

**EQUATIONS - BASICS**

<b>Equation Means</b>	mathematical statement of equality
<b>Identity Equation</b>	If equality is true for all the values of variable, ex. $2x + 3 = x + x + 3$
<b>Conditional Equation</b>	If the equality is true for certain value of the variable ex. $2x + 1 = 3$
<b>Solution or Root</b>	It is the value of variable that satisfies the equation
<b>Degree</b>	Highest power of variable in equation

**SIMPLE EQUATION**

Type	Linear equation with one unknown	Linear equation with two unknowns	Quadratic Equation	Cubic Equation
<b>Form</b>	$ax + b = 0$ , where a and b are constants	$ax + by + c = 0$ a,b,c are constants	$ax^2 + bx + c = 0$ a,b,c are constants with $a \neq 0$	$ax^3 + bx^2 + cx + d = 0$
<b>Degree</b>	1 (One)	1	2	3
<b>Roots</b>	1 (One)	1 each for both	2 ( $\alpha, \beta$ )	3
<b>Remarks</b>	NA	Need minimum two equations to get roots	Trial Error/ Formula based	Trial and Error
<b>Methods for solution</b>	NA	1. Elimination 2. Cross Multiplication	$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$	NA

**LINEAR EQUATIONS WITH TWO UNKNOWNNS**

<b>Elimination</b>	Eliminate one variable by algebraic operations on given equations, and then calculate the value of variable that remains. Using this value, find out the value of other root.
<b>Cross Multiplication</b>	$a_1x + b_1y + c_1 = 0, a_2x + b_2y + c_2 = 0$ Solution is given by: $\frac{x}{b_1c_2 - b_2c_1} = \frac{y}{c_1a_2 - c_2a_1} = \frac{1}{a_1b_2 - a_2b_1}$

**QUADRATIC EQUATION**

<b>Formula</b>	$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$												
<b>Sum of Roots</b>	$\alpha + \beta = -\frac{b}{a} = \frac{\text{coefficient of } x}{\text{coefficient of } x^2}$												
<b>Product of Roots</b>	$\alpha \times \beta = \frac{c}{a} = \frac{\text{constant term}}{\text{coefficient of } x^2}$												
<b>How to construct a quadratic equation</b>	$x^2 - (\text{sum of roots: } \alpha + \beta)x + \text{Product of Roots: } \alpha \times \beta = 0$												
<b>Nature of Roots</b>	<table border="1"> <thead> <tr> <th>Condition</th> <th>Nature of Roots</th> </tr> </thead> <tbody> <tr> <td><math>b^2 - ac = 0</math></td> <td>Real and Equal (<math>\alpha = \beta</math>)</td> </tr> <tr> <td><math>b^2 - ac &gt; 0</math></td> <td>Real and Unequal</td> </tr> <tr> <td><math>b^2 - ac &lt; 0</math></td> <td>Imaginary</td> </tr> <tr> <td><math>b^2 - ac</math> is a perfect square</td> <td>Real, Unequal and Rational</td> </tr> <tr> <td><math>b^2 - ac &gt; 0</math> but not perfect square</td> <td>Real, Unequal and Irrational</td> </tr> </tbody> </table>	Condition	Nature of Roots	$b^2 - ac = 0$	Real and Equal ( $\alpha = \beta$ )	$b^2 - ac > 0$	Real and Unequal	$b^2 - ac < 0$	Imaginary	$b^2 - ac$ is a perfect square	Real, Unequal and Rational	$b^2 - ac > 0$ but not perfect square	Real, Unequal and Irrational
Condition	Nature of Roots												
$b^2 - ac = 0$	Real and Equal ( $\alpha = \beta$ )												
$b^2 - ac > 0$	Real and Unequal												
$b^2 - ac < 0$	Imaginary												
$b^2 - ac$ is a perfect square	Real, Unequal and Rational												
$b^2 - ac > 0$ but not perfect square	Real, Unequal and Irrational												
<b>Irrational Roots</b>	If one root is $(m + \sqrt{n})$ , then other root will be $(m - \sqrt{n})$												

