

GASTRACH – Gas Analyzer Probe (GAP-100) RS485 (Modbus RTU) Register Set

This document details the Modbus register set developed to control and analyse data from the GAP-100 oxygen analyzer.



NOTE: Register set valid for product configuration GAP-100

Contents

1	DEFINITI	ONS	1-1
2	MODBU:	S SETUP	2-1
3	MODBU:	S REGISTERS	3-1
	3.1 Sys	em Information and Communication Registers	3-1
	3.1.1	System Information Registers	3-1
	3.1.2	System Information File Registers	3-1
	3.1.3	Serial Registers	3-1
	3.1.4	Changing Communication Settings	3-2
	3.2 Sen	sor Registers	3-3
	3.2.1	O ₂ Sensor Registers	3-3
	3.2.2	Calibrating the O ₂ Sensor	3-8
	3.2.3	Configuring the O₂ Sensor – Cooldown Delay	3-8
	3.2.4	Changing the O₂ Sensor Diagnostic Value	3-9
	3.2.5	Temperature Sensor Registers	3-10
	3.2.6	Pressure Sensor Registers	3-13
	3.3 Rela	ay and 4-20mA Registers	3-16
	3.3.1	Relay Registers	3-16
	3.3.2	Configuring Relay 1 Switch Points and Hysteresis	3-20
	3.3.3	Configuring Relay 1 System States	3-21
	3.3.4	Configuring Relay 2 System States	3-25
	3.3.5	4 – 20mA Registers	3-26
	3.3.6	Configuring the Sensor Range Applied to the 4-20mA Output	3-30
	3.3.7	Configuring the 4-20mA Output Value During Other System States	3-30

1 DEFINITIONS

The following definitions apply to WARNINGS, CAUTIONS, ACTIONS and NOTES used throughout this manual.



WARNING:

The warning symbol is used to indicate instructions that, if they are not followed, can result in minor, serious or even fatal injuries to personnel.



CAUTION:

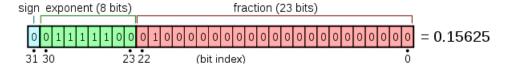
The caution symbol is used to indicate instructions that, if they are not followed, can result in damage to the equipment (hardware and/or software), or a system failure occurring.

ACTION: How data from the device should be used during normal operation.

NOTE: Operating conditions or statements pertaining to the recommended action.

The following terminology and acronyms are used throughout this manual:

- Input registers are read only 16-bit registers. Valid address range starts at 30001.
- Holding registers are read / write 16-bit registers. Valid address range starts at 40001.
- MSB Most Significant Bits.
- LSB Least Significant Bits.
- **EEPROM** Electrically Erasable Programmable Read-Only Memory.
- **32-bit Integers** Unsigned 32-bit integers are split over two 16-bit registers where the MSB and LSB are identified.
- Floating point numbers are digitally represented using the IEEE–754 format. Single precision floating point numbers are used throughout and they require 32-bits of data. Since a Modbus register holds 16-bits, it takes two registers to represent a floating point number. The IEEE 754 standard specifies a binary32 as having:
 - Sign bit: 1 bit
 - Exponent width: 8 bits
 - Significand precision: 24 bits (23 explicitly stored)



For example, 20.7 in IEEE 754 format is: 0 10000011 0100101100110011011010

2 MODBUS SETUP

The half-duplex RS485 interface allows multiple sensors or systems to be connected on a single bus and individually addressed following the Modbus RTU protocol.

NOTE: Background reading is strongly recommended if there is no prior knowledge of Modbus. A good place to start is www.modbus.org, where the specification and resources can be obtained in the technical resources page.

The Modbus interface is configured using the following setup:

Modbus mode: RTU
Address: One
Baudrate: 9600
Parity: None
Stopbits: Two

3 MODBUS REGISTERS

NOTE: Default values are shown in **bold**.

NOTE: Values shown in grey are reserved, not applicable or indicate that they should not be changed.

3.1 System Information and Communication Registers

3.1.1 System Information Registers

Table 3-1 – System Information - Input Registers

Name	Register Address	Description	Actions / Notes
Modbus	0x7531	32-bit Integer	ACTION: For reference
Register Set	(30001)	(MSB 16-bits)	NOTE: Used for
Revision	0x7532	32-bit Integer	diagnostic purposes
	(30002)	(LSB 16-bits)	
Software	0x7533	32-bit Integer	
Revision	(30003)	(MSB 16-bits)	
	0x7534	32-bit Integer	
	(30004)	(LSB 16-bits)	

3.1.2 System Information File Registers

Table 3-2 - System Information - File Records

Name	File Number	Record Number	Actions / Notes
Part Number	0x000 (0x000)	0	ACTION: For reference NOTE: Read only –
Serial number	0x000 (0x000)	1	Used for system identification
Date Code	0x000 (0x000)	2	

3.1.3 Serial Registers

Table 3-3 - Serial - Input Registers

Name	Register Address	Description	Actions / Notes
Serial Status	0x7535 (30005)	0 = Unavailable Serial parameters are fixed 1 = Not Ready Serial changes are currently not permitted 2 = Ready Serial changes are permitted 3 = Busy Serial changes in process 4 = Complete Serial changes committed to memory, system will restart in 1s with the new communication settings 5 = Error Error committing serial changes to memory	ACTION: Monitor in system NOTE: Used in Section 3.1.4 on page 3-2.

Table 3-4 – Serial - Holding Registers

Name	Register Address	Description / Valid Values	Actions / Notes
Serial Address	0x9C41 (40001)	1-247	ACTION: Set/Monitor in system
Serial Baudrate	0x9C42 (40002)	0 = 2400 1 = 4800 2 = 9600 3 = 19200 4 = 38400 5 = 57600 6 = 115200	NOTES: Any committed changes are saved in EEPROM and retained on power loss. Any invalid requests are ignored. Used in Section 3.1.4 on page 3-2.
Serial Parity	0x9C43 (40003)	0 = None 1 = Even 2 = Odd	
Serial Control	0x9C44 (40004)	0 = Idle 1 = Save and reset	

3.1.4 Changing Communication Settings

- 1. Confirm Serial Status = Ready (30005 = 2).
- 2. Set Serial Address (40001), Baudrate (40002) and/or Parity (40003) as required.
- 3. Set Serial Control to Save and Reset (40004 = 1).
- 4. Monitor *Serial Status* input register which will change to *Busy* momentarily then *Complete* for 1s before the system resets and communication to the master is lost. $(30005 = 3 \rightarrow 4 \rightarrow 1s \text{ delay} \rightarrow \text{reset}).$

To restore communications, the master should now be configured to the new communication settings.

3.2 Sensor Registers

In addition to the zirconia dioxide oxygen sensor, the GAP has a pressure sensor and Pt-100 temperature sensor fitted.

