

Instruction

Thank you for purchasing the "QUICRUN 3650 SENSORED" brushless motor(s) for RC cars! The high power system can be very dangerous, so please read this manual carefully before using and follow the operating procedures strictly. In that we have no control over the installation, use and maintenance of this product, no liability shall be assumed nor accepted for damages, losses or costs resulting from the use of this product. Besides, we own the right to change the product design, appearance, functions and operational requirements without any notifications.

Safety Notes

This product is NOT a toy and it is for use by adults and teens over 14 only, so please keep it out of children's reach. Please keep the following points in mind; otherwise it may damage the product and cause property loss and physical injuries to users.

- 1) Never leave this product unsupervised when it is powered on. If any problem occurs, the product may cause a fire and jeopardize peripheral devices.
- 2) Please check wire sequences between the ESC & the motor carefully before the connection, to avoid any possible mistakes.
- 3) Please insure all the wires and interconnecting pieces are well insulated before the connection, as short circuits may damage the product.
- 4) Never allow water, oil, fuel or other conducting liquids to get inside this product or other electronic parts, as these liquids may contain harmful minerals for electrical circuits. If that really happens, please turn off the device immediately, and then clear and blow-dry it carefully.
- 5) Please read through manuals of each power equipment (like ESC, motor, battery, etc) and chassis to ensure the power system configuration is rational before the use, as the incorrect power system configuration may result in overload and eventually damage the equipments.
- 6) Prohibit the full throttle operation before the pinion installation. Under non-loaded circumstances, over-high RPM may cause damage to the motor.
- 7) Make sure all the parts are well connected, as misconnection or poor connection may lead to abnormal control, damage or other unpredictable problems.
- 8) Never let the temperature of the motor can (shell) exceeds 90°C (194°F), otherwise the motor will be damaged and (or) the rotor will be demagnetized.

Installation & Connection

1. To Install the Motor

- 1) Screws used for installation are 3mm in diameter & 5mm in length. Before mounting the motor onto the vehicle, please ensure that all the screws are applicable to avoid damaging the motor. In general it's ok to adopt screws which are 3 mm in diameter and less than 8mm in length; the specific length is up to the chassis size.
- 2) Install the golden connectors; here it adopts the brand new method to fasten male & female connectors by screws. (Please check Figure 1 for reference).

2. To Connect the Motor

- 1) Three power wires need to be connected to the motor, and they often differ in colors: Phase wire A is Blue, Phase wire B is Yellow and Phase wire C is Orange. Please note the ESC mark while connecting ESC output wires to motor power wires and ensure connections are: A-A, B-B and C-C.
- 2) If you are using a sensored ESC, please insure Hall-sensor wires are clean and undamaged; then connect them in the correct direction to the sensor ports of the motor & the ESC respectively. **Warning:** In such a case, the wire sequence of the ESC and the motor must strictly follow the rules of A-A, B-B and C-C. Do not change the wires sequence.
- 3) While if the ESC is a sensorless one, then connect the motor and the ESC according to the above way may cause the motor to rotate in the opposite direction, because definitions of phase (#A / #B / #C) are different among manufacturers, at this time you only need to swap any of two wire connections.

3. Checkup

Recheck the installation and all the connections carefully before turning on the power.



Figure 1

Specifications

Model	Purchase Number	KV	Lipo	Resistance (Ω)	No-load Current	Max. Output Power	Current at the Point of M.O.P*	Dimension (mm)	Shaft* (mm)	Poles	Weight (g)	Applicable
QUICRUN-3650-10.5T	30404110001	3300KV	2~3S	0.0178	2.1A	240W	62A	Outer Diameter 35.8	Diameter 3.17	2	160	1/10 ,1/12 On-Road (Truggy/Drifting Car/F1/Monster) & Off-Road (Buggy/2WD SC Truck/Truck) STOCK/SPORT Race (choose the motor base on competition rules.) Free/casual run for new beginners. Rock Crawler (21.5T only)
QUICRUN-3650-13.5T	30404110002	2500KV		0.0285	1.5A	180W	50A	Length of projecting part 52.5	161			
QUICRUN-3650-17.5T	30404110003	1900KV		0.0588	1.3A	125W	35A				160	
QUICRUN-3650-21.5T	30404110004	1700KV		0.0895	1.0A	95W	28A					

Notes: M.O.P=Maximum Output Power.

