Wiper Direct Actuator WDA

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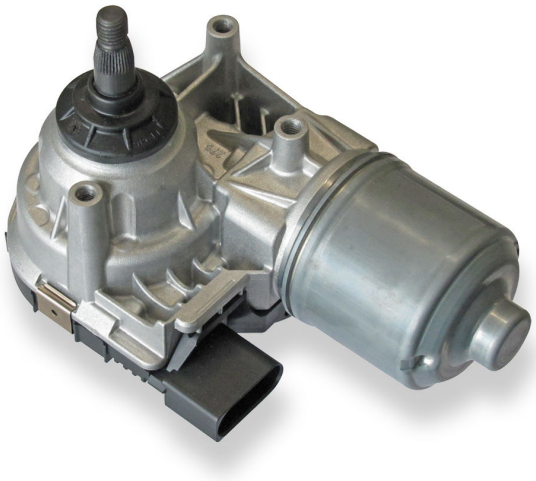


- Analog and LIN versions available
- Optimized hardware for motorsport applications
- Customer specific calibration of wiping angles and speed

The WDA is a wiper motor designed to execute reversing movements instead of rotating 360° like a conventional wiper.
Its function and many operating modes are managed by integrated control electronics. The user is able to control the desired operating mode simply by switching its analog inputs to ground (Analog version) or via LIN (LIN version). The gear, the motor and the electronics are all installed in the same housing.
The main benefit of this wiper motor is its direct rotation movement which replaces external gears and the possibility of programming the operating speed and end positions of all its function modes, upon request.

Application

Operating temperature range	-40 to 85°C

Technical Specifications

WDA Analog Operating modes	• Stop • Interval • Speed 1 • Speed 2
WDA LIN Operating modes	• Stop • Interval • Speed 1 • Speed 2 • Single stroke

Mechanical Data

Max. Vibration	30 % of Vibration Profile 1 or 100 % of Vibration Profile 1 in combination with silentblocks (see Accessories)
Size	104.7 x 174.7 x 117.1 mm
Max. wipe cycles/min	Depending on wipe angle
Max. wipe angle	160°
Max. torque	35 Nm
Weight	1,270 g

Electrical Data

Power supply	9 to 16 V
Supply current at 40 cycles/min.	Typ. 3.4 A
Supply current at 60 cycles/min.	Typ. 6.3 A

LIN Protocol

LIN Version	2.0
LIN Speed	19.2 kBaud/s
Message ID	0x31
Interframe-Space	20 to 40 ms

BYTE 0 Value	0	0	Kl. X	Kl. 15	Counter
Bit	7	6	5	4	3 2 1 0

BYTE 1 Value	SPD2	SPD1	INT	SST	INT Mode
Bit	7	6	5	4	3 2 1 0

BYTE 2 Value	0	0	0	0	0 0 0 0
Bit	7	6	5	4	3 2 1 0

BYTE 3 Value	0	0	0	0	0 0 0 0
Bit	7	6	5	4	3 2 1 0

BYTE 4 Value	0	0	0	0	0 0 0 0
Bit	7	6	5	4	3 2 1 0

BYTE 5 Value	0	0	0	0	0 0 0 0
Bit	7	6	5	4	3 2 1 0

Byte	Bit	Signal	Explanation	Values [dez]
0	0 ... 3	Counter	The counter has to be increased with each LIN-message	0 ... 15
0	4	Kl. 15	Clamp 15 Bit has to be enabled for operation	ON=1 OFF=0
0	5	Kl. X	Clamp X Bit has to be enabled for operation	ON=1 OFF=0
1	0 ... 3	INT Mode	Interval Mode (enabled if operation mode interval is set)	Interval speed: 1=1 2=5 3=9 4=13
1	4	SST	Single stroke operation mode (enabled once if Bit is set temporary)	ON=1 OFF=0
1	5	INT	Operation mode interval	ON=1 OFF=0
1	6	SPD1	Operation mode speed 1	ON=1 OFF=0
1	7	SPD2	Operation mode speed 2	ON=1 OFF=0
		STOP	Operation mode stop is enabled if SST, INT, SPD1 and SPD2 are OFF (default)	