3.2.1 O₂ Sensor Registers

Table 3-5 – O₂ Sensor - Input Registers

Name	Register Address	Description	Actions / Notes
O ₂ ID	0x7536 (30006)	-	ACTION: For reference NOTE: Unique sensor identifier
O ₂ Warning	0x7537 (30007)	16-bit bitmask Each bit represents an individual warning state	ACTION: Monitor in system NOTES: Warnings are not retained on power loss.
			Refer to list of Warnings given in <i>UG- 003, GAP User's Guide.</i>
O ₂ Error	0x7538 (30008)	16-bit bitmask Each bit represents an individual error state	ACTION: Monitor in system NOTES: Errors are not retained on power loss.
			Refer to list of Errors given in <i>UG-003, GAP User's Guide.</i>
O ₂ Uncalibrated Value	0x7539 (30009)	Floating point IEEE 754 (MSB 16-bits) Unit = % O ₂	ACTION: Monitor in system NOTES: This value can be greater than or less than the 0 – 25% O ₂ sensor range and is
	0x753A (30010)	Floating point IEEE 754 (LSB 16-bits) Unit = % O ₂	used to determine measurement stability during the calibration process.
			Used in Section 3.2.2 on page 3-8.
O ₂ Calibrated Value	0x753B (30011)	Floating point IEEE 754 (MSB 16-bits) Unit = % O ₂ Valid Range = 0.00 to 25.00	ACTION: Monitor in system NOTE: Used in Section 3.2.2 on
	0x753C (30012)	Floating point IEEE 754 (LSB 16-bits) Unit = $\%$ O ₂ Valid Range = 0.00 to 25.00	page 3-8.

Name	Register Address	Description	Actions / Notes
O ₂ Status	0x753D (30013)	O = Loading System initialising, no O ₂ measurements, sensor heater off 1 = OFF No O ₂ measurements, sensor heater off 2 = Standby No O ₂ measurements, sensor heater on at half power 3 = Warm-up No O ₂ measurements, sensor heater on at full power Warm-up time = 60s coming from OFF Warm-up time = 20s coming from Standby 4 = ON Valid O ₂ measurements, sensor heater on at full power 5 = Cool-down No O ₂ measurements, sensor heater on at full power 6 = Calibration Invalid O ₂ measurements, calibration in process, sensor heater on at full power	ACTION: Monitor in system NOTE: Used in Section 3.2.2 on page 3-8.
O ₂ Calibration Status	0x753E (30014)	0 = Reserved 1 = Not Ready Calibration is currently disabled 2 = Ready Calibration enabled 3 = Busy Calibration in progress 4 = Complete Calibration complete 5 = Error Error during the calibration process	ACTION: Monitor in system NOTES: Calibration is only enabled when O_2 Control = ON (40005 = 2) for greater than 5 minutes. This delay is required to allow the sensor to stabilise at the correct operating temperature. Used in Section 3.2.2 on page 3-8.
O ₂ Configuration Value Type	0x753F (30015)	0 = Invalid 1 = 32-bit integer 2 = Floating point IEEE 754	ACTION: For reference NOTES: O ₂ Configuration Value data format (40015 and 40016) Used in Section 3.2.3
O ₂ Configuration Status	0x7540 (30016)	0 = Reserved 1 = Not Ready Configuration is currently disabled 2 = Ready Configuration enabled 3 = Busy Configuration in progress 4 = Complete Configuration complete 5 = Error Error during the configuration process	on page 3-8. ACTION: Monitor in system NOTE: Used in Section 3.2.3 on page 3-8.

Name	Register Address	Description / Valid Values	Actions / Notes
O ₂ Diagnostic Value Type	0x7541 (30017)	0 = Invalid 1 = 32-bit integer 2 = Floating point IEEE 754	ACTION: For reference NOTES: O ₂ Diagnostic Value data format (30018 and 30019) Used in Section 3.2.4 on page 3-9.
O ₂ Diagnostic Value	0x7542 (30018)	MSB 16-bits	ACTION: Monitor in system NOTES: Returned diagnostic value of currently selected O_2 Diagnostic Index (40016). See O_2
	0x7543 (30019)	LSB 16-bits	Diagnostic Value Type (30017) for data format. Used in Section 3.2.4 on page 3-9.
O ₂ Diagnostic Status	0x7544 (30020)	0 = Reserved 1 = Not Ready Diagnostic values are currently disabled 2 = Ready Diagnostic values enabled 3 = Busy Diagnostic index change in progress 4 = Complete Diagnostic index change complete 5 = Error Error during the diagnostic index change process	ACTION: Monitor in system NOTES: After a successful diagnostic index change the updated value will be available in O ₂ Diagnostic Value (30018 and 30019). Used in Section 3.2.4 on page 3-9.

Table 3-6 – O₂ Sensor - Holding Registers

Name	Register Address	Description / Valid Values	Actions / Notes
O ₂ Control	0x9C45 (40005)	0 = OFF Turns the O ₂ measurement off and then the sensor heater off after the set cool-down delay 1 = Standby Turns the O ₂ measurement off and reduces the heater voltage to half power 2 = ON Turns the O ₂ measurement on and increases the heater voltage to full power Warm-up time = 60s coming from OFF Warm-up time = 20s coming from Standby	ACTION: Set/Monitor in system NOTES: Standby protects the sensor from condensation. It is recommended that this state should be used when no O ₂ measurements are required. If this register is forced to OFF by the device then it is due to a system error. This can be confirmed by reading the O ₂ error (30008).
Clear O ₂ Warning	0x9C46 (40006)	0 = Idle 1 = Reserved	ACTION: None NOTE: Any warning present in O_2 Warning (30007) will auto clear if the condition that caused the warning is removed.
Clear O ₂ Error	0x9C47 (40007)	0 = Idle 1 = Clear Error	ACTION: Set in system NOTE: If an error present in O_2 Error (30008) has forced O_2 Status to OFF (30015 = 1) the error may be cleared using this register and an attempt made to restart the sensor by setting the O_2 Control to ON (40005 = 2). If the error persists, contact support@co2meter.com for guidance.
O ₂ Calibration Type	0x9C48 (40008)	0 = Gain	ACTION: None NOTE: Due to the O ₂ sensor technology, no "zero" calibration is required and only a "Gain" (or span) calibration needs to be performed.