- 1) The maximum output power is the test value obtained when the voltage is 7.4V, the ESC timing is set to 0°. It is neither the maximum input power nor the rated power. The calculation formula used here is: RPM x Torque / 9550.
- 2) The value of the maximum output power is always lower than the value of the input power. Therefore, it's meaningless to compare the maximum output power mentioned in the form above with the input power of motors of other brands. Besides, values in the form above may differ from the test data of other factories because of different test benches.
- 3) The input current at the point of the maximum output power is useful for the load configuration and the ESC selection; here we strongly suggest users not make the load quota bigger than the "maximum output power point", that means please don't make the input current larger than the current at the maximum output power point.
- 4) As the power of 10.5T, 13.5T, 17.5T & 21.5T motor is not big, so they are not applicable for 4WD/Monster trucks and other high weight and heavy load vehicles or games need very great power. If forcibly use them in those conditions, perhaps they will get burnt. Hereby, we suggest users choose the 4-pole motor with great power like QUICRUN-3656 (KV=3800) when high power is needed.

Gear Selection (IMPORTANT!)

It is very important to select the reasonable gear ratio, as inappropriate selection may cause great loss to users.

Please select the correct gear ratio according to the following points!

1. Operating Temperature of the Motor

During the operation, the motor temperature should be lower than 90°C (194°F). Temperatures above 90°C will demagnetize the magnet & may melt the coils and eventually damage the ESC (because of strong current). Therefore, the most effective way to prevent over-heat is to select the right gear ratio.

2. Principle of Gear Selection

To avoid potential risks, caused by overheating, which may lead to ESC/motor damage or malfunction, please start with very small pinion and check ESC & motor temperatures frequently throughout a run. This is the only way to guarantee that you are not causing excessive heating. If Motor and the ESC temperatures remain stable and low in the running, then you can slowly increase the pinion (with more teeth) while again monitoring the temperatures to determine the safe gearing for your vehicle and motor. Because the climate and track conditions always change, please keep monitoring ESC & motor temperatures to protect your electronics from damage.

