The function LEDs below show the current status and mode of the power supply. See page 15 for details.

- 1. **Voltage Knob**

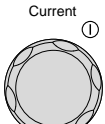
Voltage



Used to set the voltage value or select a parameter number in the Function settings.

- 2. **Current Knob**


Current



Used to set the current value or change the value of a Function parameter.







- 3. **Function Button**


Function





M1

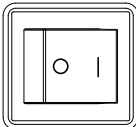
Used to configure the various functions.


- | | | |
|----------------------|---|--|
| M1 Button | | (+Shift) Used to recall the M1 setup.
(+Shift and hold) Used to save the current setup to M1. |
| 4. Test Button | <p>TEST</p>  <p>M2</p> | Used to run customized scripts for testing. |
| M2 Button | | (+Shift) Used to recall the M2 setup.
(+Shift and hold) Used to save the current setup to M2. |
| 5. Set Button | <p>SET</p>  <p>M3</p> | Used to set and confirm the output voltage and output current. |
| M3 Button | | (+Shift) Used to recall the M3 setup.
(+Shift and hold) Used to save the current setup to M3. |
| 6. Shift Button |   <p>PWR_DSPL</p> | Used to enable the functions that are written in blue characters below certain buttons. |
| PWR_DSPL | | (Long push) Displays the output power on the voltage meter or current meter. Press the Voltage knob for V/W, Press the Current knob for A/W. |
| 7. Lock/Local Button | <p>Lock/Local</p>  | Used to lock all front panel buttons other than the Output Button or it switches to local mode. |
| Unlock Button | <p>Unlock</p>  | (Long push) Used to unlock the front panel buttons. |

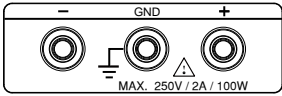
8. PROT Button  Used to set and display OVP, OCP and UVL.

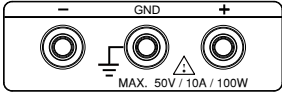
ALM_CLR Button  (Long push) Used to release protection functions that have been activated.

9. Output Button  Used to turn the output on or off.

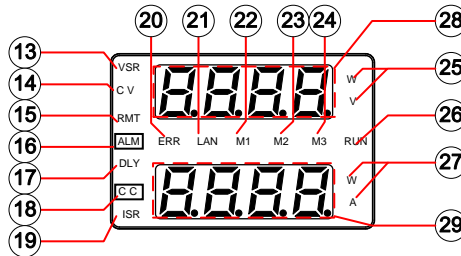
10. Power Switch  Used to turn the power on/off.

11. USB A Port  USB A port for data transfer, loading test scripts etc.

12 Output terminal  DC output terminal for PFR-100M is European Type Jack Terminal. The max. output is 250V/2A/100W

 DC output terminal for PFR-100L is Binding Posts Terminal or European Type Jack Terminal. The max. output is 50V/10A/100W

Display Area



- | | |
|-------------|--|
| 13. VSR LED | Lights up when CV Slew Rate Priority is enabled. |
| 14. CV LED | Lights in green during constant voltage mode. |
| 15. RMT LED | Lights in green during remote control. |
| 16. ALM LED | Lights in red when a protection function has been activated. |
| 17. DLY LED | The Output On/Off Delay indicator LED. |
| 18. CC LED | Lights in green during constant current mode. |
| 19. ISR LED | Lights up when CC Slew Rate Priority is enabled. |
| 20. ERR LED | Lights in red when an error has occurred. |
| 21. LAN LED | Lights up when the LAN remote connection is established. |
| 22. M1 LED | Lights in green when the memory value are being recalled or saved. |

- 23. M2 LED Lights in green when the memory value are being recalled or saved.

- 24. M3 LED Lights in green when the memory value are being recalled or saved.

- 25. V or W LED Display Voltage or Watt unit.

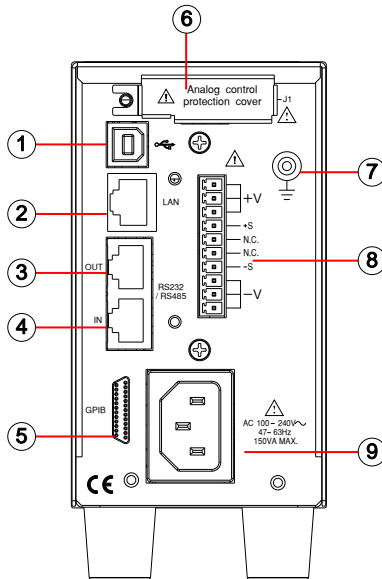
- 26. RUN LED Lights up when a Test Script has been activated.

- 27. A or W LED Display Current or Watt unit.

- 28. Voltage Meter Displays the voltage or the parameter number of a Function parameter.

- 29. Current Meter Displays the current or the value of a Function parameter.

Rear Panel



1. USB USB port for controlling the PFR-100 remotely.
2. LAN Ethernet port for controlling the PFR-100 remotely.
3. Remote-OUT RJ-45 connector that is used to daisy chain power supplies with the Remote-IN port to form a communication bus.
4. Remote-IN Two different types of cables can be used for RS232 or RS485-based remote control.
PFR-232: RS232 cable with DB9 connector kit.
PFR-485: RS485 cable with DB9 connector kit.
5. GPIB GPIB connector for units equipped with IEEE programming option. (Factory Installed Options)

6. J1 External analog remote control connector.

7. Ground
Screw Connectors for grounding the output.

8. Output
Terminals It uses a 9 pin connector and a plug for the
output and sense terminal connections.

9. Line Voltage
Input AC inlet.

Configuration Settings

Setting Normal Function Settings

The Normal Function settings, F-01~F-61, F-71~F-78 and F-88~F-89 can be easily configured with the Function key.

- Ensure the load is not connected.
- Ensure the output is off.
- Function settings F-90~94 can only be viewed.



Note

Function setting F-89 (Show Version) can only be viewed, not edited.

Configuration settings F-90~ F-94 cannot be edited in the Normal Function settings. Use the Power On Configuration settings. See page 19 for details.

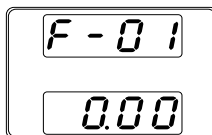
Steps

1. Press the Function key. The function key will light up.

Function

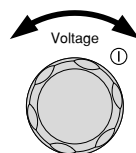


2. The display will show F-01 on the top and the configuration setting for F-01 on the bottom.

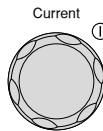


3. Rotate the Voltage knob to change the F setting.

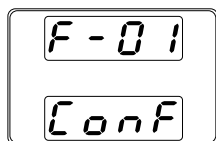
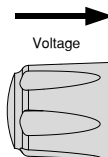
Range F-00~F-61, F-70~F-78,
F-88~F-94



- 4. Use the Current knob to set the parameter for the chosen F setting.



Press the Voltage knob to save the configuration setting. ConF will be displayed when it is configuring.



Exit

Press the Function key again to exit the configuration settings. The Function key light will turn off.

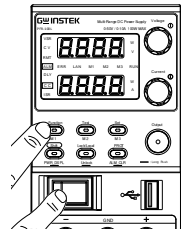


Setting Power On Configuration Settings

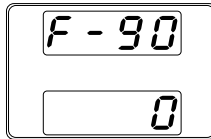
Background The Power On configuration settings can only be changed during power up to prevent the configuration settings being inadvertently changed.

- Ensure the load is not connected.
- Ensure the power supply is off.

Steps 1. Hold the Function key whilst turning the power on.

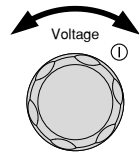


2. The display will show F-90 on the top and the configuration setting for F-90 on the bottom.

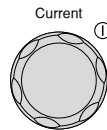


3. Rotate the Voltage knob to change the F setting.

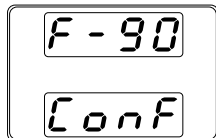
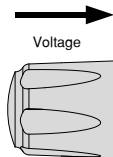
Range F-90~ F-94



4. Use the Current knob to set the parameter for the chosen F setting.



- Press the Voltage knob to save the configuration setting. Conf will be displayed when successful.



Exit

Cycle the power to save and exit the configuration settings.

Configuration Table

Please use the configuration settings listed below when applying the configuration settings.

Normal Function Settings	Setting	Setting Range
Output ON delay time	F-01	0.00s~99.99s
Output OFF delay time	F-02	0.00s~99.99s
V-I mode slew rate select	F-03	0 = CV high speed priority (CVHS) 1 = CC high speed priority (CCHS) 2 = CV slew rate priority (CVLS) 3 = CC slew rate priority (CVLS)
Rising voltage slew rate	F-04	0.1V/s ~ 100.0V/s (PFR-100L) 0.1V/s ~ 500.0V/s (PFR-100M)
Falling voltage slew rate	F-05	0.1V/s ~ 100.0V/s (PFR-100L) 0.1V/s ~ 500.0V/s (PFR-100M)
Rising current slew rate	F-06	0.01A/s ~ 20.00A/s (PFR-100L) 0.001A/s ~ 4.000A/s (PFR-100M)
Falling current slew rate	F-07	0.01A/s ~ 20.00A/s (PFR-100L) 0.001A/s ~ 4.000A/s (PFR-100M)
Bleeder circuit control	F-09	0 = OFF, 1 = ON, 2 = AUTO
Buzzer ON/OFF control	F-10	0 = OFF, 1 = ON
Detection Time of OCP	F-12	0.0 ~ 2.0 sec

Current Setting Limit (I-Limit)	F-13	0 = OFF (The limit function of current setting is disabled.) 1 = ON (The limit function of current setting is enabled.)
Voltage Setting Limit (V-Limit)	F-14	0 = OFF (The limit function of voltage setting is disabled.) 1 = ON (The limit function of voltage setting is enabled.)
Memory Recall Display	F-15	0 = OFF, 1 = ON
Measurement Average Setting	F-17	0 = Low, 1 = Middle, 2 = High
Lock Mode	F-19	0:Lock Panel, Allow Output OFF 1:Lock Panel, Allow Output ON/OFF
USB/GPIB Settings		
Front panel USB status	F-20	0 = None, 1 = Mass Storage
Rear panel USB status	F-21	0 = None, 1 = Linking to PC
GPIB Address	F-23	0 ~ 30
Show GPIB available status	F-25	0 = No GPIB, 1 = GPIB is available
Interface Select	F-29	0 = Disable, 1 = RS232, 2 = RS485, 3 = USB-CDC / NO Mass Storage, 4 = GPIB, 5 = LAN SOCKET, 6 = LAN WEB
LAN Settings		
MAC Address-1	F-30	0x00~0xFF
MAC Address-2	F-31	0x00~0xFF
MAC Address-3	F-32	0x00~0xFF
MAC Address-4	F-33	0x00~0xFF
MAC Address-5	F-34	0x00~0xFF
MAC Address-6	F-35	0x00~0xFF
DHCP	F-37	0 = OFF, 1 = ON
IP Address-1	F-39	0~255
IP Address-2	F-40	0~255
IP Address-3	F-41	0~255
IP Address-4	F-42	0~255
Subnet Mask-1	F-43	0~255
Subnet Mask-2	F-44	0~255
Subnet Mask-3	F-45	0~255
Subnet Mask-4	F-46	0~255

Gateway-1	F-47	0~255
Gateway-2	F-48	0~255
Gateway-3	F-49	0~255
Gateway-4	F-50	0~255
DNS address-1	F-51	0~255
DNS address-2	F-52	0~255
DNS address-3	F-53	0~255
DNS address-4	F-54	0~255
Web Password Enable/Disable	F-60	0 = Disable, 1 = Enable
Web Enter Password	F-61	0000~9999
UART Settings		
UART Baud Rate	F-71	0 = 1200, 1 = 2400, 2 = 4800, 3 = 9600, 4 = 19200, 5 = 38400, 6 = 57600, 7 = 115200
UART Data Bits	F-72	0 = 7 bits, 1 = 8 bits
UART Parity	F-73	0 = None, 1 = Odd, 2 = Even
UART Stop Bit	F-74	0 = 1 bit, 1 = 2 bits
UART TCP	F-75	0 = SCPI
UART Address	F-76	00 ~ 30
UART Multi-Drop control	F-77	0 = Disable, 1 = Master, 2 = Slave, 3 = Display information
UART Multi-Drop status	F-78	Displayed parameter: AA-S AA: 00~30 (Address), S: 0~1 (Off-line/On-line status).
System Settings		
Factory Default Configuration	F-88	0 = None 1 = Return to factory default settings
Show Version	F-89	0, 1 = Version 2, 3, 4, 5 = Build date (YYYYMMDD) 6, 7 = Keyboard CPLD Version 8, 9 = Analog-Control CPLD Version
Power On Configuration Settings*		
CV Control	F-90	0 = Panel control (local) 1 = External Voltage control 2 = External Resistance control- Rising ↙ 3 = External Resistance control- Falling ↘

CC Control	F-91	0 = Panel control (local) 1 = External Voltage control 2 = External Resistance control- Rising ↙ 3 = External Resistance control- Falling ↘
Power ON Output	F-92	0 = Safe Mode (Output OFF at startup) 1 = Force Mode (Output ON at startup) 2 = Auto Mode (Status before last time Power OFF)
External Output Logic Control	F-94	0 = High ON, 1 = Low ON, 2 = Disable
Special Function		
Special Function	F-00	0000 ~ 9999

REMOTE CONTROL

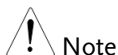
This chapter describes basic configuration of IEEE488.2 based remote control.

Interface Configuration	28
USB Remote Interface.....	28
Configuration	28
USB CDC Function Check.....	29
GPIB Remote Interface	30
Configuration	30
GPIB Function Check.....	31
UART Remote Interface.....	35
Configure UART.....	35
UART Function Check.....	38
Multiple Unit Connection	38
Multi-Drop mode	45
Multiple units Function Check	48
Configure Ethernet Connection.....	50
Web Server Configuration.....	50
Web Server Remote Control Function Check.....	51
Sockets Server Configuration.....	53
Socket Server Function Check.....	54
Socket Server Examples	59
Visual Basic Example.....	59
C++ Example.....	60
LabVIEW Example	62
Command Syntax	63
Command List	67
Status Register Overview	119
Introduction to the Status Registers	119
The Status Registers.....	121
Questionable Status Register Group	122
Operation Status Register Group.....	126
Standard Event Status Register Group	129
Status Byte Register & Service Request Enable Register.....	131

Error List	133
Command Errors	133
Execution Errors	137
Device Specific Errors.....	139
Query Errors.....	140

Interface Configuration

USB Remote Interface



Note

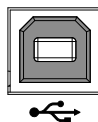
When using the USB Remote Interface, The USB port on the front panel will become disabled and fail to be used.

Configuration

USB Configuration	PC side connector	Type A, host
	PFR-100 side connector	Rear panel Type B, slave
	Speed	1.1 (full speed)
	USB Class	CDC (communications device class)

Steps

1. Connect the USB cable to the rear panel USB B port.



2. Set the Function setting F-29 (Interface port). F-29 = 3 (USB-CDC)

Page 8

3. Check to see that the USB is detected by PFR-100. The F-21 setting indicates the rear USB port

F-21 = 0 Indicates the rear USB port is not detected.

F-21 = 1 Indicates the rear USB port is available.

- The RMT indicator will turn on when a remote connection has been established.



RMT indicator

USB CDC Function Check

Functionality
check

Invoke a terminal application such as Realterm.

To check the COM port No., see the Device Manager in the PC

Run this query command via the terminal application after the instrument has been configured for USB remote control.

*idn?

This should return the Manufacturer, Model number, Serial number, and Firmware version in the following format.

GW-INSTEK,PFR-100L,TW1234567,01.01.12345678

Manufacturer: GW-INSTEK

Model number : PFR-100L

Serial number : TW1234567

Firmware version : 01.01.12345678

GPIB Remote Interface

Configuration

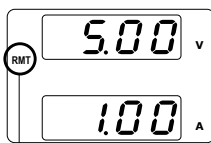
To use GPIB, the optional GPIB option (GW Instek part number: PFR-GL) must be installed. This is a factory installed option and cannot be installed by the end-user. Only one GPIB address can be used at a time.

- Configure GPIB
1. Ensure the PFR-100 is off before proceeding.
 2. Connect the GPIB cable (GW Instek part number: GTL-258) from a GPIB controller to the GPIB port on the PFR-100.
 3. Turn the PFR-100 on.
 4. Press the Function key to enter the Page 8 Normal configuration settings.
 5. Set the following GPIB settings.

F-29 = 4	Enable the GPIB port
F-23 = 0~30	Set the GPIB address (0~30)
 6. Check to see that the GPIB option is detected by the PFR-100. The F-25 setting indicates the GPIB port status.

F-25 = 0	Indicates that the GPIB port is not detected.
F-25 = 1	Indicates that the GPIB port is available.

- The RMT indicator will turn on when a remote connection has been established.