Name	Register Address	Description / Valid Values	Actions / Notes
O ₂ Calibration Value	0x9C49 (40009) 0x9C4A (40010)	Floating point IEEE 754 (MSB 16-bits) Unit = % O ₂ Valid Range = 0.00 to 25.00 Recommended Range = 5.00 to 25.00 Floating point IEEE 754 (LSB 16-bits) Unit = % O ₂ Valid Range = 0.00 to 25.00 Recommended Range = 5.00 to 25.00	ACTION: Set/Monitor in system NOTES: Any changes are saved in EEPROM and retained on power loss. Default = 20.70% for fresh air. Used in Section 3.2.2 on page 3-8.
O ₂ Calibration Control	0x9C4B (40011)	 0 = Idle 1 = Reserved 2 = Apply Calibration 3 = Reset Status 	ACTION: Set in system NOTE: Used in Section 3.2.2 on page 3-8.
O ₂ Configuration Index	0x9C4C (40012)	0 = Cool-down Delay	ACTION: None NOTE: Cool-down is the only configurable option available.
O ₂ Configuration Value	0x9C4D (40013)	MSB 16-bits Unit = seconds Valid Range = 0 to 43200 (12hrs)	ACTION: Set/Monitor in system NOTES: Any changes are saved in EEPROM and retained on power loss. See O ₂ Configuration
	0x9C4E (40014)	LSB 16-bits Unit = seconds Valid Range = 0 to 43200 (12hrs)	Value Type (30015) for data format. Default = 0s Used in Section 3.2.3 on page 3-8.
O ₂ Configuration Control	0x9C4F (40015)	0 = Idle 1 = Reserved 2 = Apply Configuration 3 = Reset Status	ACTION: Set in system NOTE: Used in Section 3.2.3 on page 3-8.
O ₂ Diagnostic Index	0x9C50 (40016)	0 = TD 1 = Asymmetry 2 = TP 3 = T1 4 = T2 5 = T4 6 = T5 7 = Heater Voltage	ACTION: Set/Monitor in system NOTES: Sensor diagnostics are read only; they are available to assist in fault-finding if there is a warning condition present. Contact Support@co2meter.com for assistance when using this feature. Used in Section 3.2.4 on page 3-9.
O ₂ Diagnostic Control	0x9C51 (40017)	0 = Idle 1 = Change Index 2 = Reset Status	ACTION: Set in system NOTE: Used in Section 3.2.4 on page 3-9.

3.2.2 Calibrating the O₂ Sensor

- 1. Confirm O_2 Calibration Status = Ready (30014 = 2).
- 2. Apply the calibration gas for a minimum of 5 minutes. The calibration gas used must be within the 0 25% O₂ sensor range and gain calibrations below 5% O₂ are not recommended. When calibrating in fresh air it is assumed that the O₂ concentration is 20.7%.
- 3. Monitor O_2 Uncalibrated Value (30009 and 30010) and wait until the value has been stable to $\pm 0.1\%$ O_2 for a minimum of 30s.
- 4. Input the O_2 % of the calibration gas into O_2 Calibration Value (40009 and 40010).
- 5. Set O_2 Calibration Control to Apply Calibration (40011 = 2).
- 6. During the calibration routine O_2 Calibration Status will change to Busy (30014 = 3) and O_2 Status will change to Calibration (30013 = 6). O_2 measurements are not valid during this phase.
- 7. When the calibration routine is complete O_2 Calibration Status will change to Complete (30014 = 4) and O_2 Status will return to ON (30013 = 4).
- 8. Set O_2 Calibration Control to Reset Status (40011 = 3) to return O_2 Calibration Status to Ready (30014 = 2).
- 9. Confirm the O_2 Calibrated Value (30011 and 30012) is within ±0.1% O_2 of the calibration gas applied. If not, repeat Steps 3 to 8 and allow the O_2 Uncalibrated Value (30009 and 30010) to stabilise for a longer period. If multiple calibration attempts do not result in an accurate calibration, contact Support@CO2Meter.com for guidance.

3.2.3 Configuring the O₂ Sensor – Cooldown Delay

When operating in warm, humid environments it is important the sensor remains at a higher temperature than its surroundings, especially if there are corrosive components in the measurement gas. During operation this is not an issue as the heater operates at 700°C, however this means when the sensor or application is being powered down the sensor heater must be the last thing to be turned off after the temperature of the surroundings have suitably cooled.

- 1. Confirm O_2 Configuration Status = Ready (30016= 2).
- 2. Change O_2 Configuration Value (40013 and 40014) to the new cool-down delay, see O_2 Configuration Value Type (30015) for the required data format.
- 3. Set O_2 Configuration Control to Apply Configuration to commit the change (40015 = 2).
- 4. Monitor O_2 Configuration Status which will change to Busy momentarily then Complete (30016 = 3 \rightarrow 4).
- 5. Set O_2 Configuration Control to Reset Status (40015 = 3) to return O_2 Configuration Status to Ready (30016= 2).
 - The newly saved cool-down delay will be applied the next time the O_2 Control is set to OFF (40005 = 0) when the current state of O_2 Status = ON (30013 = 4).

3.2.4 Changing the O₂ Sensor Diagnostic Value

- 1. Confirm O_2 Diagnostic Status = Ready (30020 = 2).
- 2. Change O_2 Diagnostic Index (40016) to the new diagnostic value you would like to view
- 3. Set O_2 Diagnostic Control to Change Index to commit the change (40017 = 1).
- 4. Monitor O_2 Diagnostic Status which will change to Busy momentarily then Complete (30020 = 3 \rightarrow 4).
- 5. Set O_2 Diagnostic Control to Reset Status (40017 = 2) to return O_2 Diagnostic Status to Ready (30020 = 2).
- 6. Read the new value in O_2 Diagnostic Value (30018 and 30019). See O_2 Diagnostic Value Type (30017) for the data format.

3.2.5 Temperature Sensor Registers

Table 3-7 – Temperature Sensor - Input Register

Name	Register Address	Description	Actions / Notes
Temperature ID	0x7545 (30021)	-	ACTION: For reference NOTE: Unique sensor identifier
Temperature Warning	0x7546 (30022)	16-bit bitmask Each bit represents an individual warning state	ACTION: Monitor in system NOTES: Warnings are not retained on power loss. Refer to list of Warnings given in UG-003, GAP User's Guide.
Temperature Error	0x7547 (30023)	16-bit bitmask Each bit represents an individual error state	ACTION: Monitor in system NOTES: Errors are not retained on power loss. Refer to list of Errors given in UG-003, GAP User's Guide.
Temperature Uncalibrated Value	0x7548 (30024) 0x7549 (30025)	Reserved Reserved	ACTION: None
Temperature Calibrated Value	0x754A (30026) 0x754B (30027)	Floating point IEEE 754 (MSB 16-bits) Unit = °C Valid Range = -50 to 600 Floating point IEEE 754 (LSB 16-bits) Unit = °C Valid Range = -50 to 600	ACTION: Monitor in system
		-	
Temperature Status	0x754C (30028)	O = Loading System initialising, no temperature measurements 1 = OFF No temperature measurements 2 = Reserved 3 = Reserved 4 = ON Valid temperature measurements 5 = Reserved 6 = Reserved	ACTION: Monitor in system

