

TECHNICAL DATASHEET #TDAX030120

10 Universal Signal Inputs CAN Controller

V, mA, Digital, PWM, Hz/RPM, Counter Inputs CAN (SAE J1939) with Simulink® with Electronic Assistant®

P/N: AX030120

Features:

- 10 user selectable signal inputs:
 - o 0-5 V
 - o 0-10 V
 - o 0-20 mA
 - o 4-20 mA
 - o PWM (low or high frequency)
 - o Frequency/RPM
 - o Counter
 - o Digital
- 12V, 24Vdc (nominal) power input
- 1 CAN port (SAE J1939) (CANopen® in P/N AX030121)
- Rugged packaging and connectors (TE Deutsch)
- · Standard control logic
- CE mark (EMC Directive)
- Developed with Simulink®
- Electronic Assistant® for parameter configuration



Description: The 10 Universal Signal Input Module accepts up to 10 analog or digital type inputs (0-5V, 0-10V, 0-20 mA or 4-20 mA, Digital, PWM, Frequency/RPM or Counter). The modules can be connected to a variety of analog machine sensors or levers, PLC's, switches, PWM signals, etc. It interfaces with the machine's CAN network (SAE J1939). Standard embedded software is provided. Rugged IP67 rated packaging in addition to a wide-ranging power supply input section for 12V or 24Vdc power suits applications in the harsh environment of mobile equipment with on-board battery power. All setpoints are user configurable using the Electronic Assistant®. The device operates with Simulink® for easy graphical programming in a model based simulation and development environment.

Applications: The controller is designed to meet the rugged demands of construction equipment, power generator sets and heavy duty industrial machine control applications.

Ordering Part Numbers:

SAE J1939 Controller: For baud rate, refer to the table below for the appropriate P/N	٧.
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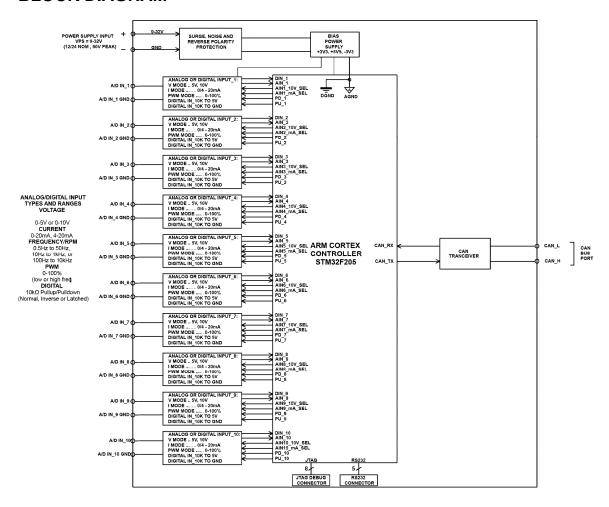
Model P/N	Baud Rate	Standard Reference
AX030120	250 kBit/s	J1939/11, J1939/15.
AX030120-01	500 kBit/s	J1939/14. New standard
AX030120-02	1Mbit/s	Non-standard

Accessories:

PL-DTM06-12SA-12SB Mating Plug Kit (1 DTM06-12S, DTM06-12SB, 2 WM12S, 24 contacts)

Electronic Assistant® Configuration KIT: AX070502

BLOCK DIAGRAM



Technical Specifications:

Specifications are indicative and subject to change. Actual performance will vary depending on the application and operating conditions. Users should satisfy themselves that the product is suitable for use in the intended application. All our products carry a limited warranty against defects in material and workmanship. Please refer to our Warranty, Application Approvals/Limitations and Return Materials Process as described on www.axiomatic.com/service.html.

Power Input Specifications

· · · · · · · · · · · · · · · · · · ·				
Power Supply Input - Nominal	12 or 24Vdc nominal operating voltage 860 Vdc power supply range for voltage transients			
Surge Protection	Provided			
Reverse Polarity Protection	Provided			
Quiescent Current	< 25mA @ Vin = 24V			

