

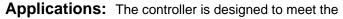
TECHNICAL DATASHEET #TDAX022002 CAN-Dual Valve Controller CAN (SAE J1939)

with Electronic Assistant®

P/N: AX022002

Features:

- Two independent software controlled outputs selectable as: Proportional Current (up to 3A); Hotshot Digital; PWM Duty Cycle; Proportional Voltage; or On/Off Digital types (4A)
- 9...60VDC (12VDC or 24VDC nominal)
- 1 CAN (SAE J1939) port
- Aluminum enclosure with integral 12-pin connector
- IP67
- Electronic Assistant® for user programmability



rugged demands of mobile equipment and heavy duty industrial machine control applications. These applications include, but are not limited to the following.

- PID Closed Loop Valve Control
- Hydraulic Valve Control

Ordering Part Numbers:

Controller: AX022002

Accessories: AX070105 Mating Plug Kit (DT06-12SA, W12S, 12 0462-201-16141, 3 plugs)

AX070502 Electronic Assistant® Configuration KIT includes the following.

USB-CAN Converter P/N: AX070501

1 ft. (0.3 m) USB Cable P/N: CBL-USB-AB-MM-1.5

12 in. (30 cm) CAN Cable with female DB-9 P/N: CAB-AX070501

AX070502IN CD P/N: CD-AX070502, includes: **Electronic Assistant®** software; EA & USB-CAN User Manual UMAX07050X; USB-CAN drivers & documentation; CAN Assistant (Scope and Visual) software & documentation; and the SDK Software Development Kit.

NOTE: To order this kit, you need only to specify P/N: AX070502.

Description: The CAN-2 Valve Controller (CAN-2O) is a highly programmable controller, allowing the user to configure it for their application. It must be integrated into a CAN J1939 network of controllers. Its sophisticated control algorithms allow for open or closed loop drive of the proportional outputs. All logical function blocks on the unit are inherently independent from one another, but can be programmed to interact in a large number of ways. While Figure 1A shows the hardware features, Figure 1B shows the logical function blocks (software) available on the CAN-2O. All setpoints are user configurable using the Electronic Assistant®.

The CAN-2O has a number of built-in protection features that can shut off the outputs in adverse conditions. These features include hardware shutoffs to protect the circuits from being damaged as well as software shutdown features that can be enabled in safety critical systems.

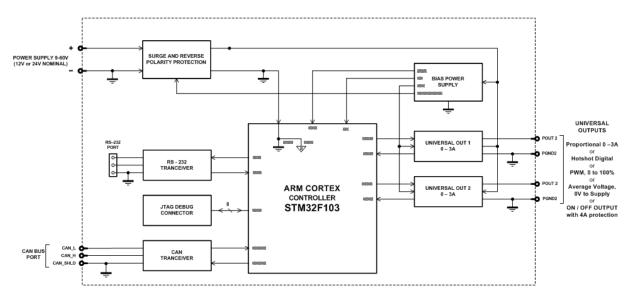


Figure 1A – Hardware Functional Block Diagram

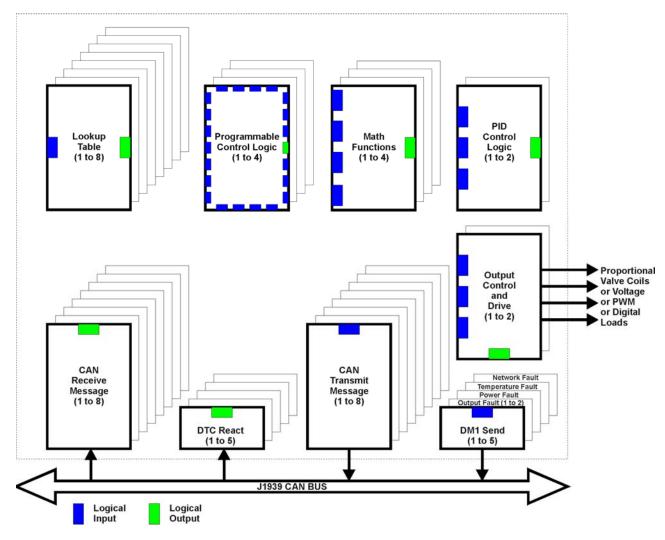


Figure 1B -Logical Functional Block Diagram

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Technical Specifications: Inputs

Power Supply Input	12VDC or 24VDC nominal (960 VDC power supply range)
Protection	Reverse polarity protection is provided. Surge protection up to 75V is provided. Under-voltage protection (software, hardware shutdown at 7.5V) is provided. Over-voltage shutdown of the output load is provided.
CAN	SAE J1939 Command