RMT indicator

- GPIB constraints
- Maximum 15 devices altogether, 20m cable length, 2m between each device
 - Unique address assigned to each device
 - At least 2/3 of the devices turned On
 - No loop or parallel connection

GPIB Function Check

Background To test the GPIB functionality, National Instruments Measurement and Automation Explorer can be used. This program is available on the NI website, www.ni.com, via a search for the VISA Run-time Engine page, or “downloads” at the following URL, <http://www.ni.com/visa/>

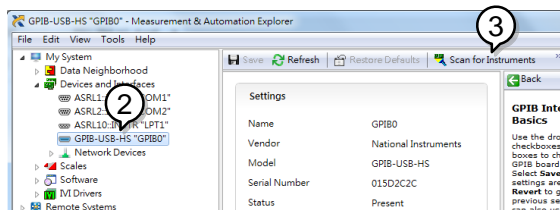
Requirements Operating System: Windows XP, 7, 8

- Functionality check
1. Start the NI Measurement and Automation Explorer (MAX) program. Using Windows, press:

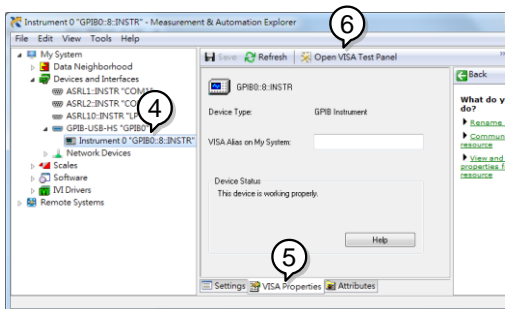
Start>All Programs>National Instruments>Measurement & Automation



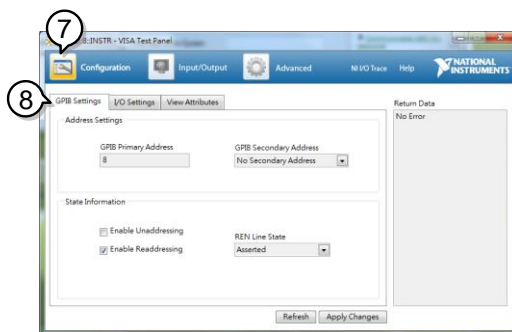
2. From the Configuration panel access;
My System>Devices and Interfaces>GPIB
3. Press *Scan for Instruments*.



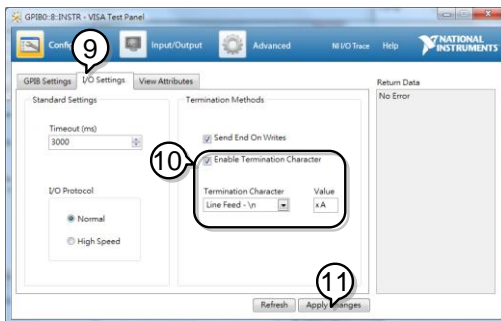
4. Select the device (GPIB address of PFR-100) that now appears in the *System>Devices and Interfaces > GPIB-USB-HS "GPIBX"* node.
5. Click on the *VISA Properties* tab on the bottom.
6. Click *Open Visa Test Panel*.



7. Click on *Configuration*.
8. Click on the *GPIB Settings* tab and confirm that the GPIB settings are correct.



9. Click on the *I/O Settings* tab.
10. Make sure the *Enable Termination Character* check box is checked, and the terminal character is \n (Value: xA).
11. Click *Apply Changes*.



12. Click on *Input/Output*.

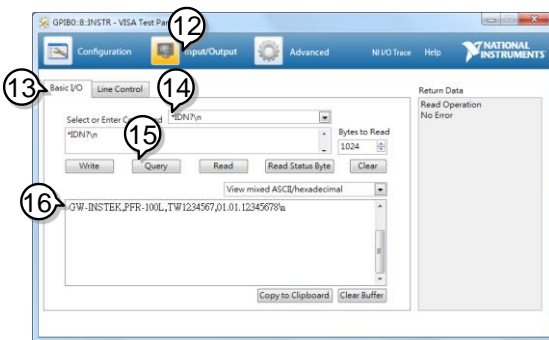
13. Click on the *Basic I/O* tab.

14. Enter **IDN?* in the *Select or Enter Command* drop down box.

15. Click *Query*.

16. The **IDN?* query will return the Manufacturer, model name, serial number and firmware version in the dialog box.

GW-INSTEK,PFR-100L,TW1234567,01.01.12345678



UART Remote Interface

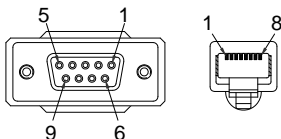
Configure UART

Overview

The PFR-100 uses the IN & OUT ports for UART communication coupled with RS232 (GW Instek Part number: PSU-232) or RS485 adapters (GW Instek part number: PSU-485).

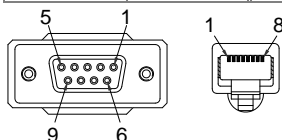
The pin outs for the adapters are shown below.

PSU-232 RS232 cable with DB9 connector	DB-9 Connector		Remote IN Port		Remarks
	Pin No.	Name	Pin No.	Name	
	Housing	Shield	Housing	Shield	
	2	RX	7	TX	Twisted pair
	3	TX	8	RX	
	5	SG	1	SG	



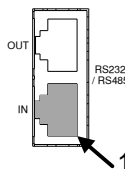
PSU-485 RS485 cable with DB9 connector

DB-9 Connector		Remote IN Port		Remarks
Pin No.	Name	Pin No.	Name	
Housing	Shield	Housing	Shield	
9	TXD -	6	RXD -	Twisted pair
8	TXD +	3	RXD +	
1	SG	1	SG	
5	RXD -	5	TXD -	Twisted pair
4	RXD +	4	TXD +	



Steps

1. Connect the RS232 serial cable (include in the PSU-232 connection kit) or RS485 serial cable (include in the PSU-485 connection kit) to the Remote IN port on the real panel.



Connect the other end of the cable to the PC.

2. Press the Function key to enter the Normal configuration settings. Page 8

Set the following UART settings:

F-29 = 1 or 2	Interface port: 1 = RS232 or 2 = RS485
F-71 = 0 ~ 7	Set the baud rate: 0=1200, 1=2400, 2=4800, 3=9600, 4=19200, 5=38400, 6=57600, 7=115200
F-72 = 0 or 1	Data bits: 0=7 or 1=8
F-73 = 0 ~2	Parity: 0 = none, 1 = odd, 2 = even

F-74 = 0 or 1	Stop bits: 0 = 1, 1 = 2
F-75 = 0	TCP: 0 = SCPI
F-76 = 0~30	UART address for multi-unit remote connection.
F-77 = 0~3	Multi-Drop control 0 = Disable, 1 = Master, 2 = Slave, 3 = Display Information
F-78 = 0~30	Multi-Drop status display Displayed parameter: AA-S AA: 0~30 (Address), S: 0~1 (Off-line/On-line status).

3. The RMT indicator will turn on when a remote connection has been established.



RMT indicator

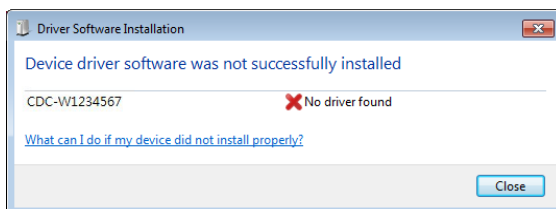
UART Function Check

Background To test the USB CDC functionality, National Instruments Measurement and Automation Explorer can be used. This program is available on the NI website, www.ni.com, via a search for the VISA Run-time Engine page, or "downloads" at the following URL, <http://www.ni.com/visa/>

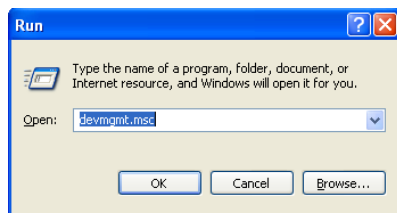
Requirements Operating System: Windows XP, 7, 8,10

Functionality check

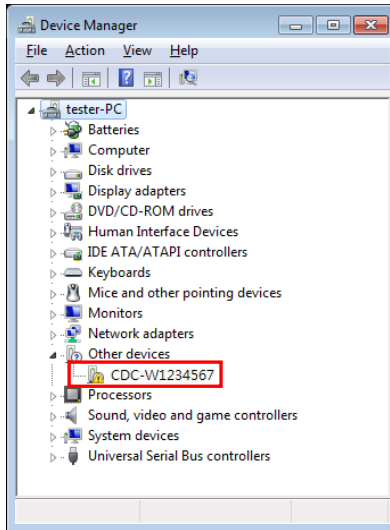
1. In case of Window 7 64 bits, once the USB Cable was connected to PC correctly for a while (around 1 min). It may show below message at the lower right area of display.



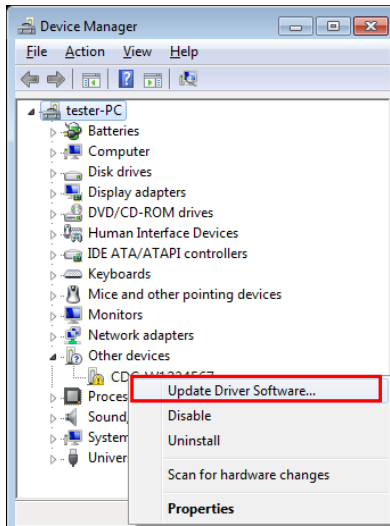
2. Open the "Run" dialog box by pressing and holding the Windows key and then press the R key ("Run").
3. Type devmgmt.msc and click "OK".



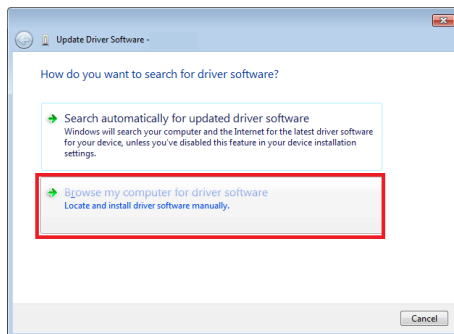
4. The Device Manager will show up CDC-WXXXXXX on "Other Devices".



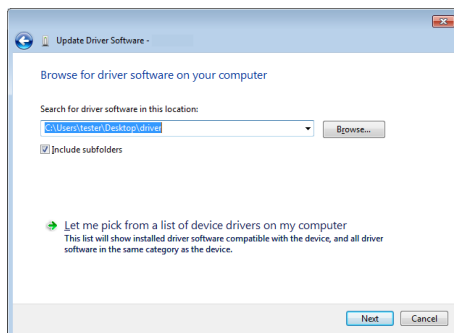
5. Select the CDC-WXXXXXX and click the right button of mouse to "Update Driver Software".



6. Select "Locate and install driver software manually."



7. Indicate the driver folder to the system and then press "Next".



And this folder should consist of below 2 files.

 gw_pfr.cst	04/02/2016 13:32
 gw_pfr.inf	04/02/2016 13:31

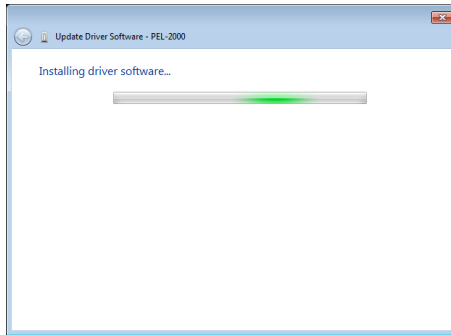


Note

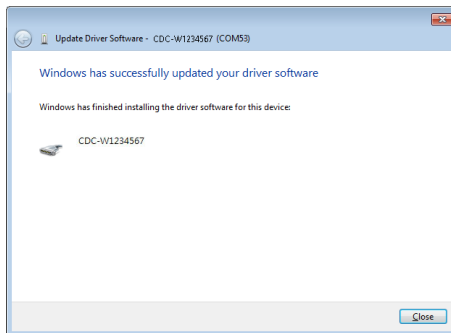
The USB driver of PFR-100 can be downloaded from download area of PFR-100 on the GW Instek website

<http://www.gwinstek.com/en-global/Support/download>

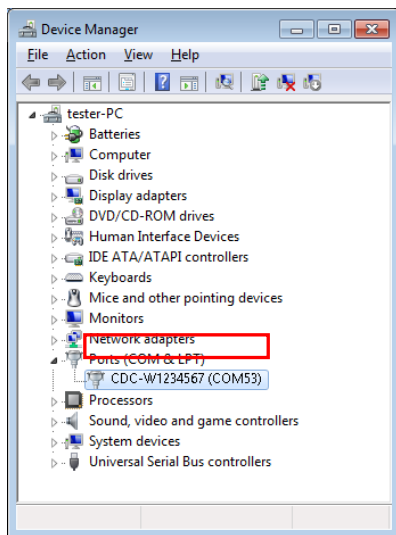
8. Windows 7 will install the driver for a while.



9. If everything works fine, you may get below message. And the COM53 is the USB CDC ACM port of PFR-100.



10. Double check the "Device Manager". The port should like below.



Steps 1~10 are for the USB CDC Driver installation.

11. Start the NI Measurement and Automation Explorer (MAX) program. Using Windows, press:

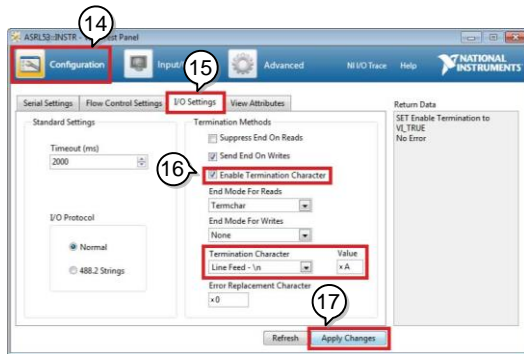
Start>All Programs>National Instruments>Measurement & Automation



12. From the Configuration panel access;
My System>Devices and Interfaces>Network Devices
13. Click Open VISA Test Panel.



14. Click the Configuration icon,
15. Click on I/O Settings.
16. Make sure the Enable Termination Character check box is checked, and the terminal character is \n (Value: xA).
17. Click Apply Changes.



18. Click the Input/Output icon.
19. Enter *IDN? in the Select or Enter Command dialog box if it is not already.

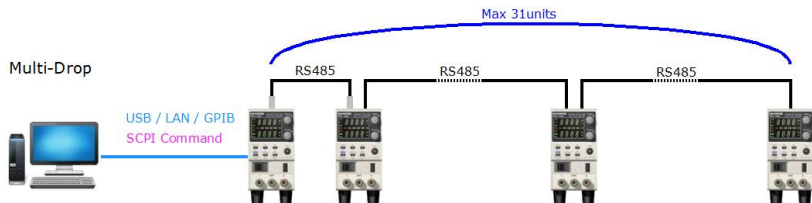
20. Click the Query button.
21. The *IDN? query will return the Manufacturer, model name, serial number and firmware version in the dialog box.

GW-INSTEK,PFR-100L,TW1234567,01.01.12345678



Multiple Unit Connection

The PFR-100 power supplies can have up to 31 units daisy-chained together using the 8 pin connectors (IN OUT ports) on the rear panel. The first unit (master) in the chain is remotely connected to a PC using USB, GPIB or LAN (Multi-Drop mode). Each subsequent unit (slave) is daisy-chained to the next using a RS485 local bus. The OUT port on the last terminal must be terminated by the end terminal connector.

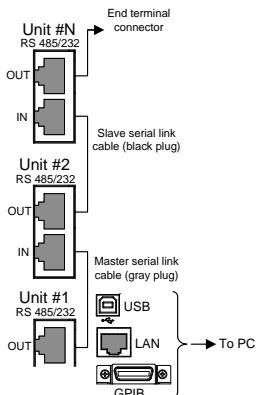


There is a mode for controlling multiple units. This mode allows the user to enter the SCPI commands developed for the instrument (Multi-Drop mode). In this mode, only the Multi-Drop parameters have to be specified. Each unit is assigned a unique address and can then be individually controlled from the host PC.

Multi-Drop mode

- Operation
1. All units must be powered down before starting the Multi-Drop mode configuration.
 2. Connect the first unit's LAN, USB or GPIB port to a PC.
 3. Connect the OUT port on the first unit to the IN port of the second unit using the master serial link cable (gray plug) supplied in the PSU-232 or PSU-485 connection kit.

4. Connect all the remaining units between the OUT port and the IN port with the slave serial link cable (black plug) supplied in the PSU-232 or PSU-485 connection kit until all the desired units have been daisy-chained together.



5. Terminate the OUT port of the last unit with the end terminal connector included in the PFR-232 or PFR-485 connection kit.

6. Power up all slave units.

Page 8

7. Set the addresses of all slave units using the F-76 parameter.

F-76 = 00~30

Set the address of the master unit. It must be a unique address identifier.

8. Set the Multi-Drop setting parameter (F-77) to Slave for all slave units.

F-77 = 2

Set the Multi-Drop setting to slave.

9. Power up the master unit.

10. Set the addresses of the master units using the F-76 parameter.

F-76 = 0 ~ 30

Set the address of the unit. It must be a unique address identifier.

11. You can check the slaves' addresses by using the F-77 parameter on the master unit.

F-77 = 3 Display on each slave units the configured address. This can show if identical addresses have been assigned individually to each slave units.

12. Set the Multi-Drop setting parameter (F-77) to Master.

F-77 = 1 Set the Multi-Drop setting to master.

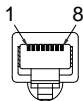
13. You can display the status of each slave unit by using the F-78 parameter.

F-78 = 0~30 Displayed parameter: AA-S
AA: 0~30 (Address),
S: 0~1 (Off-line/On-line status).

14. Multiple units can now be operated using SCPI commands. See the programming manual or see the function check below for usage details.

Slave serial link cable with RJ-45 shielded connectors from PSU-232 or PSU-485 connection kit	RS-485 slave serial link pin assignment			
	8 Pin Connector (IN)		8 Pin Connector (OUT)	
	Pin No.	Name	Pin No.	Name
	Housing	Shield	Housing	Shield
	1	SG	1	SG
	6	TXD -	6	TXD -
	3	TXD +	3	TXD +
Master serial link cable with RJ-45 shielded connectors from PSU-232 or PSU-485 connection	RS-485 master serial link pin assignment			
	8 Pin Connector (IN)		8 Pin Connector (OUT)	
	Pin No.	Name	Pin No.	Name
	Housing	Shield	Housing	Shield
	1	SG	1	SG
	6	TXD -	5	RXD -
	3	TXD +	4	RXD +

kit	5	RXD -	6	TXD -
	4	RXD +	3	TXD +



Multiple units Function Check

Functionality check Invoke a terminal application such as Realterm.
 To check the COM port No, see the Device Manager in the PC.