Signal Input Specifications

Signal Input Specification					
Inputs	10 user selectable inputs (See Table 1.0.)				
	 Analog 12-bit (0-5V, 0-10V, 0-20 mA, 4-20 mA) 				
	PWM 12-bit (low or high frequency)				
	Frequency/RPM				
	Counter input 16-bit				
	 Digital (active high/active low) [ON when input ≥ 1.5V] 				
	The "Input Sensor Type" setpoint is used to configure input type.				
	Table 1.0. Inputs – Sensor Type Selections				
	Setpoint Input Type				
	0 Disabled 1 Voltage (0-5 V)				
	13 Voltage (0-10 V)				
	2 Current (0-20 mA)				
	21 Current (4-20 mA)	U H-/			
	40 Frequency (0.5 to 5				
	41 Frequency (10 Hz to 4 Frequency (100 Hz		7)		
	3 PWM Low Frequency				
	51 PWM High Frequent	, ,		- 	
	5 16-bit Counter	oy (~100			
	6 Digital (normal)				
	61 Digital (inverse)				
	62 Digital (latched)				
	All innuts with the averation of 40.5):t C			1
	All inputs with the exception of 16-E Analog Input types have a 12-bit re			led every	ims.
	Analog input types have a 12-bit re	Solution.			
	With current inputs, short circuit pro	tection i	s provided.		
Minimum and Maximum Ratings	Table 2.0 Absolute Maximum	and Mir	nimum Ratio	nas	
	Table 2.0. Absolute Maximum and Minimum Ratings				
	Characteristic	Min	Max	Unite	
	Characteristic Power Supply	Min	Max	Units	
	Power Supply	8	60	V dc	
	Power Supply Voltage Input	8	60 43	V dc V dc	
	Power Supply Voltage Input Current Input	8 0 0	60 43 21	V dc V dc mA	
	Power Supply Voltage Input Current Input Current Input – Voltage Level	8 0 0 0	60 43 21 12	V dc V dc mA Vdc	
	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level	8 0 0	60 43 21	V dc V dc mA	
	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage	8 0 0 0	60 43 21 12	V dc V dc mA Vdc	
	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level	8 0 0 0	60 43 21 12 43	V dc V dc mA Vdc Vdc	
	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle	8 0 0 0 0	60 43 21 12 43	V dc V dc mA Vdc Vdc	
	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency	8 0 0 0 0 0 0 50	60 43 21 12 43 100 10 000	V dc V dc mA Vdc Vdc Hz	
Input Accuracy	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk	8 0 0 0 0 0 0 50	60 43 21 12 43 100 10 000 43	V dc V dc mA Vdc Vdc Hz V dc	
Input Accuracy	Power Supply Voltage Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency	8 0 0 0 0 0 0 50 0 50	60 43 21 12 43 100 10 000 43	V dc V dc mA Vdc Vdc Hz V dc	ution
Input Accuracy	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Table 3.0. Input Accuracy Input Type	8 0 0 0 0 0 0 50 0 50	60 43 21 12 43 100 10 000 43 10 000	V dc V dc mA Vdc Vdc Hz V dc Hz Resolu	ution
Input Accuracy	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Table 3.0. Input Accuracy Input Type Voltage	8 0 0 0 0 0 50 0 50	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1%	V dc V dc mA Vdc Vdc Hz V dc Hz I mV Resolu	ution
Input Accuracy	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Table 3.0. Input Accuracy Input Type Voltage Current	8 0 0 0 0 0 50 0 50	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1% +/- 1%	V dc V dc mA Vdc Vdc Hz V dc Hz I [mV] 1 [uA]	
Input Accuracy	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Table 3.0. Input Accuracy Input Type Voltage	8 0 0 0 0 0 50 0 550	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1% +/- 1% +/- 1%	V dc V dc mA Vdc Vdc Hz V dc Hz I mV Resolu	
Input Accuracy	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Table 3.0. Input Accuracy Input Type Voltage Current	8 0 0 0 0 0 0 50 0 50	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1% +/- 1%	V dc V dc mA Vdc Vdc Hz V dc Hz I [mV] 1 [uA]	