Connectors and Wires

Connector	CEP2M-AMP-4
Mating connector	F 02U B00 542-01
Various motorsport and automotive connectors available on request	

Pinout Analog

Pin 1	AN2
Pin 2	AN1
Pin 3	Gnd
Pin 4	U_S

Pinout LIN

Pin 1	LIN
Pin 2	Special functions, e.g. Master/ Slave
Pin 3	Gnd
Pin 4	U_S

Installation Notes

The WDA Analog can be operated by switching the analog inputs between ground and voltage supply.

The WDA LIN can be operated by all ECUs with LIN 2.X Master function. Further information about the LIN-Frame available upon request.

Make sure that the wiper is in its workspace when restarting after a power failure (upper and lower limit).

Please contact us to define the desired angle of all the operating modes.

The acceleration values can be exceeded by using silentblocks (F02U 003 027-01).

Please ensure that the environmental conditions do not exceed the specifications.

Please find further application hints in the offer drawing at our homepage.

Please deliver the calibration sheet with your order placement.

Delivery Status

The motor will be delivered with three mounting screws. The screws are pre-assembled with a few thread turns.

- Self-tapping screw referred to DIN 7500
- PE M6x20
- Maximum tightening torque: 8 Nm

Ordering Information

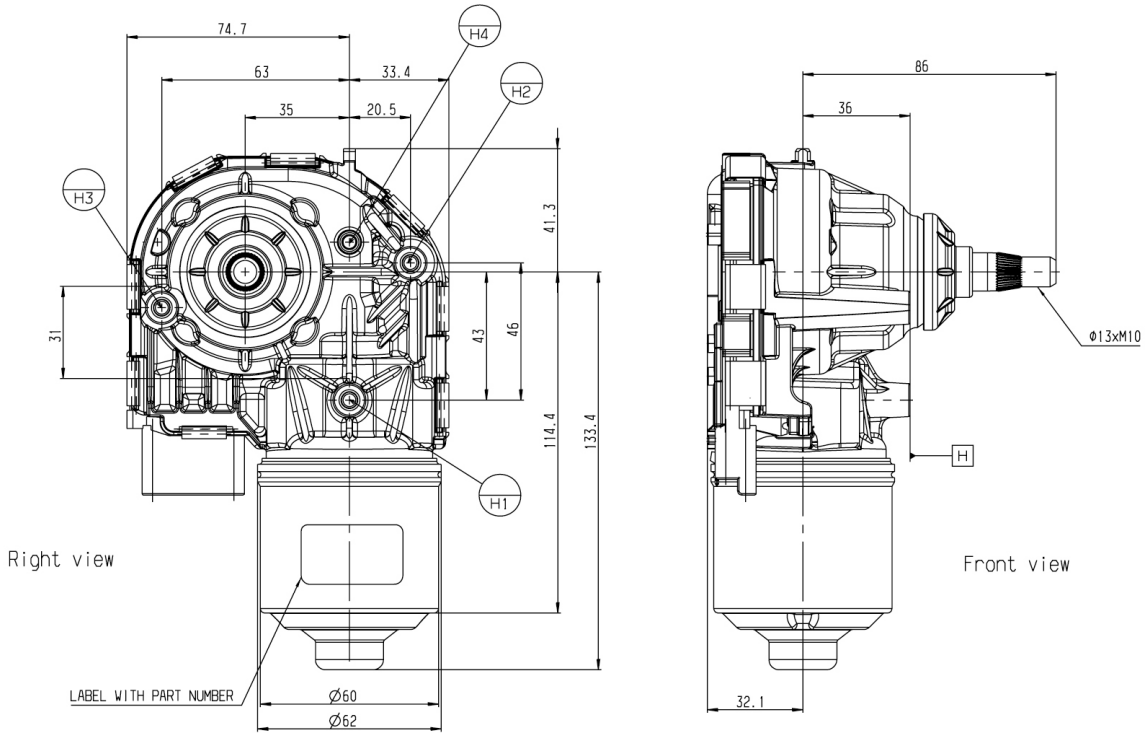
WDA Analog
Order number **F 02U V00 938-03**