Multi-Drop mode When using the Multi-Drop mode, the entire SCPI command list developed for the PFR-100 can be used. Each unit can be individually controlled after a slave unit has been selected. For this function check, we will assume that the master unit is assigned to address 0, while a slave is assigned address 5.

Run this query command via the terminal application after the instruments have been configured for multi-unit control with Multi-Drop mode. See page 38.

INST:SEL 0

*IDN?

GW-INSTEK,PFR-100L,TW1234567,
01.01.12345678

Selects the unit with address 0 and returns its identity string.

INST:SEL 5

*IDN?

GW-INSTEK,PFR-100M,TW1234567,
01.01.12345678

Selects the unit with address 5 and returns its identity string.

INST:SEL 6

Selects the unit with address 6 (not configured in our example). An error is displayed on the master front panel.

SYST:ERR?

Settings conflict

Query the system errors. "Settings conflict" is returned.

INST:STAT?

33,0

Returns the active units and master unit in the bus.

33=0b100001

The units at address 0 and address 5 are on-line.

0

Master device's address is 0.

Configure Ethernet Connection

The Ethernet interface can be configured for a number of different applications. Ethernet can be configured for basic remote control or monitoring using a web server or it can be configured as a socket server.

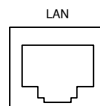
The PFR-100 series supports both DHCP connections so the instrument can be automatically connected to an existing network or alternatively, network settings can be manually configured.

Ethernet configuration	For details on how to configure the Ethernet settings, please see the configuration chapter on page 50.	
Parameters	DHCP Enable/Disable	MAC Address (display only)
	Subnet Mask	IP Address
	DNS Address	Gateway
	Web Enter Password	Web Password Enable/Disable

Web Server Configuration

Configuration This configuration example will configure the PFR-100 as a web server and use DHCP to automatically assign an IP address to the PFR-100.

1. Connect an Ethernet cable from the network to the rear panel Ethernet port.



2. Press the Function key to enter the Page 8 Normal configuration settings.

Set the following LAN settings:

F-29 = 6	Interface port select & Turn LAN (Web) on
F-37 = 1	Enable DHCP
F-60 = 0 or 1	Set to 0 to disable web password, set to 1 to enable web password.
F-61 = 0000 ~9999	Set the web password

3. The LAN indicator will turn on when a network cable is plugged in.



Note

It may be necessary to cycle the power or refresh the web browser to connect to a network.

Web Server Remote Control Function Check

Functionality check

Enter the IP address of the power supply in a web browser after the instrument has been configured as a web server.

The web server allows you to monitor the function settings of the PFR-100.

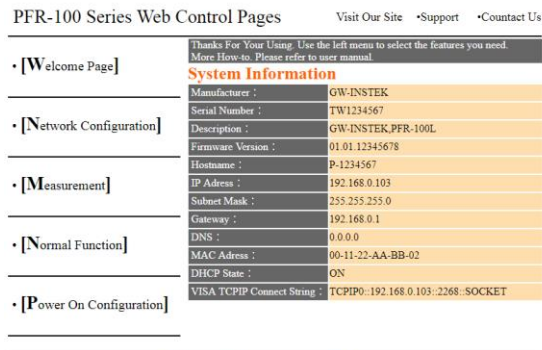
You can check the IP address by checking F-39 to F-42.

F-39 = AAA	IP Address part 1 of 4
F-40 = BBB	IP Address part 2 of 4

F-41 = CCC IP Address part 3 of 4
 F-42 = DDD IP Address part 4 of 4

http:// AAA.BBB.CCC.DDD

The web browser interface appears.



Copyright 2017 © Good Will Instrument Co., Ltd All Rights Reserved.

The web browser interface allows you to access the following:

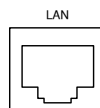
- Network configuration settings
- Measurement setting
- Normal Function setting
- Power On Configuration setting

Sockets Server Configuration

Configuration This configuration example will configure the PFR-100 socket server.

The following configuration settings will manually assign the PFR-100 an IP address and enable the socket server. The socket server port number is fixed at 2268.

1. Connect an Ethernet cable from the network to the rear panel Ethernet port.



2. Press the Function key to enter the Page 8 Normal configuration settings.

Set the following LAN settings:

F-29 = 5	Interface port select & Turn LAN(Socket) on
F-37 = 0	Disable DHCP
F-39 = 172	IP Address part 1 of 4
F-40 = 16	IP Address part 2 of 4
F-41 = 5	IP Address part 3 of 4
F-42 = 133	IP Address part 4 of 4
F-43 = 255	Subnet Mask part 1 of 4
F-44 = 255	Subnet Mask part 2 of 4
F-45 = 128	Subnet Mask part 3 of 4
F-46 = 0	Subnet Mask part 4 of 4
F-47 = 172	Gateway part 1 of 4
F-48 = 16	Gateway part 2 of 4
F-49 = 21	Gateway part 3 of 4
F-50 = 101	Gateway part 4 of 4

Socket Server Function Check

Background To test the socket server functionality, National Instruments Measurement and Automation Explorer can be used. This program is available on the NI website, www.ni.com, via a search for the VISA Run-time Engine page, or “downloads” at the following URL, <http://www.ni.com/visa/>

Requirements Operating System: Windows XP, 7, 8

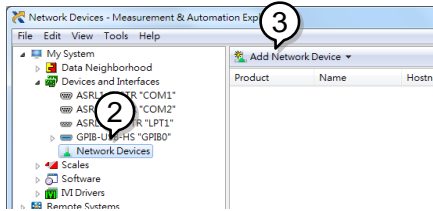
Functionality check

1. Start the NI Measurement and Automation Explorer (MAX) program. Using Windows, press:

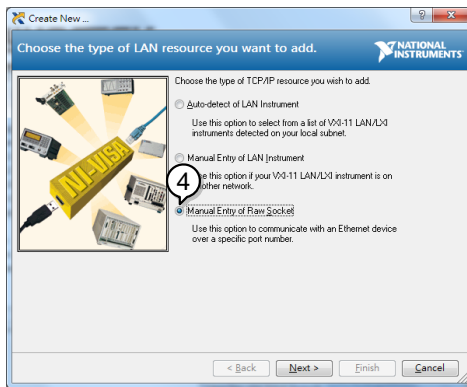
Start>All Programs>National Instruments>Measurement & Automation



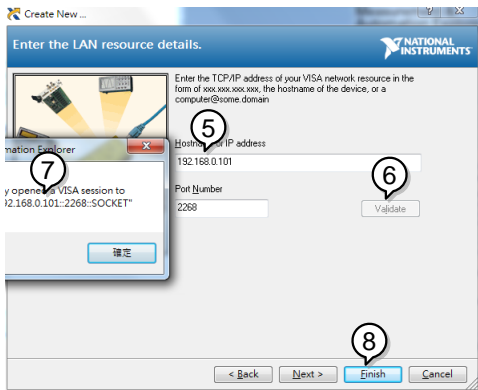
2. From the Configuration panel access; *My System>Devices and Interfaces>Network Devices*
3. Press *Add New Network Device>Visa TCP/IP Resource...*



4. Select *Manual Entry of Raw Socket* from the popup window.

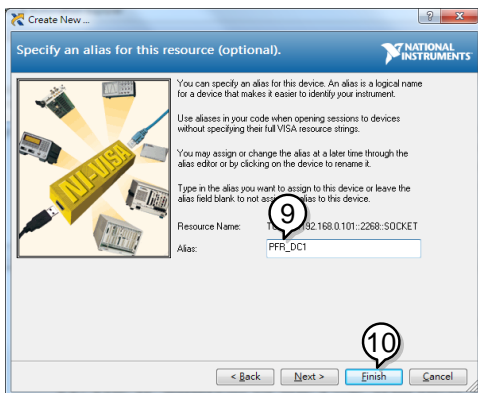


5. Enter the IP address and the port number of the PFR-100. The port number is fixed at 2268.
6. Click the Validate button.
7. A popup will appear if a connection is successfully established.
8. Click Next.



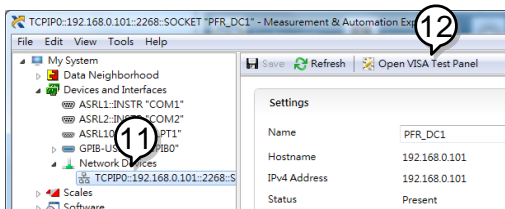
9. Next configure the Alias (name) of the PFR-100 connection. In this example the Alias is: PFR_DC1.

10. Click finish.

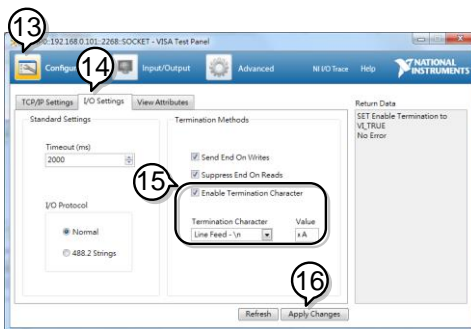


11. The IP address of the PFR-100 will now appear under Network Devices in the configuration panel. Select this icon now.

12. Click *Open VISA Test Panel*.

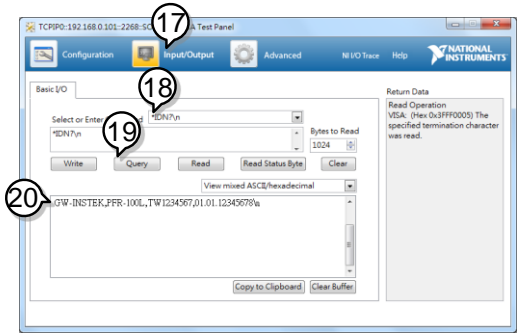


13. Click the *Configuration* icon,
14. Click on *I/O Settings*.
15. Make sure the *Enable Termination Character* check box is checked, and the terminal character is \n (Value: xA).
16. Click *Apply Changes*.



17. Click the *Input/Output* icon.
18. Enter **IDN?* in the *Select or Enter Command* dialog box if it is not already.
19. Click the *Query* button.
20. The **IDN?* query will return the Manufacturer, model name, serial number and firmware version in the dialog box.

GW-INSTEK,PFR-100L,TW1234567,01.01.12345678



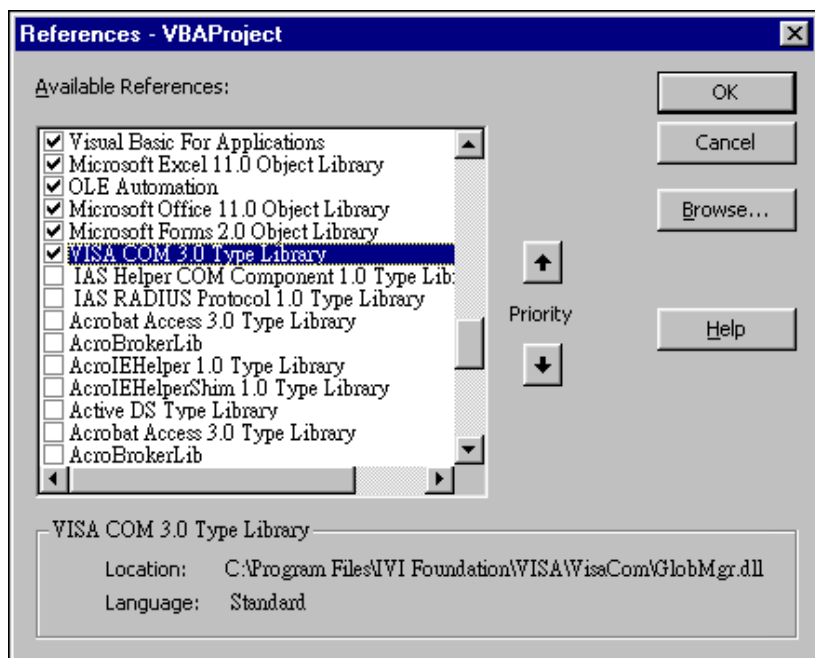
Socket Server Examples

Visual Basic Example	59
C++ Example	60
LabVIEW Example	62

Visual Basic Example

Background

The following visual basic programming example uses the VISA COM 3.0 Type Library. The example will connect to the PFR-100 using the IP address of 172.15.5.133 over port 2268. The program will send the *IDN? to the PFR-100, print the return string and then close the connection.



```
'Create VISA ResourceManager object
Dim rm As New VisaComLib.ResourceManager
Dim accessMode As VisaComLib.accessMode
Dim serial As String
Dim timeOut As Integer
Dim optionString As String
Dim psw As VisaComLib.IMessage
Dim pswcom As VisaComLib.FormattedIO488
Dim pswsfc As VisaComLib.IAsynchMessage

Private Sub CommandButton1_Click()
    accessMode = VisaComLib.accessMode.NO_LOCK

    timeOut = 0

    optionString = ""

    'Connect to the PSW

    Set psw = rm.Open("TCPIP0::172.16.5.133::2268::SOCKET", _
        accessMode, _
        timeOut, _
        optionString)
    Set pswsfc = psw
    pswsfc.TerminationCharacterEnabled = True

    'Query the System Identify Name
    psw.WriteString ("*IDN?" & vbCrLf)

    Worksheets("Sheet1").Cells(1, 5) = psw.ReadString(256)

    'Close the communication
    psw.Close

End Sub
```

C++ Example

Background The following program creates a connection to the PFR-100 and sets the voltage to 3.3 volts and the current 1.5 amps. The voltage and current reading is then read back and the connection is closed.



Note

Add visa32.lib to the project library when building the following sample program.

```
#include "stdio.h"
#include "string.h"
#include "visatype.h"
#include "visa.h"
#define IPAddr "172.16.20.181"
int main(int argc, char* argv[])
{
    ViSession defaultRm, instr;
    // Create VISA ResourceManager object
    ViStatus status = viOpenDefaultRM(&defaultRm);
    if (status < VI_SUCCESS)
    {
        // Initialization error
        return -1;
    }
    ViChar rsc[256];
    sprintf(rsc, "TCPIP0::%s::2268::SOCKET", IPAddr);
    ViAccessMode accessMode = VI_NO_LOCK;
    ViUInt32 timeout = 0;
    // Connect the device
    viOpen(defaultRm, rsc, accessMode, timeout, &instr);
    /* Set the timeout for message-based communication */
    status = viSetAttribute(instr, VI_ATTR_TMO_VALUE, 5000);
    status = viSetAttribute(instr, VI_ATTR_TERMCHAR, 10);
    status = viSetAttribute(instr, VI_ATTR_TERMCHAR_EN, VI_TRUE);
    ViUInt32 count;
    // Set the Voltage to 3.3, Current to 1.5
    ViBuf buf = (ViBuf)":volt 3.3;:curr 1.5\n";
    viWrite(instr, buf, (ViUInt32)strlen((ViPChar)buf), &count);

    // Query the Voltage, and Current
    buf = (ViBuf)":apply?\n";
    status = viWrite(instr, buf, (ViUInt32)strlen((ViPChar)buf), &count);
    ViChar result[257];
    status = viRead(instr, (ViPBuf)result, 256, &count);
    if (status=VI_SUCCESS_TERM_CHAR)
    {
        result[count] = 0;
        printf("Voltage(V), Current(A)= %s\n", result);
    }else
        printf("Error\n");

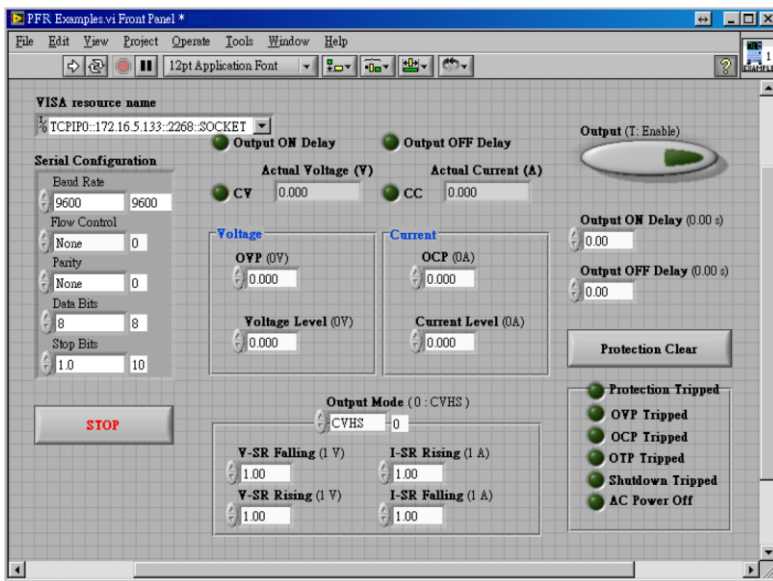
    // Close the device
    viClose(instr);
    viClose(defaultRm);

    return 0;
}
```

LabVIEW Example

Background

The following picture shows a LabVIEW programming example for the PFR-100.



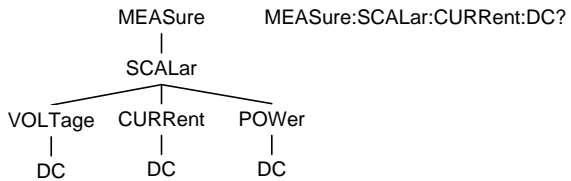
Command Syntax

Compatible Standard	IEEE488.2	Partial compatibility
	SCPI, 1999	Partial compatibility

Command Structure

SCPI commands follow a tree-like structure, organized into nodes. Each level of the command tree is a node. Each keyword in a SCPI command represents each node in the command tree. Each keyword (node) of a SCPI command is separated by a colon (:).