Input Accuracy	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Table 3.0. Input Accuracy Input Type Voltage Current PWM	8 0 0 0 0 0 50 0 50	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1% +/- 1% +/- 1% (<5kHz)	V dc V dc mA Vdc Vdc Hz V dc Hz 0.1 [9]	6]
Input Accuracy	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Table 3.0. Input Accuracy Input Type Voltage Current	8 0 0 0 0 0 50 0 50	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1% +/- 1% (<5kHz) +/- 2%	V dc V dc mA Vdc Vdc Hz V dc Hz I [mV] 1 [uA]	6]
, , ,	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Table 3.0. Input Accuracy Input Type Voltage Current PWM	8 0 0 0 0 0 50 0 50	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1% +/- 1% (<5kHz) +/- 2% (>5kHz)	V dc V dc mA Vdc Vdc Hz V dc Hz 0.1 [9]	6]
Input Accuracy Input Impedance	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Table 3.0. Input Accuracy Input Type Voltage Current PWM	8 0 0 0 0 0 50 0 50	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1% +/- 1% (<5kHz) +/- 2% (>5kHz)	V dc V dc mA Vdc Vdc Hz V dc Hz 0.1 [9]	6]
, ,	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Input Type Voltage Current PWM Frequency/RPM 0-5V: 1 MOhm 0-10V: 170 kOhm 0(4)-20mA: 249 Ohm	8 0 0 0 0 0 50 0 50	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1% +/- 1% (<5kHz) +/- 2% (>5kHz) +/- 1%	V dc V dc mA Vdc Vdc Hz V dc Hz 0.1 [9]	6]
Input Impedance	Power Supply Voltage Input Current Input Current Input – Voltage Level Digital Type Input – Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Input Type Voltage Current PWM Frequency/RPM 0-5V: 1 MOhm 0-10V: 170 kOhm 0(4)-20mA: 249 Ohm Frequency/Digital Input: Pull Up/Pu	8 0 0 0 0 0 50 0 50	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1% +/- 1% (<5kHz) +/- 2% (>5kHz) +/- 1%	V dc V dc mA Vdc Vdc Hz V dc Hz 0.1 [9]	6]
, , ,	Power Supply Voltage Input Current Input — Voltage Level Digital Type Input — Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Table 3.0. Input Accuracy Input Type Voltage Current PWM Frequency/RPM 0-5V: 1 MOhm 0-10V: 170 kOhm 0(4)-20mA: 249 Ohm Frequency/Digital Input: Pull Up/Pu Each input is scanned in 100uS.	8 0 0 0 0 0 0 50 0 50 0 50 0 0 0 0 0 0 0	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1% (<5kHz) +/- 1% (<5kHz) +/- 1%	V dc V dc MA Vdc Vdc % Hz V dc Hz 0.01 [9	6] Hz]
Input Impedance Scan Rate	Power Supply Voltage Input Current Input — Voltage Level Digital Type Input — Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Table 3.0. Input Accuracy Input Type Voltage Current PWM Frequency/RPM 0-5V: 1 MOhm 0-10V: 170 kOhm 0(4)-20mA: 249 Ohm Frequency/Digital Input: Pull Up/Pu Each input is scanned in 10ouS. A complete scan of 10 inputs occur	8 0 0 0 0 0 0 50 0 50 0 50 0 s with new swith new swith new switch	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1% (<5kHz) +/- 1% (<5kHz) +/- 1%	V dc V dc MA Vdc Vdc % Hz V dc Hz 0.01 [9	6] Hz]
Input Impedance	Power Supply Voltage Input Current Input — Voltage Level Digital Type Input — Voltage Level PWM Duty Cycle PWM Frequency PWM Voltage pk - pk RPM Frequency Table 3.0. Input Accuracy Input Type Voltage Current PWM Frequency/RPM 0-5V: 1 MOhm 0-10V: 170 kOhm 0(4)-20mA: 249 Ohm Frequency/Digital Input: Pull Up/Pu Each input is scanned in 100uS.	8 0 0 0 0 0 0 50 0 50 0 50 0 s with new swith new swith new switch	60 43 21 12 43 100 10 000 43 10 000 Accuracy +/- 1% (<5kHz) +/- 1% (<5kHz) +/- 1%	V dc V dc MA Vdc Vdc % Hz V dc Hz 0.01 [9	6] Hz]