Name	Register Address	Description	Actions / Notes
Temperature Calibration Status	0x754D (30029)	<pre>0 = Unavailable Not applicable to this sensor 1 = Reserved 2 = Reserved 3 = Reserved 4 = Reserved 5 = Reserved</pre>	ACTION: None
Temperature Configuration Value Type	0x754E (30030)	0 = Invalid 1 = Reserved 2 = Reserved	ACTION: None
Temperature Configuration Status	0x754F (30031)	<pre>0 = Unavailable Not applicable to this sensor 1 = Reserved 2 = Reserved 3 = Reserved 4 = Reserved 5 = Reserved</pre>	ACTION: None
Temperature Diagnostic Value Type	0x7550 (30032)	0 = Invalid 1 = 32-bit integer 2 = Floating point IEEE 754	ACTION: For reference NOTES: Temperature Diagnostic Value data format (30033 and 30034).
Temperature Diagnostic Value	0x7551 (30033)	MSB 16-bits	ACTION: Monitor in system NOTES: Pt100 resistance measurement. See Temperature
	(30034)	Unit = Ω	Diagnostic Value Type (30032) for data format.
Temperature Diagnostic Status	0x7553 (30035)	0 = Reserved 1 = Not Ready Diagnostic value is currently disabled 2 = Ready Diagnostic value enabled 3 = Reserved 4 = Reserved 5 = Reserved	ACTION: Monitor in system

Table 3-8 – Temperature Sensor - Holding Registers

Name	Register Address	Description / Valid Values	Actions / Notes
Temperature Control	0x9C52 (40018)	0 = Reserved	ACTION: Monitor in system NOTE: The temperature measurement cannot be switched off.
Clear Temperature Warning	0x9C53 (40019)	0 = Idle 1 = Reserved	ACTION: None NOTE: Any warning present in <i>Temperature</i> Warning (30022) will auto clear if the condition that caused the warning is removed.
Clear Temperature Error	0x9C54 (40020)	0 = Idle 1 = Reserved	ACTION: None NOTE: If an error is present in Temperature Error (30023) contact support@co2meter.com for guidance.
Temperature Calibration Type	0x9C55 (40021)	Reserved	ACTION: None
Temperature Calibration Value	0x9C56 (40022) 0x9C57	Reserved Reserved	ACTION: None
Temperature Calibration Control	(40023) 0x9C58 (40024)	Reserved	ACTION: None NOTE: Calibration of the temperature sensor is not allowed.
Temperature Configuration Index	0x9C59 (40025)	Reserved	ACTION: None
Temperature Configuration Value	0x9C5A (40026) 0x9C5B (40027)	Reserved Reserved	ACTION: None
Temperature Configuration Control	0x9C5C (40028)	Reserved	ACTION: None
Temperature Diagnostic Index	0x9C5D (40029)	0 = Pt100 Resistance	ACTION: None
Temperature Diagnostic Control	0x9C5E (40030)	Reserved	ACTION: None

3.2.6 Pressure Sensor Registers

Table 3-9 – Pressure Sensor - Input Registers

Name	Register Address	Description	Actions / Notes
Pressure ID	0x7554 (30036)	-	ACTION: For reference NOTE: Unique sensor identifier
Pressure Warning	0x7555 (30037)	16-bit bitmask Each bit represents an individual warning state	ACTION: Monitor in system NOTES: Warnings are not retained on power loss. Refer to list of Warnings given in UG-003, GAP User's Guide.
Pressure Error	0x7556 (30038)	16-bit bitmask Each bit represents an individual error state	ACTION: Monitor in system NOTES: Errors are not retained on power loss. Refer to list of Errors given in UG-003, GAP User's Guide.
Pressure Uncalibrated	0x7557 (30039)	Reserved	ACTION: None
Value	0x7558 (30040)	Reserved	
Pressure Calibrated Value	0x7559 (30041)	Floating point IEEE 754 (MSB 16-bits) Unit = mbar Valid Range = 260 to 1260 Floating point IEEE 754 (LSB 16-bits)	ACTION: Monitor in system
	(30042)	Unit = mbar Valid Range = 260 to 1260	
Pressure Status	0x755B (30043)	0 = Loading System initialising, no pressure measurements 1 = OFF No pressure measurements 2 = Reserved 3 = Reserved 4 = ON Valid pressure measurements 5 = Reserved 6 = Reserved	ACTION: Monitor in system
Pressure Calibration Status	0x755C (30044)	O = Unavailable Not applicable to this sensor 1 = Reserved 2 = Reserved 3 = Reserved 4 = Reserved 5 = Reserved	ACTION: None

Name	Register Address	Description	Actions / Notes
Pressure Configuration Value Type	0x755D (30045)	0 = Invalid 1 = Reserved 2 = Reserved	ACTION: None
Pressure Configuration Status	0x755E (30046)	<pre>0 = Unavailable Not applicable to this sensor 1 = Reserved 2 = Reserved 3 = Reserved 4 = Reserved 5 = Reserved</pre>	ACTION: None
Pressure Diagnostic Value Type	0x755F (30047)	Reserved	ACTION: None
Pressure Diagnostic Value	0x7560 (30048) 0x7561 (30049)	Reserved Reserved	ACTION: None
Pressure Diagnostic Status	0x7562 (3000)	<pre>0 = Unavailable Not applicable to this sensor 1 = Reserved 2 = Reserved 3 = Reserved 4 = Reserved 5 = Reserved</pre>	ACTION: None

Table 3-10 – Pressure Sensor - Holding Registers

Name	Register Address	Description / Valid Values	Actions / Notes
Pressure Control	0x9C5F (40031)	0 = Reserved	ACTION: Monitor in system NOTE: The pressure measurement cannot be switched off.
Clear Pressure Warning	0x9C60 (40032)	0 = Idle 1 = Reserved	ACTION: None NOTE: Any warning present in <i>Pressure</i> Warning (30037) will auto clear if the condition that caused the warning is removed.
Clear Pressure Error	0x9C61 (40033)	0 = Idle 1 = Reserved	ACTION: None NOTE: If an error is present in Pressure Error (30038) contact Support@co2meter.com for guidance.
Pressure Calibration Type	0x9C62 (40034)	Reserved	ACTION: None
Pressure Calibration Value	0x9C63 (40035) 0x9C64	Reserved Reserved	ACTION: None
Pressure Calibration Control	(40036) 0x9C65 (40037)	Reserved	ACTION: None NOTE: Calibration of the pressure sensor is not allowed.
Pressure Configuration Index	0x9C66 (40038)	Reserved	ACTION: None
Pressure Configuration Value	0x9C67 (40039) 0x9C68	Reserved Reserved	ACTION: None
Pressure Configuration Control	(40040) 0x9C69 (40041)	Reserved	ACTION: None
Pressure Diagnostic Index	0x9C6A (40042)	Reserved	ACTION: None
Pressure Diagnostic Control	0x9C6B (40043)	Reserved	ACTION: None

3.3 Relay and 4-20mA Registers

3.3.1 Relay Registers

Relays provide Single Pole Single Throw (SPST) contact outputs; unless otherwise specified, relays are normally open as standard.