For example, the diagram below shows an SCPI sub-structure and a command example.



Command types

There are a number of different instrument commands and queries. A command sends instructions or data to the unit and a query receives data or status information from the unit.

Command types

Simple A single command with/without a parameter

Example *IDN?

Query A query is a simple or compound command followed by a question mark (?). A parameter (data) is returned.

Example meas:curr:dc?

Compound Two or more commands on the same command line. Compound commands are separated with either a semi-colon (;) or a semi-colon and a colon (;:).

A semi-colon is used to join two related commands, with the caveat that the last command must begin at the last node of the first command.

A semi-colon and colon are used to combine two commands from different nodes.

Example meas:volt:dc?::meas:curr:dc?

Command Forms Commands and queries have two different forms, long and short. The command syntax is written with the short form of the command in capitals and the remainder (long form) in lower case.

The commands can be written in capitals or lower-case, just so long as the short or long forms are complete. An incomplete command will not be recognized.

Below are examples of correctly written commands.

Long form	STATus:OPERation:NTRansition? STATUS:OPERATION:NTRANSITION? status:operation:ntransition?
Short form	STAT:OPER:NTR? stat:oper:ntr?

Square Brackets Commands that contain square brackets indicate that the contents are optional. The function of the command is the same with or without the square bracketed items, as shown below.

Both “DISPlay:MENU[:NAME]?” and “DISPlay:MENU?” are both valid forms.

Command Format

APPLY 1.5,5.2

1. Command header
2. Space
3. Parameter 1
4. Comma (no space before/after comma)
5. Parameter 2

Parameters	Type	Description	Example
	<Boolean>	Boolean logic	0, 1

<NR1>	integers	0, 1, 2, 3
<NR2>	decimal numbers	0.1, 3.14, 8.5
<NR3>	floating point	4.5e-1, 8.25e+1
<NRf>	any of NR1, 2, 3	1, 1.5, 4.5e-1
<block data>	Definitive length arbitrary block data. A single decimal digit followed by data. The decimal digit specifies how many 8-bit data bytes follow.	

Message Terminator	LF	Line feed code
--------------------	----	----------------

Command List

Abort Command	:ABORt	71
Apply Commands	:APPLy	71
Display Commands	:DISPlay:MENU[:NAME]	72
	:DISPlay[:WINDow]:TEXT:CLEAr	72
	:DISPlay[:WINDow]:TEXT[:DATA]	73
	:DISPlay:BLINK	73
Initiate Commands	:INITiate:CONTInuous[:TRANsient]	74
	:INITiate[:IMMediate]:NAME	74
	:INITiate[:IMMediate][:TRANsient]	75
Instrument Commands	:INSTRument:SCAN	76
	:INSTRument:SELEct	76
	:INSTRument:STATe	76
	:INSTRument:DISPlay	77
Measure Commands	:MEASure[:SCALar]:ALL[:DC]	78
	:MEASure[:SCALar]:CURREnt[:DC]	78
	:MEASure[:SCALar]:VOLTage[:DC]	78
	:MEASure[:SCALar]:POWEr[:DC]	79
Output Commands	:OUTPut:DELAy:ON	80
	:OUTPut:DELAy:OFF	80
	:OUTPut:MODE	81
	:OUTPut[:STATe][:IMMediate]	81
	:OUTPut[:STATe]:TRIGgered	81
	:OUTPut:PROTEction:CLEAr	82
	:OUTPut:PROTEction:TRIPped	82

Sense	:SENSe:AVERAge:COUNT	83
Commands		
Status	:STATus:OPERation[:EVENT]	84
Commands	:STATus:OPERation:CONDition	84
	:STATus:OPERation:ENABle	85
	:STATus:OPERation:PTRansition	85
	:STATus:OPERation:NTRansition	85
	:STATus:QUEStionable[:EVENT]	85
	:STATus:QUEStionable:CONDition	86
	:STATus:QUEStionable:ENABle	86
	:STATus:QUEStionable:PTRansition	86
	:STATus:QUEStionable:NTRansition	86
	:STATus:QUEStionable:INSTrument:	
	ISUMmary<n>[:EVENT]	87
	:STATus:QUEStionable:INSTrument:	
	ISUMmary<n>:CONDition	87
	:STATus:QUEStionable:INSTrument:	
	ISUMmary<n>:ENABle	87
	:STATus:PRESet	88
Source	[:SOURce]:CURRent[:LEVel][:IMMediate]	
Commands	[:AMPLitude]	90
	[:SOURce]:CURRent[:LEVel]:TRIGgered	
	[:AMPLitude]	91
	[:SOURce]:CURRent:LIMit:AUTO	91
	[:SOURce]:CURRent:PROTection:DELay	92
	[:SOURce]:CURRent:PROTection[:LEVel]	92
	[:SOURce]:CURRent:PROTection:TRIPped	93
	[:SOURce]:CURRent:SLEWrate:RISing	93
	[:SOURce]:CURRent:SLEWrate:FALLing	93
	[:SOURce]:MODE?	94
	[:SOURce]:VOLTagE[:LEVel][:IMMediate]	
	[:AMPLitude]	94
	[:SOURce]:VOLTagE[:LEVel]:TRIGgered	
	[:AMPLitude]	95
	[:SOURce]:VOLTagE:LIMit:AUTO	95
	[:SOURce]:VOLTagE:LIMit:LOW	96
	[:SOURce]:VOLTagE:PROTection[:LEVel]	96
	[:SOURce]:VOLTagE:PROTection:TRIPped	96
	[:SOURce]:VOLTagE:SLEWrate:RISing	97
	[:SOURce]:VOLTagE:SLEWrate:FALLing	97

System	:SYSTem:BEEPer[:IMMediate]	100
Commands	:SYSTem:CONFigure:BEEPer[:STATe]	100
	:SYSTem:CONFigure:BLEeder[:STATe]	101
	:SYSTem:CONFigure:CURRent:CONTRol	101
	:SYSTem:CONFigure:VOLTage:CONTRol	102
	:SYSTem:CONFigure:OUTPut:PON[:STATe]	102
	:SYSTem:CONFigure:OUTPut:EXTernal:MODE	103
	:SYSTem:COMMunicate:ENABLE	103
	:SYSTem:COMMunicate:GPIB[:SELF]:ADDReSS	104
	:SYSTem:COMMunicate:LAN:IPADdress	104
	:SYSTem:COMMunicate:LAN:GATEWay	105
	:SYSTem:COMMunicate:LAN:SMASk	105
	:SYSTem:COMMunicate:LAN:MAC	105
	:SYSTem:COMMunicate:LAN:DHCP	106
	:SYSTem:COMMunicate:LAN:DNS	106
	:SYSTem:COMMunicate:RLState	106
	:SYSTem:COMMunicate:TCPIp:CONTRol	107
	:SYSTem:COMMunicate:SERial[:RECeive]	
	:TRANsmit:BAUD	107
	:SYSTem:COMMunicate:SERial[:RECeive]	
	:TRANsmit:BITS	108
	:SYSTem:COMMunicate:SERial[:RECeive]	
	:TRANsmit:PARity	108
	:SYSTem:COMMunicate:SERial[:RECeive]	
	:TRANsmit:SBITs	109
	:SYSTem:COMMunicate:MULTidrop:CONTRol	109
	:SYSTem:COMMunicate:USB:FRONt:STATe	109
	:SYSTem:COMMunicate:USB:REAR:STATe	110
	:SYSTem:ERRor	110
	:SYSTem:KLOCK	110
	:SYSTem:KEYLock:MODE	110
:SYSTem:ERRor:ENABLE	111	
:SYSTem:PRESet	111	
:SYSTem:VERSIon	111	
:SYSTem:REBoot	111	
Trigger Commands	:TRIGger:OUTPut:SOURce	112
	:TRIGger:OUTPut[:IMMediate]	112
	:TRIGger[:TRANsient]:SOURce	112
	:TRIGger[:TRANsient][:IMMediate]	113
	Trigger Command Examples	113

Common Commands	*CLS	115
	*ESE	115
	*ESR	116
	*IDN	116
	*OPC	116
	*RCL	117
	*RST	117
	*SAV	117
	*SRE	117
	*STB	118
	*TRG	118
	*TST	118
	*WAI	118

Abort Command

:ABORt 71

:ABORt



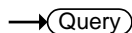
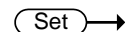
Description The :ABORt command will cancel any triggered actions.

Syntax :ABORt

Apply Commands

:APPLy 71

:APPLy



Description The apply command sets the voltage and current at the same time.

Syntax :APPLy
{<NRf>(V)|MINimum|MAXimum[,<NRf>(A)|MINimum|MAXimum]}

Query Syntax :APPLy?

Parameter/	<NRf>(V)	Voltage setting.
Return parameter	MINimum	Minimum voltage level
	MAXimum	Maximum voltage level
	<NRf>(A)	Current setting.
	MINimum	Minimum voltage level
	MAXimum	Maximum voltage level

Example APPL MIN, MIN
Sets the current and voltage to the minimum settings.

Display Commands

:DISPlay:MENU[:NAME]	72
:DISPlay[:WINDow]:TEXT:CLEAr.....	72
:DISPlay[:WINDow]:TEXT[:DATA].....	73
:DISPlay:BLINK.....	73

:DISPlay:MENU[:NAME] (Set) →
← (Query)

Description	The DISPlay MENU command selects a screen menu or queries the current screen menu.	
Syntax	:DISPlay:MENU[:NAME] <NR1>	
Query Sytax	:DISPlay:MENU[:NAME]?	
Parameter/ Return parameter	<NR1>	Description
	0	Measure voltage & current
	1~2	Not Used
	3	Set Menu
	4	OVP / OCP Menu
	5~99	Not Used.
	100~199	F-00~99 Menu.
	200~229	F100~F129 Menu.
Example	DISP:MENU:NAME 0 Sets the display to the Voltage/Current display screen.	

:DISPlay[:WINDow]:TEXT:CLEAr (Set) →

Description	Clears the text on the main screen from the :DISPlay[:WINDow]:TEXT[:DATA] command.	
Syntax	:DISPlay[:WINDow]:TEXT:CLEAr	

:DISPlay[:WINDow]:TEXT[:DATA]  

Description Sets or queries the data text that will be written to the display. Writing to the display will overwrite data that is currently on the screen. Overwriting a display area with a shorter string may or may not overwrite the screen. The string must be enclosed in quotes: "STRING". Only ASCII characters 20H to 7EH can be used in the <string>.

Syntax :DISPlay[:WINDow]:TEXT[:DATA] <string>

Query Syntax :DISPlay[:WINDow]:TEXT[:DATA]?

Parameter/Return parameter <string> ASCII character 20H to 7EH can be used to in the string parameter. The string must be enclosed in quotes: "STRING"

Example DISP:WIND:TEXT:DATA "STRING"
Writes STRING to the display.

Query Example DISP:WIND:TEXT:DATA?
"STRING"
Returns the text data string on the screen.

:DISPlay:BLINK  

Description Turns blink on or off for the display. Blink is set to OFF by default.

Syntax :DISPlay:BLINK {<bool>|OFF|ON}

Query Syntax :DISPlay:BLINK?

Parameter OFF | 0 Turns blink OFF
ON | 1 Turns blink ON

Return parameter <bool> Returns the blink status.

Example DISP:BLIN 1
Turns blink ON.

Initiate Commands

:INITiate:CONTInuous[:TRANsient]	74
:INITiate[:IMMEDIATE]:NAME	74
:INITiate[:IMMEDIATE][:TRANsient]	75

:INITiate:CONTInuous[:TRANsient] (Set) →
→ (Query)

Description	This command continuously initiates software triggers for the transient or output triggers.
Syntax	:INITiate:CONTInuous[:TRANsient] {<bool> OFF ON}
Query Syntax	:INITiate:CONTInuous[:TRANsient]?
Parameter	OFF 0 OFF ON 1 ON
Return parameter	0 OFF 1 ON
Example	INIT:TRAN 1 Turns on the continuous trigger.

:INITiate[:IMMEDIATE]:NAME (Set) →

Description	The INITiate command starts the TRANsient or OUTPut trigger.
Syntax	:INITiate[:IMMEDIATE]:NAME {TRANsient OUTPut}
Parameter	TRANsient Starts the TRANsient trigger. OUTPut Starts the OUTPut trigger.
Example	INITiate:NAME TRANient Starts the TRANsient trigger.

:INITiate[:IMMEDIATE][:TRANSient]

Set →

Description	This command controls the enabling of output triggers. When a trigger is enabled, a trigger causes the specified action to occur. If the trigger system is not enabled, all triggers are ignored.
Syntax	:INITiate[:IMMEDIATE][:TRANSient]
Example	INIT

Instrument Commands

:INSTrument:SCAN.....	76
:INSTrument:SELEct	76
:INSTrument:STATe	76
:INSTrument:DISPlay.....	77

:INSTrument:SCAN

Set →

Description Links the units which could be scanned from system when using Multi-Drop mode.

Syntax :INSTrument:SCAN

:INSTrument:SELEct

Set →

→ Query

Description Specifies the address of the unit to which communication will be established when using the Multi-Drop mode.

Syntax :INSTrument :SELEct {<NR1>}

Query Syntax :INSTrument :SELEct?

Parameter <NR1> The address of the unit to be selected (0~30).

Return parameter <NR1> The currently selected address.

Example :INST:SEL?
>30

The currently selected address is 30.

:INSTrument:STATe

→ Query

Description Displays the status (on-line/off-line) of each slave unit and the address of master unit, when using the Multi-Drop mode.

Query Syntax :INSTrument:STATe?

Return parameter	<NR1>,<NR1>	<p>0~2147483647, 0~30 (2147483647=2³¹-1)</p> <p>First value:</p> <p>Each bit of the binary value corresponds to a unit from 0 to 30 (LSB to MSB). The bit will be set to 1 when the corresponding unit is on-line.</p> <p>Second value:</p> <p>This value represents the master address.</p>
------------------	-------------	---

Example

```
:INST:STAT?
33,0
33=0b100001
```

The units at address 0 and address 5 are on-line.

```
0
```

Master device's address is 0.

:INSTrument:DISPlay



Description	Displays information (configured address) for all slave units when using the Multi-Drop mode.
Syntax	:INSTrument:DISPlay
Example	:INST:DISP

Measure Commands

:MEASure[:SCALar]:ALL[:DC]	78
:MEASure[:SCALar]:CURRent[:DC]	78
:MEASure[:SCALar]:VOLTage[:DC]	78
:MEASure[:SCALar]:POWer[:DC]	79

:MEASure[:SCALar]:ALL[:DC] → Query

Description	Takes a measurement and returns the average output current and voltage	
Syntax	:MEASure[:SCALar]:ALL[:DC]?	
Return parameter	" +0.0000,+0.0000"	<voltage>,<current> Returns the voltage (V) and current (A), respectively.

:MEASure[:SCALar]:CURRent[:DC] → Query

Description	Takes a measurement and returns the average output current	
Syntax	:MEASure[:SCALar]:CURRent[:DC]?	
Return parameter	" +0.0000"	Returns the current in amps.

:MEASure[:SCALar]:VOLTage[:DC] → Query

Description	Takes a measurement and returns the average output voltage.	
Syntax	:MEASure[:SCALar]:VOLTage[:DC]?	
Return	" +0.0000"	Returns the voltage in volts.

:MEASure[:SCALar]:POWer[:DC]

→ Query

Description	Takes a measurement and returns the average output power.
Syntax	:MEASure[:SCALar]:POWer[:DC]?
Return	" +0.0000 " Returns the power measured in watts.

Output Commands

:OUTPut:DElay:ON	80
:OUTPut:DElay:OFF	80
:OUTPut:MODE	81
:OUTPut[:STATe][:IMMediate]	81
:OUTPut[:STATe]:TRIGgered	81
:OUTPut:PROTection:CLear	82
:OUTPut:PROTection:TRIPped	82

:OUTPut:DElay:ON

Set →

→ Query

Description	Sets the Delay Time in seconds for turning the output on. The delay is set to 0.00 by default.	
Syntax	:OUTPut:DElay:ON {<NR2> MINimum MAXimum}	
Query Syntax	:OUTPut:DElay:ON?	
Parameter	<NR2>	0.00~99.99 seconds, where 0=no delay.
Return parameter	"0.00"	Returns the delay on time in seconds until the output is turned on.

Set →

→ Query


:OUTPut:DElay:OFF

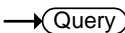
Description	Sets the Delay Time in seconds for turning the output off. The delay is set to 0.00 by default.	
Syntax	:OUTPut:DElay:OFF {<NR2> MINimum MAXimum}	
Return Syntax	:OUTPut:DElay:OFF?	
Parameter	<NR2>	0.00~99.99 seconds, where 0=no delay.
Return parameter	"0.00"	Returns the delay off time in seconds until the output is turned off.

:OUTPut:MODE




Description	Sets the PFR-100 output mode. This is the equivalent to the F-03 (V-I Mode Slew Rate Select) settings.
Syntax	:OUTPut:MODE {<NR1> CVHS CCHS CVLS CCLS}
Return Syntax	:OUTPut:MODE?
Parameter	CVHS 0 CV high speed priority CCHS 1 CC high speed priority CVLS 2 CV slew rate priority CCLS 3 CC slew rate priority
Return parameter	<NR1> Returns the output mode.

