

Leica Geosystems intelligent CONstruction.

Whether you construct buildings, roads, bridges or tunnels, you benefit from intelligent CONstruction. Leica iCON is more than a new product line or software package, it enables you to enhance your performance, and increase your profitability through perfecting your construction workflow.

Understanding construction demands outstanding solutions:

- Custom-built
- Complete
- Straightforward
- High performance

When it has to be right.



Swiss Technology y Leica Geosyste

The Bluetooth® word mark and logos are owned by Bluetooth SIG, Inc. and any use of such marks by Leica Geosystems AG is under license. Other trademarks and trade names are those of their respective owners.









Leica iCON CC80 Robust, light-weight tablet with multi touchscreen and versatile communication

capabilities.

Leica iCON builder 60

The intuitive user

interface paired



Leica Builder Intuitive, powerful and scalable manual total station series for routine construction tasks



Leica iCON robot 60 perfects one-person construction layout and 3D machine control.

Its high performance tracking, innovative lock \mathcal{E} find mechanisms and software that is tailored per work step, make it the ideal partner on site.

The powerful iCONstruct field software used as remote control optimises the functionality.

- Setup Pilot world's first fully automatic setup measurement method
 - Cube Search boosts prism search to a maximum
 - Target Snap ignores other prisms, just locks to yours
- \bigcirc ATACK support for PaveSmart 3D

steers rod-man to line of sight

Electronic Guide Light (EGL)

3.280 ft

Illustrations, descriptions and technical data are not binding. All rights reserved. Printed in Switzerland – Copyright Leica Geosystems AG, Heerbrugg, Switzerland, 2017. 793560en - 03.17

Leica Geosystems AG

leica-geosystems.com



© 2017 Hexagon AB and/or its subsidiaries and affiliates. Leica Geosystems is part of Hexagon. All rights reserved.



Leica iCON robot 60 Product information



- when it has to be **right**



Leica iCON robot 60 One instrument for many tasks

Applications



Layout lines for footings or chalk line for formwork on foundation



Layout points on blinding layer such as pipe insert or cut-outs before pouring concrete



MEP layout of wall penetrations for pipes, hanger locations for HVAC and duct work, inserts and slits for sheet metal work



Controlling a wide variety of machines, such as curb & gutter or milling machines, asphalt or concrete pavers, graders or dozers, rock drilling machines or excavators

Hardware Features



Cube Search builds a virtual cube around the prism position, dynamically updates its position and searches only within its dimensions when the tracking is interrupted.



- Industry leading coloured touch screen for best visibility
- Target Snap ensures to lock only to your pole or machine prism by excluding any "learned" points during a search routine



Finish job in two-person mode if controller is unavailable



PinPoint R1000 laser for highest measurement precision

Software Features



Setup Pilot automatically finds and measures all prisms in range, compares their geometry and calculates the total station's position without user interaction



ATACK supports the automated track alignment procedure of curb & gutter and main line pavers



Graphical map view for quick navigation and point/ line selection

No matter if on-board manual total stations, in combination with GPS or on a tablet as remote control of robotic total stations, the same iCONstruct software is now seamlessly integrated across the entire portfolio

Legend technical specifications: tandard deviation ISO 17123-3.

Overcast, no haze, visibility about 40 km; no heat shimmer Standard deviation ISO 17123-4

To Round Prism GPR1.

Under optimal conditions on Kodak Grey Card (90% reflective). Maximu range varies with atmospheric conditions, target reflectivity and

surface structure. Distance >500 m 4 mm + 2 ppm.

Single measurement every 30 second at 25° C. Battery time may be shorter if battery is not new. Reflectorless measurement time may vary according to measuring

objects, observation situations and environmental conditions. Target perfectly aligned to the

Technical Specifications iCON robot 60

| X | Angle Measurement (Hz, V) | | | |
|----------------|--|---|--|--|
| | Accuracy 1) | 1" (0.3 mgon), 2" (0.6 mgon), 5" (1.5 mgon) | | |
| | Method | Absolute, continuous, diametrical | | |
| - | Display resolution | 1" / 0.1 mgon | | |
| | Compensation | Quadruple Axis compensation | | |
| | Compensator setting accuracy | 0.5" (0.2 mgon), 1.5" (0.5 mgon) | | |
| = | Distance Measurement (Prism) | | | |
| ÷ | Range 2) | | | |
| | Round prism (Leica GRP1) | 3.500 m (12.000 ft) | | |
| _ | 360° prism (MPR122, GRZ4, GRZ122) | 2.000 m (7.000 ft) | | |
| | 360° mini prism (Leica CRZ101) | 1.000 m (3.300 ft) | | |
| | Mini prism (Leica CRP111, GMP101) | 2.000 m (7.000 ft) | | |
| | Reflective tape (60 mm x 60 mm) | 250 m (800 ft) | | |
| | Accuracy ^{3) 4)} , Measurement time | | | |
| | Standard: | 1.0 mm + 1.5 ppm / typ. 2.4 s | | |
| | Tracking: | 3.0 mm + 1.5 ppm / typ. < 0.15 s | | |
| T | Distance Measurement (Any Surface) ⁸⁾ | | | |
| | Range ⁵⁾ PinPoint R1000 | 1000 m (3.280 ft) | | |
| | Accuracy ^{3) 6)} , Measurement time | 2 mm + 2 ppm / typ. 3 s | | |
| | Laser dot size | At 30 m: approx. 7 x 10 mm | | |
| | | At 50 m: approx. 8 x 20 mm | | |
| | Shortest measurable distance | 1.5 m | | |
| | Data storage / Communication | | | |
| (\mathbf{v}) | Internal memory | 1 GB, > 50.000 points | | |
| | USB memory stick | 1 GB | | |
| | SD card | 8 GB | | |
| | Interfaces | - Serial (Baudrate up to 115'200) | | |
| | | – USB Type A and mini B, | | |
| | | - Bluetooth® Wireless, class 1 | | |
| | | Bluetooth[®] > 1000 m (with TCPS29-S) | | |
| | Data formats | TXT/CSV (ASCII), DXF, HeXML, TRM, GEO, LIN | | |