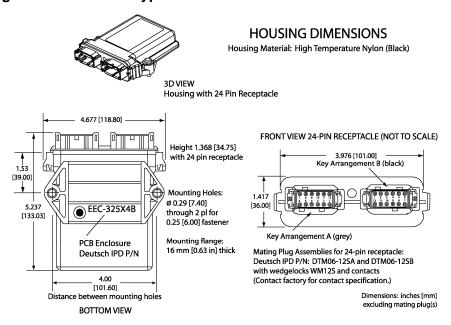
General Specifications

Microprocessor	STM32F205VGT6				
Communications	1 CAN port (2.0B, SAE J1939)				
	500 kpbs and 1 Mbps baud rate models are available. (See ordering part numbers.)				
	A CANopen® model is available (PN AX030121). An on-board RS-232 port is used for factory programming only.				
FMC Compliance	An on-board RS-232 port is used for factory programming only. CE mark				
EMC Compliance Vibration					
	MIL-STD-202G, Method 204D, test condition A – 10 g peak (Sine) MIL-STD-202G, Method 214A, test condition B – 7.68 Grms (Random)				
Shock	MIL-STD-202G, Method 213B, test condition A 50 g half sine pulse, 6 ms, 6 pulses per axis				
User Interface	User configuration and diagnostics are provided with the Axiomatic				
	Electronic Assistant®. The Axiomatic Service Tool is a Windows-based graphical user interface that allows easy configuration of the controller setpoints.				
	Set up of SAE J1939 Controller on a CAN Network: Other CAN Modules and Termination				
	Axiomatic Electronic Assistant* Axiomatic Controller with CAN				
	USB Cable Axiomatic USB-CAN Axiomatic USB-CAN				
	AX070501 — Axiomatic Controller Computer — with CAN				
	Other CAN Modules and Termination				
Network Termination	It is necessary to terminate the network with external termination resistors. The resistors are 120 Ohm, 0.25W minimum, metal film or similar type. They should be placed between CAN_H and CAN_L terminals at both ends of the network.				
Control Logic	Configurable properties of the controller are divided into function blocks, namely input function block, diagnostic function block; lookup table function block, programmable logic function block, math function block, CAN receive message function block and CAN transmit message function block. Input function block includes properties used to select input sensor functionality. Diagnostic function block properties are used to configure fault detection and reaction functionalities. The Math function block gives user an opportunity to process inputs with basic mathematical of logical functions. The CAN transmit message function block configures properties of the messages sent to the CAN bus.				
	 The software was designed to provide flexibility to the user with respect to messages sent from the module (ECU) over the CAN bus, by providing: Configurable ECU Instance in the NAME (to allow multiple ECU's on the same network) Configurable Input Parameters Configurable PGN and Data Parameters Configurable Diagnostic Messaging Parameters, as required Diagnostic Log, maintained in non-volatile memory 				
	The CAN Transmit function block is used to send any output from another function block (i.e. input, math) to the J1939 network. The AX030120 ECU has ten CAN Transmit Messages and each message has 5 signals.				
	The " Transmit PGN " setpoint sets PGN used with the message. The user should be familiar with the SAE J1939 standard, and select values for PGN/SPN combinations as appropriate from section J1939/71. By default, all messages are sent on Proprietary B PGNs as broadcast messages.				
	None of the application layer PGNs are supported as part of the default configurations, but they can be selected as desired for transmit function blocks.				
	Setpoints are accessed using standard Memory Access Protocol (MAP) with				

	proprietary addresses. The Electronic Assistant® (EA) allows for quick and easy				
	configuration of the unit over CAN network.				
	Refer to the User Manual UMAX030120 for details.				
	The AX030120 can be upgraded with new application firmware over the CAN bus				
	using the Electronic Assistant. For application-specific control logic, contact				
SAE J1939 Compliance	Axiomatic. The ECU is compliant with the following SAE J1939 standards.				
CAL 01000 Compilance	 J1939 Recommended Practice for a Serial Control and Communications Vehicle Network, SAE, April 2011 				
		 J1939/21 Data Link Layer, SAE, December 2010 J1939/71 Vehicle Application Layer, SAE, March 2011 			
		939/73 Application Layer-I			
	• J1	939/81 Network Managem	ent, SAE, Ma	y 2003	
	It supports for	ollowing PGNs from the sta	andard.		
	Table 4.0	SAE J1939 PGNs			
		39-21 – Data Link Layer			
		Request	59904	0x00EA00	
		Acknowledgement	59392	0x00E800	
		Acknowledgement	00002	OAUULUUU	
		Transport Protocol –	00445	0.005000	
		Connection	60416	0x00EC00	
		Management			
		Transport Protocol –			
		Data Transfer	60160	0x00EB00	
		Message			
			From	0x00FF00	
		Danie d'atama D	65280	0.0001100	
		Proprietary B	To 65535	0x00FFFF	
				one of the second of the secon	
	From J193	39-73 – Diagnostics	1		
		DM1 – Active Diagnostic Trouble 65226 0x00		0x00FECA	
		Codes	00220	Sider Zerr	
		DMO Dwodowsky	1		
		DM2 – Previously Active Diagnostic	65227	0x00FECB	
		Trouble Codes	00221	0.001 200	
	DM3 – Diagnostic Data Clear/Reset for				
		Previously Active	65228	0x00FECC	
		DTCs			
		DM44 Diamantia	1		
	DM11 – Diagnostic Data Clear/Reset for 65235 0x00FED3		0x00FED3		
	Active DTCs				
	From J193	39-81 – Network Manager	nent		
	Address Claimed/Cannot Claim 60928 0x00EE00				
	Commanded Address 65240 0x00FED8				
	From J1939-71 – Vehicle Application Layer				
		Software Identification	65242	0x00FEDA	