- Relay 1 User configurable O₂ measurement alarm
- Relay 2 O₂ sensor fault indication

Table 3-11 – Relay 1 – Input Registers

Name	Register Address	Description	Actions / Notes
Relay 1 ID	0x7562 (30050)	-	ACTION: For reference NOTE: Unique output identifier
Relay 1 Warning	0x7563 (30051)	Reserved	ACTION: None
Relay 1 Error	0x7564 (30052)	Reserved	ACTION: None
Relay 1 Value	0x7565 (30053)	32-bit integer (MSB 16-bits)	ACTION: Monitor in system
	0x7566 (30054)	32-bit integer (LSB 16-bits) 0 = Open 1 = Closed	
Relay 1 Status	0x7567 (30055)	O = Loading System initialising, Relay 1 in start-up state 1 = Reserved 2 = Standby O ₂ sensor measurements off, Relay 1 in standby state 3 = ON O ₂ sensor measurements on, Relay 1 state depends the O ₂ measurement and the set switch points	ACTION: Monitor in system NOTE: Relay 1 Mode = Override (40046 = 1) allows the relay state in Standby and ON to be overridden for test purposes.
Relay 1 Switch Points Status	0x7568 (30056)	0 = Reserved 1 = Not Ready Modification of the switch points is currently disabled 2 = Ready Modification of the switch points enabled 3 = Busy Modification of the switch points in progress 4 = Complete Modification of the switch points complete 5 = Error Error during the modification of the switch points	ACTION: Monitor in system NOTE: Used in Section 3.3.2 on page 3-20.

Name	Register Address	Description / Valid Values	Actions / Notes
Relay 1 Configuration Value Type	0x7569 (30057)	0 = Invalid 1 = 32-bit integer 2 = Floating point IEEE 754	ACTION: For reference NOTES: Relay 1 Configuration Value data format (40059 and 40060). Used in Section 3.3.3 on page 3-21.
Relay 1 Configuration Status	0x756A (30058)	0 = Reserved 1 = Not Ready Configuration is currently disabled 2 = Ready Configuration enabled 3 = Busy Configuration in progress 4 = Complete Configuration complete 5 = Error Error during the configuration process	ACTION: Monitor in system NOTE: Used in Section 3.3.3 on page 3-21.
Relay 1 Diagnostic Value Type	0x756B (30059)	Reserved	ACTION: None
Relay 1 Diagnostic Value	0x756C (30060) 0x756D	Reserved Reserved	ACTION: None
	(30061)	Neserveu	
Relay 1 Diagnostic Status	0x756E (30062)	<pre>0 = Unavailable Not applicable to this sensor 1 = Reserved 2 = Reserved 3 = Reserved 4 = Reserved 5 = Reserved</pre>	ACTION: None

Table 3-12 – Relay 1 - Holding Registers

Name	Register	Description / Valid Values	Actions / Notes
Delay 1	Address 0x9C6C	Deserved	ACTION: None
Relay 1	(40044)	Reserved	ACTION: None
Warning	0x9C6D	Reserved	ACTION: None
Relay 1 Error	(40045)	Reserved	ACTION: Notice
Relay 1 Mode	0x9C6E	0 = Normal	ACTION: Set in system
	(40046)	Relay state depends on O2 sensor value	NOTE: When Override
		1 = Override	is selected, the relay
		User controls the relay state for test purposes	state is set by changing the value in <i>Relay 1</i>
			Override Value (40047
			and 40048).
Relay 1	0x9C6F	32-bit integer (MSB 16-bits)	ACTION: Set/Monitor
Override	(40047)		in system
Value		0	
	0x9C70	32-bit integer (LSB 16-bits)	
	(40048)		
		0 = Open	
		1 = Closed	
Relay 1	0x9C71	0 = Window	ACTION: None
Switch Points	(40049)	The relay will switch from the set normal state to	NOTE: Window
Туре		the opposite state within the window	function is the only
			option available.
Relay 1	0x9C72	-	ACTION: For reference
Switch Points	(40050)		NOTE: O ₂ sensor
- Input Sensor ID			unique identifier that Relay 1 function is
Selisol ID			linked to.
Relay 1 Lower	0x9C73	Floating point IEEE 754 (MSB 16-bits)	ACTION: Set/Monitor
Switch Point	(40051)	Floating point lete 754 (WISD 10-DICS)	in system
	(1000-)	Unit = % O ₂	NOTES: Any changes
		Valid Range = 0.00 to (Relay 1 Upper Switch Point –	are saved in EEPROM
		2*(Relay 1 Switch Points Hysteresis)	and retained on power
			loss. This value must
			be less than <i>Relay 1</i>
	0.0074	Floating point IFFF 7F4 (ICD 4C hita)	Upper Switch Point (40053 and 40054)
	0x9C74 (40052)	Floating point IEEE 754 (LSB 16-bits)	minus 2 <i>x Relay 1</i>
	(40032)	Unit = % O ₂	Switch Points
		Valid Range = 0.00 to (Relay 1 Upper Switch Point –	Hysteresis (40055 and
		2*(Relay 1 Switch Points Hysteresis)	40056).
			Used in Section 3.3.2
			on page 3-20.

Name	Register Address	Description / Valid Values	Actions / Notes
Relay 1 Upper Switch Point	0x9C75 (40053)	Floating point IEEE 754 (MSB 16-bits) Unit = % O ₂ Valid Range = 0.00 to (<i>Relay 1 Lower Switch Point</i> + 2*(<i>Relay 1 Switch Points Hysteresis</i>)	ACTION: Set/Monitor in system NOTES: Any changes are saved in EEPROM and retained on power loss. This value must be greater than Relay 1
	0x9C76 (40054)	Floating point IEEE 754 (LSB 16-bits) Unit = % O ₂ Valid Range = 0.00 to (Relay 1 Lower Switch Point + 2*(Relay 1 Switch Points Hysteresis)	Lower Switch Point (40051 and 40052) plus 2 x Relay 1 Switch Points Hysteresis (40055 and 40056). Used in Section 3.3.2 on page 3-20.
Relay 1 Switch Points Hysteresis	0x9C77 (40055)	Floating point IEEE 754 (MSB 16-bits) Unit = % O ₂ Valid Range = 0.00 to 25.00 Recommended Range = 0.00 to 1.00	ACTION: Set/Monitor in system NOTES: Any changes are saved in EEPROM and retained on power
	0x9C78 (40056)	Floating point IEEE 754 (LSB 16-bits) Unit = % O ₂ Valid Range = 0.00 to 25.00 Recommended Range = 0.00 to 1.00	Used in Section 3.3.2 on page 3-20.
Relay 1 Switch Points Control	0x9C79 (40057)	 0 = Nothing 1 = Reserved 2 = Apply Switch Points 3 = Reset Status 	ACTION: Set in system NOTE: Used in Section 3.3.2 on page 3-20.
Relay 1 Configuration Index	0x9C7A (40058)	O = Start-up State of the relay when the system is initialising 1 = Standby State of the relay when O ₂ measurements are off 2 = Error State of the relay during an error condition 3 = Normal Normal state of the relay when O ₂ sensor measurement is outside the set switch points window and the O ₂ sensor is not in an error state	ACTION: Set/Monitor in system NOTE: Used in Section 3.3.3 on page 3-21.
Relay 1 Configuration Value	0x9C7B (40059)	MSB 16-bits 0	ACTION: Set/Monitor in system NOTES: Any changes are saved in EEPROM
	0x9C7C (40060)	LSB 16-bits 0 = Open 1 = Closed	and retained on power loss. See <i>Relay 1 Configuration Value Type</i> (30057) for data format. Used in Section 3.3.3 on page 3-21.