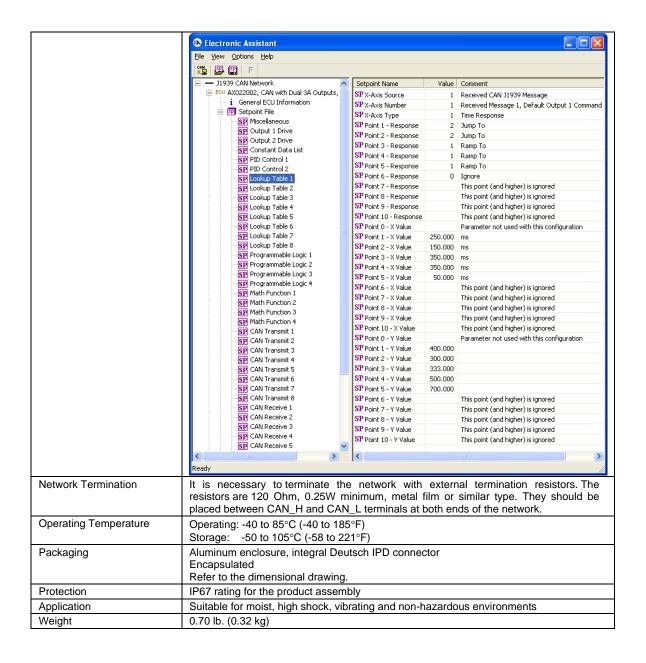
Outputs

CAN	SAE J1939 Messages
Output	Two independent software controlled outputs selectable as: Proportional Current; Hotshot Digital; PWM Duty Cycle; Proportional Voltage; or On/Off Digital types
	Half-bridge outputs, current sensing, grounded load. High side sourcing up to 3A
	Current Outputs: 1mA resolution, accuracy +/- 2% error Software controlled PID current Fully configurable dither from 50 to 400Hz.
	High frequency drive at 25kHz Note: Both outputs use the same dither and drive frequencies
	Voltage Outputs: 0.1V resolution, accuracy +/- 3% error Average output based on unit power supply High frequency drive at 25kHz
	PWM Outputs: 0.1% resolution, accuracy +/- 1% error Output Frequency: 1Hz to 25kHz
	Configurable frequency ONLY if no current output types are used, otherwise default 25kHz is used
	Digital On/Off: Load at supply voltage must not draw more than 3A.
Protection for Output + Terminal	Fully protected against short circuit to ground or +Vcc Grounded short circuit protection will engage at 4.5A +/- 0.5A Unit will fail safe in the case of a short-circuit condition, and is self-recovering when the short is removed.

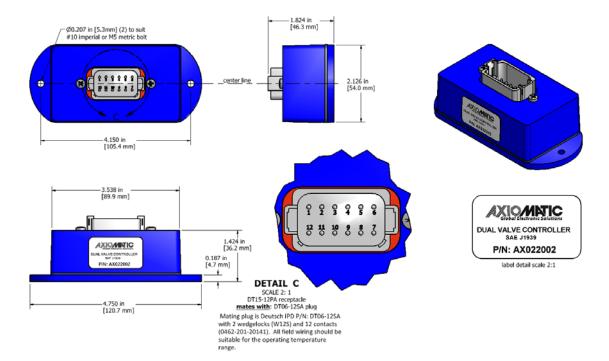
General Specifications

Microprocessor	STM32F103
	32-bit, 128 KByte flash program memory
Control Logic	User programmable functionality using Electronic Assistant® Refer to UMAX07050X for details. (Application-specific control logic or factory programmed setpoints are available on request.)
Diagnostics	Each input and output channel can be configured to send diagnostic messages to the J1939 CAN network if the I/O goes out of range. Diagnostic data is stored in a non-volatile log. Refer to Section 1.7 for details
Additional Fault Feedback	There are several types of faults that the controller will detect and provide a response: unit power supply under-voltage and over-voltage, microprocessor over temperature and lost communication. They can be sent to the J1939 CAN bus.
Communications	1 CAN port (SAE J1939), CANopen is available on request.
Reflashing over CAN	Yes, per J1939 standard using Electronic Assistant® 29-bit IDs, 250 kbps baud rate
User Interface	Electronic Assistant® for <i>Windows</i> operating systems, P/N: AX070502 It comes with a royalty-free license for use on multiple computers.

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Electrical Connections

12 pin Deutsch IPD connector P/N: DT15-12PA

A mating plug kit is available as Axiomatic P/N: **AX070105**. It is comprised of Deutsch IPD P/N's DT06-12SA, W12S, 12 0462-201-16141, and 3 plugs.

CAN and I/O Connector		
Pin#	Function	
1	Output 1 + (Sourcing to 3A)	
2	Output 1 GND	
3	BATT +	
4	CAN Shield	
5	CAN Low	
6	CAN High	
7	Not Used (plug)	
8	Not Used (plug)	
9	Frame GND	
10	BATT -	
11	Output 2 GND	
12	Output 2 + (Sourcing to 3A)	

Installation

The controller can be mounted directly on the valve block or remotely.

Mounting holes are sized for #10 or M4.5 bolts. The bolt length will be determined by the end-user's mounting plate thickness. The mounting flange of the controller is 0.19 inches (4.75 mm) thick.

If the module is mounted without an enclosure, it should be mounted to reduce the likelihood of moisture entry. Install the unit with appropriate space available for servicing and for adequate wire harness access (6 inches or 15 cm) and strain relief (12 inches or 30 cm).

The CAN wiring is considered intrinsically safe. The power wires are not considered intrinsically safe and so in hazardous locations, they need to be located in conduit or conduit trays at all times. The module must be mounted in an enclosure in hazardous locations for this purpose.

All field wiring should be suitable for the operating temperature range of the module.

All chassis grounding should go to a single ground point designated for the machine and all related equipment.

CANopen® is a registered community trade mark of CAN in Automation e.V.

Electronic Assistant® is a registered U.S. trade mark of Axiomatic Technologies Corporation.

Specifications are indicative and subject to change. Actual performance will vary depending on the application and operating conditions. Users should satisfy themselves that the product is suitable for use in the intended application. All our products carry a limited warranty against defects in material and workmanship. Please refer to our Warranty, Application Approvals/Limitations and Return Materials Process as described on www.axiomatic.com/service.html.

Form: TDAX022002-06/04/12

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