:OUTPut[:STATe][:IMMediate]




Description	Turns the output on or off.
Syntax	:OUTPut[:STATe][:IMMediate] { <bool> OFF ON }
Query Syntax	:OUTPut[:STATe][:IMMediate]?
Parameter	OFF 0 Turns the output off. ON 1 Turns the output on.
Return parameter	<bool> Returns output status of the instrument.

:OUTPut[:STATe]:TRIGgered




Description	Turns the output on or off when a software trigger is generated.
Syntax	:OUTPut[:STATe]:TRIGgered { <bool> OFF ON }
Query Syntax	:OUTPut[:STATe]:TRIGgered?
Parameter	OFF 0 Turns the output off when a software trigger is generated (*TRG). ON 1 Turns the output on when a software trigger is generated (*TRG).
Return parameter	<bool> Returns output trigger status of the instrument.

:OUTPut:PROTection:CLEar (Set) →

Description Clears over-voltage, over-current and over-temperature (OVP, OCP, OTP) protection circuits. It also clears the shutdown and sense protection circuit. The AC failure protection cannot be cleared.

Syntax :OUTPut:PROTection:CLEar

:OUTPut:PROTection:TRIPped → (Query)


Description Queries the unit to see if a protection circuit has been tripped.

Syntax :OUTPut:PROTection:TRIPped?

Return <boolean> 0 = No protection error
 1 = A protection error had occurred

Sense Commands

:SENSe:AVERAge:COUNT.....83

:SENSe:AVERAge:COUNT




Description	Sets or queries the level of smoothing for the average setting.	
Syntax	:SENSe:AVERAge:COUNT	
Return Syntax	{<NR1> LOW MIDDLE HIGH}	
	:SENSe:AVERAge:COUNT?	
Parameter	LOW 0	Low setting
	MIDDLE 1	Middle setting
	HIGH 2	High setting
Return Parameter	<NR1>	Returns the average setting.

Status Commands

For an overview of all the status registers, their associated register contents and the system diagram, please see the status overview on page 118

:STATus:OPERation[:EVENT]	84
:STATus:OPERation:CONDition	84
:STATus:OPERation:ENABle	85
:STATus:OPERation:PTRansition	85
:STATus:OPERation:NTRansition	85
:STATus:QUEStionable[:EVENT]	85
:STATus:QUEStionable:CONDition	86
:STATus:QUEStionable:ENABle	86
:STATus:QUEStionable:PTRansition	86
:STATus:QUEStionable:NTRansition	86
:STATus:QUEStionable:INSTrument:	
ISUMmary<n>[:EVENT]	87
:STATus:QUEStionable:INSTrument:	
ISUMmary<n>:CONDition	87
:STATus:QUEStionable:INSTrument:	
ISUMmary<n>:ENABle	87
:STATus:PRESet	88

:STATus:OPERation[:EVENT] → Query

Description	Queries the Operation Status Event register and clears the contents of the register.
-------------	--

Syntax	:STATus:OPERation[:EVENT]?
--------	----------------------------

Return	<NR1> Returns the bit sum of the Operation Status Event register.
--------	---

:STATus:OPERation:CONDition → Query

Description	Queries the Operation Status register. This query will not clear the register.
-------------	--

Syntax	:STATus:OPERation:CONDition?
--------	------------------------------

Return <NR1> Returns the bit sum of the Operation Condition register.

Set →

:STATus:OPERation:ENABLE

→ Query

Description Sets or queries the bit sum of the Operation Status Enable register.

Syntax :STATus:OPERation:ENABLE <NR1>

Query Syntax :STATus:OPERation:ENABLE?

Parameter <NR1> 0~32767

Return parameter <NR1> 0~32767

Set →

:STATus:OPERation:PTRansition

→ Query

Description Sets or queries the bit sum of the positive transition filter of the Operation Status register.

Syntax :STATus:OPERation:PTRansition <NR1>

:STATus:OPERation:PTRansition?

Parameter <NR1> 0~32767

Return parameter <NR1> 0~32767

Set →

:STATus:OPERation:NTRansition

→ Query

Description Sets or queries the bit sum of the negative transition filter of the Operation Status register.

Syntax :STATus:OPERation:NTRansition <NR1>

Query Syntax :STATus:OPERation:NTRansition?

Parameter <NR1> 0~32767

Return parameter <NR1> 0~32767

:STATus:QUESTionable[:EVENT]

→ Query

Description Queries the bit sum of the Questionable Status Event register. This query will also clear the contents of the register.

Query Syntax :STATus:QUEStionable[:EVENT]?

Return parameter <NR1> 0~32767

:STATus:QUEStionable:CONDition → (Query)

Description Queries the status (bit sum) of the Questionable Status register. This query will not clear the register.

Query Syntax :STATus:QUEStionable:CONDition?

Return parameter <NR1> 0~32767

(Set) →

:STATus:QUEStionable:ENABle → (Query)

Description Sets or queries the bit sum of the Questionable Status Enable register.

Syntax :STATus:QUEStionable:ENABle <NR1>

Query Syntax :STATus:QUEStionable:ENABle?

Parameter <NR1> 0~32767

Return parameter <NR1> 0~32767

(Set) →

:STATus:QUEStionable:PTRansition → (Query)

Description Sets or queries the bit sum of the positive transition filter of the Questionable Status register.

Syntax :STATus:QUEStionable:PTRansition <NR1>

Return Syntax :STATus:QUEStionable:PTRansition?

Parameter <NR1> 0~32767

Return parameter <NR1> 0~32767

(Set) →

:STATus:QUEStionable:NTRansition → (Query)

Description Sets or queries the negative transition filter of the Questionable Status register.

Syntax	:STATus:QUESTIONable:NTRansition <NR1>
Query Syntax	:STATus:QUESTIONable:NTRansition?
Parameter	<NR1> 0~32767
Return parameter	<NR1> 0~32767

**:STATus:QUESTIONable:INSTRument:
ISUMmary<n>[:EVENT]** → Query

Description Queries the bit sum of the Questionable Instrument Summary Status Event register. This query will also clear the contents of the register (Multi-Drop mode).

Query Syntax	:STATus:QUESTIONable:INSTRument:ISUMmary <n>[:EVENT]?
Parameter	<n> 1,2 or 3
Return parameter	<NR1> 0~32767

**:STATus:QUESTIONable:INSTRument:
ISUMmary<n>:CONDition** → Query

Description Queries the status (bit sum) of the Questionable Instrument Summary Status Condition register. This query will not clear the register (Multi-Drop mode).

Query Syntax	:STATus:QUESTIONable:INSTRument:ISUMmary<n>:CONDition?
Parameter	<n> 1, 2 or 3
Return parameter	<NR1> 0~32767

**:STATus:QUESTIONable:INSTRument:
ISUMmary<n>:ENABLE** Set →
→ Query

Description Sets or queries the bit sum of the Questionable Instrument Summary Status Enable register. (Multi-Drop mode).

Syntax	:STATus:QUEStionable:INSTRument:ISUMmary <n>:ENABle <NR1>	
Query Syntax	:STATus:QUEStionable:INSTRument:ISUMmary <n>:ENABle?	
Parameter	<n>	1,2 or 3
	<NR1>	0~32767
Return parameter	<NR1>	0~32767

:STATus:PRESet



Description This command resets the ENABle register, the PTRansition filter and NTRansition filter on the Operation Status and Questionable Status Registers. The registers/filters will be reset to a default value.

Default Register/Filter Values	Setting
QUEStionable Status Enable	0x0000
QUEStionable Status Positive Transition	0x7FFF
QUEStionable Status Negative Transition	0x0000
QUEStionable Instrument Summary1 Status Enable	0x7FFF
QUEStionable Instrument Summary2 Status Enable	0x7FFF
QUEStionable Instrument Summary3 Status Enable	0x7FFF
Operation Status Enable	0x0000
Operation Status Positive Transition	0x7FFF
Operation Status Negative Transition	0x0000



Summary: The Questionable Status Enable registers and the Operation Status Enable registers are both reset to 0.

The Questionable Status and Operation Status Positive Transition filters are all set high (0x7FFF) and the Negative Transition filters are all set low (0x0000). I.e., only positive transitions will be recognized for the Questionable Status and Operation Status registers.

Syntax :STATus:PRESet

Source Commands

[:SOURce]:CURRent[:LEVel][:IMMediate]	
[:AMPLitude].....	90
[:SOURce]:CURRent[:LEVel]:TRIGgered	
[:AMPLitude].....	91
[:SOURce]:CURRent:LIMit:AUTO	91
[:SOURce]:CURRent:PROTection:DELay.....	92
[:SOURce]:CURRent:PROTection[:LEVel]	92
[:SOURce]:CURRent:PROTection:TRIPped	93
[:SOURce]:CURRent:SLEWrate:RISing.....	93
[:SOURce]:CURRent:SLEWrate:FALLing	93
[:SOURce]:MODE?	94
[:SOURce]:VOLTage[:LEVel][:IMMediate]	
[:AMPLitude].....	94
[:SOURce]:VOLTage[:LEVel]:TRIGgered	
[:AMPLitude].....	95
[:SOURce]:VOLTage:LIMit:AUTO	95
[:SOURce]:VOLTage:LIMit:LOW	96
[:SOURce]:VOLTage:PROTection[:LEVel]	96
[:SOURce]:VOLTage:PROTection:TRIPped.....	96
[:SOURce]:VOLTage:SLEWrate:RISing	97
[:SOURce]:VOLTage:SLEWrate:FALLing.....	97

[:SOURce]:CURRent[:LEVel][:IMMediate] 
[:AMPLitude] 

Description	Sets or queries the current level in amps. For externally set current levels (from the analog control connector) the set current level is returned.	
Syntax	[:SOURce]:CURRent[:LEVel][:IMMediate][:AMPLitude] {<NR2>(A) MINimum MAXimum}	
Query Syntax	[:SOURce]:CURRent[:LEVel][:IMMediate][:AMPLitude]?	
Parameter/Return parameter	<NR2>	0~105% of the rated current output level.
	MIN	Minimum current level.
	MAX	Maximum current level.

Set →
 → Query

[[:SOURce]:CURRent:PROTection:DELay	
Description	Sets the Delay Time for OCP in seconds for turning the output off. The delay is set to 0.1 by default.
Syntax	[[:SOURce]:CURRent:PROTection:DELay {<NR2> MINimum MAXimum}
Query Syntax	[[:SOURce]:CURRent:PROTection:DELay?
Parameter	<NR2> 0.1~2.0 seconds, where 0=no delay MAX The maximum allowed delay time MIN The minimum allowed delay time
Return parameter	<NR2> Returns the delay time in seconds
Example	SOUR:CURR:PROT:DEL MAX Sets the current protection delay to the maximum.

Set →
 → Query

[[:SOURce]:CURRent:PROTection[:LEVel]	
Description	Sets or queries the OCP (over-current protection) level in amps.
Syntax	[[:SOURce]:CURRent:PROTection[:LEVel] {<NR2>(A) MINimum MAXimum}
Query Syntax	[[:SOURce]:CURRent:PROTection[:LEVel]?
Parameter	<NR2> Current protection level. Minimum: Depend on the unit type: if Irated * 0.1 > 5A, then minimum = 5A, else minimum = Irated * 0.1 Maximum: Irated * 1.1 MIN Minimum current level. MAX Maximum current level.
Return parameter	<NR2> Returns the current protection level.
Example	SOUR:CURR:PROT:LEV? +5.000 Returns the minimum possible current level in amps.


`[[:SOURce]:CURRent:PROTection:TRIPped` → 

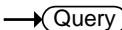
Description Returns the state of the current protection circuits.

Query Syntax `[[:SOURce]:CURRent:PROTection:TRIPped?`

Return parameter `<bool>` Returns protection status.

Example `SOUR:CURR:PROT:TRIP?`
`>0`
 The protection circuit has not been tripped.



`[[:SOURce]:CURRent:SLEWrate:RISing` → 

Description Sets or queries the rising current slew rate. This is only applicable for CC slew rate priority mode.

Syntax `[[:SOURce]:CURRent:SLEWrate:RISing`
`{<NR2>(A)|MINimum|MAXimum}`


Query Syntax `[[:SOURce]:CURRent:SLEWrate:RISing?`

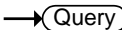
Parameter

<code><NR2></code>	Per step is between 0.001A/msec and rated current divided by 100 msec.
<code>MIN</code>	Minimum rising current slew rate is 0.001A/msec.
<code>MAX</code>	Maximum rising current slew rate is rated current divided by 100msec.

Return parameter `<NR2>` Returns the step current in amps.

Example `SOUR:CURR:SLEW:RIS?`
`0.950`
 Sets the rising current slew rate to 0.950 A/ms.



`[[:SOURce]:CURRent:SLEWrate:FALLing` → 

Description Sets or queries the falling current slew rate. This is only applicable for CC slew rate priority mode.

Syntax `[[:SOURce]:CURRent:SLEWrate:FALLing`
`{<NR2>(A)|MINimum|MAXimum}`

Query Syntax	[:SOURce]:CURRent:SLEWrate:FALLing?	
Parameter	<NR2>	Per step is between 0.001A/msec and rated current divided by 100 msec.
	MIN	Minimum falling current slew rate is 0.001A/msec.
	MAX	Maximum falling current slew rate is rated current divided by 100msec.
Return Parameter	<NR2>	Returns the step current
Example	SOUR:CURR:SLEW:FALL MAX Sets the falling current slew rate to the maximum.	

[:SOURce]:MODE? → (Query)

Description	Returns the status of the output mode (CC, CV, Off) of the power supply. The interface will return "CV" if the supply is in Constant Voltage Mode, "CC" if the supply is in Constant Current Mode or "OFF" if the supply output is off.	
Query Syntax	[:SOURce]:MODE?	
Return parameter	<string>	Returns the output state as a string, "CC", "CV", "OFF"
Example	:SOUR:MODE? >CC The power supply is currently in CC mode.	

[:SOURce]:VOLTage[:LEVel][:IMMediate] [:AMPLitude] (Set) →
→ (Query)

Description	Sets or queries the voltage level in volts.	
Syntax	[:SOURce]:VOLTage[:LEVel][:IMMediate][:AMPLitude] {<NR2>(V) MINimum MAXimum}	
Query Syntax	[:SOURce]:VOLTage[:LEVel][:IMMediate][:AMPLitude]?	
Parameter	<NRf>	0~105% of the rated output voltage in volts.
	MIN	Minimum voltage level
	MAX	Maximum voltage level

Return parameter <NR2> Returns the voltage level in volts

Example SOUR:VOLT:LEV:IMM:AMPL 10
Sets the voltage level to 10 volts.

[[:SOURce]:VOLTage[:LEVel]:TRIGgered
[:AMPLitude] (Set) →
← (Query)

Description Sets or queries the voltage level in volts when a software trigger has been generated.

Syntax [[:SOURce]:VOLTage[:LEVel]:TRIGgered[:AMPLitude] {<NR2>(V)|MINimum|MAXimum}

Query Syntax [[:SOURce]:VOLTage[:LEVel]:TRIGgered[:AMPLitude]?

Parameter <NR2> 0%~105% of the rated voltage output in volts.
MIN Minimum current level.
MAX Maximum current level.

Return parameter <NR2> Returns the voltage level.

Example SOUR:VOLT:LEV:TRIG:AMPL 10
Sets the voltage level to 10 volts when a software trigger is generated.

[[:SOURce]:VOLTage:LIMit:AUTO (Set) →
← (Query)

Description Sets whether to limit the voltage setting so that it does not exceed the OVP setting or become lower than the UVL setting.

If you enable the limit when the OVP setting is lower than the voltage setting, the OVP setting will be set to 105 % of the voltage setting.

If you enable the limit when the UVL setting is higher than the voltage setting, the UVL setting will be set equal to the voltage setting.

Syntax [[:SOURce]:VOLTage:LIMit:AUTO {<bool>|OFF|ON}

Query Syntax [[:SOURce]:VOLTage:LIMit:AUTO?

Parameter OFF | 0 Disable the limit setting
ON | 1 Enable the limit setting

Return parameter <bool> Returns the setting in <bool> format.

Example SOUR:VOLT:LIM:AUTO 0
Disables the limit setting.

Set →

[:SOURce]:VOLTage:LIMit:LOW

→ Query

Description Sets or queries the under voltage (UVL) trip point.

Syntax [:SOURce]:VOLTage:LIMit:LOW
<NR2>(V)|MINimum|MAXimum

Query Syntax [:SOURce]:VOLTage:LIMit:LOW?

Parameter/Return <NR2> 0 ~ the present setting voltage
MIN Minimum allowed voltage level
MAX Maximum allowed voltage level

Example SOUR:VOLT:LIM:LOW MAX
Sets the UV> level to its maximum.

Set →

[:SOURce]:VOLTage:PROTection[:LEVel]

→ Query

Description Sets or queries the overvoltage protection level.

Syntax [:SOURce]:VOLTage:PROTection[:LEVel]
{<NR2>(V)|MINimum|MAXimum}

Query Syntax [:SOURce]:VOLTage:PROTection[:LEVel]?

Parameter/Return <NR2> Minimum: Depends on the unit type:
if Vrated * 0.1 > 5V, then Minimum = 5V,
else Minimum = Vrated * 0.1
Maximum: Vrated * 1.1
MIN Minimum OVP level
MAX Maximum OVP level

Example SOUR:VOLT:PROT:LEV MAX
Sets the OVP level to its maximum.

[:SOURce]:VOLTage:PROTection:TRIPped

→ Query

Description Sets or queries the overvoltage protection level.

Query Syntax	[:SOURce]:VOLTage:PROTection:TRIPped?	
Return parameter	<bool>	
	0	Protection not tripped
	1	Protection tripped

Example SOUR:VOLT:PROT:TRIP?
>0
Indicates that the OVP protection has not been tripped.