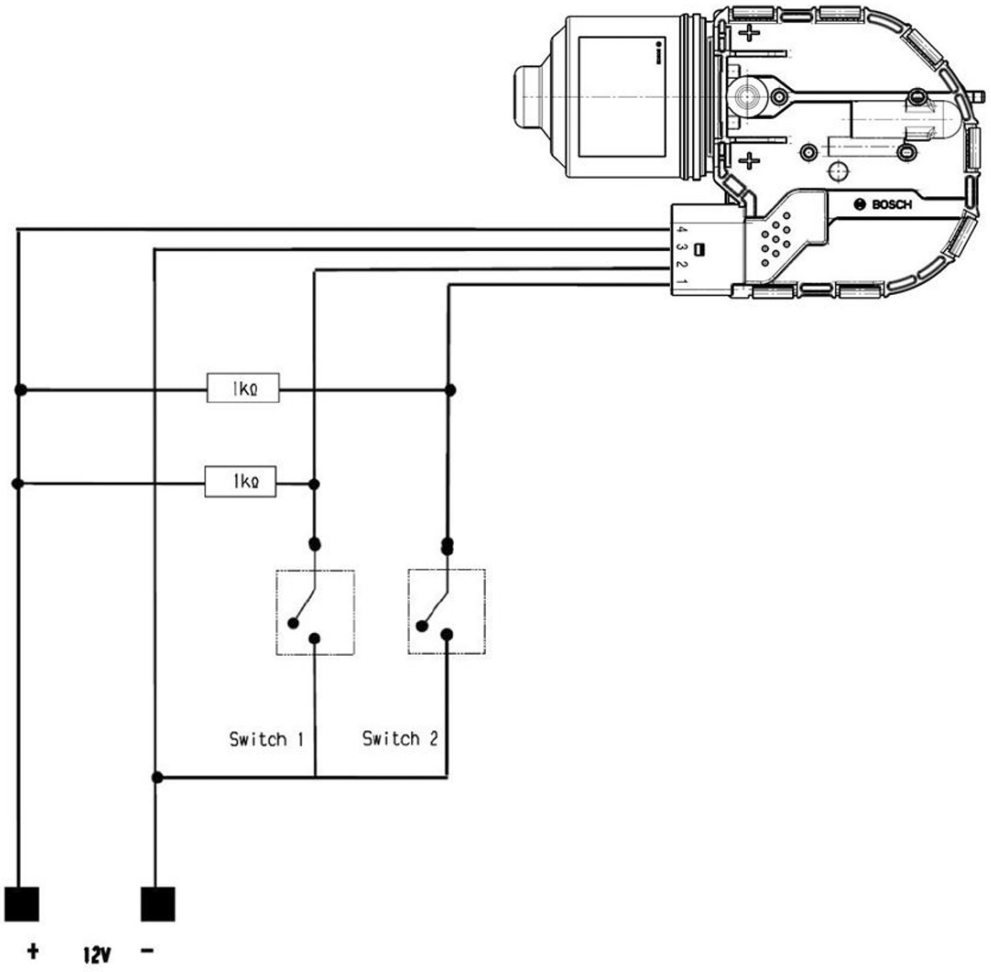
WDA LIN
Order number **F 02U V00 838-04**

Accessories

Silentblock
Order number **F 02U 003 027-01**

Dimensions





Operating modes referring analog inputs configuration

Operating Mode	AN1 (Pin 2)	AN2 (Pin 1)
Stop	Power Supply	Power Supply
Interval	Power Supply	GND
Speed 1	GND	GND
Speed 2	GND	Power Supply

Operating modes referring switch configuration

Operating Mode	Switch 1	Switch 2
Stop	opened	opened
Interval	opened	closed
Speed 1	closed	closed
Speed 2	closed	opened

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