**MATRICES**

<b>Matrix</b>	A rectangular array of numbers (real/complex) with m rows and n columns
<b>Order of Matrix</b>	Order is $m \times n$ where m= no. of rows and n = no. of columns
<b>Row Matrix</b>	Matrix having only one row $[1 \ 4 \ 2]$
<b>Column Matrix</b>	Matrix having only one column $\begin{bmatrix} 1 \\ 4 \\ 2 \end{bmatrix}$
<b>Zero/ Null Matrix</b>	If all the elements of matrix (any order) are zero $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$
<b>Square Matrix</b>	If in a matrix, no. of columns = no. of rows $\begin{bmatrix} 1 & 3 \\ 9 & 2 \end{bmatrix}$
<b>Rectangular Matrix</b>	If in a matrix, no. of columns $\neq$ no. of rows $\begin{bmatrix} 1 & 3 & 2 \\ 9 & 2 & 5 \end{bmatrix}$
<b>Leading Diagonal</b>	Diagonal elements starting from top left to bottom right
<b>Diagonal Matrix</b>	A square matrix where all the elements except leading diagonal elements are zero. $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$
<b>Scalar Matrix</b>	A diagonal square matrix where all the leading elements are equal $\begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$
<b>Unit Matrix</b>	A scalar matrix whose leading diagonal elements are equal to 1 $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
<b>Upper Triangle Matrix</b>	A matrix whose all the elements below the leading diagonal are zero $\begin{bmatrix} 3 & 4 & 5 \\ 0 & 1 & 9 \\ 0 & 0 & 5 \end{bmatrix}$
<b>Lower Triangle Matrix</b>	A matrix whose all the elements above the leading diagonal are zero $\begin{bmatrix} 3 & 0 & 0 \\ 5 & 1 & 0 \\ 2 & 8 & 5 \end{bmatrix}$
<b>Sub Matrix</b>	The matrix obtained by deleting one or more rows or columns or both of a matrix is called its sub matrix.
<b>Equal Matrices</b>	Two matrices are equal matrices if order of both is same and corresponding elements are same
<b>Addition/ Subtraction</b>	All the corresponding elements will be added/ subtracted to make a new matrix. (only possible when both matrix are of same order)
<b>Properties of Addition/ Subtraction</b>	<b>a.</b> $A+B = B+A$ [Commutative], <b>b.</b> $(A+B)+C = A+(B+C)$ [Associative], <b>c.</b> $k(A+B) = kA + kB$ , k is constant
<b>Multiplication</b>	Multiplication of two matrices is possible only when no. of columns of first matrix = no. of rows of second matrix. [To understand how to do multiplication – refer page 2.40 Example 3]
<b>Properties of Multiplication</b>	<b>a.</b> In general, $A \times B \neq B \times A$ , <b>b.</b> $(A \times B) \times C = A \times (B \times C)$ if defined, <b>c.</b> $A(B+C) = AB + AC$ also, $(A+B)C = AC+BC$ , <b>d.</b> if $AB = AC$ then $B \neq C$ in general, <b>e.</b> $A \times O = O$ [O means null matrix], <b>f.</b> $A \times I = IA = A$ [I means Unit Matrix],

<b>Transpose of a Matrix</b>	A matrix obtained by changing rows and columns of a matrix <b>A</b> is called as Transpose Matrix of <b>A</b> . It is denoted by - <b>A<sup>T</sup></b> or <b>A'</b>				
<b>Properties of Transpose</b>	<table border="1" style="width: 100%;"> <tr> <td>a. <math>A = (A')'</math></td> <td>b. <math>(A+B)' = A' + B'</math></td> <td>c. <math>(KA)' = K.A'</math></td> <td>d. <math>(AB)' = B' \times A'</math></td> </tr> </table>	a. $A = (A')'$	b. $(A+B)' = A' + B'$	c. $(KA)' = K.A'$	d. $(AB)' = B' \times A'$
a. $A = (A')'$	b. $(A+B)' = A' + B'$	c. $(KA)' = K.A'$	d. $(AB)' = B' \times A'$		
<b>Symmetric Matrix</b>	If after transposing also there is no change in matrix. $A' = A$				
<b>Skew Symmetric</b>	If after transposing a matrix, it becomes its negative. $A' = -A$				