(Set) →

[:SOURce]:VOLTage:SLEWrate:RISing → (Query)

Description Sets or queries the rising voltage slew rate. This is only applicable for CV slew rate priority mode.

Syntax	[:SOURce]:VOLTage:SLEWrate:RISing	
Query Syntax	{<NR2>(V) MINimum MAXimum}	
	[:SOURce]:VOLTage:SLEWrate:RISing?	

Parameter	<NR2>	Per step is between 0.001V/msec and rated voltage divided by 100msec.
	MIN	Minimum rising voltage slew rate is 0.001V/msec.
	MAX	Maximum rising voltage slew rate is rated voltage divided by 100msec.

Return parameter <NR2> Returns the slew rate in V/msec.

Example SOUR:VOLT:SLEW:RIS MAX
Sets the rising voltage slew rate to its maximum.

(Set) →

[:SOURce]:VOLTage:SLEWrate:FALLing → (Query)

Description Sets or queries the falling voltage slew rate. This is only applicable for CV slew rate priority mode.

Syntax	[:SOURce]:VOLTage:SLEWrate:FALLing	
Query Syntax	{<NR2>(V) MINimum MAXimum}	
	[:SOURce]:VOLTage:SLEWrate:FALLing?	

Parameter <NR2> Per step is between 0.001V/msec and rated voltage divided by 100msec.

	MIN	Minimum falling voltage slew rate is 0.001V/msec.
	MAX	Maximum falling voltage slew rate is rated voltage divided by 100msec.
Return parameter	<NR2>	Returns the voltage slew rate in V/msec
Example	SOUR:VOLT:SLEW:FALL MIN Sets the falling voltage slew rate to its minimum.	

System Function Command

:SYSTem:BEEPer[:IMMediate]	100
:SYSTem:CONFigure:BEEPer[:STATe].....	100
:SYSTem:CONFigure:BLEeder[:STATe].....	101
:SYSTem:CONFigure:CURRent:CONTRol.....	101
:SYSTem:CONFigure:VOLTAge:CONTRol	102
:SYSTem:CONFigure:OUTPut:PON[:STATe]	102
:SYSTem:CONFigure:OUTPut:EXTernal:MODE.....	103
:SYSTem:COMMunicate:ENABle.....	103
:SYSTem:COMMunicate:GPIB[:SELF]:ADDReSS	104
:SYSTem:COMMunicate:LAN:IPADdress	104
:SYSTem:COMMunicate:LAN:GATEway	105
:SYSTem:COMMunicate:LAN:SMASk.....	105
:SYSTem:COMMunicate:LAN:MAC	105
:SYSTem:COMMunicate:LAN:DHCP	106
:SYSTem:COMMunicate:LAN:DNS	106
:SYSTem:COMMunicate:RLSState.....	106
:SYSTem:COMMunicate:TCPip:CONTRol	107
:SYSTem:COMMunicate:SERial[:RECeive]	
:TRANsmit:BAUD	107
:SYSTem:COMMunicate:SERial[:RECeive]	
:TRANsmit:BITS	108
:SYSTem:COMMunicate:SERial[:RECeive]	
:TRANsmit:PARity.....	108
:SYSTem:COMMunicate:SERial[:RECeive]	
:TRANsmit:SBITs	109
:SYSTem:COMMunicate:MULTidrop:CONTRol.....	109
:SYSTem:COMMunicate:USB:FRONt:STATe.....	109
:SYSTem:COMMunicate:USB:REAR:STATe.....	110
:SYSTem:ERRor	110
:SYSTem:KLOCK	110
:SYSTem:KEYLock:MODE.....	110
:SYSTem:ERRor:ENABle.....	111
:SYSTem:PRESet.....	111
:SYSTem:VERSiOn.....	111
:SYSTem:REBoot.....	111

Set →

→ Query

:SYSTem:BEEPer[:IMMediate]

Description	This command causes an audible tone to be generated by the instrument. The duration time is specified in seconds.	
Syntax	:SYSTem:BEEPer[:IMMediate] {<NR1> MINimum MAXimum}	
Query Syntax	:SYSTem:BEEPer[:IMMediate]? [MINimum MAXimum]	
Parameter	<NR1>	0 ~ 3600 seconds.
	MINimum	Sets the beeper time to the minimum (0 seconds)
	MAXimum	Sets the beeper time to the maximum (3600 seconds)
Return parameter	<NR1>	Returns the remaining beeper duration time in seconds or returns the maximum or minimum beeper time in seconds (for the [MINimum MAXimum] query parameters).

Example 1
:SYST:BEEP 10
after a 2 second wait
:SYST:BEEP?
>8

The first command turns the beeper on for 10 seconds. After 2 seconds the SYST:BEEP? query returns the remaining beeper time (8 seconds).

Example 2
:SYST:BEEP? MAX
>3600

Returns the maximum settable beeper time in seconds.

Set →

→ Query

:SYSTem:CONFigure:BEEPer[:STATe]

Description	Sets or queries the buzzer state on/off.	
Syntax	:SYSTem:CONFigure:BEEPer[:STATe] {<bool> OFF ON}	
Query Syntax	:SYSTem:CONFigure:BEEPer[:STATe]?	

Parameter	OFF 0 ON 1	Turns the buzzer off. Turns the buzzer on.
Return parameter	<bool>	Returns the buzzer status.

Set →
 → Query

Description	Sets or queries the status of the bleeder resistor.	
Syntax	:SYSTem:CONFigure:BLEeder[:STATe]	
Query Syntax	{<NR1> OFF ON AUTO} :SYSTem:CONFigure:BLEeder[:STATe]?	
Parameter	OFF 0 ON 1 AUTO 2	Turns the bleeder resistor off. Turns the bleeder resistor on. Turn the AUTO mode on.
Return parameter	<NR1>	Returns bleeder resistor status.

Set →
 → Query

Description	Sets or queries the CC control mode (local control (panel), external voltage control, external resistance control). This setting is applied only after the unit is reset.	
Syntax	:SYSTem:CONFigure:CURRent:CONTRol { <NR1> NONE VOLTage RRISing RFALLing}	
Query Syntax	:SYSTem:CONFigure:CURRent:CONTRol?	
Parameter	<NR1> 0 NONE 1 VOLTage 2 RRISing 3 RFALLing	Description Local (Panel) control External voltage control External resistance control; 10kΩ = Io max*, 0kΩ = Io min. External resistance control; 10kΩ = Io min*, 0kΩ = Io max.
Return Parameter	<NR1>	Returns the current control configuration.

:SYSTem:CONFIgure:VOLTage:CONTRol (Set) →
→ (Query)

Description Sets or queries the CV control mode (local control (panel), external voltage control, external resistance control). This setting is applied only after the unit is reset.

Syntax :SYSTem:CONFIgure:VOLTage:CONTRol
 { <NR1>|NONE|VOLTage|RRISing|RFALLing}
 :SYSTem:CONFIgure:VOLTage:CONTRol?

Query Syntax

Parameter	<NR1>	Description
	0 NONE	Local (Panel) control
	1 VOLTage	External voltage control
	2 RRISing	External resistance control; 10kΩ or 5kΩ = I _o max*, 0kΩ = I _o min.
	3 RFALLing	External resistance control; 10kΩ or 5kΩ = I _o min*, 0kΩ = I _o max.

Return Parameter <NR1> Returns the current control configuration.

:SYSTem:CONFIgure:OUTPut:PON[:STATe] (Set) →
→ (Query)

Description Sets the output state at power-on. This is the equivalent to the F-92 (Output Status when Power ON) power on configuration settings. These settings only apply after the unit has been reset.

Syntax :SYSTem:CONFIgure:OUTPut:PON[:STATe]
Return Syntax {<NR1>|{SAFE|OFF}}|{FORCe|ON}|AUTO}
 :SYSTem:CONFIgure:OUTPut:PON[:STATe]?

Parameter	SAFE OFF 0	The PFR-100 turns on in the same state the unit was in prior to the previous shut down. The output is set to off (default).
	FORCe ON 1	The PFR-100 turns on in the same state the unit was in prior to the previous shut down. The output is set to on.

	AUTO 2	The PFR-100 turns on in the same state the unit was in prior to the previous shut down, but with the same output on/off setting.
Return parameter	0	The power on output setting is "SAFE" or "OFF".
	1	The power on output setting is "FORCe" or "ON".
	2	The power on output setting is "AUTO".

:SYSTem:CONFigure:OUTPut:EXTernal:MODE
 →
 →

Description Sets the logic used to turn the output on or off when using an external contact. This is the equivalent to the F-94 (External Output Logic Control) power on configuration settings. This setting is only applied after the unit has been reset.

Syntax :SYSTem:CONFigure:OUTPut:EXTernal:MODE
Return Syntax {<NR1>|LOW|HIGH|DISABLE}
 :SYSTem:CONFigure:OUTPut:EXTernal:MODE?

Parameter HIGH | 0 Active high
 LOW | 1 Active low
 DISable | 2 External control is not performed.

Return Parameter <NR1> Returns external mode of the instrument.

:SYSTem:COMMunicate:ENABLE
 →
 →

Description Enables/Disables GPIB, USB or other remote interfaces such as Sockets and the Web Server. This setting is only applied after the unit has been reset. Only one interface can be enabled at the same time.

Syntax :SYSTem:COMMunicate:ENABLE {<bool>|OFF|ON,RS232|RS485|USBCDC|GPIB|SOCKets|WEB}

Query Syntax	:SYSTem:COMMunicate:ENABle? {RS232 RS485 USBCDC GPIB SOCKets WEB}	
Parameter 1	OFF 0 ON 1	Disables the selected interface. Enables the selected interface.
Parameter 2	RS232 RS485 USBCDC GPIB SOCKets WEB	Select RS232 Select RS485 Select USB-CDC Select GPIB Select Sockets Select the web server
Return Parameter	<bool>	Returns the status of the selected mode.
Example	SYST:COMM:ENAB 1,USBCDC Turns the USB-CDC interface on.	
Query Example	SYST:COMM:ENAB? USBCDC 1 Queries the USB-CDC state, returns 1 (USB-CDC is on).	

:SYSTem:COMMunicate:GPIB[:SELF] Set →
:ADDRESS ← Query

Description	Sets or queries the GPIB address. Note: the setting will only be valid after the power has been cycled.	
Syntax	:SYSTem:COMMunicate:GPIB[:SELF]:ADDRESS <NR1>	
Query Syntax	:SYSTem:COMMunicate:GPIB[:SELF]:ADDRESS?	
Parameter/Return	<NR1>	0~30
Example	SYST:COMM:GPIB:SELF:ADDR 15 Sets the GPIB address to 15.	

:SYSTem:COMMunicate:LAN:IPAddress Set →
← Query

Description	Sets or queries LAN IP address. Note: the setting will only be valid after the power has been cycled.	
-------------	---	--

Syntax :SYSTem:COMMunicate:LAN:IPADdress <string>

Query Syntax :SYSTem:COMMunicate:LAN:IPADdress?

Parameter/Return <string> LAN IP address in string format ("address")
Applicable ASCII characters: 20H to 7EH

Example SYST:COMM:LAN:IPAD "172.16.5.111"
Sets the IP address to 172.16.5.111.

:SYSTem:COMMunicate:LAN:GATEway Set →
→ Query

Description Sets or queries the Gateway address. Note: the setting will only be valid after the power has been cycled.

Syntax :SYSTem:COMMunicate:LAN:GATEway <string>

Query Syntax :SYSTem:COMMunicate:LAN:GATEway?

Parameter/Return <string> Gateway address in string format ("address")
Applicable ASCII characters: 20H to 7EH

Example SYST:COMM:LAN:GATE "172.16.0.254"
Sets the LAN gateway to 172.16.0.254.

:SYSTem:COMMunicate:LAN:SMASK Set →
→ Query

Description Sets or queries the LAN subnet mask. Note: the setting will only be valid after the power has been cycled.

Syntax :SYSTem:COMMunicate:LAN:SMASK <string>

Query Syntax :SYSTem:COMMunicate:LAN:SMASK?

Parameter/Return <string> Subnet mask in string format ("mask")
Applicable ASCII characters: 20H to 7EH

Example SYST:COMM:LAN:SMASK "255.255.0.0"
Sets the LAN mask to 255.255.0.0.

:SYSTem:COMMunicate:LAN:MAC → Query

Description Returns the unit MAC address as a string. The MAC address cannot be changed.

Query Syntax :SYSTem:COMMunicate:LAN:MAC?

Return parameter <string> Returns the MAC address in the following format "FF-FF-FF-FF-FF-FF"

Example SYST:COMM:LAN:MAC?
02-80-AD-20-31-B1
Returns the MAC address.

Set →

→ Query

:SYSTem:COMMunicate:LAN:DHCP

Description Turns DHCP on/off. Queries the DHCP status. Note: the setting will only be valid after the power has been cycled.

Syntax :SYSTem:COMMunicate:LAN:DHCP
{<bool>|OFF|ON}

Query Syntax :SYSTem:COMMunicate:LAN:DHCP?

Parameter OFF | 0 DHCP off
ON | 1 DHCP on

Return parameter <bool> Returns the DHCP status.

Set →

→ Query

:SYSTem:COMMunicate:LAN:DNS

Description Sets or queries the DNS address. Note: the setting will only be valid after the power has been cycled.

Syntax :SYSTem:COMMunicate:LAN:DNS <string>

Query Syntax :SYSTem:COMMunicate:LAN:DNS?

Parameter/Return <string> DNS in string format ("mask")
Applicable ASCII characters: 20H to 7EH

Example SYST:COMM:LAN:DNS "172.16.1.252"
Sets the DNS to 172.16.1.252.

Set →

→ Query

:SYSTem:COMMunicate:RLState

Description Enables or disables local/remote state of the instrument.

Syntax :SYSTem:COMMunicate:RLState
{LOCAL|REMOTE|RWLock}

Query Syntax :SYSTem:COMMunicate:RLState?

Parameter/Return parameter	LOCAL	All keys are valid. This instrument is controlled by the front panel controls.
	REMOTE	All keys are invalid, except for the [local] key and the ability to turn the output off.
	RWLock	All keys are invalid. The instrument can only be controlled remotely.

Example :SYST:COMM:RLST LOCAL
Sets the operating mode to local.

:SYSTem:COMMunicate:TCPip:CONTRol → (Query)

Description Queries the socket port number.

Query Syntax :SYSTem:COMMunicate:TCPip:CONTRol?

Return parameter <NR1> 0000 ~ 9999

Example SYST:COMM:TCP:CONT?
>2268
Returns the socket port number.

:SYSTem:COMMunicate:SERial[:RECEive] (Set) →
:TRANsmit:BAUD → (Query)



Description Sets or queries the UART baud rate. Note: the setting will only be valid after the power has been cycled.

Syntax :SYSTem:COMMunicate:SERial[:RECEive]:TRANsmit

Query Syntax :BAUD <NR1>
:SYSTem:COMMunicate:SERial[:RECEive]:TRANsmit
:BAUD?

Parameter/Return <NR1> 2400, 4800, 9600, 19200, 38400, 57600,
115200

Example SYST:COMM:SER:TRAN:BAUD?
>2400
Returns the baud rate settings.

`:SYSTem:COMMunicate:SERial[:RECEive]` 
`:TRANsmit:BITS` 

Description Sets or queries the UART number of data bits.
 Note: the setting will only be valid after the power has been cycled.


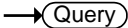
Syntax `:SYSTem:COMMunicate:SERial[:RECEive]:TRANsmit`
`:BITS <NR1>`

Query Syntax `:SYSTem:COMMunicate:SERial[:RECEive]:TRANsmit`
`:BITS?`

Parameter/Return parameter

<code><NR1></code>	
0	7 bits
1	8 bits

Example `SYST:COMM:SER:TRAN:BITS?`
`>1`
 Indicates that 8 data bits are used for the UART connection.

`:SYSTem:COMMunicate:SERial[:RECEive]` 
`:TRANsmit:PARity` 

Description Sets or queries the parity of the UART connection.
 Note: the setting will only be valid after the power has been cycled.

Syntax `:SYSTem:COMMunicate:SERial[:RECEive]:TRANsmit`
`:PARity <NR1>`

Query Syntax `:SYSTem:COMMunicate:SERial[:RECEive]:TRANsmit`
`:PARity?`

Parameter/Return parameter

0	None
1	Odd
2	Even

Example `SYST:COMM:SER:TRAN:PARity?`
`>1`
 Indicates that odd parity is used for the UART connection.

:SYSTem:COMMunicate:USB:REAR:STATe → **Query**

Description	Queries the rear panel USB-B port state.	
Query Syntax	:SYSTem:COMMunicate:USB:REAR:STATe?	
Return parameter	0	<NR1>Absent
	1	<NR1>Connected to the PC

:SYSTem:ERRor → **Query**

Description	Queries the error queue. The last error message is returned. A maximum of 32 errors are stored in the error queue.	
Query Syntax	:SYSTem:ERRor?	
Return parameter	<string>	Returns an error code followed by an error message as a single string.
Example	SYSTem:ERRor? -100, "Command error"	

Set →

:SYSTem:KLOCK → **Query**

Description	Enables or disables the front panel key lock.	
Syntax	:SYSTem:KLOCK {<bool> OFF ON }	
Query Syntax	:SYSTem:KLOCK?	
Parameter	OFF 0	Panel keys unlocked
	ON 1	Panel keys locked
Return parameter	<bool>	Returns the key lock status.