Name	Register Address	Description / Valid Values	Actions / Notes
Relay 1 Configuration Control	0x9C7D (40061)	 0 = Nothing 1 = Change Index 2 = Apply Configuration 3 = Reset Status 	ACTION: Set in system NOTE: Used in Section 3.3.3 on page 3-21.
Relay 1 Diagnostic Index	0x9C7E (40062)	Reserved	ACTION: None
Relay 1 Diagnostic Control	0x9C7F (40063)	Reserved	ACTION: None

3.3.2 Configuring Relay 1 Switch Points and Hysteresis

The relay switch points set where the relay will change state depending on the current O_2 sensor measurement. When the O_2 measurement is within the set window (between the upper and lower switch points) the relay will switch to the opposite state from the configured normal state. For example, if the relay is configured as normally open it will be open above and below the set window and closed within the set window. If only one switch point is required set the upper or lower switch point to the maximum or minimum of the sensor measurement range respectively.

Hysteresis may be added to the upper and lower switch points to avoid relay jitter when the measured O_2 value is fluctuating around one of the switch points. This value is also a function of the sensor measurement range, for example, if the hysteresis was set to 0.5 the relay switch points would have $\pm 0.5\%$ O_2 hysteresis.

- 1. Confirm Relay 1 Switch Points Status = Ready (30056 = 2).
- 2. Change *Relay 1 Lower Switch Point* (40051 and 40052), *Relay 1 Upper Switch Point* (40053 and 40054) and *Relay 1 Switch Points Hysteresis* (40055 and 40056) as required.
- 3. Set *Relay 1 Switch Points Control* to *Apply Switch Points* to commit the change/s (40057 = 2).
- 4. Monitor *Relay 1 Switch Points Status* which will change to *Busy* momentarily then Complete (30056 = 3 \rightarrow 4).
- 5. Set *Relay 1 Switch Points Control* to *Reset Status* (40057 = 3) to return *Relay 1 Switch Points Status* to *Ready* (30056 = 2).

The example given on page 3-21 demonstrates the relay opening and closing as the O_2 measurement fluctuates, the relay is configured to be normally open, the lower switch point has been set to 8% O_2 and the upper to 13% O_2 with 1% O_2 hysteresis.

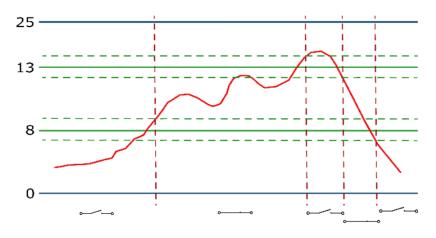


Figure 3-1

- 1. To begin with the sensor measurement is <7% O₂ so the relay is open.
- 2. When the measurement exceeds $9\% O_2$ (8% + 1% hysteresis) the relay will close.
- 3. The relay will remain closed until the O_2 measurement increases to above 14% (13% +1% hysteresis) at which point it will open again.
- 4. The relay will remain open until the O_2 reading falls below 12% (13% 1% hysteresis) at which point it will close again.
- 5. The relay will remain closed until the O_2 reading falls below 7% (8% 1% hysteresis) at which point it will open again.

3.3.3 Configuring Relay 1 System States

Configure the relay state during each of the system conditions:

- 1. Confirm Relay 1 Configuration Status = Ready (30058 = 2).
- 2. Change Relay 1 Configuration Index (40058) to the system state to be configured
- 3. Set *Relay 1 Configuration Control* to *Change Index* to load the selected system state (40061 = 1).
- 4. Change Relay 1 Configuration Value to the desired relay state.
- 5. Set *Relay 1 Configuration Control* to *Apply Configuration* to save the change (40061 = 2).
- 6. Monitor Relay 1 Configuration Status which will change to Busy momentarily then Complete (30058 = $3 \rightarrow 4$).
- 7. Set Relay 1 Configuration Control to Reset Status (40061 = 3) to return Relay 1 Configuration Status to Ready (30058 = 2).
- 8. Repeat Steps 1 to 7 for each system state as required.

Table 3-13 - Relay 2 - Input Registers

Name	Register Address	Description	Actions / Notes
Relay 2 ID	0x756F (30063)		ACTION: For reference NOTE: Unique output identifier.
Relay 2 Warning	0x7570 (30064)	Reserved	ACTION: None
Relay 2 Error	0x7571 (30065)	Reserved	ACTION: None
Relay 2 Value	0x7572 (30066)	32-bit integer (MSB 16-bits)	ACTION: Monitor in system
	0x7573 (30067)	32-bit integer (LSB 16-bits) 0 = Open 1 = Closed	
Relay 2 Status	0x7574 (30068)	O = Loading System initialising, Relay 2 in start-up state 1 = Reserved 2 = Standby O ₂ sensor measurements off, Relay 2 in standby state 3 = ON O ₂ sensor measurements on, Relay 2 state depends the O ₂ error state	ACTION: Monitor in system NOTE: Relay 2 Mode = Override (40066 = 1) allows the relay state in Standby and ON to be overridden for test purposes.
Relay 2 Switch Points Status	0x7575 (30069)	<pre>0 = Unavailable Not applicable to this output 1 = Reserved 2 = Reserved 3 = Reserved 4 = Reserved 5 = Reserved</pre>	ACTION: None
Relay 2 Configuration Value Type	0x7576 (30070)	0 = Invalid 1 = 32-bit integer 2 = Floating point IEEE 754	ACTION: For reference NOTES: Relay 2 Configuration Value data format (40079 and 40080). Used in Section 3.3.4 on page 3-25.
Relay 2 Configuration Status	0x7577 (30071)	0 = Reserved 1 = Not Ready Configuration is currently disabled 2 = Ready Configuration enabled 3 = Busy Configuration in progress 4 = Complete Configuration complete 5 = Error Error during the configuration process	ACTION: Monitor in system NOTE: Used in Section 3.3.4 on page 3-25.