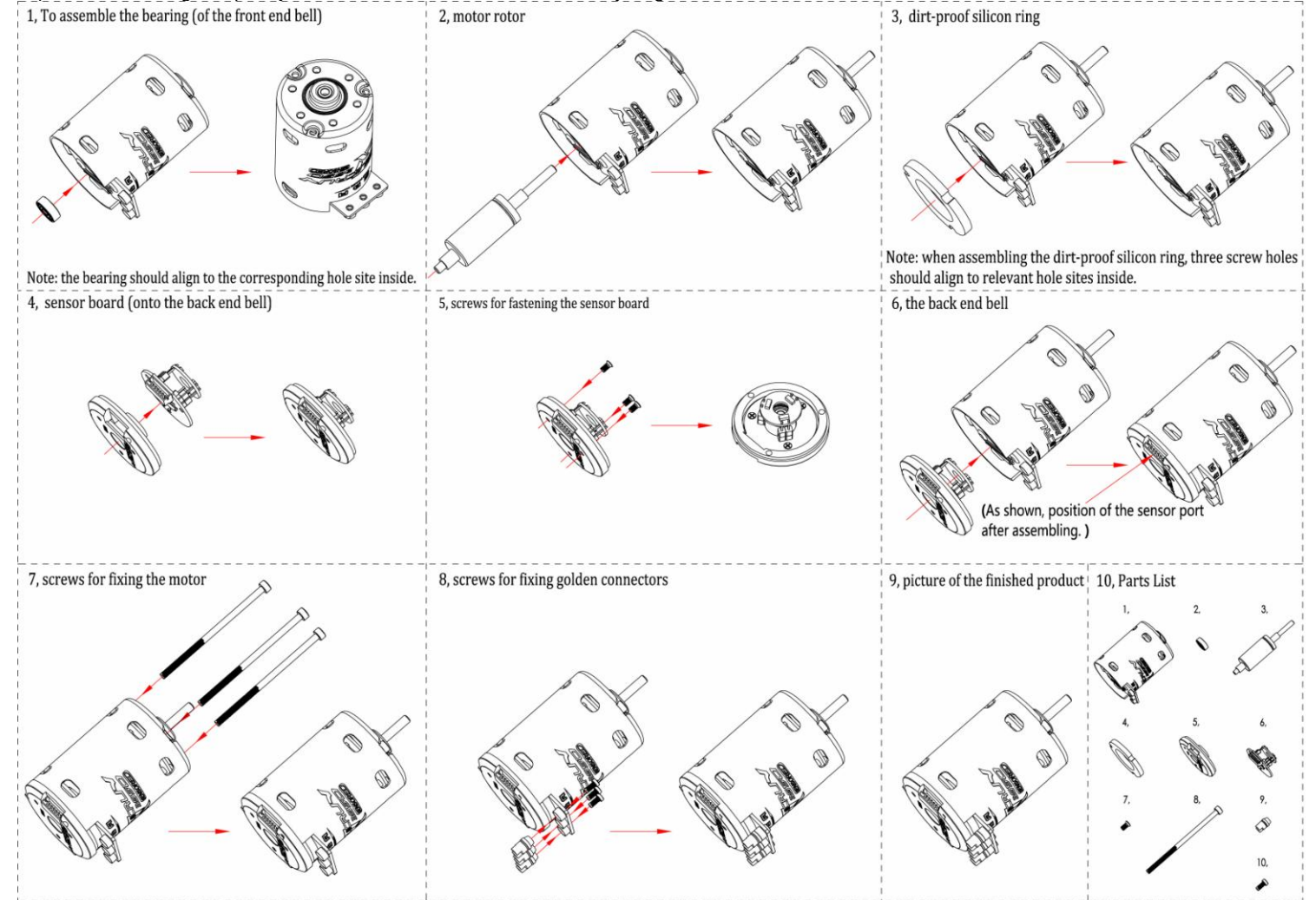
3. Gear Ratio(s) Suggested

The right form shows some rough data about gear ratios (these recommended ratios are reference values when setting the ESC to the Zero Timing Mode). If you don't know how to set the suitable gear ratio, please begin with a big ratio (i.e. small pinion) and then adjust as required, or consult with on-site drivers who are using the same power unit for basic information.

Vehicle Type	Battery	10.5T	13.5T	17.5T	21.5T
Touring Car (for Small track)	7.4V LiPo	5.5:1	4.7:1	4.0:1	3.5:1
Touring Car (for Big track)	7.4V LiPo	5.0:1	4.0:1	3.5:1	3.0:1
1/12 Touring Car	3.7V LiPo	42mm	51mm	66mm	66mm
2WD Buggy	7.4V LiPo	8.0:1	7.0:1	6.0:1	5.5:1
4WD Buggy	7.4V LiPo	8.0:1	7.0:1	6.0:1	5.5:1

Maintenance

For prolonging the motor life and raising its efficiency, we recommend users to check the bearing, and clean the motor regularly; and the specific interval depends on the usage frequency and terrains. Please follow the assembly diagram below to assemble the motor, and disassemble in reserve order.



(For high-resolution assembly diagram, please visit our website at: www.hobbywing.com)

Parts List

As shown in the diagram above, the QUICRUN-3650-SENSORED motor includes:

1) Bearing (3.175x9.525x3.967mm) x1pcs	2) Motor Rotor x1pcs	3) Outer Shell (with Front End Bell) x1pcs
4) Sensor Board x1pcs	5) Back End Bell x1pcs	6) Dirt-proof Silicon Ring x1pcs
7) Golden Connectors x3Sets	8) Screws for Fixing the Motor (M2.50x48mm) x3pcs	9) Screws for Fastening the Sensor Board (M2.00x3.0mm) x3pcs
10) Screws for Fixing Male & Female Connectors (M1.60x5.5mm) x3pcs	11) Hall-Sensor Wire (2PC: 80mm & 200mm) x1pcs	

Optional Accessories

Replaceable Part	Part No.	Product Name	Specification
Bearing	3083000001	540 MOTOR BEARING-3.175	R2ZZ bearing, 3.175*9.525*3.967
Motor Rotor	3085000034	QUICRUN-3650-Rotor-φ7-12.5	Thin magnet/No cooling fan Diameter of the through-hole in the rotor: 7mm, Outer diameter of the magnet: 12.5mm