Simulink®	Model AX030120 was developed with Simulink®. Simulink® is a model-based design tool from Mathworks®. Using Simulink®, the OEM machine designer may simulate their control system with the Axiomatic module included. This permits fine tuning of the design parameters and testing of functionality prior to machine prototype installation. The Hardware Interface Library for Simulink® is available from Axiomatic on request.		
Diagnostics	The 10 Universal Input ECU supports diagnostic messaging. DM1 message is a message, containing Active Diagnostic Trouble Codes (DTC) that is sent to the J1939 network in case a fault has been detected. The Universal Inputs setpoint group includes diagnostic related setpoints. There are three additional fault diagnostic setpoint groups namely Over Temperature, Over Voltage and Under Voltage.		
Electrical Connections	Deutsch DTM series 24 pin receptacle (DTM13-12PA-12PB-R008) Mating plug: Deutsch DTM06-12SA and DTM06-12SB with 2 wedgelocks (WM12S) and 24 contacts (0462-201-20141). 20 AWG wire is recommended for use with contacts 0462-201-20141.		
Enclosure and Dimensions	High Temperature Nylon housing - Deutsch IPD PCB Enclosure (EEC-325X4B) 4.62 x 5.24 x 1.43 inches 117.42 x 133.09 x 36.36 mm (W x L x H excluding mating plugs)		
Operating Conditions	-40 to 85°C (-40 to 185°F)		
Weight	0.55 lb. (0.25 kg)		
Protection	IP67, Unit is conformal coated in the housing.		
Mounting	Mounting holes sized for ¼ inch or M6 bolts. The bolt length will be determined by the end-user's mounting plate thickness. The mounting flange of the controller is 0.63 inches (16 mm) thick. If the module is mounted without an enclosure, it should be mounted vertically with connectors facing left and right to reduce likelihood of moisture entry. The CAN wiring is considered intrinsically safe. The power wires are not considered intrinsically safe and so in hazardous locations, they need to be located in conduit or conduit trays at all times. The module must be mounted in an enclosure in hazardous locations for this purpose.		
	All field wiring should be suitable for the operating temperature range.		
	Install the unit with appropriate space available for servicing and for adequate wire harness access (6 inches or 15 cm) and strain relief (12 inches or 30 cm).		

Housing Dimensions and Typical Connections:



Key Arrangement B (black)

Key Arrangement A (grey)

FRONT VIEW 24 PIN RECEPTACLE

Table 5.0	Table 5.0. Electrical Pin Out			
	Grey Connector	Black Connector		
Pin #	Function	Pin #	Function	
1	Analog GND 5	1	Input 6	
2	Analog GND 4	2	Input 7	
3	Analog GND 3	3	Input 8	
4	Analog GND 2	4	Input 9	
5	Analog GND 1	5	Input 10	
6	Batt -	6	CAN_H	
7	Batt +	7	CAN_L	
8	Input 1	8	Analog GND 10	
9	Input 2	9	Analog GND 9	
10	Input 3	10	Analog GND 8	
11	Input 4	11	Analog GND 7	
12	Input 5	12	Analog GND 6	

Notes:

CANopen® is a registered community trade mark of CAN in Automation e.V. Electronic Assistant® is a registered U.S. trade mark of Axiomatic Technologies Corporation. Simulink® is a registered trademark of The Mathworks, Inc.

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