Name	Register Address	Description	Actions / Notes
Relay 2 Diagnostic Value Type	0x7578 (30072)	Reserved	ACTION: None
Relay 2 Diagnostic	0x7579 (30073)	Reserved	ACTION: None
Value	0x757A (30074)	Reserved	
Relay 2 Diagnostic Status	0x757B (30075)	<pre>0 = Unavailable Not applicable to this sensor 1 = Reserved 2 = Reserved 3 = Reserved 4 = Reserved 5 = Reserved</pre>	ACTION: None

Table 3-14 - Relay 2 - Holding Registers

Name	Register Address	Description / Valid Values	Actions / Notes
Relay 2	0x9C80	Reserved	ACTION: None
Warning	(40064)		
Relay 2 Error	0x9C81	Reserved	ACTION: None
Relay 2 Mode	(40065) 0x9C82	0 = Normal	ACTION: Set in system
Nelay 2 Wode	(40066)	Relay state depends on O2 sensor error state 1 = Override User controls the relay state for test purposes	NOTE: When Override is selected the relay state is set by changing the value in Relay 2 Override Value (40067 and 40068).
Relay 2 Override Value	0x9C83 (40067)	32-bit integer (MSB 16-bits) 0	ACTION: Set/Monitor in system
	0x9C84 (40068)	32-bit integer (LSB 16-bits) 0 = Open 1 = Closed	
Relay 2 Switch Points	0x9C85 (40069)	Reserved	ACTION: None
Type	(40003)		
Relay 2 Switch Points - Input Sensor ID	0x9C86 (40070)	-	ACTION: For reference NOTE: O ₂ sensor unique identifier that Relay 2 function is linked to.
Relay 2 Lower Switch Point	0x9C87 (40071)	Reserved	ACTION: None
	0x9C88 (40072)	Reserved	
Relay 2 Upper Switch Point	0x9C89 (40073)	Reserved	ACTION: None
	0x9C8A (40074)	Reserved	
Relay 2 Switch Points Hysteresis	0x9C8B (40075) 0x9C8C (40076)	Reserved Reserved	ACTION: None
Relay 2 Switch Points Control	0x9C8D (40077)	Reserved	ACTION: None

Name	Register Address	Description	Actions / Notes
Relay 2 Configuration Index	0x9C8E (40078)	O = Start-up State of the relay when the system is initialising 1 = Standby State of the relay when O ₂ measurements are off 2 = Error State of the relay during an error condition 3 = Normal Normal state of the relay when O ₂ sensor measurement is outside the set switch points window and the O ₂ sensor is not in an error state	ACTION: Set/Monitor in system NOTE: Used in Section 3.3.4 on page 3-25.
Relay 2 Configuration Value	0x9C8F (40079) 0x9C90 (40080)	MSB 16-bits 0 LSB 16-bits 0 = Open 1 = Closed	ACTION: Set/Monitor in system NOTES: Any changes are saved in EEPROM and retained on power loss. See Relay 2 Configuration Value Type (30070) for data format. Used in Section 3.3.4 on page 3-25.
Relay 2 Configuration Control	0x9C91 (40081)	 0 = Nothing 1 = Change Index 2 = Apply Configuration 3 = Reset Status 	ACTION: Set in system NOTE: Used in Section 3.3.4 on page 3-25.
Relay 2 Diagnostic Index	0x9C92 (40082)	Reserved	ACTION: None
Relay 2 Diagnostic Control	0x9C93 (40083)	Reserved	ACTION: None

3.3.4 Configuring Relay 2 System States

Configure the relay state during each of the system conditions:

- 1. Confirm Relay 2 Configuration Status = Ready (30071 = 2).
- 2. Change Relay 2 Configuration Index (40078) to the system state to be configured.
- 3. Set *Relay 2 Configuration Control* to *Change Index* to load the selected system state (40081 = 1).
- 4. Change *Relay 2 Configuration Value* to the desired relay state.
- 5. Set *Relay 2 Configuration Control* to *Apply Configuration* to save the change (40081 = 2).
- 6. Monitor Relay 2 Configuration Status which will change to Busy momentarily then Complete (30071 = $3 \rightarrow 4$).
- 7. Set Relay 2 Configuration Control to Reset Status (40081 = 3) to return Relay 2 Configuration Status to Ready (30071 = 2).
- 8. Repeat Steps 1 to 7 for each system state as required.

3.3.5 4 – 20mA Registers

The device is factory set to output a range of $0-25\%~O_2$ via the 4-20mA analogue output (Analogue Out1).

Table 3-15 – 4-20mA - Input Registers

Name	Register	Description	Actions / Notes
4-20mA ID	0x757C (30076)	-	ACTION: For reference NOTE: Unique output identifier.
4-20mA Warning	0x757D (30077)	Reserved	ACTION: None
4-20mA Error	0x757E (30078)	Reserved	ACTION: None
4-20mA Value	0x757F (30079)	Floating point IEEE 754 (MSB 16-bits) Unit = mA Valid Range = 2.00 to 20.00	ACTION: Monitor in system
	0x7580 (30080)	Floating point IEEE 754 (LSB 16-bits) Unit = mA Valid Range = 2.00 to 20.00	
4-20mA Status	0x7581 (30081)	O = Loading System initialising, 4-20mA in start-up state 1 = Reserved 2 = Standby O ₂ sensor measurements off, 4-20mA in standby state 3 = ON O ₂ sensor measurements on, 4-20mA value depends the O ₂ measurement and the set sensor range	ACTION: Monitor in system NOTE: 4-20mA Mode = Override (40086 = 1) allows the Current value in Standby and ON to be overridden for test purposes.
4-20mA Sensor Range Status	0x7582 (30082)	0 = Reserved 1 = Not Ready Modification of the sensor range is currently disabled 2 = Ready Modification of the sensor range enabled 3 = Busy Modification of the sensor range in progress 4 = Complete Modification of the sensor range complete 5 = Error Error during the modification of the sensor range	ACTION: Monitor in system NOTE: Used in Section 3.3.6 on page 3-30.
4-20mA Configuration Value Type	0x7583 (30083)	0 = Invalid 1 = 32-bit integer 2 = Floating point IEEE 754	ACTION: For reference NOTES: 4-20mA Configuration Value data format (40099 and 40100). Used in Section 3.3.7 on page 3-30.

Name	Register Address	Description	Actions / Notes
4-20mA Configuration Status	0x7584 (30084)	0 = Reserved 1 = Not Ready Configuration is currently disabled 2 = Ready Configuration enabled 3 = Busy Configuration in progress 4 = Complete Configuration complete 5 = Error Error during the configuration process	ACTION: Monitor in system NOTE: Used in Section 3.3.7 on page 3-30.
4-20mA Diagnostic Value Type	0x7585 (30085)	Reserved	ACTION: None
4-20mA Diagnostic Value	0x7586 (30086) 0x7587 (30087)	Reserved Reserved	ACTION: None
4-20mA Diagnostic Status	0x7588 (30088)	O = Unavailable Not applicable to this sensor 1 = Reserved 2 = Reserved 3 = Reserved 4 = Reserved 5 = Reserved	ACTION: None