**DETERMINANTS**

<b>Determinants</b>	It is a valuation of a matrix using some rules. It only applies for square matrix						
<b>Denote</b>	It is denoted by <b>det A</b> or <b>  A  </b> or <b>Δ</b>						
<b>2 × 2 Matrix</b>	$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = (ad - bc)$						
<b>3 × 3 Matrix</b>	$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = a_1(b_2c_3 - b_3c_2) - a_2(b_1c_3 - b_3c_1) + a_3(b_1c_2 - b_2c_1)$						
<b>Minor</b>	$M_{ij}$ = Minor of the element located in $i^{\text{th}}$ row and $j^{\text{th}}$ column. It is equal to determinant of sub matrix obtained after $i^{\text{th}}$ row and $j^{\text{th}}$ column						
<b>Cofactor</b>	$C_{ij} = (-1)^{i+j} M_{ij}$						
<b>3 × 3 Formula using Cofactors</b>	$a_{11}c_{11} + a_{12}c_{12} + a_{13}c_{13}$						
<b>Properties</b>	<table border="1" style="width: 100%;"> <tr> <td>a. Δ remains unaltered if its rows or columns are interchanged.</td> <td>b. Δ change its sign if two rows or columns interchanges</td> </tr> <tr> <td>c. If any two rows or columns of a determinant are identical, then Δ = 0</td> <td>d. If each element of matrix is multiplied by constant k, Δ will also get multiplied by k</td> </tr> <tr> <td>e. If some or all of the elements of a row or column of a determinant are expressed as sum, then Δ is expressed as sum of Δs</td> <td>f. Δ will remain same if equi-multiple of any row or column is added to each element of any row or column</td> </tr> </table>	a. Δ remains unaltered if its rows or columns are interchanged.	b. Δ change its sign if two rows or columns interchanges	c. If any two rows or columns of a determinant are identical, then Δ = 0	d. If each element of matrix is multiplied by constant k, Δ will also get multiplied by k	e. If some or all of the elements of a row or column of a determinant are expressed as sum, then Δ is expressed as sum of Δs	f. Δ will remain same if equi-multiple of any row or column is added to each element of any row or column
a. Δ remains unaltered if its rows or columns are interchanged.	b. Δ change its sign if two rows or columns interchanges						
c. If any two rows or columns of a determinant are identical, then Δ = 0	d. If each element of matrix is multiplied by constant k, Δ will also get multiplied by k						
e. If some or all of the elements of a row or column of a determinant are expressed as sum, then Δ is expressed as sum of Δs	f. Δ will remain same if equi-multiple of any row or column is added to each element of any row or column						
<b>Singular Matrix</b>	if $\det A = 0$ , then singular matrix otherwise non-singular matrix						
<b>Adjoint Matrix</b>	Adjoint of A Matrix is the transpose of the Cofactor Matrix						
<b>Inverse Matrix</b>	If A is a square matrix, and $\det A \neq 0$ (non-singular), then $A^{-1} = \frac{1}{ A } \times \text{Adj. A}$						
<b>Cramer's rule to find solution of linear eq. in 3 variables</b>	$x = \frac{\Delta x}{\Delta}$ , $y = \frac{\Delta y}{\Delta}$ , $z = \frac{\Delta z}{\Delta}$ , provided $\Delta \neq 0$ [ $\Delta x$ means determinant of matrix by replacing first column of matrix with RHS values of equations] See Example						
<b>Properties of Cramer's</b>	<table border="1" style="width: 100%;"> <tr> <td>a. If <math>\Delta \neq 0</math>, the system has unique solution</td> <td>b. If <math>\Delta = 0</math> and atleast one of <math>\Delta x, \Delta y, \Delta z \neq 0</math>, then system has no solution and it is inconsistent</td> </tr> <tr> <td colspan="2">c. If <math>\Delta = 0</math> and all of <math>\Delta x, \Delta y, \Delta z \neq 0</math>, then system may or may not have solution. If it has solution, equations are dependent and there will be infinite no. of solutions. If it doesn't have solution, equations are inconsistent.</td> </tr> </table>	a. If $\Delta \neq 0$ , the system has unique solution	b. If $\Delta = 0$ and atleast one of $\Delta x, \Delta y, \Delta z \neq 0$ , then system has no solution and it is inconsistent	c. If $\Delta = 0$ and all of $\Delta x, \Delta y, \Delta z \neq 0$ , then system may or may not have solution. If it has solution, equations are dependent and there will be infinite no. of solutions. If it doesn't have solution, equations are inconsistent.			
a. If $\Delta \neq 0$ , the system has unique solution	b. If $\Delta = 0$ and atleast one of $\Delta x, \Delta y, \Delta z \neq 0$ , then system has no solution and it is inconsistent						
c. If $\Delta = 0$ and all of $\Delta x, \Delta y, \Delta z \neq 0$ , then system may or may not have solution. If it has solution, equations are dependent and there will be infinite no. of solutions. If it doesn't have solution, equations are inconsistent.							

COPYRIGHT LEARN WITH PRANAV