Set →

:SYSTem:KEYLock:MODE → **Query**

Description	Sets or queries the keylock mode. This setting is the equivalent to the F-19 function setting.	
Syntax	:SYSTem:KEYLock {<bool> OFF ON}	
Query Syntax	:SYSTem:KEYLock?	

Parameter/Return	0	OFF	Panel lock: allow output off.
parameter	1	ON	Panel lock: allow output on/off.

:SYSTem:ERRor:ENABle

Set →

Description Clears the Error Queue and enables all error messages to be placed in the System Error Queue.

Syntax :SYSTem:ERRor:ENABle

:SYSTem:PRESet

Set →

Description Loads the default settings.

Syntax :SYSTem:PRESet

:SYSTem:VERSion

→ Query

Description Returns the version of the PFR-100 SCPI version.

Query Syntax :SYSTem:VERSion?

Return <string> Returns the SCPI version as a string.

Query Example SYST:VERS?
>1999.9

:SYSTem:REBoot

Set →

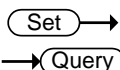
Description Reboots the PFR-100 system.

Syntax :SYSTem:REBoot

Trigger Commands

:TRIGger:OUTPut:SOURce.....	112
:TRIGger:OUTPut[:IMMediate]	112
:TRIGger[:TRANsient]:SOURce.....	112
:TRIGger[:TRANsient][:IMMediate]	113
Trigger Command Examples	113

:TRIGger:OUTPut:SOURce



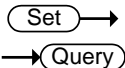
Description	Sets or queries the trigger source of the output trigger.
Syntax	:TRIGger:OUTPut:SOURce {BUS IMMediate EXternal}
Query Syntax	:TRIGger:OUTPut:SOURce?
Parameter/ Return parameter	BUS Output trigger is generated by the bus. IMMediate Output trigger is immediately generated.
Example	:TRIGger:OUTPut:SOURce? Sets the output trigger source to EXT.

:TRIGger:OUTPut[:IMMediate]



Description	Generates an immediate trigger for the output trigger system.
Syntax	:TRIGger:OUTPut[:IMMediate]
Example	:TRIG:OUTP

:TRIGger[:TRANsient]:SOURce



Description	Sets or queries the source of the transient trigger.
Syntax	:TRIGger[:TRANsient]:SOURce {BUS IMMediate EXternal}
Query Syntax	:TRIGger[:TRANsient]:SOURce?
Parameter/ Return parameter	BUS Transient trigger is generated by the bus.

Return parameter	IMMEDIATE	Transient trigger is immediately generated.
------------------	------------------	---

Example	:TRIG:SOUR? EXT	Sets the transient trigger source to EXT.
---------	--------------------	---

:TRIGger[:TRANsient][:IMMEDIATE] Set →

Description	Generates an immediate trigger for the transient trigger system.	
-------------	--	--

Syntax	:TRIGger[:TRANsient][:IMMEDIATE]	
--------	----------------------------------	--

Example	:TRIG	
---------	-------	--

Trigger Command Examples

1. The transient system for the trigger in immediate mode.

Example 1	TRIG:TRAN:SOUR IMM CURR:TRIG MAX VOLT:TRIG 5 INIT:NAME TRAN	<==The current changes to the maximum, and the voltage changes to 5V.
-----------	--	---

2. The transient system for the trigger in BUS mode.

Example 2	TRIG:TRAN:SOUR BUS CURR:TRIG MAX VOLT:TRIG 5 INIT:NAME TRAN TRIG:TRAN (or *TRG)	<==The current changes to the maximum, and the voltage changes to 5V.
-----------	---	---

3. The output system for the trigger in immediate mode.

Example 3	TRIG:OUTP:SOUR IMM OUTP:TRIG 1	
-----------	-----------------------------------	--

INIT:NAME OUTP

<==The output changes to ON.

4. The output system for the trigger in BUS mode.

Example 4

TRIG:OUTP:SOUR BUS

OUTP:TRIG 1

INIT:NAME OUTP

TRIG:OUTP (or *TRG)

<==The output changes to ON.

IEEE 488.2 Common Commands

*CLS	115
*ESE	115
*ESR	116
*IDN	116
*OPC	116
*RCL	117
*RST	117
*SAV	117
*SRE	117
*STB	118
*TRG	118
*TST	118
*WAI	118

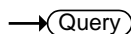
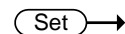
*CLS



Description The *CLS command clears all the event registers, including the status byte, event status and error queue.

Syntax *CLS

*ESE



Description Sets or queries the Standard Event Status Enable register.

Syntax *ESE <NR1>

Query Syntax *ESE?

Parameter <NR1> 0~255

Return parameter <NR1> Returns the bit sum of the Standard Event Status Enable register.

***ESR** → Query

Description Queries the Standard Event Status (Event) register. The Event Status register is cleared after it is read.

Query Syntax *ESR?

Return parameter <NR1> Returns the bit sum of the Standard Event Status (Event) register and clears the register.

***IDN** → Query

Description Queries the manufacturer, model name, serial number, and firmware version of the PFR-100.

Query Syntax *IDN?

Return parameter <string> Returns the instrument identification as a string in the following format:
 GW-INSTEK,PFR-100L,TW123456,01.00.20110101
 Manufacturer: GW-INSTEK
 Model number : PFR-100L
 Serial number : TW123456
 Firmware version : 01.00.20110101

Set →

***OPC** → Query

Description The *OPC command sets the OPC bit (bit0) of the Standard Event Status Register when all current commands have been processed.
 The *OPC? Query returns 1 when all the outstanding commands have completed.

Syntax *OPC

Query Syntax *OPC?

Return parameter 1 Returns 1 when all the outstanding commands have completed.

***RCL**

Set →

Description Recalls the contents stored in memory slot M1, M2 or M3.

Syntax *RCL {<NR1>|MAX|MIN}

Parameter	<NR1> 0, 1, 2 (as memory M1 , M2, M3)
	MIN Recalls the M1 memory contents.
	MAX Recalls the M3 memory contents.

***RST**

Set →

Description Performs a device reset. Configures the unit to a known configuration (default settings). This known configuration is independent of the usage history.

Syntax *RST

***SAV**

Set →

Description Saves the settings into memory slot M1, M2 or M3.

Syntax *SAV {<NR1>|MIN|MAX}

Return parameter	<NR1> 0, 1, 2 (as memory M1 , M2, M3)
	MIN Saves the M1 memory contents.
	MAX Saves the M3 memory contents.

***SRE**

Set →

→ Query

Description Sets or queries the Service Request Enable register. The Service Request Enable register determines which registers of the Status Byte register are able to generate service requests.

Syntax *SRE <NR1>

Query Syntax *SRE?

Parameter <NR1> 0~255

Return parameter <NR1> Returns the bit sum of the Service Request Enable register.

***STB**

→ Query

Description Queries the bit sum of the Status Byte register with MSS (Master summary Status) replacing the RQS bit (bit 6).

Query Syntax *STB?

Return parameter <NR1> Returns the bit sum of the Status Byte register with the MSS bit (bit 6).

***TRG**

Set →

Description The *TRG command is able to generate a “get” (Group Execute Trigger). If the PFR-100 cannot accept a trigger at the time of the command, an error message is generated (-211, “Trigger ignored”).

Syntax *TRG

***TST**

→ Query

Description Executes a self test.

Query Syntax *TST?

Return parameter 0 Returns “0” if there are no errors.

<NR1> Returns an error code <NR1> if there is an error.

***WAI**

Set →

Description Prevents any other commands or queries from being executed until all outstanding commands have completed.

Syntax *WAI

Status Register Overview

To program the PFR-100 power supply effectively, the Status registers need to be understood. This chapter explains in detail how the Status registers are used and how to configure them.

Introduction to the Status Registers.....	119
The Status Registers	121
Questionable Status Register Group.....	122
Operation Status Register Group	126
Standard Event Status Register Group	129
Status Byte Register & Service Request Enable Register	131

Introduction to the Status Registers

Overview

The status registers are used to determine the status of the power supply. The status registers maintain the status of the protection conditions, operation conditions and instrument errors.

The PFR-100 Series have a number of register groups:

Questionable Status Register Group

Standard Event Status Register Group

Operation Status Register Group

Status Byte Register

Service Request Enable Register

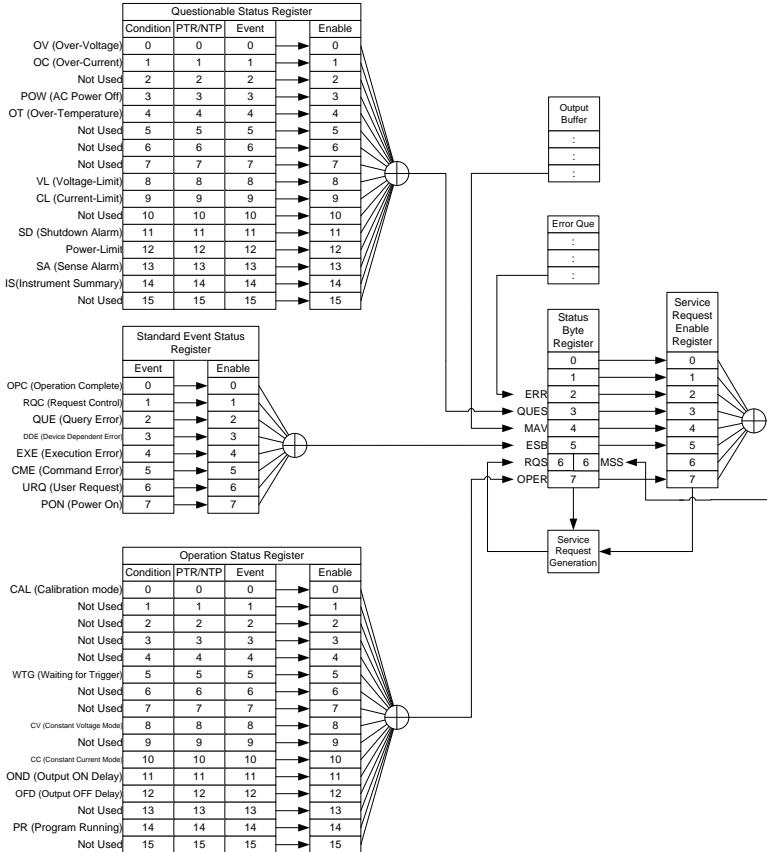
Service Request Generation

Error Queue

Output Buffer

The next page shows the structure of the Status registers.

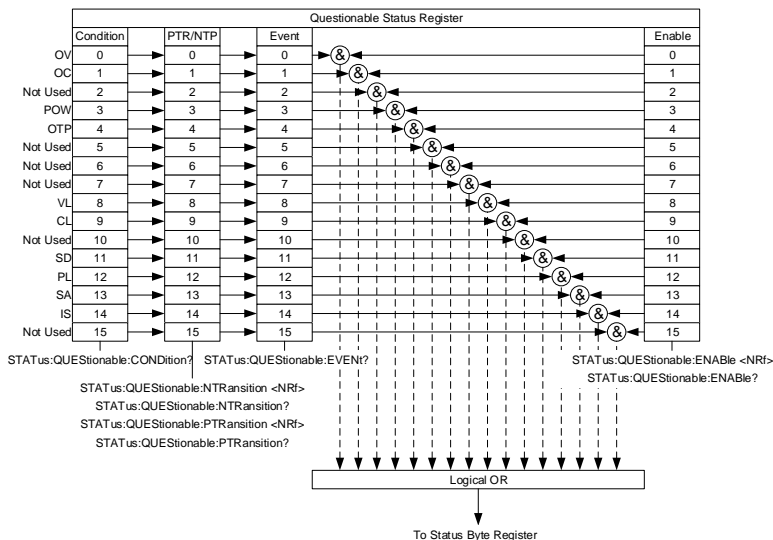
The Status Registers



Questionable Status Register Group

Overview

The Questionable Status Register Group indicates if any protection modes or limits have been tripped.



Bit Summary

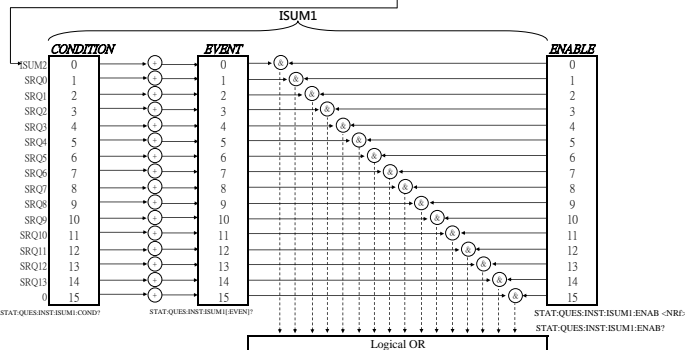
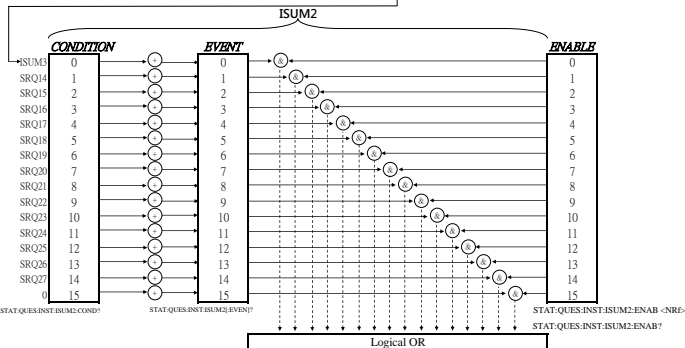
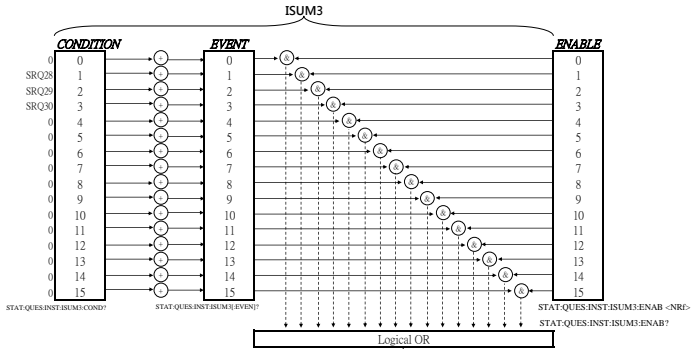
Event	Bit #	Bit Weight
OV (Over-Voltage)	0	1
Over voltage protection has been tripped		
OC (Over-Current)	1	2
Over current protection has been tripped		
POW (AC Power Off)	3	8
AC power switch is off		

	OTP(Over Temperature Protection)	4	16
	Over temperature protection has been tripped		
	VL (Voltage Limit)	8	256
	Voltage limit has been reached		
	CL (Current Limit)	9	512
	Current limit has been reached		
	SD (Shutdown Alarm)	11	2048
	PL (Power-Limit)	12	4096
	SA (Sense Alarm)	13	8192
	IS (Instrument Summary)	14	16384
Condition Register	The Questionable Status Condition Register indicates the status of the power supply. If a bit is set in the Condition register, it indicates that the event is true. Reading the condition register does not change the state of the condition register.		
PTR/NTR Filters	The PTR/NTR (Positive/Negative transition) register determines the type of transition conditions that will set the corresponding bit in the Event Registers. Use the Positive transition filter to view events that change from false to positive, and use the negative transition filter to view events that change from positive to negative.		
	Positive Transition	0→1	
	Negative Transition	1→0	
Event Register	The PTR/NTR Register will dictate the type of transition conditions will set the corresponding bits in the Event Register. If the Event Register is read, it will be cleared to 0.		

Enable Register	The Enable register determines which Events in the Event Register will be used to set the QUES bit in the Status Byte Register.
-----------------	---

Instrument
Summary
Registers

The Instrument Summary Registers indicate if the protection mode or limit of any of the instruments connected in Multi-Drop mode has been tripped.

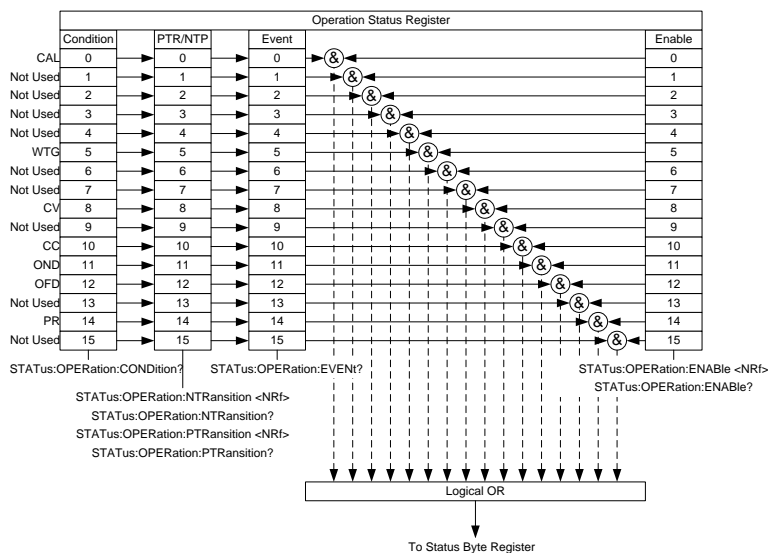


To Instrument Summary in Questionable Condition register (bit 14)

Operation Status Register Group

Overview

The Operation Status Register Group indicates the operating status of the power supply.



Bit Summary

Event	Bit #	Bit Weight
CAL (Calibration mode)	0	1
Indicates if the PFR-100 is in calibration mode.		
WTG (Waiting for trigger)	5	32
Indicates if the PFR-100 is waiting for a trigger.		