Table 3-16 – 4-20mA – Holding Registers

Name	Register Address	Description / Valid Values	Actions / Notes
4-20mA Warning	0x9C94 (40084)	Reserved	ACTION: None
4-20mA Error	0x9C95 (40085)	Reserved	ACTION: None
4-20mA Mode	0x9C96 (40086)	0 = Normal 4-20mA value depends on O ₂ sensor value 1 = Override User controls the 4-20mA value for test purposes	ACTION: Set in system NOTE: When Override is selected the 4-20mA state is set by changing the value in 4-20mA Override Value (40087 and 40088).
4-20mA Override Value	0x9C97 (40087) 0x9C98 (40088)	Floating point IEEE 754 (MSB 16-bits) Unit = mA Valid Range = 2.00 to 20.00 Floating point IEEE 754 (LSB 16-bits) Unit = mA Valid Range = 2.00 to 20.00	ACTION: Set/Monitor in system
4-20mA Sensor Range Type	0x9C99 (40089)	0 = Sensor Range The 4-20mA value will vary linearly between the minimum and maximum set sensor range	ACTION: None NOTE: Sensor range is the only option available.
4-20mA Sensor Range - Input Sensor ID	0x9C9A (40090)	-	ACTION: For reference NOTE: O ₂ sensor unique identifier that the 4-20mA function is linked to.
4-20mA Lower Sensor Range	0x9C9B (40091)	Floating point IEEE 754 (MSB 16-bits) Unit = % O ₂ Valid Range = 0.00 to (4-20mA Upper Sensor Range – 0.01) Recommended Range = 0.00 to (4-20mA Upper Sensor Range – 1.00)	ACTION: Set/Monitor in system NOTES: Any changes are saved in EEPROM and retained on power loss. This value must be less than 4-20mA Upper Sensor Range
	0x9C9C (40092)	Floating point IEEE 754 (LSB 16-bits) Unit = % O ₂ Valid Range = 0.00 to (4-20mA Upper Sensor Range – 0.01) Recommended Range = 0.00 to (4-20mA Upper Sensor Range – 1.00)	(40093 and 40094). Used in Section 3.3.6 on page 3-30.

Name	Register Address	Description / Valid Values	Actions / Notes
4-20mA Upper Sensor Range	0x9C9D (40093)	Floating point IEEE 754 (MSB 16-bits) Unit = % O ₂ Valid Range = (4-20mA Lower Sensor Range + 0.01) to 25.00 Recommended Range = (4-20mA Lower Sensor Range + 1.00) to 25.00	ACTION: Set/Monitor in system NOTES: Any changes are saved in EEPROM and retained on power loss. This value must be less than 4-20mA
	0x9C9E (40094)	Floating point IEEE 754 (MSB 16-bits) Unit = % O ₂ Valid Range = (4-20mA Lower Sensor Range + 0.01) to 25.00 Recommended Range = (4-20mA Lower Sensor Range + 1.00) to 25.00	Lower Sensor Range (40091 and 40092). Used in Section 3.3.6 on page 3-30.
4-20mA Sensor Range Hysteresis	0x9C9F (40095) 0x9CA0 (40096)	Reserved Reserved	ACTION: None
4-20mA Sensor Range Control	0x9CA1 (40097)	 0 = Nothing 1 = Reserved 2 = Apply Sensor Range 3 = Reset Status 	ACTION: Set in system NOTE: Used in Section 3.3.6 on page 3-30.
4-20mA Configuration Index	0x9CA2 (40098)	0 = Start-up 4-20mA value when the system is initialising 1 = Standby 4-20mA value when O ₂ measurements are off 2 = Error 4-20mA value during an error condition	ACTION: Set/Monitor in system NOTE: Used in Section 3.3.7 on page 3-30.
4-20mA Configuration Value	0x9CA3 (40099)	MSB 16-bits Unit = mA Valid Range = 2.00 to 20.00	ACTION: Set/Monitor in system NOTES: Any changes are saved in EEPROM and retained on power
	0x9CA4 (40100)	LSB 16-bits Unit = mA Valid Range = 2.00 to 20.00	loss. See 4-20mA Configuration Value Type (30083) for data format. Used in Section 3.3.7 on page 3-30.
4-20mA Configuration Control	0x9CA5 (40101)	 0 = Nothing 1 = Change Index 2 = Apply Configuration 3 = Reset Status 	ACTION: Set in system NOTE: Used in Section 3.3.7 on page 3-30.
4-20mA Diagnostic Index	0x9CA6 (40102)	Reserved	ACTION: None
4-20mA Diagnostic Control	0x9CA7 (40103)	Reserved	ACTION: None

3.3.6 Configuring the Sensor Range Applied to the 4-20mA Output

The 4-20mA output is factory set to represent a sensor range of 0 - 25% O₂; where 0% O₂ is equal to 4mA and 25% O₂ is equal to 20mA.

This applied sensor range is configurable; an example of changing the lower and upper sensor ranges would be in a combustion atmosphere where the O_2 range is between 5 – 21%. The user could set the lower output range to 4% and the upper output range to 22% and the 4-20mA output would vary linearly in between.

NOTE: The lower and upper ranges lock out the output at the set limits so in the example above, $4\% O_2$ or below would clamp the output to 4mA and $22\% O_2$ or above would clamp the output to 20mA.

- 1. Confirm 4-20mA Sensor Range Status = Ready (30082= 2).
- 2. Change 4-20mA Lower Sensor Range (40091 and 40092) and 4-20mA Upper Sensor Range (40093 and 40094) as required.
- 3. Set 4-20mA Sensor Range Control to Apply Sensor Range to commit the change/s (40097 = 2).
- 4. Monitor 4-20mA Sensor Range Status which will change to Busy momentarily then Complete (30082 = $3 \rightarrow 4$).
- 5. Set 4-20mA Sensor Range Control to Reset Status (40097 = 3) to 4-20mA Sensor Range Status to Ready (30082= 2).

3.3.7 Configuring the 4-20mA Output Value During Other System States

Configure the 4-20mA output during each of the other system conditions when the output is not proportional to the O_2 sensor output.

- 1. Confirm 4-20mA Configuration Status = Ready (30084 = 2).
- 2. Change 4-20mA Configuration Index (40098) to the system state to be configured.
- 3. Set 4-20mA Configuration Control to Change Index to load the selected system state (40101 = 1).
- 4. Change 4-20mA Configuration Value to the desired 4-20mA output.
- 5. Set 4-20mA Configuration Control to Apply Configuration to save the change (40101 = 2).
- 6. Monitor 4-20mA Configuration Status which will change to Busy momentarily then Complete (30084 = $3 \rightarrow 4$).
- 7. Set 4-20mA Configuration Control to Reset Status (40101 = 3) to return 4-20mA Configuration Status to Ready (30084 = 2).
- 8. Repeat Steps 1 to 7 for each system state as required.

REFERENCE DOCUMENTS

Reference documents are listed below. The CO2Meter documentation list is not exhaustive, always refer to the CO2Meter website for the latest information.

NOTE: Any industry standards referenced, always refer to the appropriate website to ensure the most up-to-date version is used.

Part Number	Title
GAP-100	Gastrack Gas Analyzer Probe (GAP-100) – Installation,
GAP-100	Operation and Maintenance Guide
GAP-100	Gastrack Gas Analyzer Probe (GAP) – Quick Start Guide
GAP-100	Gastrack Gas Analyzer Probe (GAP) – Datasheet



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For more information, visit: www.co2meter.com/pages/terms-conditions

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