| icon | Leica iCONstruct Onboard Software | | |
|------|-----------------------------------|---|--|
| | Functionality of iCON robot 60 | Data settings, Communication settings, | |
| | Starter Kit | Levelling, Field Calibration | |
| _ | Extra functionality | iCON build, iCON site, iCON build plus, iCON site p | |
| | | iCON app "As-Built", iCON app "Layout Lines", iCo | |
| | | "Machine Control", Power Search Option, Reflect | |
| | | iCONstruct MC Kit | |
| | Leica iCONstruct MC Kit | | |
| | Includes | Data Settings, Communication Settings, Levelling | |
| | | Setup Pilot, Target Snap, Cube Search. | |
| | | | |

One-person or Machine Control Mode

| Motorization | Rotation speed | 45° (50 gon) / s | | | |
|--|--|-----------------------------|---|--|--|
| Automatic Target Aiming (ATR) | Range | ATR Mode | Lock Mode | | |
| | Round prism (GPR1) | 1000 m (3300 ft) | 800 m (2600 ft) | | |
| | 360° prism (MPR122, GRZ4, GRZ122) | 800 m (2600 ft) | 600 m (2000 ft) | | |
| | 360° mini prism (GRZ101) | 350 m (1150 ft) | 200 m (660 ft) | | |
| | Mini prism (GMP101) | 500 m (1600 ft) | 400 m (1300 ft) | | |
| | Reflective tape (60 mm x 60 mm) | 45 m (150 ft) | - | | |
| | Shortest distance to 360° prism | 1.5 m | 5 m | | |
| | Maximum Speed (Lock Mode) | | | | |
| | Tangential (standard mode) | 5 m / s at 20 m, 25 m / s a | 5 m / s at 20 m, 25 m / s at 100 m | | |
| | Radial (tracking mode) | 4 m / s | 4 m / s | | |
| | Searching | | | | |
| | Search time in field of view | Typ. 1.5 s | | | |
| | Field of View | 1° 30' (1.66 gon) | 1° 30' (1.66 gon) | | |
| Power Search (PS) | Range | | | | |
| | Round prism (GPR1) | 300 m (1000 ft) | | | |
| | 360° prism ⁹ (MPR122, GRZ4, GRZ122) | 300 m (1000 ft) | | | |
| the second s | Mini prism (CPR111, GMP101) | 100 m (330 ft) | | | |
| | Shortest distance | 1.5 m | | | |
| | Searching | | | | |
| | Typical search time | 5 – 10 s | | | |
| | Default search area | Hz: 360° (400 gon), V: 36° | | | |
| | Definable default search | | arch / Power Search Window / 360° Search or combination | | |
| | Dynamic search window | Cube Search | Cube Search | | |
| | Definable search windows | Yes | | | |



| 60 | | | | |
|---------|-------------------------------------|--|--|--|
| \odot | Guide Light (EGL) | Guide Light (EGL) | | |
| 0 | Working range | 5 m – 150 m | | |
| | (average atmospheric conditions) | | | |
| _ | Positioning accuracy | 5 cm at 100 m | | |
| | Telescope | | | |
| | Magnification | 30 x | | |
| | Field of View | 1° 30' (1.66 gon) | | |
| | | 2.7 m at 100 m | | |
| | Focusing range | 1.7 m to infinity | | |
| 789 | Keyboard & Display | | | |
| | Display | High resolution Color & Touch display, | | |
| | | 65'000 colors, graphics, Full-VGA, | | |
| | | display illumination, 10 brightness levels | | |
| | Keyboard | 22 keys (4 function keys, 12 | | |
| | | alphanumeric keys), illumination | | |
| | Operating System & Processor | | | |
| | Operating system | Windows CE 6.0 | | |
| | Processor | Freescale i.MX31 533 MHz ARM Core | | |
| | Laserplummet | | | |
| | Туре | Laser point | | |
| | Centering accuracy | 1.5 mm at 1.5 m Instrument height | | |
| | Internal Battery | | | |
| | Туре | Lithium-Ion | | |
| | Operating time 7) | approx. 5-7 hours | | |
| | Weight | | | |
| | Total station including battery | 5.9 kg | | |
| | GEB222 and tribrach | | | |
| | Height / Width / Length | 345 mm / 226 mm / 203 mm | | |
| | Environmental | | | |
| | Working / Storage temperature range | -20° C to +50° C / -40° C to +70° C | | |
| | Dust / Water (IEC 60529) Humidity | IP55, 95%, non condensing | | |
| | | | | |

olus, iCON app "Sketch", iCON app "Volumes", iCON app "Stakeout", iCON app "Control Line" ON app "Cut & Fill", iCON app "Roading", iCON app "Slopes", iCON app "Checks", iCON app rless Option, Setup Pilot Option, Target Snap Option, Cube Search Option, ATACK Option,

Field Calibration, Instrument Setup, Measure app, Machine Control app, Power Search,