	CV (Constant voltage mode)	8	256
	Indicates if the PFR-100 is in CV mode.		
	CC (Constant current mode)	10	1024
	Indicates if the PFR-100 is in CC mode.		
	OND (Output ON Delay)	11	2048
	Indicates if Output ON delay time is active		
	OFD (Output OFF Delay)	12	4096
	Indicates if Output OFF delay time is active		
	PR (Program Running)	14	16384
	Indicates if a Test is running		
Condition Register	The Operation Status Condition Register indicates the operating status of the power supply. If a bit is set in the Condition register, it indicates that the event is true. Reading the condition register does not change the state of the condition register.		
PTR/NTR Filters	The PTR/NTR (Positive/Negative transition) register determines the type of transition conditions that will set the corresponding bit in the Event Registers. Use the Positive transition filter to view events that change from false to positive, and use the negative transition filter to view events that change from positive to negative.		
	Positive Transition	0→1	
	Negative Transition	1→0	

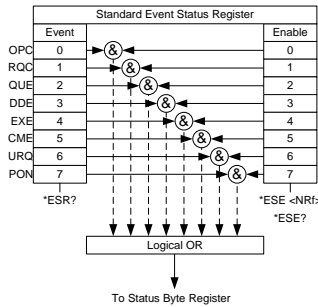
Event Register The PTR/NTR Register will dictate the type of transition conditions will set the corresponding bits in the Event Register. If the Event Register is read, it will be cleared to 0.

Enable Register The Enable register determines which registered Events in the Event Register will be used to set the OPER bit in the Status Byte Register.

Standard Event Status Register Group

Overview

The Standard Event Status Register Group indicates if any errors have occurred. The bits of the Event register are set by the error event queue.



Bit Summary

Event	Bit #	Bit Weight
OPC (Operation complete)	0	1
The OCP bit is set when all selected pending operations are complete. This bit is set in response to the *OPC command.		
RQC (Request control)	1	2
QUE (Query Error)	2	4
The Query Error bit is set in response to an error reading the Output Queue. This can be caused by trying to read the Output Queue when there is no data present.		
DDE (Device Dependent Error)	3	8
Device specific error.		

EXE (Execution Error)	4	16
-----------------------	---	----

The EXE bit indicates an execution error due to one of the following: illegal command parameter, parameter out of range, invalid parameter, the command didn't execute due to an overriding operation condition.

CME (Command Error)	5	32
---------------------	---	----

The CME bit is set when a syntax error has occurred. The CME bit can also be set when a <GET> command is received within a program message.

URQ (User Request)	6	64
--------------------	---	----

PON (Power On)	7	128
----------------	---	-----

Indicates the power is turned on.

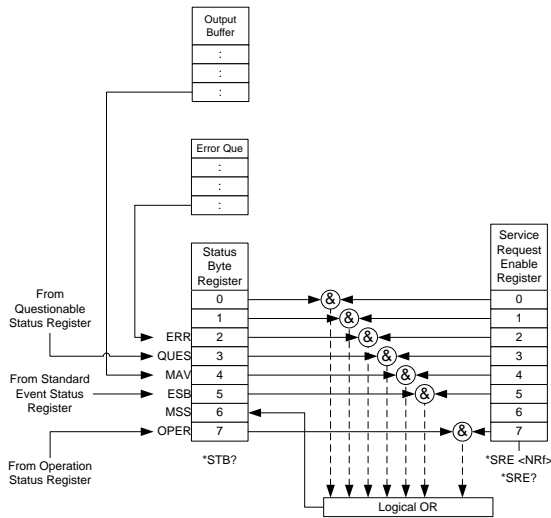
Event Register	Any bits set in the event register indicate that an error has occurred. Reading the Event register will reset the register to 0.
----------------	--

Enable Register	The Enable register determines which Events in the Event Register will be used to set the ESB bit in the Status Byte Register.
-----------------	--

Status Byte Register & Service Request Enable Register

Overview

The Status Byte register consolidates the status events of all the status registers. The Status Byte register can be read with the *STB? query and can be cleared with the *CLS command.



Bit Summary

Event	Bit #	Bit Weight
ERR (Error Event/Queue)	2	4
If data is present in the Error queue, the ERR bit will be set.		
QUES (Questionable Status Register)	3	8
The summary bit for the Questionable Status Register group.		
MAV (Message Available) This is set when there is data in the Output Queue waiting to be read.	4	16

(ESB) Event Summary Bit. The ESB is the summary bit for the Standard Event Status Register group.	5	32
MSS Bit The MSS Bit is the summary of the Status Byte Register and Service Request register (bits 1-5, 7). This will be set to 1.	6	64
OPER (Operation Status Register) Group. OPER bit is the summary bit for the Operation Status Register Group.	7	128
Status Byte Register	Any bits set in the Status byte register acts as a summary register for all the three other status registers and indicates if there is a service request, an error in the Error Queue or data in the Output Queue. Reading the Status Byte register will reset the register to 0.	
Service Request Enable Register	The Service Request Enable Register controls which bits in the Status Byte Register are able to generate service requests.	

Error List

Command Errors
Execution Errors
Device Specific Errors
Query Errors

Command Errors

Overview

An <error/event number> in the range [-199 , -100] indicates that an IEEE 488.2 syntax error has been detected by the instrument's parser. The occurrence of any error in this class shall cause the command error bit (bit 5) in the event status register (IEEE 488.2, section 11.5.1) to be set. One of the following events has occurred:

An IEEE 488.2 syntax error has been detected by the parser. That is, a controller-to-device message was received which is in violation of the IEEE 488.2 standard. Possible violations include a data element which violates the device listening formats or whose type is unacceptable to the device.

An unrecognized header was received. Unrecognized headers include incorrect device-specific headers and incorrect or unimplemented IEEE 488.2 common commands.

Events that generate command errors shall not generate execution errors, device-specific errors, or query errors; see the other error definitions in this chapter.

Error Code	Description
-100 Command Error	This is the generic syntax error for devices that cannot detect more specific errors. This code indicates only that a Command Error as defined in IEEE 488.2,11.5.1.1.4 has occurred.
-102 Syntax error	An unrecognized command or data type was encountered; for example, a string was received when the device does not accept strings.
-103 Invalid separator	The parser was expecting a separator and encountered an illegal character; for example, the semicolon was omitted after a program message unit, MEAS:VOLT:DC?:MEASCURR:DC?
-104 Data type error	The parser recognized a data element different than one allowed; for example, numeric or string data was expected but block data was encountered.
-108 Parameter not allowed	More parameters were received than expected for the header; for example, the KLOCK command only accepts one parameter, so receiving SYSTem:KLOCK 1,0 is not allowed.
-109 Missing parameter	Fewer parameters were received than required for the header; for example, the KLOCK command requires one parameter, so receiving KLOCK is not allowed.
-111 Header separator error	A character which is not a legal header separator was encountered while parsing the header; for example, no white space followed the header, thus *SRE2 is an error.

-112 Program mnemonic too long	The header contains more than twelve characters (see IEEE 488.2, 7.6.1.4.1).
-113 Undefined header	The header is syntactically correct, but it is undefined for this specific device; for example, *XYZ is not defined for any device.
-114 Header suffix out of range	The value of a numeric suffix attached to a program mnemonic, see Syntax and Style section 6.2.5.2, makes the header invalid.
-115 Unexpected number of parameters	The number of parameters received does not correspond to the number of parameters expected. This is typically due to an inconsistency with the number of instruments in the selected group.
-120 Numeric data error	This error, as well as errors -121 through -129, are generated when parsing a data element which appears to be numeric, including the nondecimal numeric types. This particular error message should be used if the device cannot detect a more specific error.
-121 Invalid character in number	An invalid character for the data type being parsed was encountered; for example, an alpha in a decimal numeric or a "9" in octal data.
-128 Numeric data not allowed	A legal numeric data element was received, but the device does not accept one in this position for the header.
-131 Invalid suffix	The suffix does not follow the syntax described in IEEE 488.2, 7.7.3.2, or the suffix is inappropriate for this device.

-141 Invalid character data	Either the character data element contains an invalid character or the particular element received is not valid for the header.
-148 Character data not allowed	A legal character data element was encountered where prohibited by the device.
-151 Invalid string data	A string data element was expected, but was invalid for some reason (see IEEE 488.2, 7.7.5.2); for example, an END message was received before the terminal quote character.
-158 String data not allowed	A string data element was encountered but was not allowed by the device at this point in parsing.
-160 Block data error	This error, as well as errors -161 through -169, are generated when parsing a block data element. This particular error message should be used if the device cannot detect a more specific error.
-161 Invalid block data	A block data element was expected, but was invalid for some reason (see IEEE 488.2, 7.7.6.2); for example, an END message was received before the length was satisfied.
-168 Block data not allowed	A legal block data element was encountered but was not allowed by the device at this point in parsing.
-178 Expression data not allowed	A legal expression data was encountered but was not allowed by the device at this point in parsing.

Execution Errors

Overview An <error/event number> in the range [-299 , -200] indicates that an error has been detected by the instrument's execution control block. The occurrence of any error in this class shall cause the execution error bit (bit 4) in the event status register (IEEE 488.2, section 11.5.1) to be set. One of the following events has occurred:

A <PROGRAM DATA> element following a header was evaluated by the device as outside of its legal input range or is otherwise inconsistent with the device's capabilities.

A valid program message could not be properly executed due to some device condition.

Execution errors shall be reported by the device after rounding and expression evaluation operations have taken place. Rounding a numeric data element, for example, shall not be reported as an execution error. Events that generate execution errors shall not generate Command Errors, device-specific errors, or Query Errors; see the other error definitions in this section.

Error Code	Description
-200 Execution error	This is the generic syntax error for devices that cannot detect more specific errors. This code indicates only that an Execution Error as defined in IEEE 488.2, 11.5.1.1.5 has occurred.

-201 Invalid while in local	Indicates that a command is not executable while the device is in local due to a hard local control (see IEEE 488.2, 5.6.1.5); for example, a device with a rotary switch receives a message which would change the switches state, but the device is in local so the message cannot be executed.
-203 Command protected	Indicates that a legal password-protected program command or query could not be executed because the command was disabled.
-211 Trigger ignored	Indicates that a GET, *TRG, or triggering signal was received and recognized by the device but was ignored because of device timing considerations; for example, the device was not ready to respond. Note: a DT0 device always ignores GET and treats *TRG as a Command Error.
-213 Init ignored	Indicates that a request for a measurement initiation was ignored as another measurement was already in progress.
-220 Parameter error	Indicates that a program data element related error occurred. This error message should be used when the device cannot detect the more specific errors described for errors -221 through -229.
-221 Settings conflict	Indicates that a legal program data element was parsed but could not be executed due to the current device state (see IEEE 488.2, 6.4.5.3 and 11.5.1.1.5.).

-222 Data out of range	Indicates that a legal program data element was parsed but could not be executed because the interpreted value was outside the legal range as defined by the device (see IEEE 488.2, 11.5.1.1.5.).
-224 Illegal parameter value	Used where exact value, from a list of possibles, was expected.

Device Specific Errors

Overview An <error/event number> in the range [-399 , -300] or [1 , 32767] indicates that the instrument has detected an error which is not a command error, a query error, or an execution error; some device operations did not properly complete, possibly due to an abnormal hardware or firmware condition. These codes are also used for self-test response errors. The occurrence of any error in this class should cause the device-specific error bit (bit 3) in the event status register (IEEE 488.2, section 11.5.1) to be set. The meaning of positive error codes is device-dependent and may be enumerated or bit mapped; the <error message>string for positive error codes is not defined by SCPI and available to the device designer.

Note that the string is not optional; if the designer does not wish to implement a string for a particular error, the null string should be sent (for example, 42,""). The occurrence of any error in this class should cause the device-specific error bit (bit 3) in the event status register (IEEE 488.2, section 11.5.1) to be set. Events that generate device-specific errors shall not generate command errors, execution errors,

or query errors; see the other error definitions in this section.

Error Code	Description
-310 System error	Indicates that some error, termed “system error” by the device, has occurred. This code is device-dependent.
-320 Storage fault	Indicates that the firmware detected a fault when using data storage. This error is not an indication of physical damage or failure of any mass storage element.

Query Errors

Overview

An <error/event number> in the range [-499 , -400] indicates that the output queue control of the instrument has detected a problem with the message exchange protocol described in IEEE 488.2, chapter 6. The occurrence of any error in this class shall cause the query error bit (bit 2) in the event status register (IEEE 488.2, section 11.5.1) to be set. These errors correspond to message exchange protocol errors described in IEEE 488.2, section 6.5. One of the following is true:

An attempt is being made to read data from the output queue when no output is either present or pending;

Data in the output queue has been lost.

Events that generate query errors shall not generate command errors, execution errors, or device-specific errors; see the other error definitions in this section.

Error Code	Description
-400 Query error	This is the generic query error for devices that cannot detect more specific errors. This code indicates only that a Query Error as defined in IEEE 488.2, 11.5.1.1.7 and 6.3 has occurred.

A PPENDIX

PFR-100 Default Settings

The following default settings are the factory configuration settings for the power supply.

Initial Settings	Default Setting	
Output	Off	
LOCK	0 (Disabled)	
Voltage	0V	
Current	0A	
OVP	1.1 X Vrate	
OCP	1.1 X Irate	
Normal Function Settings	Setting	Default Setting
Output ON delay time	F-01	0.00s
Output OFF delay time	F-02	0.00s
V-I ode slew sate select	F-03	0 = CV high speed priority
Rising Voltage slew rate	F-04	100.0V/s (PFR-100L)
		500.0V/s (PFR-100M)
Falling Voltage slew rate	F-05	100.0V/s (PFR-100L)
		500.0V/s (PFR-100M)
Rising Current slew rate	F-06	20.00A/s (PFR-100L)
		4.000A/s (PFR-100M)
Falling Current slew rate	F-07	20.00A/s (PFR-100L)
		4.000A/s (PFR-100M)
Bleeder ON/OFF control	F-09	1 = ON
Buzzer ON/OFF control	F-10	1 = ON
Detection Time of OCP	F-12	0.0 sec
Current Setting limit	F-13	0 = OFF (The limit function of current setting is disabled.)
Voltage Setting limit	F-14	0 = OFF (The limit function of voltage setting is disabled.)
Memory Recall display	F-15	0 = OFF

Measurement average setting	F-17	0 = Low
Lock Mode	F-19	0: Lock Panel, Allow Output OFF
USB / GPIB setting	Setting	Default Setting
GPIB address	F-23	8
LAN setting	Setting	Default Setting
DHCP	F-37	1 = ON
Web password enable/disable	F-60	1 = Enable
UART setting	Setting	Default Setting
UART Baudrate	F-71	7 = 115200
UART Data Bits	F-72	1 = 8 bits
UART Parity	F-73	0 = None
UART Stop Bit	F-74	0 = 1 bit
UART TCP	F-75	0 = SCPI
Power On Configuration setting	Setting	Default Setting
CV Control	F-90	0 = Panel control (local)
CC Control	F-91	0 = Panel control (local)
Power ON Output	F-92	0 = Safe Mode (Output OFF at startup)
External Output Logic Control	F-94	0 = High ON

Error Messages & Messages

The following error messages or messages may appear on the PFR-100 screen during operation.

Error Messages	Description
OHP	Over temperature protection
SENSE ALARM1	Sense Alarm1
SENSE ALARM2	Sense Alarm2
AC	AC fail
OVP	Over voltage protection
OCP	Over current protection
OPP	Over Power Protection
SHUT DOWN	Force shutdown
Err 001	USB mass storage is not present
Err 002	No (such)file in USB mass storage
Err 003	Empty memory location
Err 004	File access error
Err 005	File is too large
Err 007	Slave occurs Off-line (Multi-Drop mode)

Normal Messages	Description
MSG 001	External control of output. Output off (F-94=0, High=on)
MSG 002	External control of output. Output off (F-94=1, Low=on)

Communication Interface Messages	Description
USB ON	Rear USB port connected to PC
USB OFF	Rear USB port disconnected from PC
MS ON	Mass storage plugged into front USB port
MS OFF	Mass storage removed from front USB port

LED ASCII Table Character Set

Use the following table to read the LCD display messages.

0	1	2	3	4	5	6	7	8	9	A	B	C	D
0	1	2	3	4	5	6	7	8	9	A	b	C	d
E	F	G	H	I	J	K	L	M	N	O	P	Q	R
E	F	G	H	I	J	K	L	M	N	O	P	Q	R
S	T	U	V	W	X	Y	Z	()	+	-	,	
S	T	U	V	W	X	Y	Z	()	+	-	,	

INDEX

Accessories	10	Rear panel diagram	17
Caution symbol.....	4	Remote control.....	26
Cleaning the instrument.....	6	Command list.....	67
Configuration		Command syntax	63
normal function settings		Error list	133
operation.....	19	Ethernet configuration.....	50
power on configuration operation	21	Ethernet function check.....	51
table	22	GPIB configuration.....	30
Display format	145	GPIB function check.....	31
Disposal instructions.....	6	interface configuration	28
EN61010		local bus configuration	46
measurement category	5	multi-unit configuration.....	46
pollution degree.....	6	multi-unit function check.....	48
Environment		sockets configuration.....	53
safety instruction	6	sockets function check	38, 54
Error messages.....	144	Status registers	119
Ethernet		UART configuration	35
interface.....	50	USB configuration	28
sockets	53	USB function check	29
web server.....	50	Service operation	
Ground		about disassembly	5
symbol.....	4	Socket server examples	
LED conversion	145	C++	60
List of features	9	LabVIEW.....	62
Messages.....	144	Visual basic.....	59
Model differences	9	Socket server function check	38, 54
Optional accessories.....	10	UK power cord.....	7
Package contents	10	Warning symbol	4
		Web server function check	51